Byzantine-tolerant federated Gaussian process regression for streaming data

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Problem formulation

Network model:

- Cloud can communicate with agents
- Agents cannot communicate with each other
- Byzantine agents send arbitrary model parameters to the cloud **Observation model:**



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$$y^{[i]}(t) = \eta(\boldsymbol{z}^{[i]}(t)) + e^{[i]}(t)$$

• Training data $(\boldsymbol{z}^{[i]}(t), y^{[i]}(t))$ arrive sequentially

Objective: Design a Byzantine-tolerant algorithm which

- Correctly learns the function η
- Does not require to share local streaming data $(\boldsymbol{z}^{[i]}(t), \boldsymbol{y}^{[i]}(t))$

Byzantine-tolerant federated GPR

Contribution

Design a Byzantine-tolerant federated Gaussian process regression (GPR) algorithm which

- Can guarantee the correct predictions and tolerate less than one quarter Byzantine agents
- Can deal with streaming data and perform on-line learning



Agent-based local GPR



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Cloud-based aggregated GPR



• Byzantine-tolerant product of experts (PoE):

$$\hat{\mu}_{\boldsymbol{z}_{*}|\mathcal{D}(t)} = \frac{\hat{\sigma}_{\boldsymbol{z}_{*}|\mathcal{D}(t)}^{2}}{|\mathcal{I}(t)|} \sum_{i \in \mathcal{I}(t)} \check{\mu}_{\boldsymbol{z}_{*}|\mathcal{D}^{[i]}(t)}^{i} \check{\sigma}_{\boldsymbol{z}_{*}|\mathcal{D}^{[i]}(t)}^{\prime-2},$$
$$\hat{\sigma}_{\boldsymbol{z}_{*}|\mathcal{D}(t)}^{2} = \frac{|\mathcal{I}(t)|}{\sum_{i \in \mathcal{I}(t)} \check{\sigma}_{\boldsymbol{z}_{*}|\mathcal{D}^{[i]}(t)}^{\prime-2}}.$$

(Xu Zhang (Penn State))

Byzantine-tolerant federated GPR

Agent-based fused GPR



• Output:
$$\tilde{\mu}_{\boldsymbol{z}_*|\mathcal{D}(t)}^{[i]}, \, (\tilde{\sigma}_{\boldsymbol{z}_*|\mathcal{D}(t)}^{[i]})^2$$

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Robustness of cloud-based aggregated GPR

Assumption

Less than one quarter of the agents are Byzantine.

Dispersion: $d^{[i]}(t) \triangleq \sup_{\boldsymbol{z} \in \boldsymbol{\mathcal{Z}}} D(\boldsymbol{z}, \boldsymbol{\mathcal{Z}}^{[i]}(t))$

Theorem (Cloud-based aggregated GPR: Mean)

For any $\mathbf{z}_* \in \mathbf{Z}$ and $0 < \delta < 1$, with probability at least $1 - \delta$, it holds that $\left|\hat{\mu}_{\mathbf{z}_*|\mathcal{D}(t)} - \eta(\mathbf{z}_*)\right| \leq (1 - \frac{\kappa(d^{\max}(t))}{\sigma_f^2 + (\sigma_e^{\max})^2}) \|\eta\|_{\infty} + \frac{\sigma_f^2 \ell_\eta d^{\max}(t)}{\sigma_f^2 + (\sigma_e^{\min})^2} + \sqrt{2\sigma^2(\ln 2 - \ln \delta)} + \Delta(d^{\max}(t)) \text{ where}$ $\Delta(s) \triangleq \frac{2\alpha(\sqrt{2\sigma^2(\ln(2n) - \ln \delta)} + \frac{\sigma_f^2 \|\eta\|_{\infty}}{\sigma_f^2 + (\sigma_e^{\min})^2})}{1 - 4\beta} \frac{\sigma_f^4 + \sigma_f^2(\sigma_e^{\max})^2 - \kappa(s)^2}{\sigma_f^2(\sigma_e^{\min})^2}.$

Theorem (Cloud-based aggregated GPR: Variance)

For any
$$\boldsymbol{z}_* \in \boldsymbol{\mathcal{Z}}$$
, it holds that $\frac{\sigma_f^2(\sigma_e^{\min})^2}{\sigma_f^2 + (\sigma_e^{\max})^2} \leq \hat{\sigma}_{\boldsymbol{z}_*|\mathcal{D}(t)}^2 \leq \sigma_f^2 - \frac{\kappa (d^{\max}(t))^2}{\sigma_f^2 + (\sigma_e^{\max})^2}.$

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Experiments (Synthetic dataset)

Experiment 1: Prediction performance in terms of consistency and different $\alpha,\,\beta$



(a) Consistency evaluation

(b) Prediction performance on different β

Experiment 2: Prediction performance on different functions

Algorithm	AfPoE	BtPoE	AedPoE
MSE (×10 ⁻³)	0.0049 ± 0.007	0.0236 ± 0.172	26.5339 ± 0.019

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Experiments (Real-world datasets)

Experiment 3: Performance on different attack magnitudes







(c) Attack-free standard PoE

(d) Byzantine-tolerant PoE

(e) Attacked standard PoE



Kin40k Kin40k 10 10^{-0.2|} ŧ USW 10 à Ť USW 10^{-0.4} 10 10^{-0.6} 10 -50 50 -100 100 -10 10 -50 50 -100 100 -10 Attack magnitude Attack magnitude (g) Byzantine-tolerant PoE Attacked standard PoE (h)

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Byzantine-tolerant federated GPR

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Conclusion

- Design a Byzantine-tolerant federated GPR algorithm
- Derive the upper bounds on the prediction errors and the lower and upper bounds of the predictive variances
- Demonstrate the robustness of Byzantine-tolerant GPR algorithm through experiments

Thank you





