



# Efficient High Dimensional Bayesian Optimization with Additivity and Quadrature Fourier Features

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# Bayesian Optimization

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 $g \sim GP(0, k)$  with  
a stationary kernel  $k$
  
- **Metric:** cumulative regret:  $R_T = \sum_{t=1}^T g(x_t) - g(x^*)$
- **Challenge:** exploration vs. exploitation  $\implies$  Bayesian Optimization.

# Challenges of high dimensions

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- **Statistical**

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## Additive functions


$$g(\boxed{x_1} \boxed{x_2} \boxed{x_3} \boxed{x_4}) = g_1(\boxed{x_1} \boxed{x_2}) + g_2(\boxed{x_3}) + g_3(\boxed{x_4})$$



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$$g(\underbrace{x_1}_{\text{blue}} \underbrace{x_2}_{\text{orange}} \underbrace{x_3}_{\text{grey}} \underbrace{x_4}_{\text{green}}) = g_1(\underbrace{x_1}_{\text{blue}} \underbrace{x_2}_{\text{orange}}) + g_2(\underbrace{x_2}_{\text{orange}} \underbrace{x_3}_{\text{grey}}) + g_3(\underbrace{x_4}_{\text{green}})$$
An orange double-headed arrow labeled "shared" points from the  $x_2$  term in the first function  $g_1(x_1, x_2)$  to the  $x_2$  term in the second function  $g_2(x_2, x_3)$ .

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- **Computational**

- Kernel inversion  $\mathcal{O}(T^3) \rightarrow \mathcal{O}(T \log T)$
- Optimization of the acquisition function → coordinate optimization

# Main tool: Quadrature Fourier Features (QFF)

$$k(x-y) \stackrel{\text{Bochner}}{=} \int_{\Omega} p(\omega) \begin{pmatrix} \cos(\omega^{\top} x) \\ \sin(\omega^{\top} x) \end{pmatrix}^{\top} \begin{pmatrix} \cos(\omega^{\top} y) \\ \sin(\omega^{\top} y) \end{pmatrix} d\omega$$



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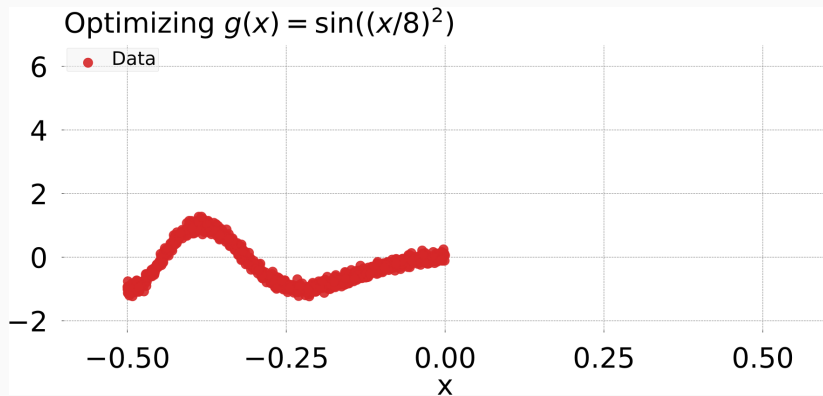
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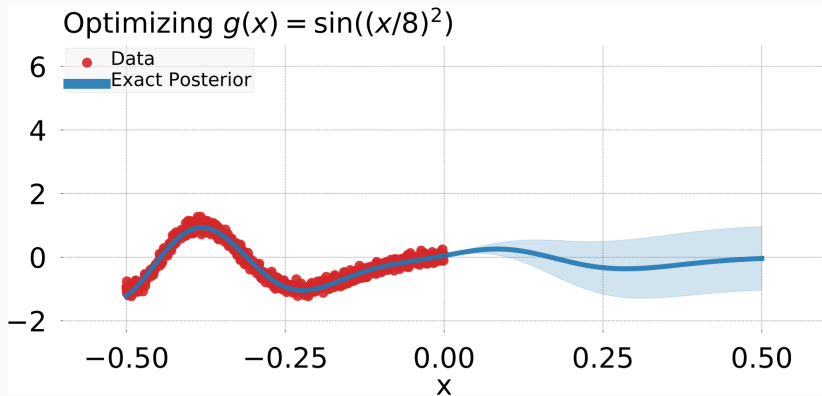
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- This work: **Gaussian Quadrature**.
- (generalized) additivity  $\implies$  favorable scaling with  $\bar{d}$ ,

$$\|k(x, y) - \Phi(x)^\top \Phi(y)\|_{\infty} = \mathcal{O}\left(2^{\bar{d}} \rho^m\right) \quad \rho < 1$$

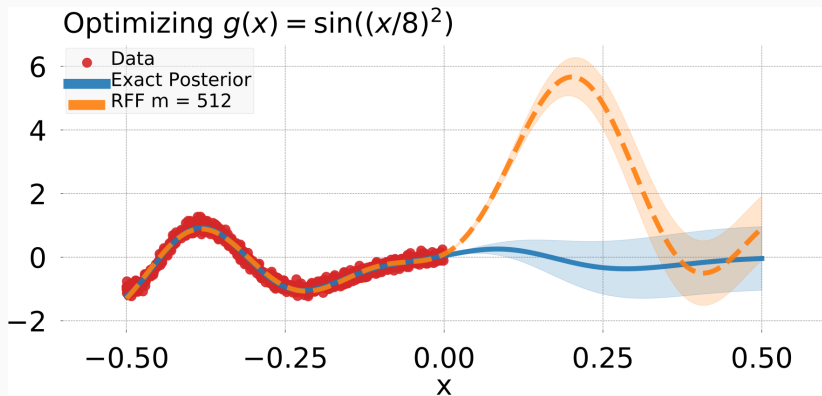
# Example



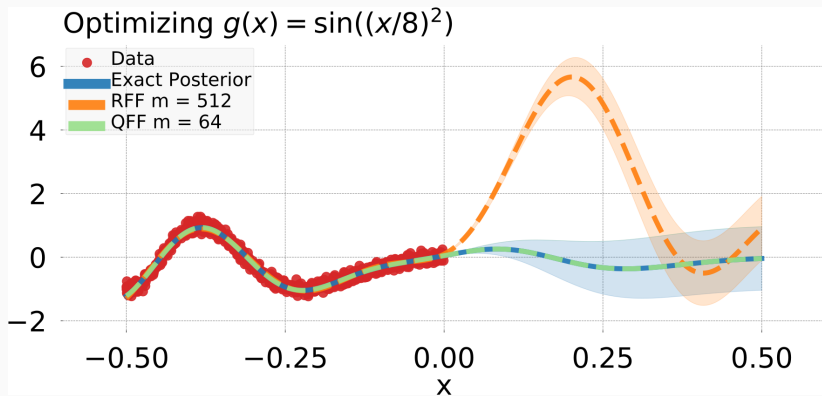
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Please come to the poster #23.

Room 210 & 230 AB



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