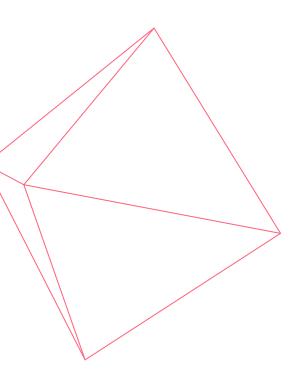
#### **DeepMind**

# Hindsight Credit Assignment

Anna Harutyunyan, Will Dabney, Thomas Mesnard, Mo Azar, Bilal Piot, Nicolas Heess, Hado van Hasselt, Greg Wayne, Satinder Singh, Doina Precup, Remi Munos



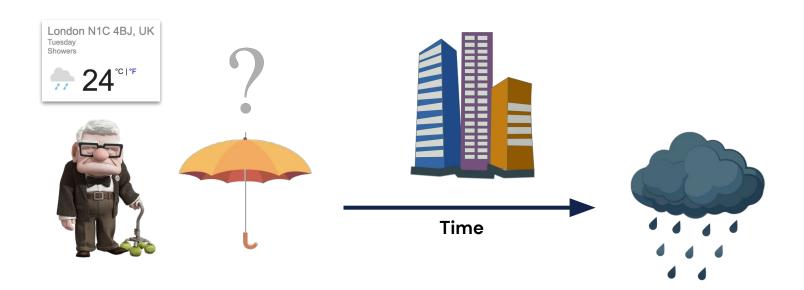




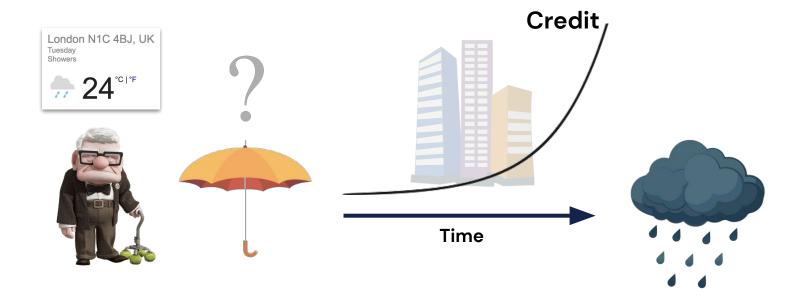




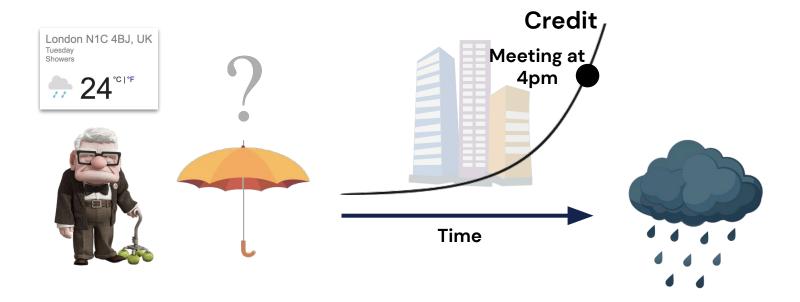




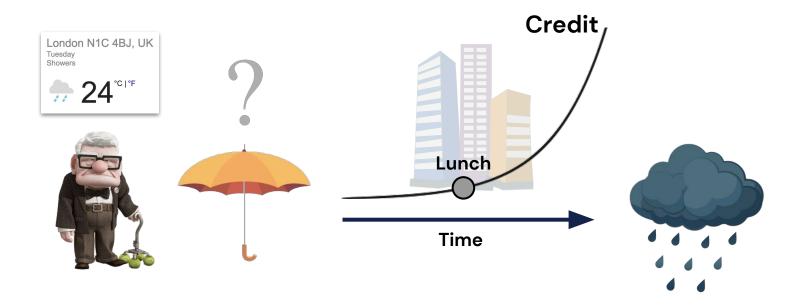




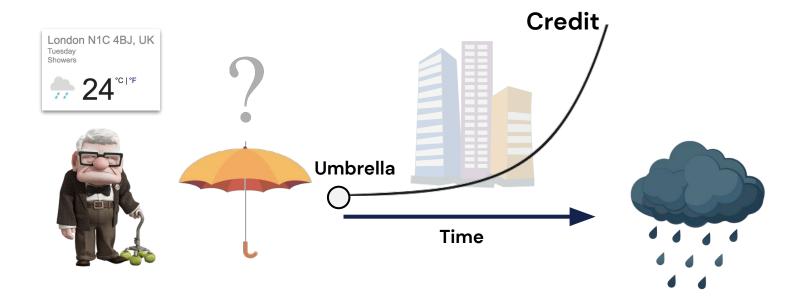




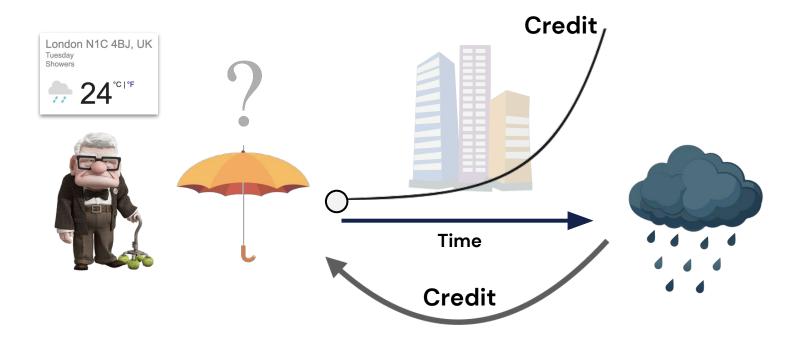










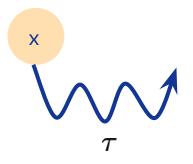




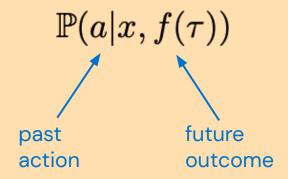


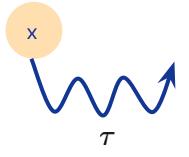




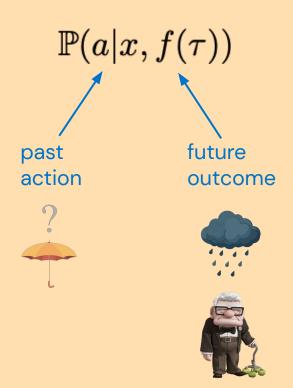


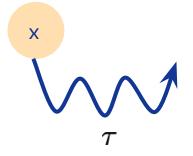




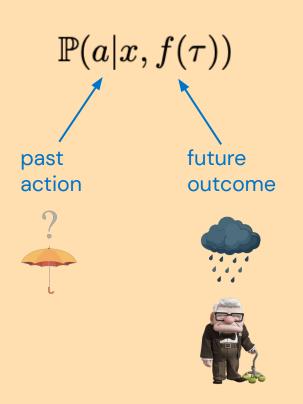


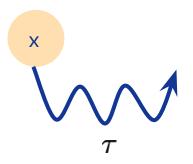




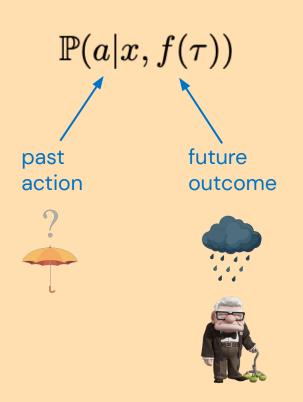


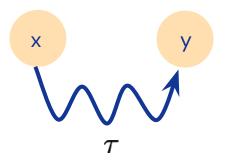




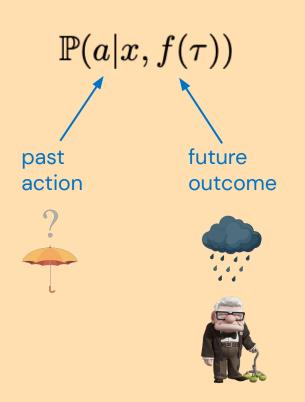


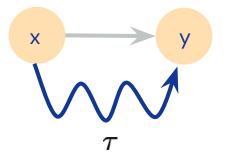




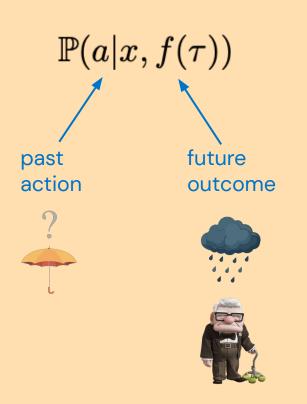


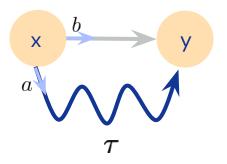




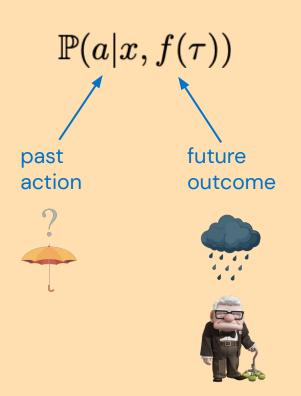


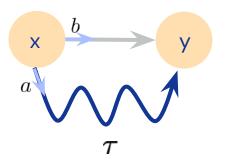






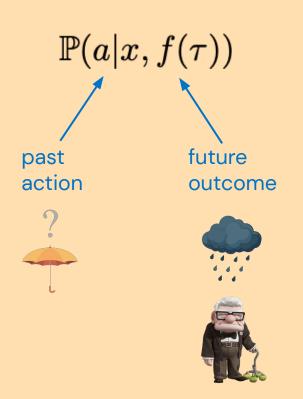


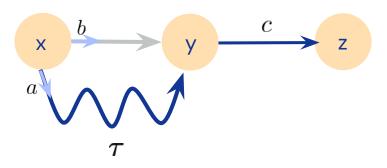




$$\mathbb{P}(b|x,y) > \mathbb{P}(a|x,y)$$

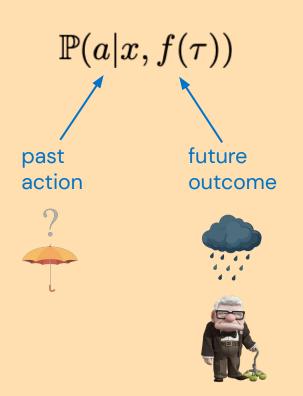


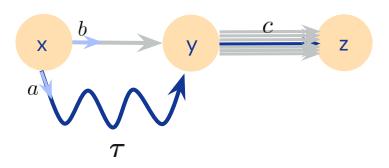




$$\mathbb{P}(b|x,y) > \mathbb{P}(a|x,y)$$

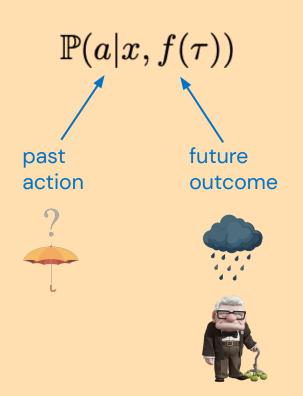


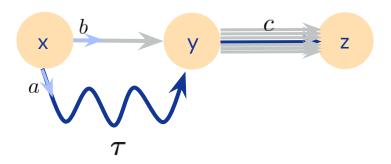




$$\mathbb{P}(b|x,y) > \mathbb{P}(a|x,y)$$



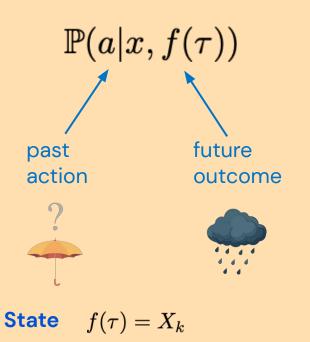


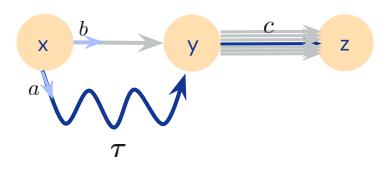


$$\mathbb{P}(b|x,y) > \mathbb{P}(a|x,y)$$

$$\mathbb{P}(c|y,z) = \pi(c|y)$$

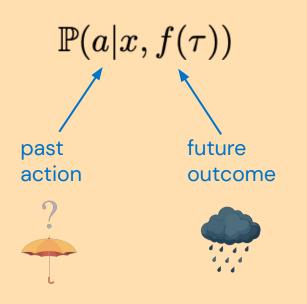




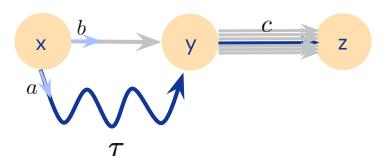


$$\mathbb{P}(b|x,y) > \mathbb{P}(a|x,y)$$
$$\mathbb{P}(c|y,z) = \pi(c|y)$$





State 
$$f(\tau) = X_k$$
 Return  $f(\tau) = Z(\tau) = \sum_{k \geq 0} \gamma^k R_k$ 



$$\mathbb{P}(b|x,y) > \mathbb{P}(a|x,y)$$
  
 $\mathbb{P}(c|y,z) = \pi(c|y)$ 



$$Q^{\pi}(x,a) = r(x,a) + \mathbb{E}_{\tau \sim \mathcal{T}(x,\pi)} \left[ \sum_{k \geq 1} \gamma^k \frac{\mathbb{P}(a|x, X_k)}{\pi(a|x)} R_k \right]$$



$$Q^{\pi}(x, a) = r(x, a) + \mathbb{E}_{\tau \sim \mathcal{T}(x, \pi)} \left[ \sum_{k > 1} \gamma^k \frac{\mathbb{P}(a|x, X_k)}{\pi(a|x)} R_k \right]$$

$$Q^{\pi}(x, a) = \mathbb{E}_{\tau \sim \mathcal{T}(x, \pi)} \left[ \frac{\mathbb{P}(a|x, Z(\tau))}{\pi(a|x)} Z(\tau) \right]$$



$$Q^{\pi}(x,a) = r(x,a) + \mathbb{E}_{\tau \sim \mathcal{T}(x,\pi)} \left[ \sum_{k>1} \gamma^k \frac{\mathbb{P}(a|x, X_k)}{\pi(a|x)} R_k \right]$$

$$Q^{\pi}(x, a) = \mathbb{E}_{\tau \sim \mathcal{T}(x, \pi)} \left[ \frac{\mathbb{P}(a|x, Z(\tau))}{\pi(a|x)} Z(\tau) \right]$$



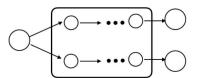
HCA Algorithms: Learn the hindsight distribution P, and use it to better estimate value functions or policy gradients

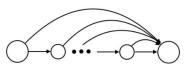
$$Q^{\pi}(x,a) = r(x,a) + \mathbb{E}_{\tau \sim \mathcal{T}(x,\pi)} \left[ \sum_{k \geq 1} \gamma^k \frac{\mathbb{P}(a|x, X_k)}{\pi(a|x)} R_k \right]$$

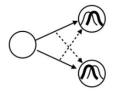
$$Q^{\pi}(x, a) = \mathbb{E}_{\tau \sim \mathcal{T}(x, \pi)} \left[ \frac{\mathbb{P}(a|x, Z(\tau))}{\pi(a|x)} Z(\tau) \right]$$



## **Experiments**

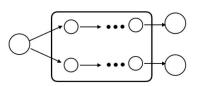


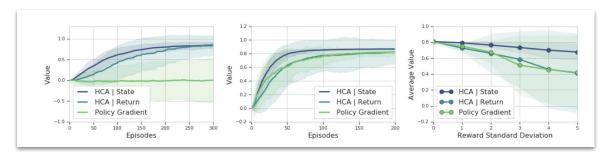


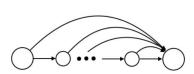


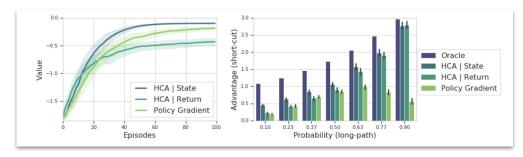


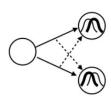
#### **Experiments**

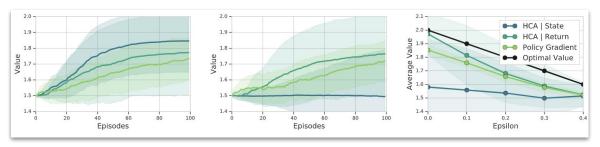
















# Thank you for your attention!

Poster #204:)

