# Non-Gaussian Tensor Programs 

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Recall the limit theorems in probability theory:

## 1. Law of Large Numbers:

An average of $n$ iid random variables converges to their mean as $n \rightarrow \infty$.

## 2. Central Limit Theorem:

An average of $n$ iid zero-mean random variables scaled by $\sqrt{n}$ converges to a zero-mean Gaussian as $n \rightarrow \infty$.

Both state universality: the limits do not depend on the distribution of random variables albeit several first moments.

A universality principle for neural networks?

## Conjecture

As width tends to infinity, two different iid random initializations induce identical training behavior as long as they sample weights with the same mean and variance.

When the above principle works:

$$
f(\xi)=\frac{1}{n} V^{\top} \phi(g(\xi)), \quad g(\xi)=W \phi(U \xi), \quad \xi \in \mathbb{R}, \quad U, V \in \mathbb{R}^{n}, \quad W \in \mathbb{R}^{n \times n}
$$

Consider two alternatives $(G)$ and $(R)$ for sampling $W$ :

$$
\text { (R) } W_{\alpha \beta} \sim \operatorname{Unif}([-\sqrt{3 / n}, \sqrt{3 / n}]) \quad \text { or } \quad \text { (G) } W_{\alpha \beta} \sim \mathcal{N}(0,1 / n) \text {. }
$$

The distribution of $g_{\alpha}(\xi)$ tends to the same Gaussian by CLT for both (R) and (G)!

When the above principle fails:

$$
f(\xi)=\frac{1}{n} U^{\top} \phi(U \xi), \quad \xi \in \mathbb{R}, \quad U \in \mathbb{R}^{n} .
$$

Consider two alternatives $(G)$ and $(R)$ for sampling $U$ :

$$
\text { (R) } U_{\alpha}= \pm 1 \text { with prob. } 1 / 2 \quad \text { or } \quad \text { (G) } U_{\alpha} \sim \mathcal{N}(0,1)
$$

Suppose $\phi(x)=x 1_{\left[-\frac{1}{2}, \frac{1}{2}\right]}(x)$. Then

$$
f(1)=0 \text { with init }(\mathrm{R}) \quad \text { but } \quad f(1) \rightarrow \mathbb{E}_{z} z \phi(z)>0 \text { with init (G) }
$$

as $n \rightarrow \infty$, where $z \sim \mathcal{N}(0,1)$.
Take-away: Universality fails for vector-shaped weights.

Universality also fails for scalar-shaped weights:

$$
f(\xi)=b+\frac{1}{n} U^{\top} \phi(U \xi), \quad \xi \in \mathbb{R}, \quad b \in \mathbb{R}, \quad U \in \mathbb{R}^{n}
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The distribution of $f(\xi)$ depends on the distribution of $b$.

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## Conjecture

As width tends to infinity, two different iid random initializations induce identical training behavior as long as

1. They sample scalar-shaped and vector-shaped weights the same way, and
2. They sample matrix-shaped weights with the same mean and variance.

Definition ([Yang et al., 2022])
Let $P$ be a parameter tensor in a neural network of any architecture. As width becomes large,

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- if $P$ 's size remains constant, then we say $P$ is scalar-like;
- if exactly one dimension of $P$ becomes large, we say $P$ is vector-like;
- if exactly two dimensions of $P$ becomes large, we say $P$ is matrix-like.


## Principle (Universality in General Neural Network Initialization)

As width becomes large, two different iid random initializations of a neural network of any architecture induce identical training behavior as long as

1. They sample scalar- and vector-like weights the same way, and
2. They sample matrix-like weights with the same mean and variance.

It is a corollary of a universality principle for tensor programs.

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A tensor program generates new vectors and scalars iteratively:

$$
\begin{equation*}
g_{\alpha}^{i} \leftarrow \sum_{\beta=1}^{n} W_{\alpha \beta}^{i} x_{\beta}^{i}, \quad c^{i} \leftarrow \frac{1}{n} \sum_{\beta=1}^{n} x_{\beta}^{i}, \quad \text { where } x_{\alpha}^{i}=\phi^{i}\left(g_{\alpha}^{1}, \ldots, g_{\alpha}^{i-1} ; c^{1}, \ldots, c^{i-1}\right), \tag{1}
\end{equation*}
$$

and

- $\phi^{i}$ is a scalar function;
- $W^{i}=A^{j}$ or $W^{i}=A^{j \top}$ for some $j \in[L]$.

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## Proposition

Let the network have $k$ outputs. For each $t$ and input $\xi$, the network output after $t$ GD steps $f_{t}(\xi)$ can be expressed as a set of $k$ scalars $c$ in some tensor program.

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## Conjecture (Universality for tensor programs)

Scalars $c^{1}, \ldots, c^{M}$ in a tensor program converge and their limits depend only on mean and variance of the distribution of entries of $A^{1}, \ldots, A^{L}$.

Theorem (Gaussian Master Theorem, [Yang, 2020b])
Consider a Tensor Program with $M$ vectors $g^{1}, \ldots, g^{M} \in \mathbb{R}^{n}$ and scalars $c^{1}, \ldots, c^{M}$. Suppose

1. All initial vectors $g^{1}, \ldots, g^{M_{0}}$ have iid entries from $\mathcal{N}(0,1)$;
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3. All the nonlinearities $\phi^{i}$ are pseudo-Lipschitz ${ }^{1}$;
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Then, as $n \rightarrow \infty$, for any $i \in[M]$,

$$
\begin{equation*}
c^{i} \xrightarrow{\text { a.s. }} \dot{c}^{i}, \tag{2}
\end{equation*}
$$

where $c^{i}$ is a deterministic scalar given by a certain recurrent formula.

[^4]
## Theorem (Non-Gaussian Master Theorem, ours)

Consider a Tensor Program with $M$ vectors $g^{1}, \ldots, g^{M} \in \mathbb{R}^{n}$ and scalars $c^{1}, \ldots, c^{M}$. Suppose

1. All initial vectors $g^{1}, \ldots, g^{M_{0}}$ have iid entries from $\mathcal{N}(0,1)$;
2. All matrices $A^{i}$ have iid entries with zero mean, variance $n^{-1}$, and each $k$-th moment bounded by $\nu_{k} n^{-k / 2}$;
3. All the nonlinearities $\phi^{i}$ are polynomially smooth ${ }^{2}$;
4. All initial scalars $c^{1}, \ldots, c^{M_{0}}$ have almost sure limits as $n \rightarrow \infty$ and all moments

Then, as $n \rightarrow \infty$, for any $i \in[M]$,

$$
\begin{equation*}
c^{i} \xrightarrow{\text { a.s. } \& L^{p}} \dot{c}^{i} \quad \forall p \in[1, \infty) \tag{3}
\end{equation*}
$$

for the same $\stackrel{c}{c}^{i}$ as in the Gaussian theorem.

[^5]\[

$$
\begin{equation*}
c^{i} \xrightarrow{\text { a.s. } \& L^{p}} \dot{c}^{i} \quad \forall p \in[1, \infty) \tag{4}
\end{equation*}
$$

\]

for the same $c^{i}$ no matter if matrix weights $A$ are Gaussian or not:

## Principle (Universality in Tensor Program Sampling)

As $n \rightarrow \infty$, two different iid random samplings of a TP's matrices and initial vectors result in identical limits of scalars as long as

1. They sample all initial vectors and initial scalars the same way, and
2. They sample all matrix entries with the same variance and zero mean .

## Applications of Master theorem:

1. NNGP correspondence: Each pre-activation output of a neural network converges to a Gaussian process as width tends to infinity. ${ }^{3}$
2. Convergence to a kernel method: Under certain parameterization, SGD training dynamics converges to the training dynamics of a kernel method as width tends to infinity. ${ }^{4}$
3. Random matrix theory: Semi-circle and Marchenko-Pastur laws.
4. Free Independence Principle: at initialization, neural network's weights become freely independent from its hidden representations as width goes to infinity. ${ }^{5}$
5. Hyperparameter transfer: optimal training hyperparameters can be transfered from thin to wide nets under certain parameterization. ${ }^{6}$
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[^0]:    ${ }^{1}$ A function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ is called pseudo-Lipschitz if there exist $C, d>0$ such that for any $x, y \in \mathbb{R}^{n}$, $\|f(x)-f(y)\| \leq C\|x-y\|\left(1+\|x\|^{d}+\|y\|^{d}\right)$.

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[^5]:    ${ }^{2}$ We call $f$ polynomially smooth if it is smooth and each derivative of order $k \geq 0$ is polynomially bounded.

[^6]:    ${ }^{3}$ [Neal, 1995, Lee et al., 2017, Garriga-Alonso et al., 2018, Novak et al., 2018, Yang, 2019]
    ${ }^{4}$ [Jacot et al., 2018, Lee et al., 2019, Yang, 2020a, Yang and Littwin, 2021]
    ${ }^{5}$ [Yang, 2020b]
    ${ }^{6}$ [Yang and Hu, 2021, Yang et al., 2022]

