

Expediting Large-Scale Vision Transformer for Dense Prediction without Fine-tuning

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Motivation

Semantic segmentation

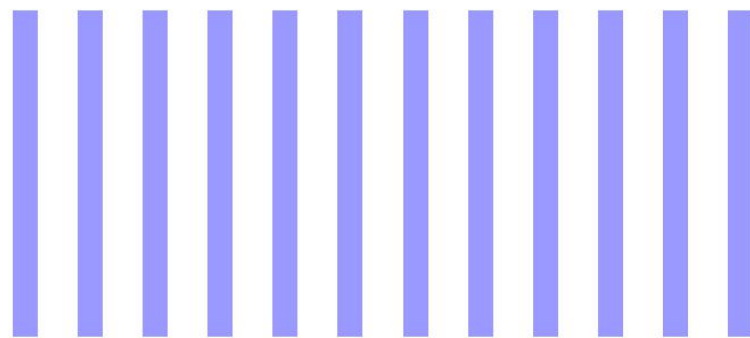
Rank	Model	Validation↑ mIoU	Test Score	Params (M)	GFLOPs (512 x 512)	Extra Training Data	Paper	Code	Result	Year	Tags
1	BEiT-3	62.8				✓	Image as a Foreign Language: BEiT Pretraining for All Vision and Vision-Language Tasks			2022	
2	FD-SwinV2-G	61.4				✓	Contrastive Learning Rivals Masked Image Modeling in Fine-tuning via Feature Distillation			2022	Swin-Transformer

Detection

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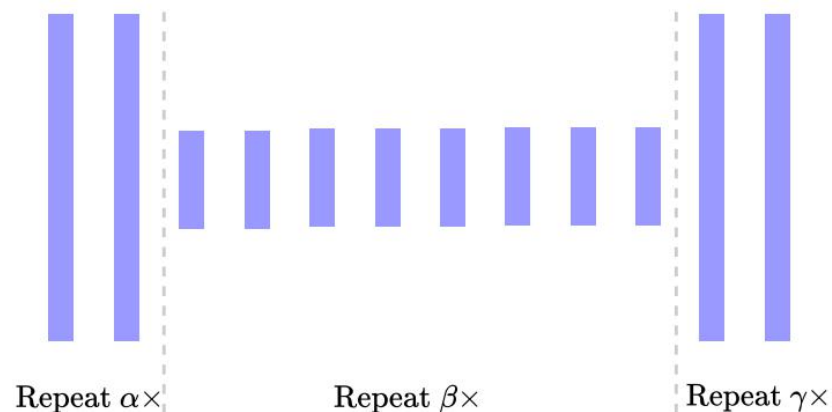
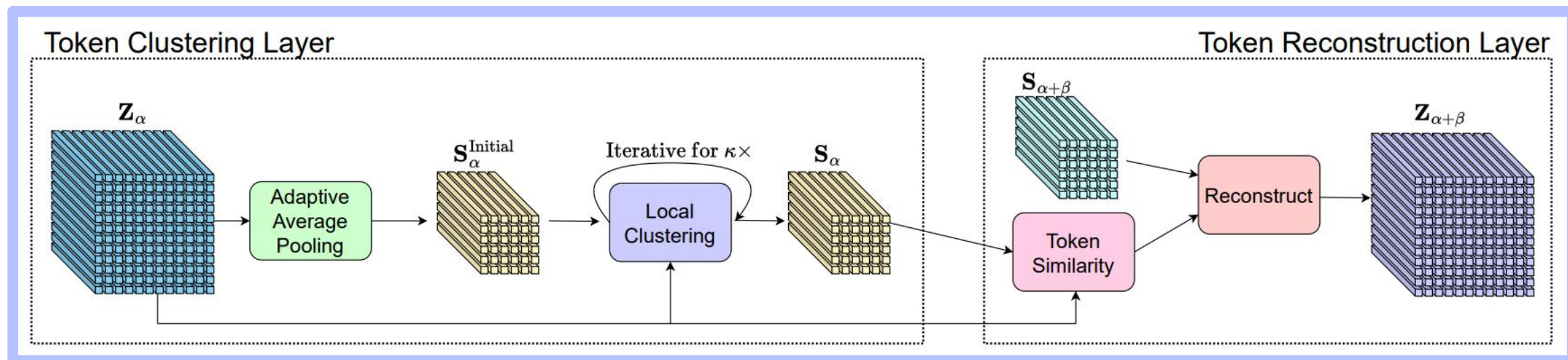
However, large-scale vision transformers suffer from **huge computation overheads** and **expensive latency**.

Our Approach



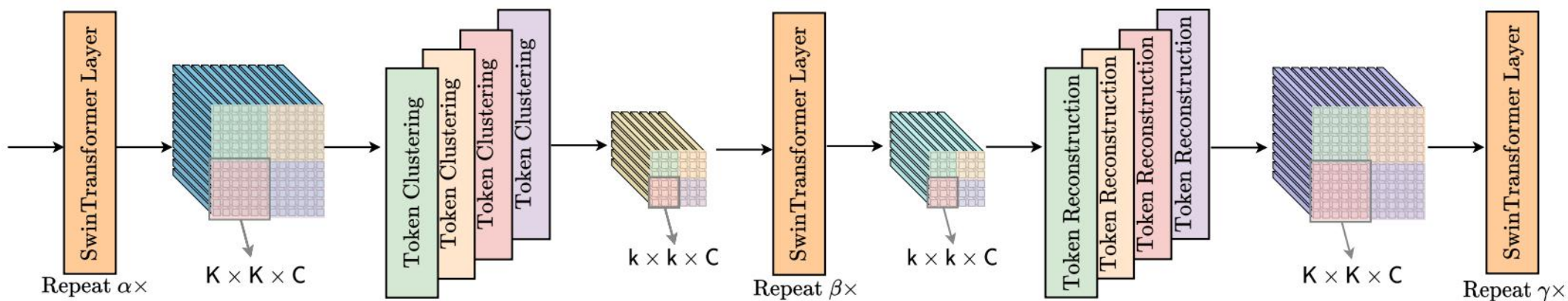
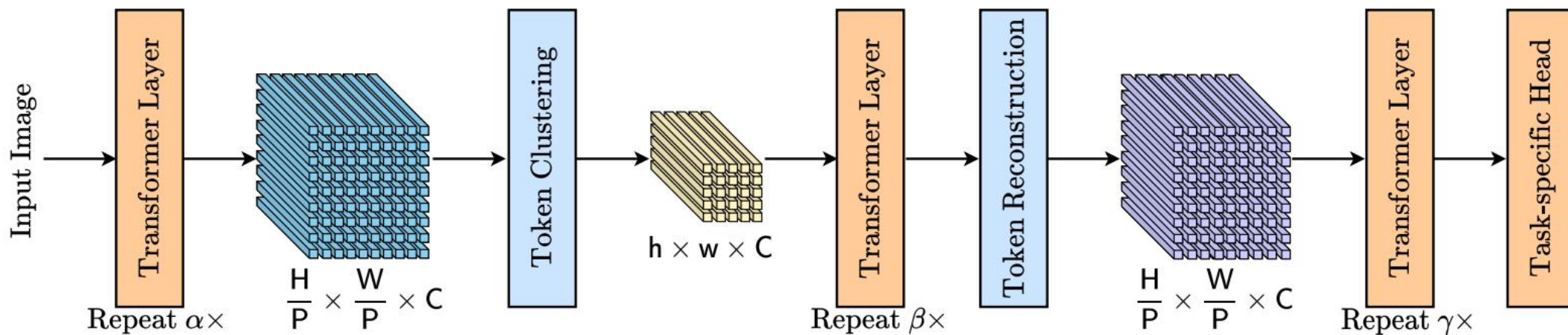
Repeat $L \times$

Plain high-resolution vision transformer during training



U-shape high-to-low-high resolution vision transformer during evaluation

Our Approach for standard ViT and Swin Transformer



Expediting various vision tasks with our approach

Method	COCO Object Det.			COCO Instance Seg.		
	FLOPs	FPS	mAP(%)	FLOPs	FPS	mask AP(%)
SwinV2-L + HTC++	921G	2.3	58.9	921G	2.3	51.2
+ Ours	748G	2.8	57.7	748G	2.8	50.3

Method	COCO Panoptic Seg.			ADE20K Semantic Seg.			COCO Instance Seg.		
	FLOPs	FPS	PQ(%)	FLOPs	FPS	mIoU(%)	FLOPs	FPS	mask AP(%)
Mask2Former	937G	4.3	57.8	937G	4.3	55.8	937	4.3	50.1
+ Ours	663G	5.9	56.8	620G	6.2	55.6	705	5.4	49.1

Method	KITTI			NYUv2		
	FLOPs	FPS	RMSE	FLOPs	FPS	RMSE
DPT	810G	11.4	2.57	560G	17.6	0.36
+ Ours	627G	14.8	2.60	404G	24.0	0.36

Our approach saves around **25%** of computation cost but keeps **98%** of performance.

QR code of Paper & Code



Paper



Code