

Random Noise Defense Against Query-based Black-Box Attacks

Zeyu Qin¹, Yanbo Fan², Hongyuan Zha¹, Baoyuan Wu¹

¹School of Data Science, Shenzhen Research Institute of Big Data,
The Chinese University of Hong Kong, Shenzhen

²Tencent AI Lab



香港中文大學(深圳)
The Chinese University of Hong Kong, Shenzhen

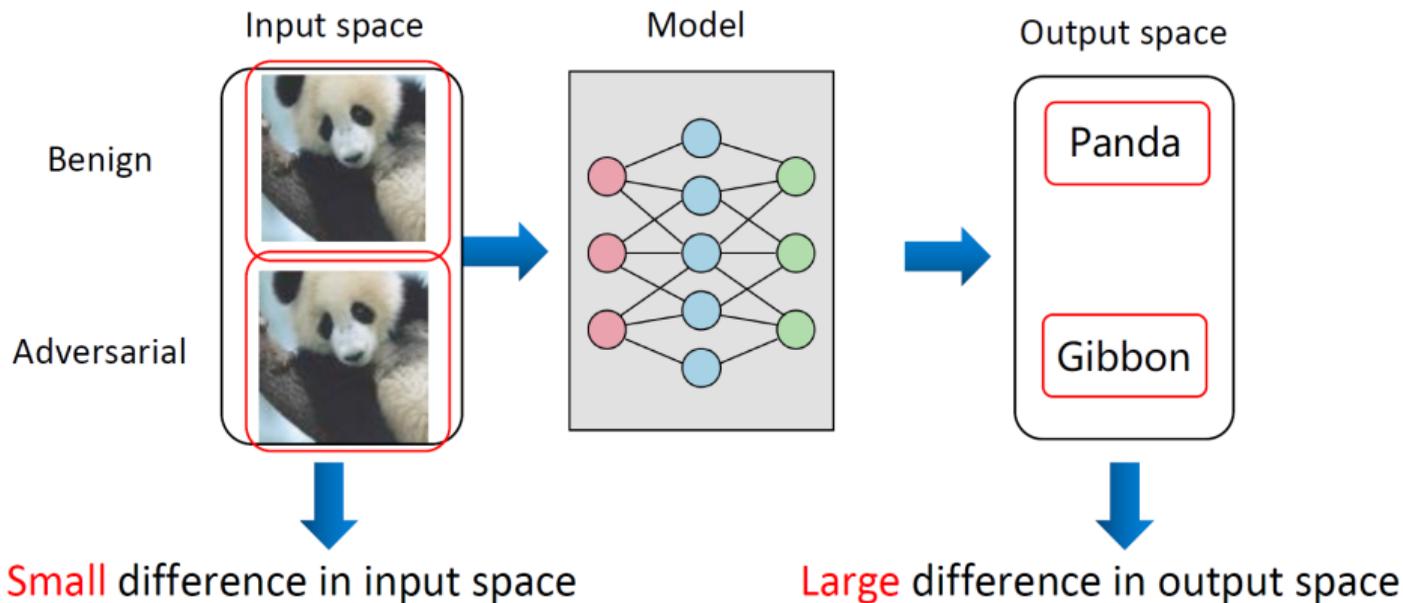


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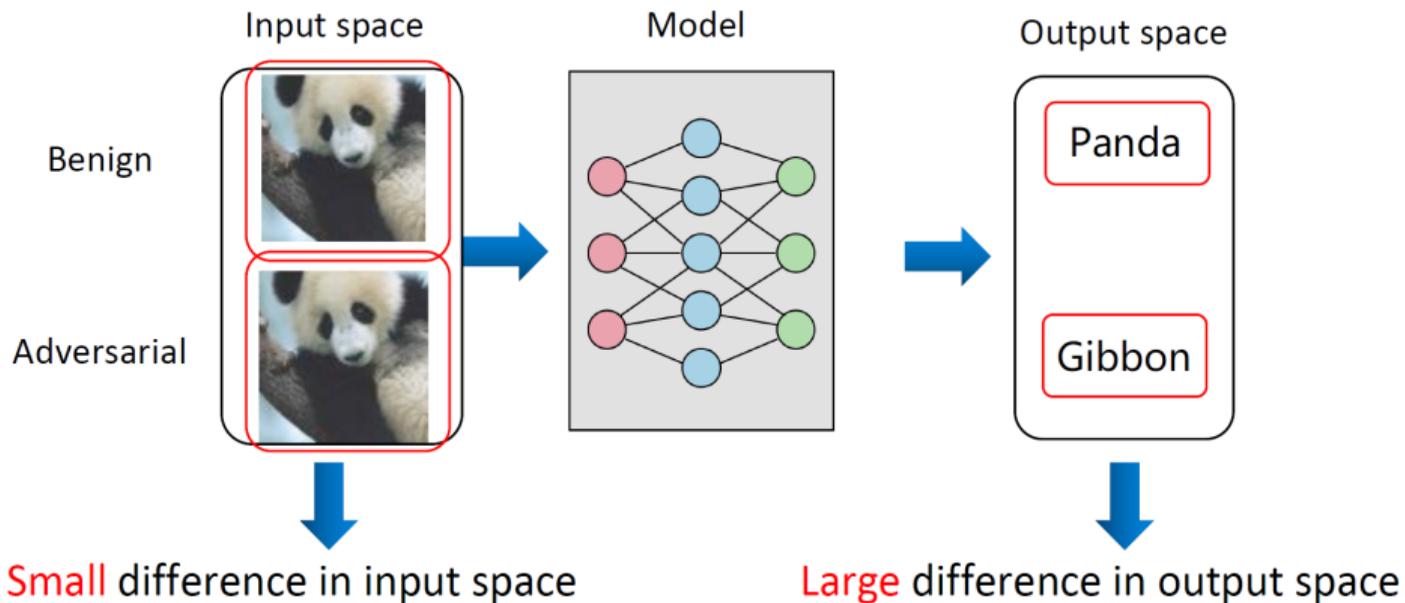
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Adversarial Examples



- ▶ Imperceptible: $\|x_{adv} - x\|_p \leq \epsilon$
- ▶ Misclassified: $y \neq \arg \max \mathcal{F}(x_{adv})$

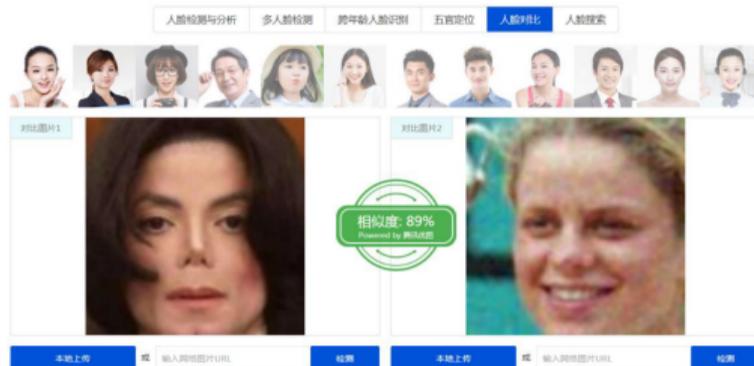
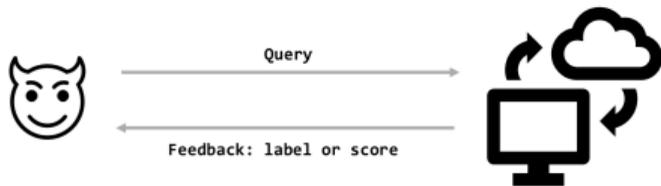
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Query-based Black-Box attacks

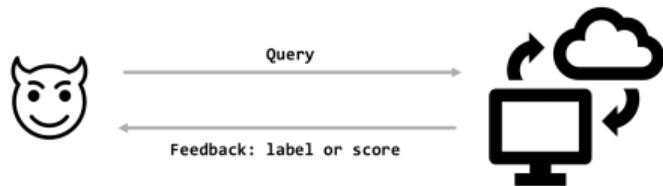
- ▶ However, in real scenarios such as autonomous driving, face recognition and verification, the DNN model as well as the training dataset, are often hidden from users.
- ▶ Only the model feedback for each query (labels or confidence scores) are accessible.
- ▶ By iteratively querying the targeted model, the attackers generate adversarial examples x_{adv} based on exact feedback of each query.



reference face vs target face, similarity 89%

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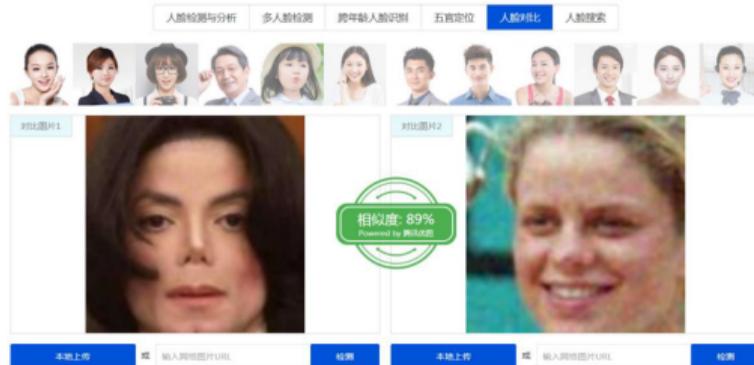
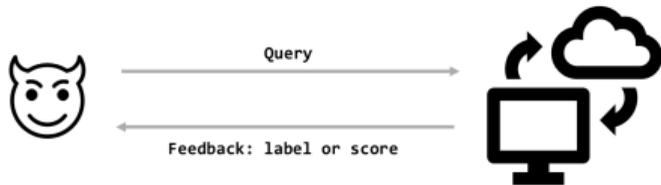
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Score-based attacks

► Score-based : confidence score returned

- untargeted attack:

$$\min_{\mathbf{x}_{adv}} f(\mathbf{x}_{adv}) = \max(0, \mathcal{F}(\mathbf{x}_{adv}, \mathbf{y}) - \max_{j \neq y} \mathcal{F}(\mathbf{x}_{adv}, \mathbf{j})), \quad s.t. \|\mathbf{x}_{adv} - \mathbf{x}\|_p \leq \epsilon \quad (1)$$

- targeted attack:

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Objects

Labels

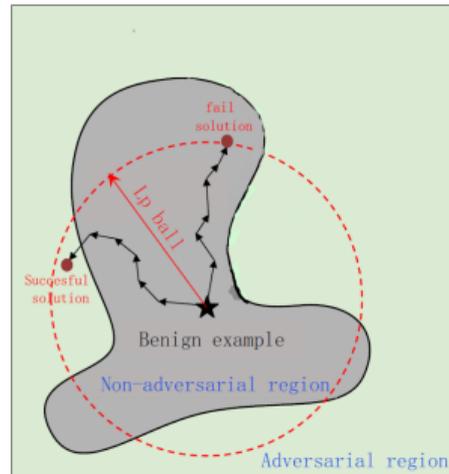
Properties

Safe Search



6.png

Green	92%
Vertebrate	92%
Botany	89%
Organism	87%
Terrestrial Plant	84%
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Plant	75%



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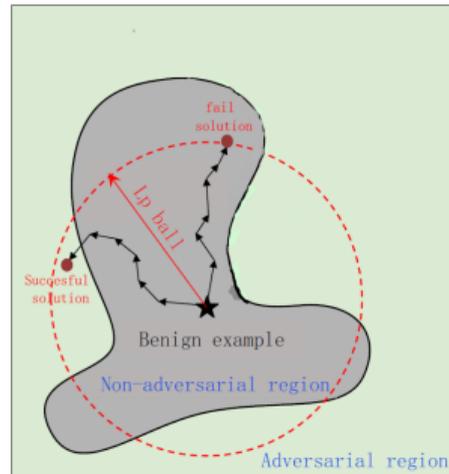
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How to find the adversarial directions

► Zero Order (ZO) Attacks:

- Randomized Gradient-Free (RGF) method (ZO Optimization) [1,2]:

$$g_{\mu}(\mathbf{x}) = \frac{f(\mathbf{x} + \mu\mathbf{u}) - f(\mathbf{x})}{\mu} \mathbf{u}, \quad (3)$$

where f represents $f(\mathbf{x}_{adv})$.

- Conducting projection gradient descent:

$$\mathbf{x}_{t+1} = \text{Proj}_{\mathcal{N}_R(\mathbf{x})}(\mathbf{x}_t - \eta_t g_{\mu}(\mathbf{x}_t)). \quad (4)$$

► Search-based Attacks:

- Random Search:

$$s_{\mu}(\mathbf{x}) = \mathbb{I}\{h_{\mu}(\mathbf{x}) < 0\} \cdot \mu\mathbf{u} \quad \text{where } h_{\mu}(\mathbf{x}) = f(\mathbf{x} + \mu\mathbf{u}) - f(\mathbf{x}), \quad (5)$$

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[1] Yurii Nesterov et al., Random gradient-free minimization of convex functions, 2017

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Black-Box Defense

- ▶ Main challenges in real scenarios,
 - the defender should not significantly influence the model's feedback to normal queries, but it is difficult to know whether a query is normal or malicious;
 - the defender has no information about what kinds of black-box attack strategies adopted by the attacker.
- ▶ We define defense task to address the above two challenges as **Black-Box Defense**. For product providers, the Black-Box defense should satisfy the below requirements:
 - well keeping clean accuracy
 - being robust against all kinds of black-box attacks
- ▶ However, the SOTA white-box defense, Adversarial Training (AT), is not suitable choice:
 - significant degradation of the clean accuracy
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Random Noise Defense

- ▶ The core of query-based attack: find an attack direction by **gradient estimation or random search based on the exact feedback** of consecutive queries.

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- ▶ *Random Noise Defense* (RND) is realized by **adding a random noise to each query at the inference time**. There the gradient estimator and searching direction become

$$g_{\mu,\nu}(\mathbf{x}) = \frac{f(\mathbf{x} + \mu\mathbf{u} + \nu\mathbf{v}_1) - f(\mathbf{x} + \nu\mathbf{v}_2)}{\mu} \mathbf{u} \quad (7)$$

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Random Noise Defense

- ▶ For RND, the feedback for one query is $\mathcal{F}(\mathbf{x} + \nu \mathbf{v})$, with $\mathbf{v} \sim \mathcal{N}(0, \mathbf{I})$. And, ν controls magnitude of random noise.
- ▶ RND should satisfy two conditions
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- ▶ In the following, we provide the theoretical analysis of RND, which can shed light on the setting of ν .

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Theoretical Analysis of RND Against ZO Attacks

To facilitate subsequent analyses, we first introduce some assumptions, definitions, and notations.

Assumption 1.

$f(\mathbf{x})$ is Lipschitz-continuous, i.e., $|f(\mathbf{y}) - f(\mathbf{x})| \leq L_0(f)\|\mathbf{y} - \mathbf{x}\|$.

Assumption 2.

$f(\mathbf{x})$ is continuous and differentiable, and $\nabla f(\mathbf{x})$ is Lipschitz-continuous, i.e., $\|\nabla f(\mathbf{y}) - \nabla f(\mathbf{x})\| \leq L_1(f)\|\mathbf{y} - \mathbf{x}\|$.

Definition 1.

The Gaussian-Smoothing function corresponding to $f(\mathbf{x})$ with $\nu > 0$, $\mathbf{v} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ is

$$f_\nu(\mathbf{x}) = \frac{1}{(2\pi)^{d/2}} \int f(\mathbf{x} + \nu\mathbf{v}) \cdot e^{-\frac{1}{2}\|\mathbf{v}\|_2^2} d\mathbf{v}. \quad (9)$$

Theoretical Analysis of RND Against ZO Attacks

Notations.

- ▶ The perturbation measure is specified as ℓ_2 norm, $\mathcal{N}_R(\mathbf{x}) = \{\mathbf{x}' \mid \|\mathbf{x}' - \mathbf{x}\|_2 \leq R\}$.
- ▶ $d = |\mathbf{X}|$ denotes the input dimension.
- ▶ $\mathbf{U}_t = \{\mathbf{u}_0, \mathbf{u}_1, \dots, \mathbf{u}_t\}$, $\mathbf{V}_t = \{\mathbf{v}_{01}, \mathbf{v}_{02}, \dots, \mathbf{v}_{t1}, \mathbf{v}_{t2}\}$, represent the noise added by attacker or defenders. t is the iteration index.
- ▶ The benign example \mathbf{x} is used as the initial solution, *i.e.*, $\mathbf{x}_0 = \mathbf{x}$.
- ▶ The generated sequential solutions are denoted as $\{\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_Q\}$.
- ▶ We define $S_Q = \sum_{t=0}^Q \eta_t$.

We study the convergence property of ZO attacks in Eq.(11) with $g_{\mu,\nu}(\mathbf{x})$ in Eq.(10) being the gradient estimator.

$$g_{\mu,\nu}(\mathbf{x}) = \frac{f(\mathbf{x} + \mu\mathbf{u} + \nu\mathbf{v}_1) - f(\mathbf{x} + \nu\mathbf{v}_2)}{\mu} \mathbf{u} \quad (10)$$

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Theoretical Analysis of RND Against ZO Attacks

Theorem 1.

Under Assumption 1, for any $Q \geq 0$, consider a sequence $\{\mathbf{x}_t\}_{t=0}^Q$ generated according to the descent update Eq.(11) using the gradient estimator $g_{\mu,\nu}(\mathbf{x})$. Then, we have

$$\frac{1}{S_Q} \sum_{t=0}^Q \eta_t \mathbb{E}_{\mathcal{U}_t, \mathcal{V}_t} (\|\nabla f_{\mu,\nu}(\mathbf{x}_t)\|^2) \leq \frac{f_{\mu,\nu}(\mathbf{x}_0) - f_\nu^*}{S_Q} + \frac{1}{S_Q} \sum_{t=0}^Q \eta_t^2 L_0(f)^3 d^{\frac{5}{2}} \left(\frac{1}{2\mu} + \frac{\sqrt{2}\nu}{\mu^2} + \frac{\nu^2}{\mu^3} \right).$$

We have $|f_{\mu,\nu}(\mathbf{x}) - f_\nu(\mathbf{x})| \leq \mu L_0(f) d^{1/2}$. To ensure $|f_{\mu,\nu}(\mathbf{x}_t) - f_\nu(\mathbf{x}_t)| \leq \epsilon$, We choose

$$\mu \leq \frac{\epsilon}{d^{1/2} L_0(f)} \text{ and set } \alpha = \frac{\nu}{\mu}. \text{ With constant stepsize, } \eta = \left[\frac{R\epsilon}{(\alpha + \frac{\sqrt{2}}{2})^2 d^3 L_0^3(f) (Q+1)} \right]^{1/2}, \text{ we have}$$

$$\frac{1}{Q+1} \sum_{t=0}^Q \mathbb{E}_{\mathcal{U}_t, \mathcal{V}_t} (\|\nabla f_{\mu,\nu}(\mathbf{x}_t)\|^2) \leq \frac{2L_0(f)^{\frac{5}{2}} R^{\frac{1}{2}} d^{\frac{3}{2}}}{(Q+1)^{\frac{1}{2}} \epsilon^{\frac{1}{2}}} \left(\alpha + \frac{\sqrt{2}}{2} \right). \quad (12)$$

In order to ensure that expected squared norm of $\nabla f_{\mu,\nu}$ can reach δ , **the query complexity is** $O\left(\left(\alpha + \frac{\sqrt{2}}{2}\right)^2 \frac{d^3 L_0^5(f) R}{\epsilon \delta^2}\right)$.

Theoretical Analysis of RND Against ZO Attacks

Remark 1.

- ▶ Due to the non-convexity assumption, we only guarantee the convergence to a stationary point of the function $f_{\mu,\nu}(\mathbf{x})$, which is a smoothing approximation of f_ν .
- ▶ To make sure $|f_{\mu,\nu}(\mathbf{x}_t) - f_\nu(\mathbf{x}_t)| \leq \epsilon$, $\forall \mathbf{x}_t \in \mathcal{N}_R(\mathbf{x}_0)$, we utilize the Theorem 1 in [1], $|f_{\mu,\nu}(\mathbf{x}) - f_\nu(\mathbf{x})| \leq \mu L_0(f) d^{1/2}$. So, we could choose $\mu \leq \frac{\epsilon}{d^{1/2} L_0(f)}$.
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Theoretical Analysis of RND Against ZO Attacks

- ▶ Theorem 1 shows the convergence rate is positive related to the ratio $\frac{\nu}{\mu}$. **The larger ratio $\frac{\nu}{\mu}$ will lead to the higher upper bound of convergence error and slower convergence rate.**
- ▶ Under the queries limited setting, the attack efficiency will be significantly reduced, leading to failed attacks or a much larger number of queries for successful attacks.
- ▶ The larger ratio $\frac{\nu}{\mu}$ leads the effectiveness of RND.

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Theoretical Analysis of RND Against ZO Attacks

- ▶ Trade-off of Larger ν and Clean Accuracy:

If $f(\mathbf{x})$ is Lipschitz-continuous, then $|f_\nu(\mathbf{x}) - f(\mathbf{x})| \leq \nu L_0(f) d^{1/2}$. The larger ν is, the larger the gap between $f_\nu(\mathbf{x})$ and $f(\mathbf{x})$. So the clean accuracy of model with adding larger noise will also decrease. This forms a **trade-off between defense performance of RND and clean accuracy**.

- ▶ Larger Noise Size μ Adopted by Attackers:

The attacker may be aware of the defense mechanism, so they can also increase the adopted noise size μ . As shown in figure in next page, for NES attack, the attack failure rate is almost 0, when $\nu = \mu = 0.01$.

However, increasing the noise size μ will also lead less accurate gradient estimation and random search in Eq.(3) and Eq.(5), **leading to a significant decrease in attack performance**.

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Experimental results verify our theoretical findings.

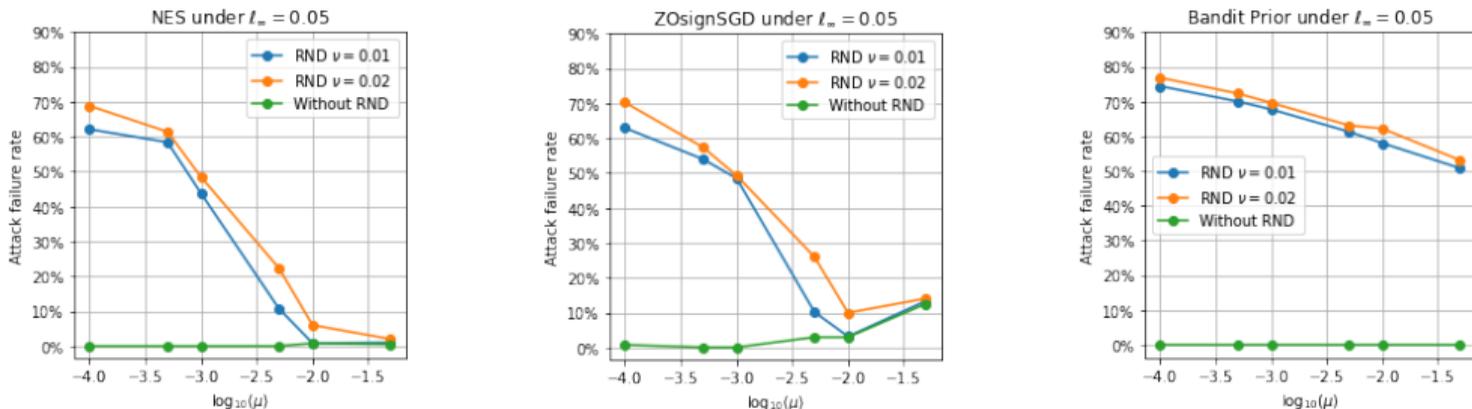


Figure: Attack failure rate (%) of query-based attacks on VGG-16 and CIFAR-10 under different values of μ and ν . We adopt logarithm scale for better illustration.

Theoretical Analysis of RND Against Adaptive Attacks

- ▶ As suggested in recent studies of robust defense [1, 2], the defender should take a robust evaluation against the **corresponding adaptive attack**, in which case **the attacker is aware of the defense mechanism**.
- ▶ Since the idea of RND is to insert random noise, an adaptive attacker could utilize Expectation Over Transformation (EOT) [1] to obtain a more accurate estimation, *i.e.*, querying one sample multiple times to obtain the average.
- ▶ Then, the original gradient estimator used in ZO attacks Eq.(11) is

$$g_{\mu,\nu}(\mathbf{x}) = \frac{f(\mathbf{x} + \mu\mathbf{u} + \nu\mathbf{v}_1) - f(\mathbf{x} + \nu\mathbf{v}_2)}{\mu} \mathbf{u}$$

Now, it becomes

$$\tilde{g}_{\mu,\nu}(\mathbf{x}) = \frac{1}{M} \sum_{j=1}^M \frac{f(\mathbf{x} + \mu\mathbf{u} + \nu\mathbf{v}_{j1}) - f(\mathbf{x} + \nu\mathbf{v}_{j2})}{\mu} \mathbf{u}, \quad (13)$$

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Theoretical Analysis of RND Against Adaptive Attacks

The convergence analysis of ZO attack with Eq.(13) against RND is presented in Theorem 2.

Theorem 2.

Under Assumption 1 and 2, for any $Q \geq 0$, consider a sequence $\{\mathbf{x}_t\}_{t=0}^Q$ generated according to the descent update Eq.(11) using the gradient estimator $\tilde{g}_{\mu,\nu}(\mathbf{x})$ Eq.(13), we have

$$\begin{aligned} \frac{1}{S_Q} \sum_{t=0}^Q \eta_t \mathbb{E}_{\mathcal{U}_t, \mathcal{V}_t} (\|\nabla f_{\mu,\nu}(\mathbf{x}_t)\|^2) &\leq \frac{L_0(f)R}{S_Q} + \frac{1}{S_Q} \sum_{t=0}^Q \eta_t^2 (L_0(f)^2 L_1(f) d^2 \left(\frac{1}{2} + \frac{2\nu^2}{\mu^2 M}\right) \\ &\quad + \frac{\nu^2 L_0(f) L_1(f)^2}{\mu} d^{\frac{5}{2}} + \frac{\nu^4 L_1(f)^3 (M+1)}{2\mu^2 M} d^3) \end{aligned} \quad (14)$$

Theoretical Analysis of RND Against Adaptive Attacks

- The larger M for EOT:

Theorem 2 shows that with larger M , the upper bound will decrease. Therefore, EOT can mitigate the defense effect caused by the randomness of RND.

However, with $M \rightarrow \infty$, the upper bound of expected convergence error (i.e., Eq. (14)) becomes

$$\frac{1}{S_Q} \sum_{t=0}^Q \eta_t \mathbb{E}_{\mathcal{U}_t, \mathcal{V}_t} (\|\nabla f_{\mu, \nu}(\mathbf{x}_t)\|^2) \leq \frac{L_0(f)R}{S_Q} + \frac{1}{S_Q} \sum_{t=0}^Q \eta_t^2 \left(\frac{1}{2} L_0(f)^2 L_1(f) d^2 + \frac{\nu^2 L_0(f) L_1(f)^2}{\mu} d^{\frac{5}{2}} + \frac{\nu^4 L_1(f)^3}{2\mu^2} d^3 \right)$$

which is still dominated by the max term $\frac{\nu^4}{\mu^2} d^3$. **It implies that the attack improvement from EOT is limited, especially with the larger ratio $\frac{\nu}{\mu}$.**

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settings	Methods	M=1	M=5	M= 10	Methods	M=1	M=5	M= 10
adaptive	NES	1448/0.484	4078/0.361	5763/0.342	NES	2532/0.762	5364/0.705	7582/0.691
	ZS	1489/0.493	3189/0.374	5912/0.349	ZS	2824/0.825	5735/0.761	7662/0.740
fixed	NES	1448/0.484	2528/0.452	3246/0.443	NES	2533/0.762	5240/0.775	5658/0.781
	ZS	1489/0.493	2765/0.448	3123/0.421	ZS	2824/0.825	4023/0.842	4652/0.861
	Bandit	436/0.696	276/0.582	314/0.543	Bandit	305/0.604	759/0.523	946/0.49
	Square	380/0.301	181/0.162	223/0.121	Square	93/0.353	145/0.20	328/0.171
	SignHunter	459/0.367	559/0.224	759/0.191	SignHunter	173/0.532	336/0.456	659/0.431
	ECO	904/0.720	1681/0.761	2560/0.793	ECO	1237/0.666	3065/0.678	3091/0.692
	SimBA	1353/0.650	3852/0.467	4103/0.396	SimBA	274/0.891	468/0.878	517/0.869

Figure: The evaluation of EOT with ℓ_∞ attack on CIFAR-10 and ImageNet under the *adaptive and fixed query setting*. The left part is the results on **CIFAR-10** and the right part is on **ImageNet**. **The average number of query of successful attack as well as the attack failure rate are reported.**

Theoretical Analysis of RND Against Search-based Attacks

Recall the original searching direction is

$$s_{\mu}(\mathbf{x}) = \mathbb{I}\{h_{\mu}(\mathbf{x}) < 0\} \cdot \mu \mathbf{u} \quad \text{where } h_{\mu}(\mathbf{x}) = f(\mathbf{x} + \mu \mathbf{u}) - f(\mathbf{x}).$$

Therefore, the searching direction under RND becomes

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- ▶ When the random noise $\nu \mathbf{v}$ causes inconsistency between $\text{Sign}(h_{\nu}(\mathbf{x}))$ and $\text{Sign}(h_{\mu}(\mathbf{x}))$, RND will mislead the attackers to select the incorrect attack directions (*i.e.*, abandoning the descent direction *w.r.t.* f or selecting the ascent direction), so as to decrease the attack performance.

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Theorem 3.

Under Assumption 1, considering the direction update Eq.(6) with Eq.(15) in search-based attacks, we have,

$$P(\text{Sign}(h_\mu(\mathbf{x})) \neq \text{Sign}(h_\nu(\mathbf{x}))) \leq \frac{2L_0(f)\nu\sqrt{d}}{|h_\mu(\mathbf{x})|} \quad (16)$$

Remark 2.

- ▶ Theorem 3 shows the probability of misleading attacker is positive correlated with $\frac{\nu}{|h_\mu(\mathbf{x})|}$.
- ▶ Due to the small value μ and local linearity of smooth function, we $|h_\mu(\mathbf{x})| = |f(\mathbf{x} + \mu\mathbf{u}) - f(\mathbf{x})| \approx C\mu\|\mathbf{u}\|$. The $|h_\mu(\mathbf{x})|$ is also positive correlated with the stepsize μ within the small neighborhoods.
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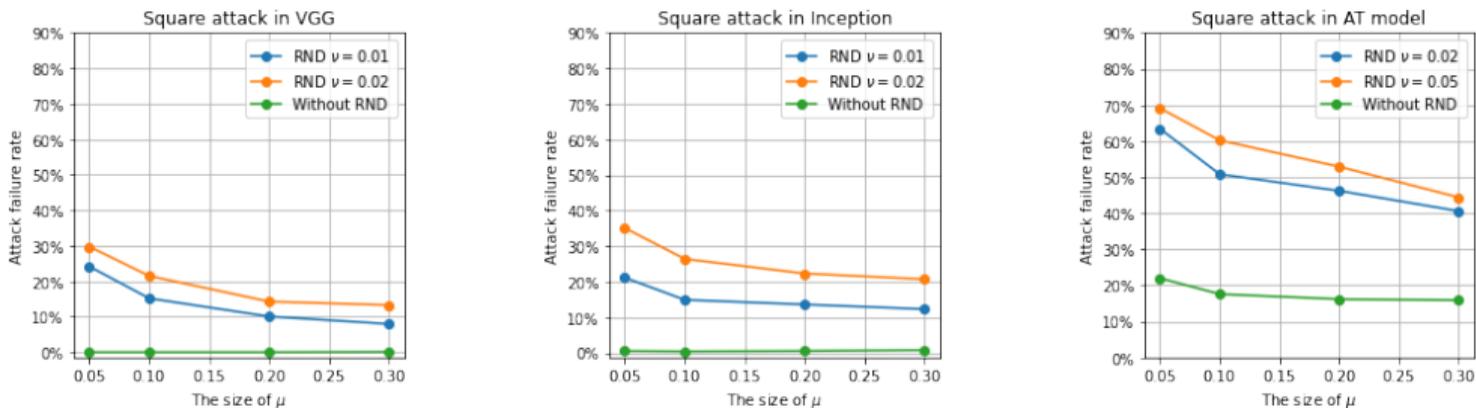


Figure: Attack failure rate (%) of Square ℓ_∞ attacks on VGG-16(CIFAR-10), Inception v3(ImageNet) and AT model (ImageNet) under different values of μ and ν , where μ is the square size in Square attacks.

Better Trade-off Between Defense Effect and Clean Accuracy

- ▶ To achieve a high-quality balance, we could reduce the sensitivity of the target model to random noises.
- ▶ We propose to utilize **Gaussian Augmentation Fine-tuning (GF)**, the loss function (CE loss) is

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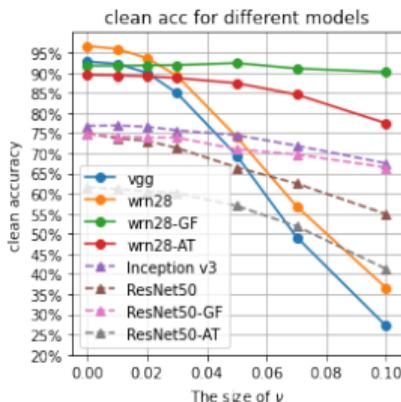


Figure: Clean accuracy for different models on CIFAR-10 and ImageNet. The **circle lines** and **triangle lines** represent models on **CIFAR-10** and **ImageNet** respectively.

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- ▶ Compared with RND, **RNG-GF** significantly improves the defense performance under all attack methods while maintaining the good clean accuracy.
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Table 2: The comparison of RND ($\nu = 0.02$), GF, RND-GF ($\nu = 0.05$), AT, RND-AT ($\nu = 0.05$), PNI, RSE, and FD on CIFAR-10 and Imagenet. **The average number of queries** of successful attack and **the attack failure rates** are reported. The best and second best attack failure rate under each attack are highlighted in bold and underlined, respectively. The evaluation under ℓ_2 attack is shown in Section B.6 of supplementary materials.

Datasets	Methods	Clean Acc	NES(ℓ_∞)	ZS(ℓ_∞)	Bandit(ℓ_∞)	Sign(ℓ_∞)	Square(ℓ_∞)	SimBA(ℓ_2)	ECO(ℓ_∞)
CIFAR-10 (WideNet-28)	Clean Model	96.60%	465.5/0.01	581.8/0.06	210.2/0.03	167.6/0.03	137.1/0.02	457.2/0.04	457.8/0.0
	GF	91.72%	999.0/0.407	759.9/0.544	744.5/0.116	348.3/0.027	581.0/0.061	1146.8/0.395	883.9/0.067
	RSE[30]	84.12%	1246.3/0.396	1327.8/0.422	281.7/0.372	243.7/0.221	413.3/0.243	498.3/0.337	578.3/0.534
	PNI[23]	87.20%	1071.4/0.725	1310.7/0.823	324.9/0.824	267.0/0.708	295.3/0.612	945.0/0.857	2342.2/0.623
	AT[20]	89.48%	<u>821.6/0.807</u>	<u>614.9/0.862</u>	1451.5/0.623	766.3/0.476	1135.4/0.499	1523.2/0.635	1180.4/0.484
	RND	<u>93.60%</u>	842.5/0.05	941.8/0.143	273.1/0.478	977.2/0.226	762.4/0.116	2112.6/0.549	912.8/0.688
	RND-GF	92.40%	2805.7/0.516	2966.3/0.730	1223.5/0.841	1017.1/0.407	1207.3/0.378	1220.2/0.863	687.2/0.872
	RND-AT	87.40%	2499.2/0.842	2625.7/0.923	891.5/0.891	767.9/0.737	1170.7/0.730	1787.4/0.912	687.4/0.911
ImageNet (ResNet-50)	Clean Model	74.90%	1031.9/0.0	2013.0/0.235	329.2/0.02	264.1/0.03	76.5/0.0	1234.5/0.281	347.7/0.0
	GF[37]	<u>74.70%</u>	1685.5/0.03	1712.1/0.347	601.4/0.02	329.0/0.0	97.28/0.0	1417.4/0.112	362.4/0.0
	FD[49]	54.20%	1997.2/0.679	1555.5/0.775	1579.2/0.426	1633.1/0.332	1092.4/0.242	2607.9/0.613	1501.0/0.240
	AT[17]	61.60%	2113.4/0.724	1688.7/0.815	1091.5/0.416	1522.7/0.289	1109.0/0.159	2638.2/0.651	1440.6/0.200
	RND	73.00%	3041.5/0.245	2266.2/0.330	390.6/0.536	661.0/0.314	81.5/0.101	825.3/0.612	2435.5/0.540
	RND-GF	71.15%	2489.3/0.421	2053.5/0.563	495.9/0.603	514.0/0.348	1009.9/0.146	777.2/0.762	994.8/0.702
	RND-AT	58.15%	2556.6/0.864	2596.6/0.870	448.0/0.810	724.2/0.632	1306.3/0.386	1210.5/0.953	631.1/0.865

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	PNI[23]	87.20%	1071.4/0.725	1310.7/0.823	324.9/0.824	267.0/0.708	295.3/0.612	945.0/0.857	2342.2/0.623
	AT[20]	89.48%	<u>821.6/0.807</u>	<u>614.9/0.862</u>	1451.5/0.623	766.3/0.476	1135.4/0.499	1523.2/0.635	1180.4/0.484
	RND	<u>93.60%</u>	842.5/0.05	941.8/0.143	273.1/0.478	977.2/0.226	762.4/0.116	2112.6/0.549	912.8/0.688
	RND-GF	92.40%	2805.7/0.516	2966.3/0.730	1223.5/0.841	1017.1/0.407	1207.3/0.378	1220.2/0.863	687.2/0.872
	RND-AT	87.40%	2499.2/0.842	2625.7/0.923	891.5/0.891	767.9/0.737	1170.7/0.730	1787.4/0.912	687.4/0.911
ImageNet (ResNet-50)	Clean Model	74.90%	1031.9/0.0	2013.0/0.235	329.2/0.02	264.1/0.03	76.5/0.0	1234.5/0.281	347.7/0.0
	GF[37]	<u>74.70%</u>	1685.5/0.03	1712.1/0.347	601.4/0.02	329.0/0.0	97.28/0.0	1417.4/0.112	362.4/0.0
	FD[49]	54.20%	1997.2/0.679	1555.5/0.775	1579.2/0.426	1633.1/0.332	1092.4/0.242	2607.9/0.613	1501.0/0.240
	AT[17]	61.60%	2113.4/0.724	1688.7/0.815	1091.5/0.416	1522.7/0.289	1109.0/0.159	2638.2/0.651	1440.6/0.200
	RND	73.00%	3041.5/0.245	2266.2/0.330	390.6/0.536	661.0/0.314	81.5/0.101	825.3/0.612	2435.5/0.540
	RND-GF	71.15%	2489.3/0.421	2053.5/0.563	495.9/0.603	514.0/0.348	1009.9/0.146	777.2/0.762	994.8/0.702
	RND-AT	58.15%	2556.6/0.864	2596.6/0.870	448.0/0.810	724.2/0.632	1306.3/0.386	1210.5/0.953	631.1/0.865