

Efficient Regret Minimization Algorithm for Extensive-Form Correlated Equilibrium

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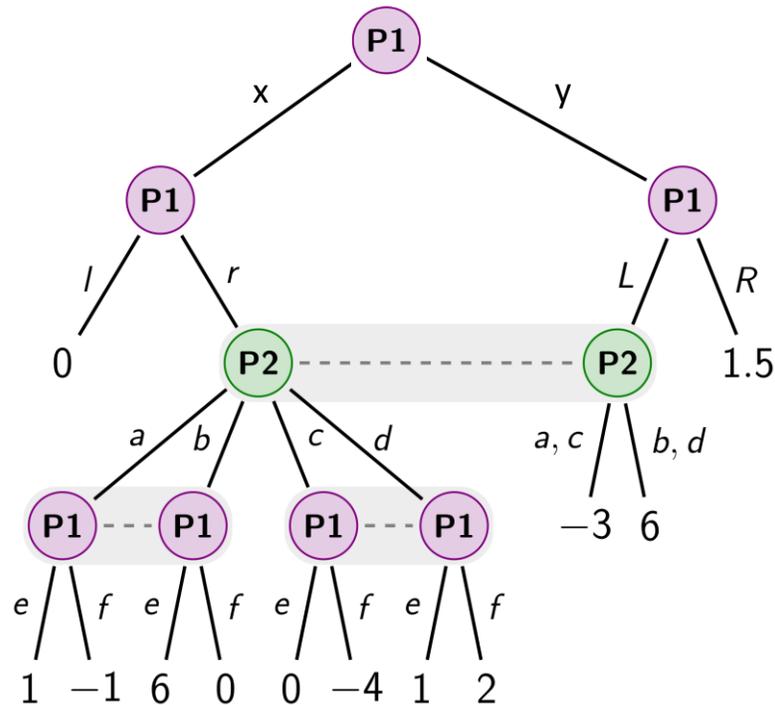
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Extensive-Form Games



- Can capture sequential and simultaneous moves
- Private information
- Each information set contains a set of “indistinguishable” tree nodes
- We assume perfect recall: no player forgets what the player knew earlier

Extensive-Form Correlated Equilibrium (EFCE)

- Introduced by von Stengel and Forges in 2008
- Correlation device selects a recommended strategy for each player before the game starts
 - The correlated **distribution** of strategies is known in advance to all players
- Recommendations are revealed incrementally, move by move, as the players progress in the game tree
 - A recommended move is only revealed to the acting player when the player reaches the decision point for which the recommendation is relevant
 - Players are free to not follow the recommendation, at the cost of future recommendations

Extensive-Form Correlated Equilibrium (EFCE)

- An optimal (e.g., social-welfare-maximizing) mediator that is provably incentive-compatible can be constructed in polynomial time in two-player general-sum games with no chance moves [von Stengel and Forges, 2008]
 - Players can be induced to play strategies with significantly higher social welfare than Nash equilibrium...
 - ...despite the fact that each player is free to not follow the recommendations
 - Added benefit: players get told what to do---they do not need to come up with their own optimal strategy as in Nash equilibrium

Computing EFCEs

- Original formulation [von Stengel and Forges, 2008] is based on linear programming
 - Does not scale beyond toy problems
 - Prohibitive amount of memory (>500GB for a game with 1M sequences per player)
- Another paper of ours in NeurIPS-19 (“Correlation in Extensive-Form Games: Saddle-Point Formulation and Benchmarks”) formulates the problem as a bilinear saddle point problem and proposes a method based on projected subgradient descent
 - Transforms problem into a zero-sum game between a mediator and deviator, the latter of which is finding the worst possible deviation by the players for the given correlation plan given by the mediator
 - Scales better than an LP, but still faces issues with large games. The main hurdle is the projection onto the set of feasible EFCEs

Regret minimization has become a standard module in leading approaches for finding Nash equilibrium in very large, zero-sum extensive form games

[Bowling et al. Science 2015; Moravcik et al. Science 2017; Brown and Sandholm, Science 2017&2019]

Q: Can regret minimization be used to compute optimal EFCEs in two-player games without chance moves?

A: Yes. We give the first efficient regret minimization algorithm that operates on the set of correlation plans

- Significantly more complicated than the Nash equilibrium case
 - The constraints that define the set of correlation plans lack the clean, hierarchical structure of sequential strategies
 - The constraints form cycles!

Ingredient 1: Scaled Extension

- Powerful operation for constructing certain structured sets, including strategy spaces. We use it to construct the space of EFCEs
- Idea: extend \mathcal{X} with a scaled version of \mathcal{Y}

$$\mathcal{X} \triangleleft^h \mathcal{Y} := \{(x, y) : x \in \mathcal{X}, y \in h(x)\mathcal{Y}\}.$$

- Scaled extension preserves convexity and compactness of \mathcal{X} and \mathcal{Y}

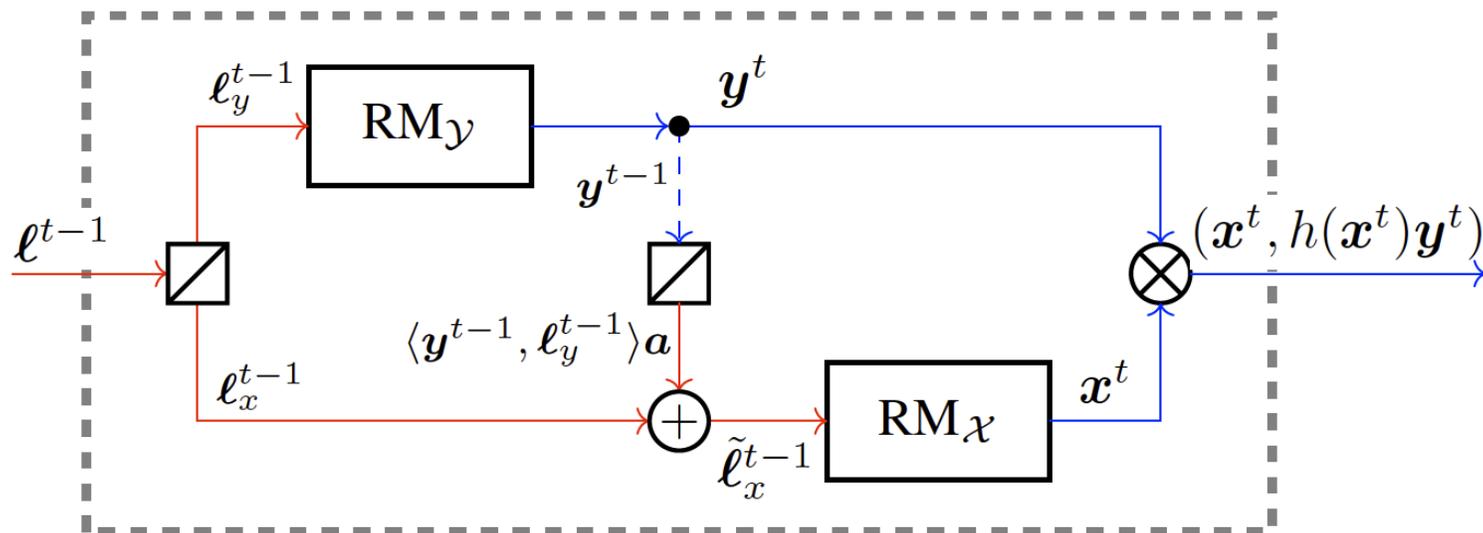
Ingredient 2: Correlation plans as composition of scaled extensions

- Some of the constraints that define the space of correlation plans are redundant and can be safely eliminated
- We propose an algorithm which can safely identify which of these constraints are redundant and removes them
- The remaining constraints form a tree
- The set generated by the remaining constraints can be equivalently generated by composing several scaled extension operations

Ingredient 3: Regret Circuits

[Farina, Kroer, Sandholm ICML'19]

- General methodology for constructing regret minimizers obtained from convexity-preserving operations
 - Given regret minimizers for convex sets \mathcal{X} and \mathcal{Y} , can we compose them and construct a regret minimizer for, say, the convex hull/Cartesian product/intersection of \mathcal{X} and \mathcal{Y} ?
- In this NeurIPS-19 paper we construct a regret circuit for the scaled extension operation



Summary of main contributions

- We introduce **scaled extension**, a novel convexity-preserving operation between sets
- For games with no chance: space of correlation plans may be constructed top down using a series of scaled extension operators
- We show that an **efficient regret minimizer** for the scaled extension of two sets can be constructed starting from any regret minimizer for each individual set
 - Regret circuit approach as in Farina, Kroer, Sandholm [ICML'19]
- Therefore: optimal EFCEs in two-player games without chance can be computed using regret minimization
 - Much faster than subgradient descent
 - Does not need projections: it is guaranteed to always produce feasible iterates