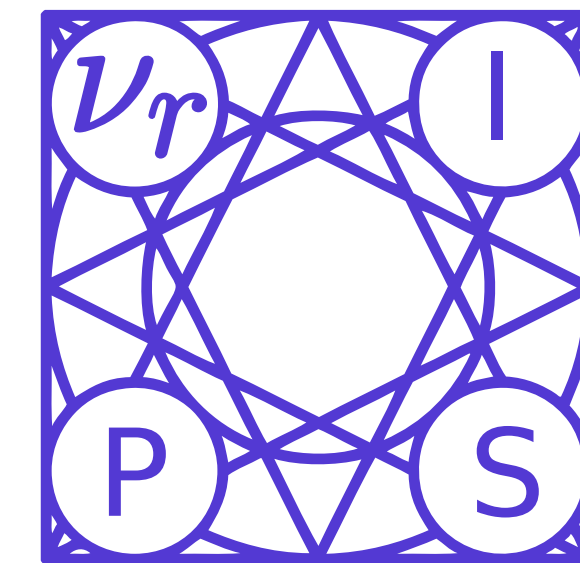




THE UNIVERSITY OF
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Likelihood-Free Overcomplete ICA and Applications In Causal Discovery

Chenwei Ding¹ Mingming Gong² Kun Zhang³ Dacheng Tao¹
¹the University of Sydney
²The University of Melbourne
³Carnegie Mellon University

● Previous Works on Causal Discovery

- Constraint-based methods, e.g. PC and FCI.
- Score-based methods, e.g. GES
- Functional Causal Models, e.g. LiNGAM (ICA based)

● Independent Component Analysis (ICA)

- $\mathbf{x} = \mathbf{A}\mathbf{s}$, where mixtures $\mathbf{x} \in \mathbb{R}^p$, independent components $\mathbf{s} \in \mathbb{R}^d$, mixing matrix $\mathbf{A} \in \mathbb{R}^{p \times d}$.

● Overcomplete ICA

- $p < d$
- Some causal discovery problems, e.g. causal discovery from measurement error and causal discovery from missing common causes, can be seen as extension of OICA.

● **Maximum Likelihood Learning Based Solutions for OICA**

- Assume parametric distribution for the ICs.
- Significant computational challenges.
- Restrictive for many real-world applications.

● **Likelihood Free Solution for OICA (Ours)**

- No explicit assumptions on the density functions of the ICs.
- Implicitly learn the distribution of ICs.
- Computationally efficient.

● LFOICA Framework

- Sample independently from some easy distribution, i.g. Gaussian.

z_1

z_2

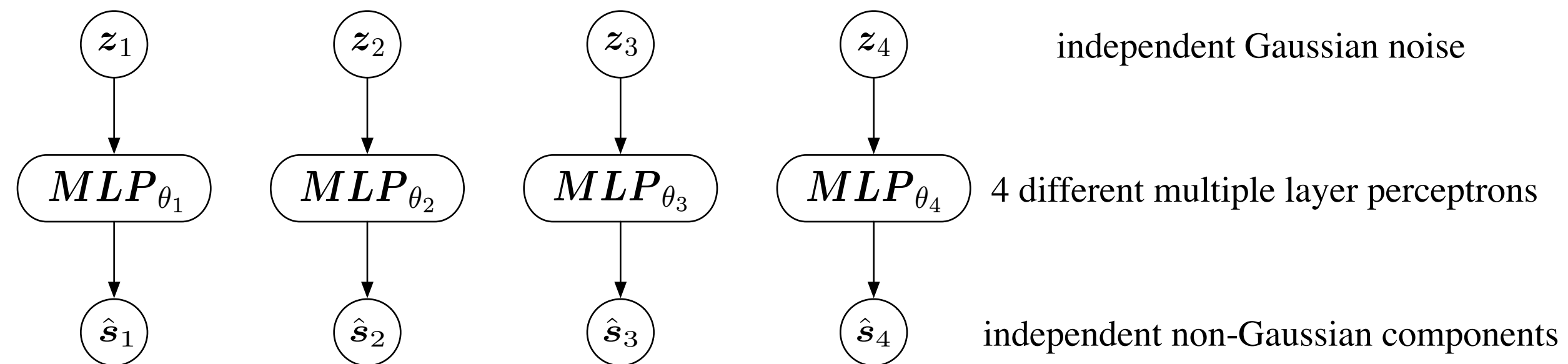
z_3

z_4

independent Gaussian noise

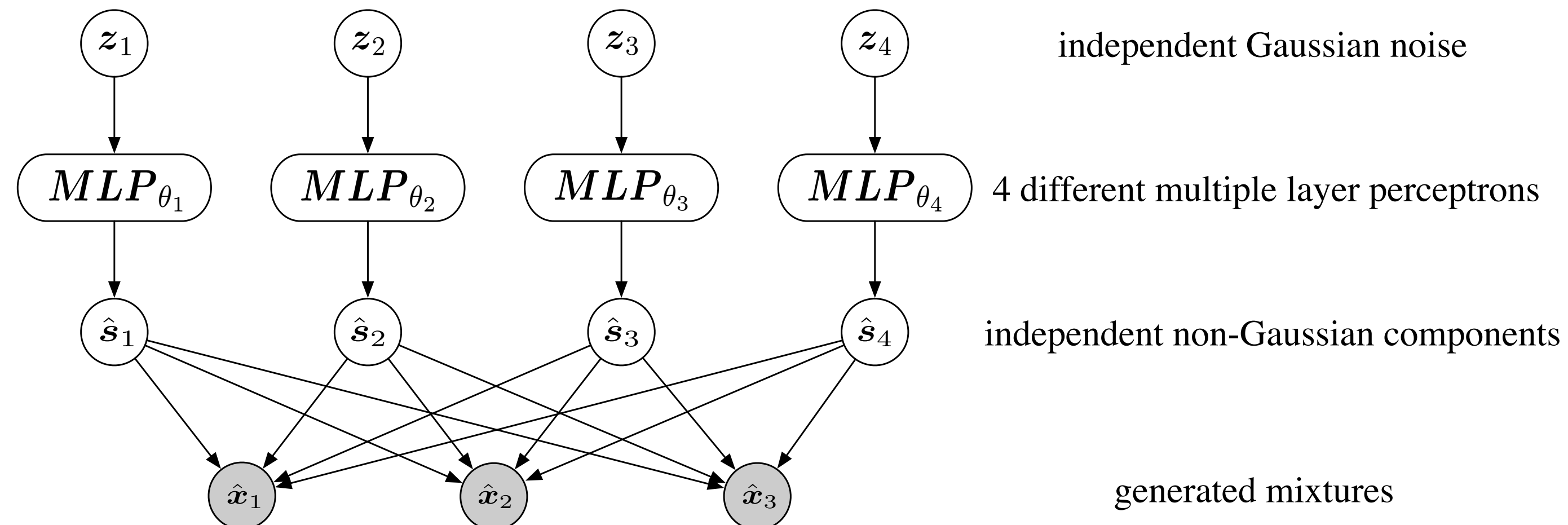
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• LFOICA Framework

- Sample independently from some easy distribution, i.g. Gaussian.
- For each IC, initialize a separate MLP. Generate corresponding IC.
- Initialize a mixing matrix, mix the ICs and generate the mixtures.
- Calculate the MMD between the distribution of true mixtures and the distribution of generated mixtures.
- Minimize MMD by updating the mixing matrix and the parameters in MLPs.



• Causal Discovery under Measurement Error

- Causal model without measurement error.

$$\tilde{\mathbf{X}} = \mathbf{B}\tilde{\mathbf{X}} + \tilde{\mathbf{E}}$$

- Add measurement error to the causal model.

$$\mathbf{X} = \tilde{\mathbf{X}} + \mathbf{E} = (\mathbf{I} - \mathbf{B})^{-1}\tilde{\mathbf{E}} + \mathbf{E} = [(\mathbf{I} - \mathbf{B})^{-1}\mathbf{I}] \begin{bmatrix} \tilde{\mathbf{E}} \\ \mathbf{E} \end{bmatrix}$$

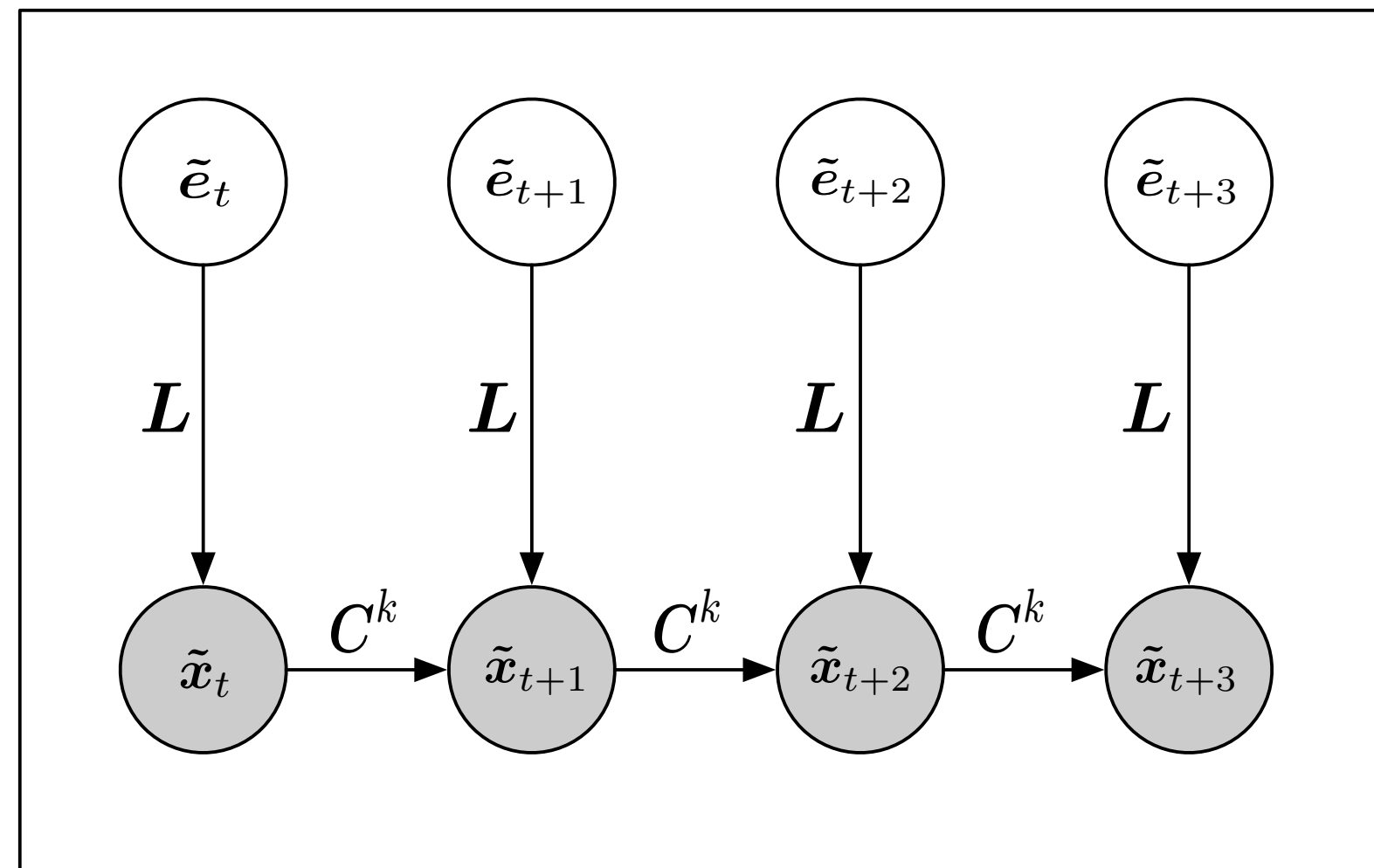
- The causal model with measurement error can be seen as an OICA model and LFOICA can be applied.

● Causal Discovery from Subsampled Time Series

- First assume that data at the original causal frequency follows a VAR(1) process $\mathbf{x}_t = \mathbf{C}\mathbf{x}_{t-1} + \mathbf{e}_t$

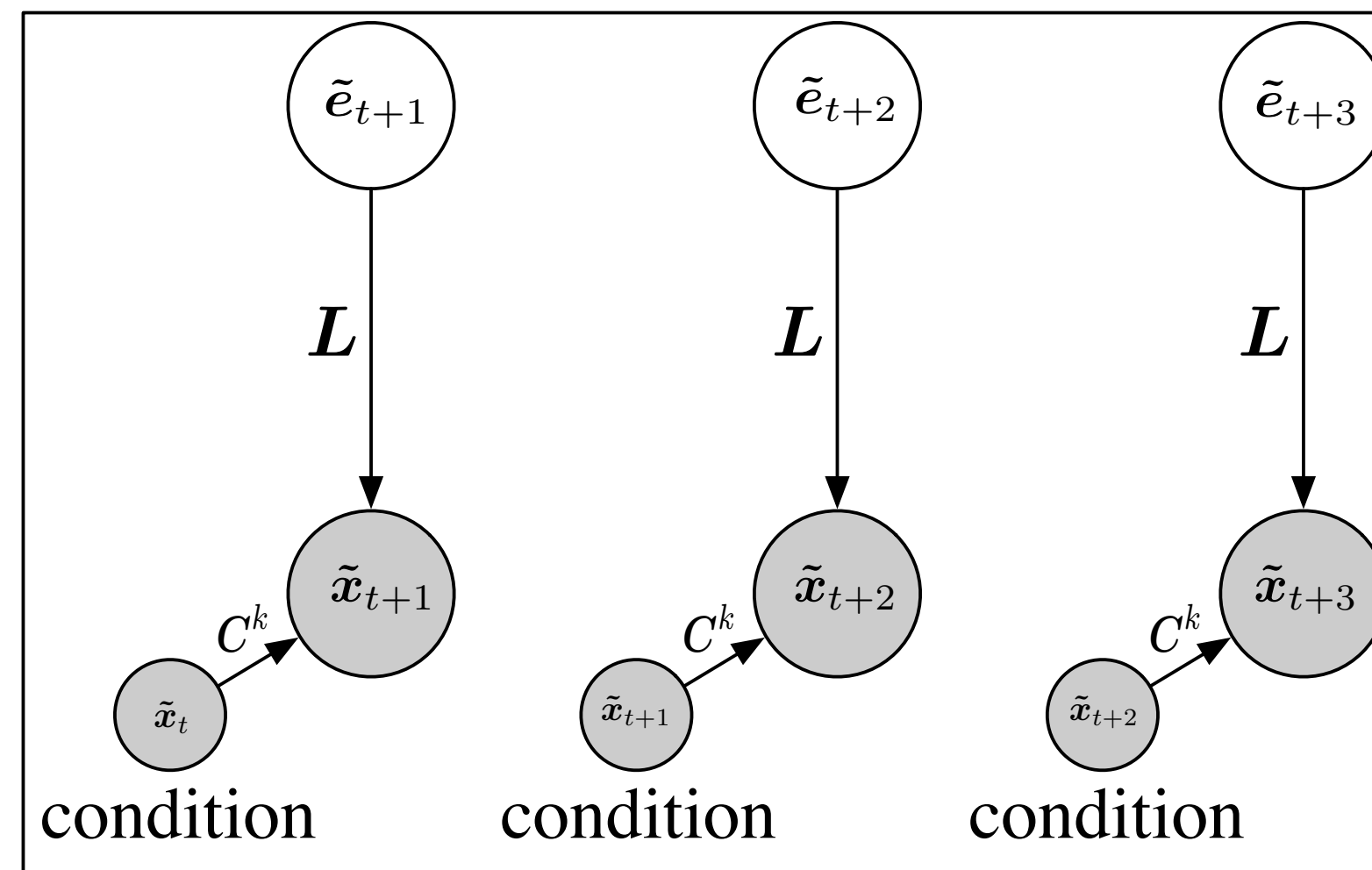
- The observed subsampled data with subsampling factor k can be represented as

$$\tilde{\mathbf{x}}_{t+1} = \mathbf{C}^k \tilde{\mathbf{x}}_t + \mathbf{L} \tilde{\mathbf{e}}_{t+1}, \text{ where } \mathbf{L} = [\mathbf{I}, \mathbf{C}, \mathbf{C}^2, \dots, \mathbf{C}^{k-1}] \text{ and } \tilde{\mathbf{e}}_t = \left(\mathbf{e}_{1+tk-0}^\top, \mathbf{e}_{1+tk-1}^\top, \dots, \mathbf{e}_{1+tk-(k-1)}^\top \right)^\top$$



● Causal Discovery from Subsampled Time Series

- We propose to model the conditional probability $\mathbb{P}(\tilde{\mathbf{x}}_{t+1} | \tilde{\mathbf{x}}_t)$



- In this case, the model for subsampled data can be seen as an extension of OICA with \mathbf{L} as mixing matrix and $\tilde{\mathbf{e}}_{t+1}$ as ICs. LFOICA can be applied.

Poster #45

Tue Dec 10, 2019

East Exhibition Hall B + C