

Locality defeats the curse of dimensionality in convolutional teacher-student scenarios

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Learning in high dimensions

- **Supervised learning:** learn a target function $f^*(\mathbf{x})$ from P observations

$$\{(\mathbf{x}^\mu, y^\mu)\}_{\mu=1}^P$$

$$\mathbf{x}^\mu \in \mathbb{R}^d, \quad y^\mu = f^*(\mathbf{x}^\mu)$$

- **How many observations?** If one only assumes f^* is Lipschitz continuous, one needs $\mathcal{O}(\epsilon^{-d})$ observations to learn f^* up to error ϵ : **curse of dimensionality**

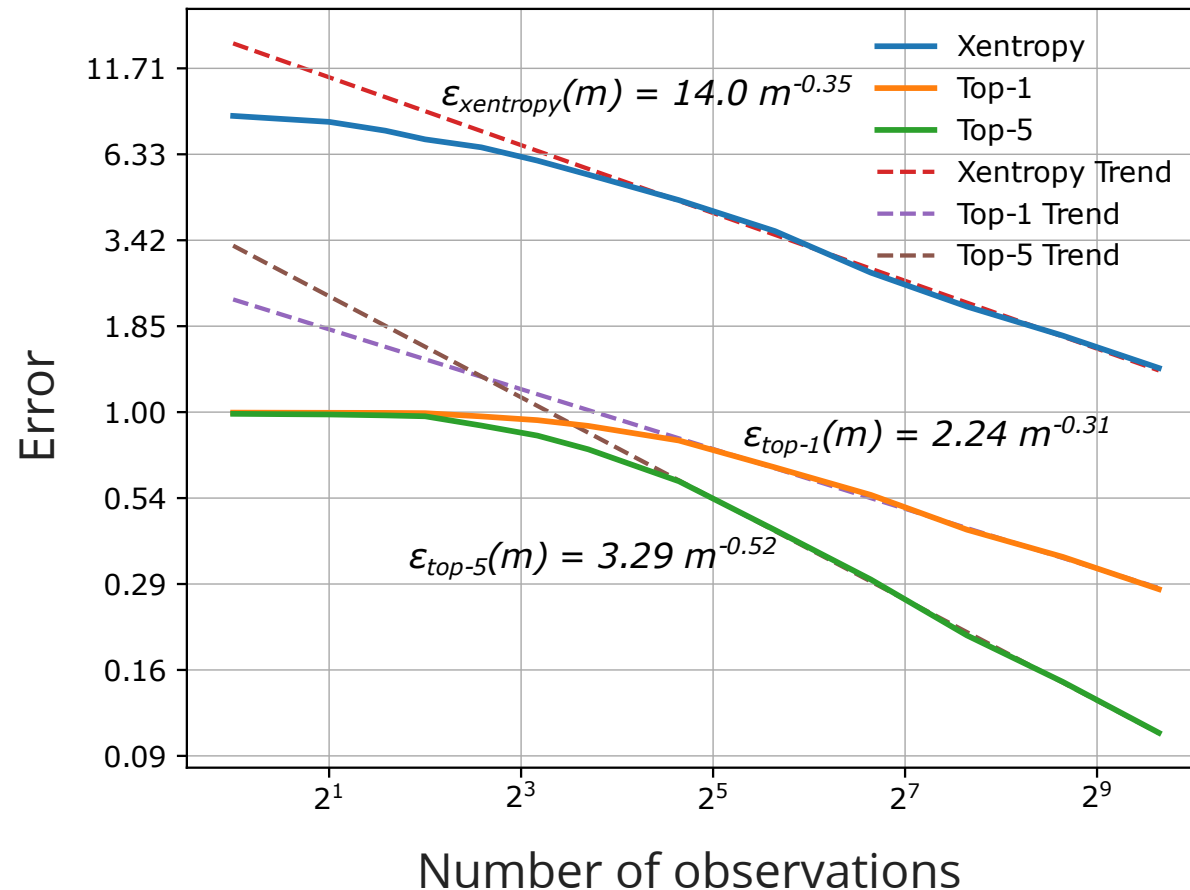
$$\epsilon = \mathcal{O}(P^{-1/d})$$

Learning seems impossible!

Learning in high dimensions

- **How many observations in practice?** For ResNets on ImageNet ($d = 6.2 \times 10^4$)

$$\epsilon \sim P^{-0.3} \text{ [Hestness 1712.00409]}$$

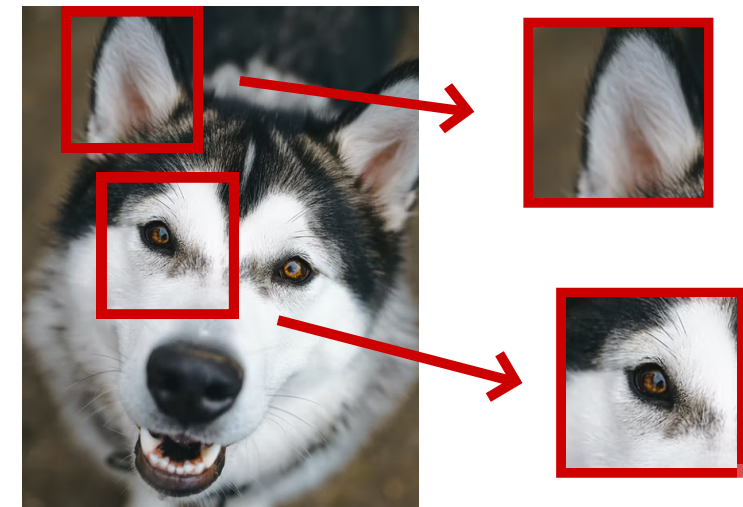


Images are physically structured

- If deep learning works in high dimensions, **data must be very structured**
- Several ideas:
 - Data live on a **manifold** \mathcal{M} of lower dimensionality $d_{\mathcal{M}} \ll d$
 - Presence of **invariants**, as shift-invariance or deformation stability
 - The task is **local** and **compositional**

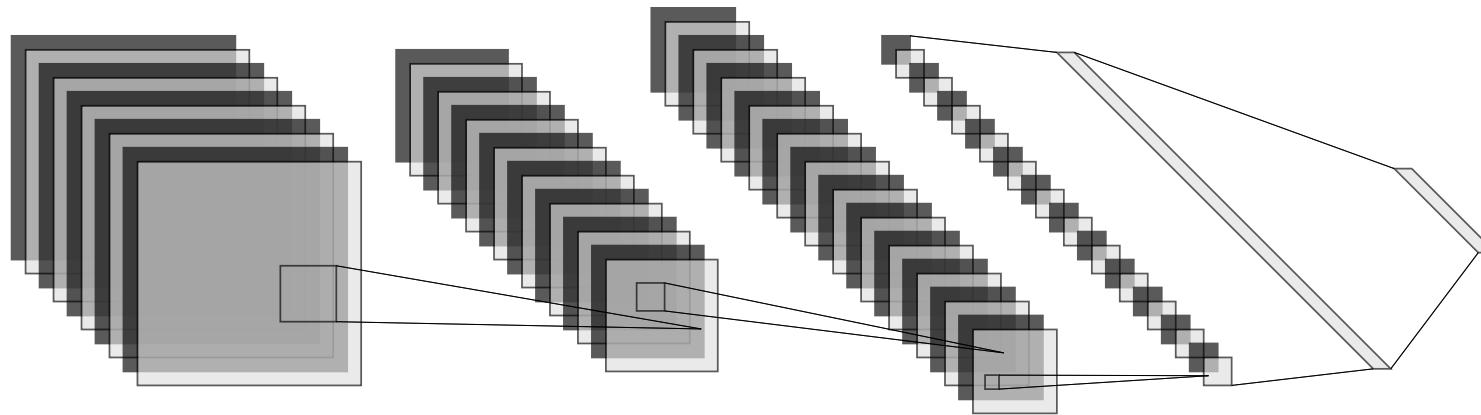
[Poggio 1611.00740, 2006.13915] [Bietti 2102.10032]

Does a local compositional structure affect the learning curve?



Good architectures have good priors

- **Convolutional neural networks** have shared filter weights with local support



- Numerical experiments suggest that **local connectivity is key to performance** [Neyshabur 2017.13657]

Can we quantify the respective advantages of weight sharing and local connectivity?

Learning scenario: the teacher

- **Inputs** are d -dimensional random sequences

$$\mathbf{x} = (x_1, \dots, \underbrace{x_i, \dots, x_{i+t-1}}_{\mathbf{x}_i \text{ } t\text{-dimensional patch}}, \dots, x_d)$$

- The **target function** is either

- **local** $f^{*LC} = \sum_{i=1}^d g_i(\mathbf{x}_i)$, e.g. $f^{*LC}(x_1, x_2, x_3) = g_1(x_1, x_2) + g_2(x_2, x_3) + g_3(x_3, x_1)$

- or **convolutional** $f^{*CN} = \sum_{i=1}^d g(\mathbf{x}_i)$

$g_i : \mathbb{R}^t \rightarrow \mathbb{R}$ is a Gaussian random function with controlled smoothness α_t

Learning scenario: the student

- Kernel method with a **local** or **convolutional** kernel with s -dimensional patches and smoothness α_s learns from P examples

$$K^{LC}(\mathbf{x}, \mathbf{x}') = \frac{1}{d} \sum_{i=1}^d C(\mathbf{x}_i, \mathbf{x}'_i)$$

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- Including the kernels of simple CNNs as special cases! [[Jacot 1806.07572](#)]
- **Generalization error** $\epsilon = \mathbb{E}_{\mathbf{x}, f^*} [(f(\mathbf{x}) - f^*(\mathbf{x}))^2] \sim P^{-\beta}$

Generalization in kernel regression

- **Mercer's theorem:** spectral decomposition $K(\mathbf{x}, \mathbf{x}') = \sum_{\rho} \lambda_{\rho} \phi_{\rho}(\mathbf{x}) \phi_{\rho}(\mathbf{x}')$
- We can expand f^* in the (student) kernel basis: $f^*(\mathbf{x}) = \sum_{\rho} c_{\rho} \phi_{\rho}(\mathbf{x})$
- From statistical physics, **kernel regression learns the first P projections**
[Bordelon 2002.02561] [Spigler 1905.10843]

$$\epsilon(P) \sim \sum_{\rho > P} \mathbb{E}[c_{\rho}^{*2}]$$

Asymptotic learning curves

- K_T conv. with **t -dimensional constituents** (filter size) and **smoothness α_t**
- K_S conv./loc. with **s -dimensional constituents**, $s \geq t$, and **smoothness α_s**
with $\alpha_s \geq \alpha_t/2 - s$

$$\text{conv. student} \quad \epsilon(P) \sim P^{-\alpha_t/s}$$

$$\text{loc. student} \quad \epsilon(P) \sim \left(\frac{P}{d}\right)^{-\alpha_t/s}$$

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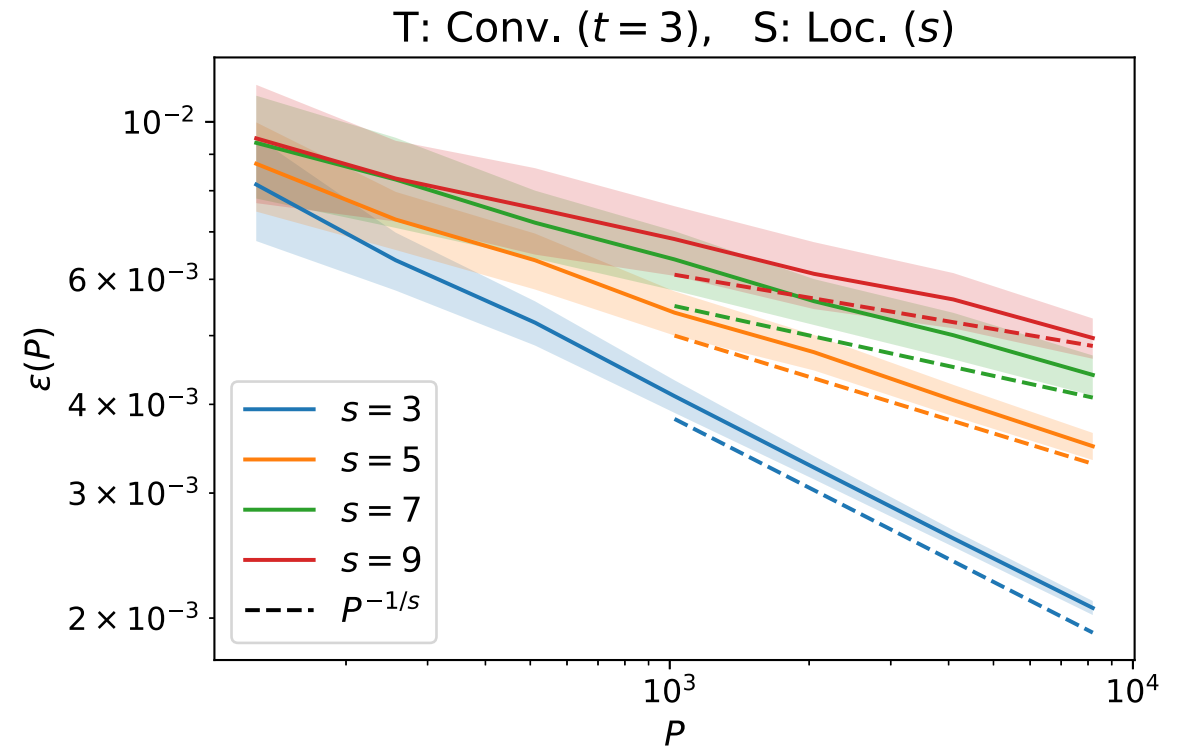
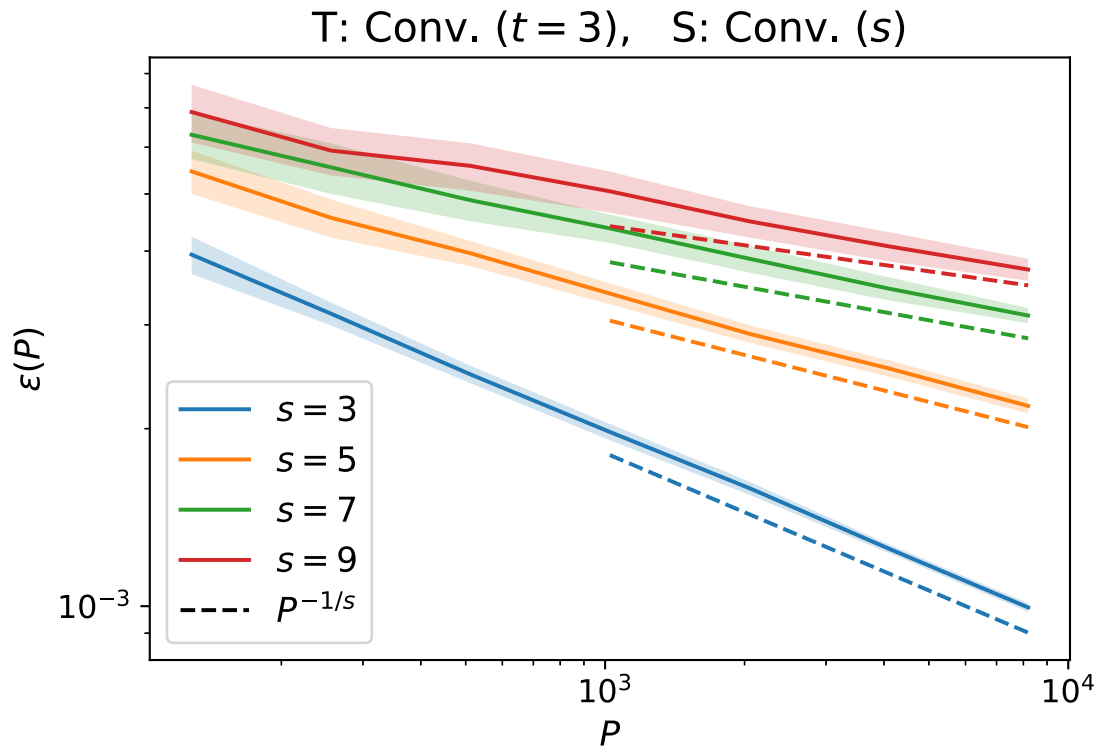
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- **The exponent is independent of d : no curse of dimensionality!**
 - **Locality changes the error's decay**
 - **Shift-invariance just affects the prefactor**

Asymptotic learning curves

- These predictions are **confirmed numerically** for several kernels and data distributions



Conclusions and perspectives

- **Local kernels beat the curse of dimensionality** when learning local functions
- This effect can be appreciated for **real data** also, e.g. regression on CIFAR-10
- What's missing? Exploring the **benefits of depth** by considering more complex compositional tasks as **hierarchical target** functions