

Last iterate convergence of SGD for Least-Squares in the Interpolation regime

Aditya Varre*, Loucas Pillaud-Vivien*, Nicolas Flammarion*

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Problem Setting

- **Least-Square:** A stream of i.i.d samples $(x_i, y_i)_{i=1}^T$ from an unknown distribution ρ . We want to minimize the population risk:

$$\mathcal{R}(\theta) = \frac{1}{2} \mathbb{E}_{\rho} (\langle \theta, x \rangle_{\mathcal{H}} - y)^2,$$

where $\theta, x \in \mathcal{H}$, (possibly infinite dimensional) Hilbert space and $y \in \mathbb{R}$.

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- **Aim: bound the excess risk.** Denote $\theta_* := \operatorname{argmin}_{\theta \in \mathcal{H}} \mathcal{R}(\theta)$, we bound the excess risk of the estimator given by the T -th iterate:

$$\mathbb{E} \mathcal{R}(\theta_T) - \mathcal{R}(\theta_*)$$

Last Iterate of SGD

- Last iterate of the constant step-size SGD may not converge, Why ?

Noise = Additive (model noise) + Multiplicative (SGD sampling noise)

Additive noise forces to use **variance reduction techniques** for SGD to converge.

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- **The noiseless setting:** We make the hypothesis that the model is perfect, i.e., there is no additive noise, i.e there exists a perfect regressor θ_*

$$\langle \theta_*, x \rangle = y \quad a.s.$$

Last iterate of SGD should converge in this model !

Noiseless Least Squares

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- **Non-strongly convex**. For, strongly convex we have linear rates on last iterate. However, for non-strongly convex it was **open**.
- **Covariance** The covariance operator on \mathcal{H} :

$$\mathbf{H} := \mathbb{E}_\rho[x \otimes x].$$

The non-strongly convex setting corresponds to the **smallest eigen value** being **arbitrarily small** and close to 0.

Main Result

Recall, **Risk** : $\mathcal{R}(\theta) = \frac{1}{2} \mathbb{E}_\rho (\langle \theta, x \rangle - Y)^2$, **SGD**: $\theta_{t+1} = \theta_t - \gamma (\langle \theta_t, x_t \rangle - y_t) x_t$.

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$$\exists \mathbf{R} \text{ s.t. } \mathbb{E} \left[\begin{array}{c} \|x\|^2 \\ xx^\top \end{array} \right] \preceq \mathbf{RH} \text{ and } \|\theta_*\|_{\mathcal{H}} < +\infty \quad (1)$$

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$$\exists R \text{ s.t. } \mathbb{E} \left[\|x\|^2 \ x x^\top \right] \preceq R \mathbf{H} \text{ and } \|\theta_*\|_{\mathcal{H}} < +\infty \quad (1)$$

Main Result

For $T \geq 2$, if we set $\gamma = (4R \ln(T))^{-1}$, we have the following bound for the expected risk of the estimator given by the T^{th} iterate of SGD:

$$\mathbb{E} \mathcal{R}(\theta_T) \leq 3 R \|\theta_*\|_{\mathcal{H}}^2 \frac{\ln(T)}{T}. \quad (2)$$

Non-parametric Rates

With further refinements over the **spectrum of co-variance** i.e. **capacity condition**

$$\exists \alpha > 0, R_\alpha > 0 \text{ s.t. } \mathbb{E} \left[\langle x, \mathbf{H}^{-\alpha} x \rangle x x^\top \right] \preceq R_\alpha \mathbf{H} \quad (3)$$

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and **regularity of optimum** i.e. **source condition** like

$$\exists \beta > -1, C_\beta > 0 \text{ s.t. } C_\beta = \|\mathbf{H}^{-\beta/2} \theta_*\|_{\mathcal{H}}^2 \quad (4)$$

Non-parametric rates

For $T \geq 3$, where $\gamma^{1-\alpha} \leq (32\xi_\alpha R_\alpha)^{-1}$ and $\xi_\alpha = \sum_{n \geq 1} \frac{1}{n^{1+\alpha}}$, we have

$$\mathbb{E} \mathcal{R}(\theta_T) \leq 2 \left(\frac{1+\beta}{\gamma} \right)^{1+\beta} \frac{C_\beta}{T^{1+\alpha \wedge \beta}} \quad (5)$$

Conclusion

Contributions:

- **No additive noise** implies **no variance reduction**. Last iterate of the **constant step-size SGD** converges!

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- Insights into optimization of general convex (even non-convex) overparamaterized models.

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- A new **Lyapunov technique** to control the bias error in standard least square analysis.

Perspectives:

- Insights into optimization of general convex (even non-convex) overparamaterized models.
- A simple and effective setting for understanding interplay between **momentum** with **stochastic/multiplicative** noise.