



# **HYPRO: A Hybridly Normalized Probabilistic Model for Long-Horizon Prediction of Event Sequence**

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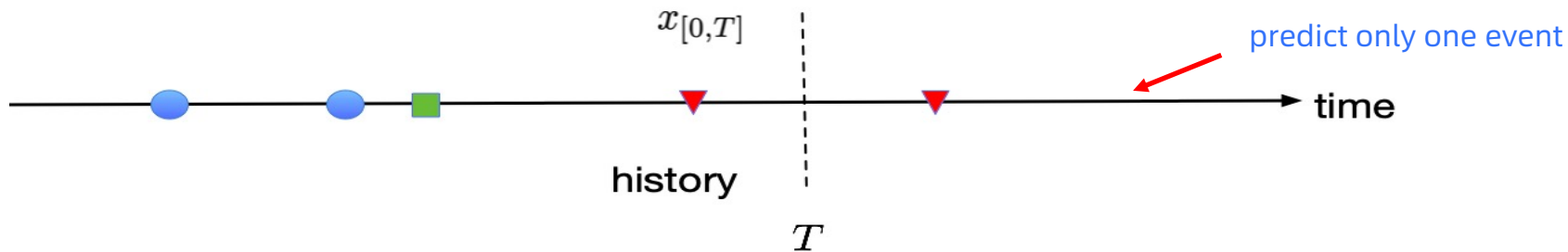
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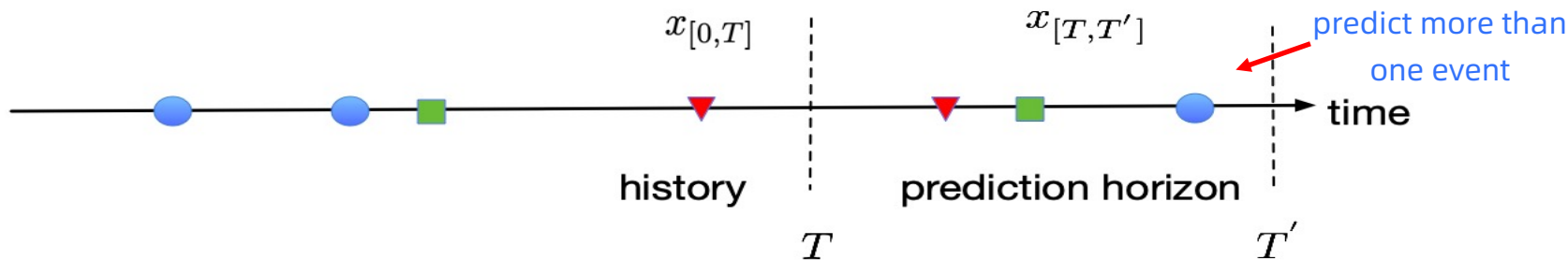
# Problem

Given an event sequence  $x_{[0,T]} = \{(t_0, k_0), (t_1, k_1), \dots, (t_n, k_n)\}, t_i \in R, k_i \in N$

The typical problem: predict next event



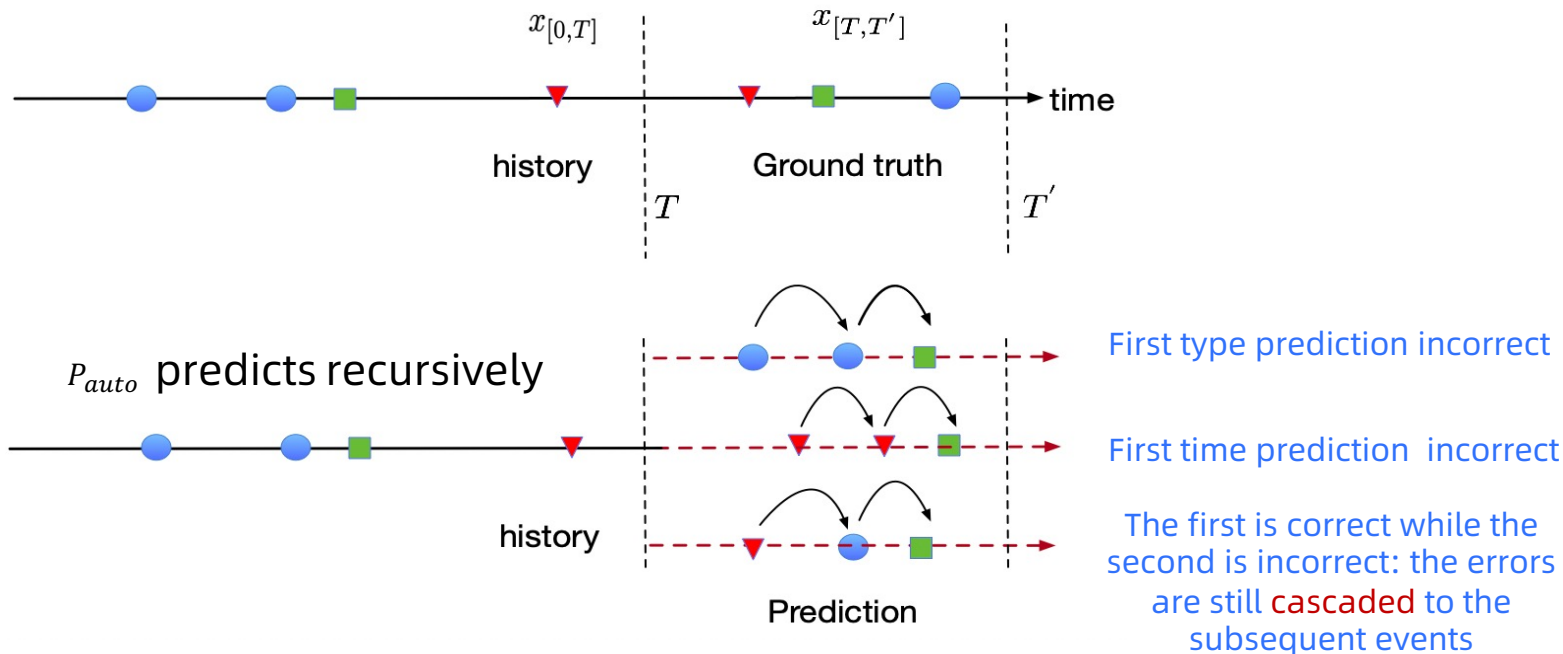
Our problem: predict **next multiple events over a long future horizon**  $[T, T']$ .



# Challenge: Cascading Error and Local Normalization

A typical solution is **autoregressive** model  $P_{auto}$

$$P(x_{i+k}, \dots, x_{i+1} | x_i, \dots, x_0) = \prod P(x_{i+k} | \hat{x}_{i+k-1}, \dots, x_{\leq i}) \dots P(x_{i+2} | \hat{x}_{i+1}, x_{\leq i}) P(x_{i+1} | x_{\leq i})$$

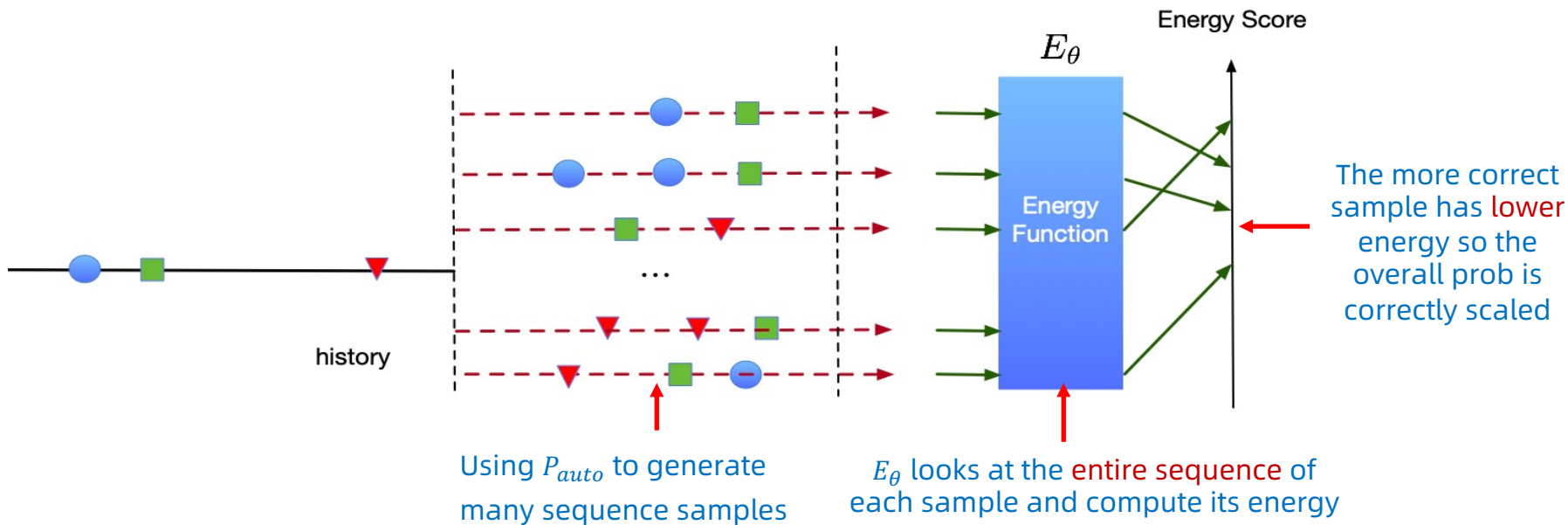


Whenever you make mistakes, you'll never have a chance to correct it !

# Our Key Idea: Using Energy-based Model

$$p_{\text{PHYPRO}}(x_{(T,T')} | x_{[0,T]}) = p_{\text{auto}}(x_{(T,T')} | x_{[0,T]}) \frac{\exp(-E_{\theta}(x_{[0,T']}))}{Z_{\theta}(x_{[0,T]})}$$

Hybridly normalized      Locally normalized      Globally normalized



Our energy function looks at each entire sequence, so it has a chance to correct any earlier errors!

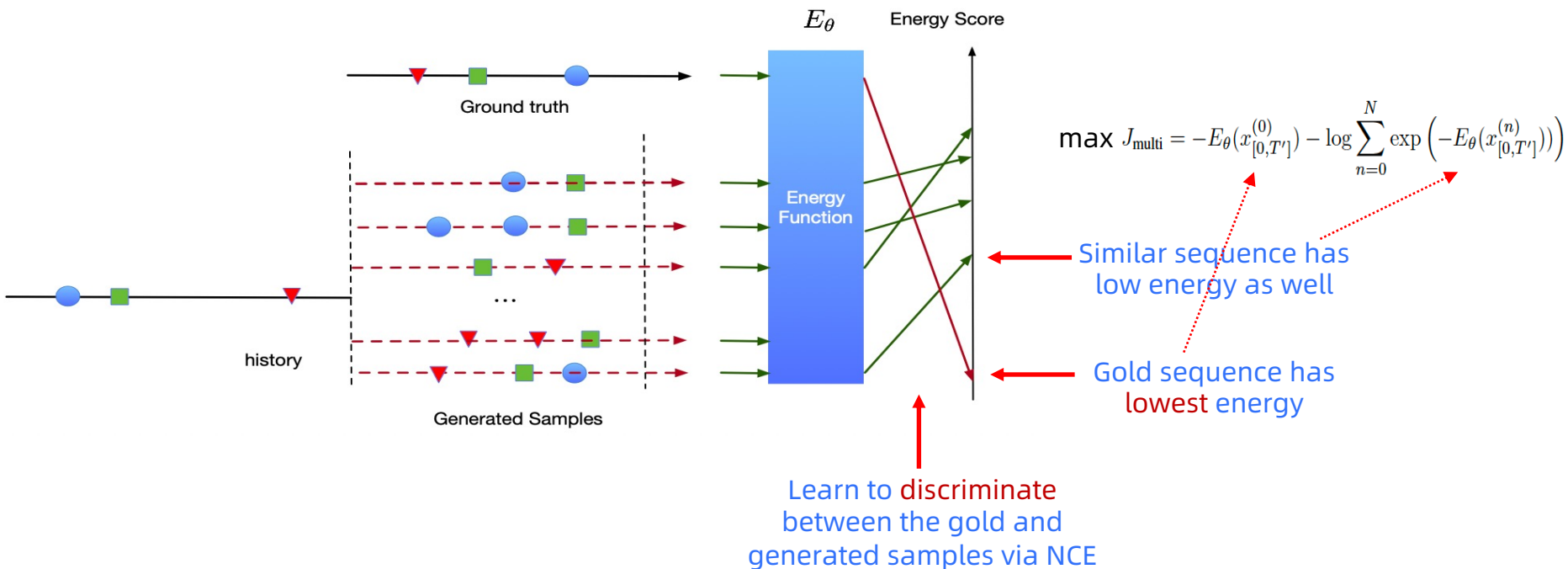
# Model Training: Noise-Contrastive Learning

$$p_{\text{HYPRO}}(x_{(T,T')} | x_{[0,T]}) = p_{\text{auto}}(x_{(T,T')} | x_{[0,T]}) \frac{\exp(-E_{\theta}(x_{[0,T']}))}{Z_{\theta}(x_{[0,T]})}$$

Hybridly normalized

Locally normalized

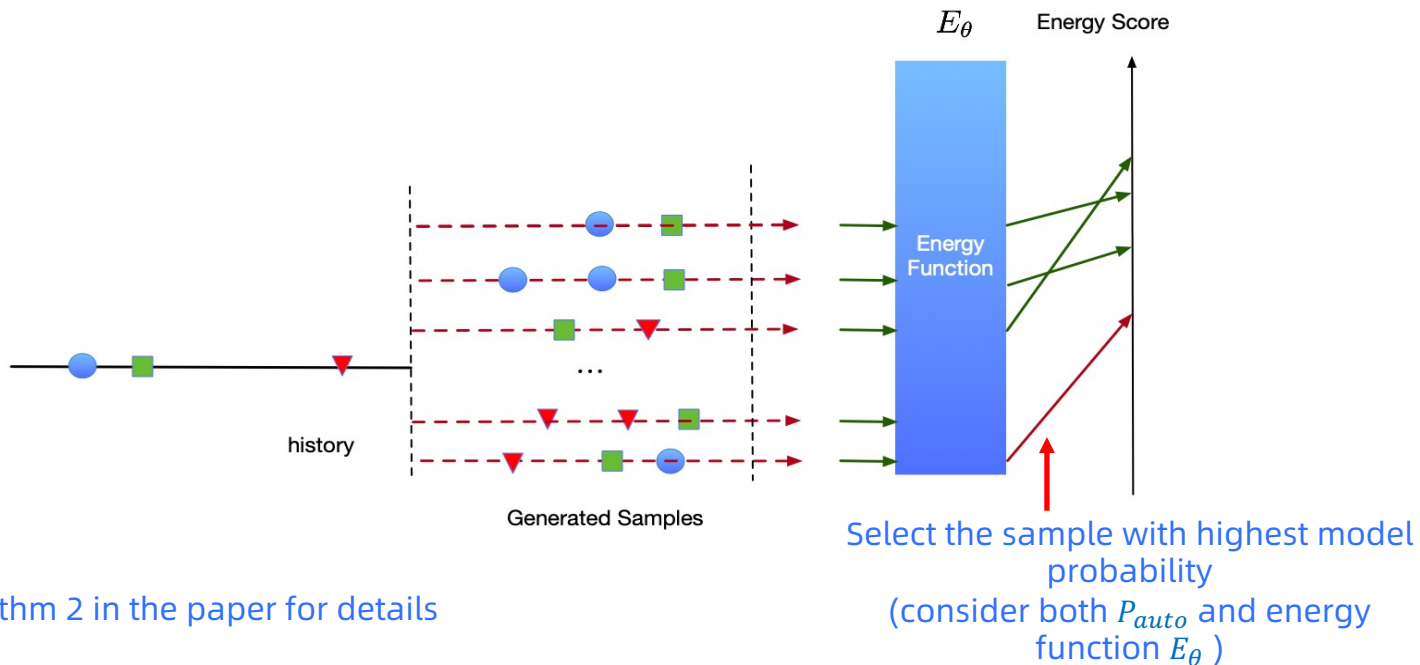
Globally normalized



# Model Inference : Normalized Importance Sampling

$$p_{\text{HYPRO}}(x_{(T,T')} | x_{[0,T]}) = p_{\text{auto}}(x_{(T,T')} | x_{[0,T]}) \frac{\exp(-E_{\theta}(x_{[0,T']}))}{Z_{\theta}(x_{[0,T]})}$$

Hybridly normalized      Locally normalized      Globally normalized



See Algorithm 2 in the paper for details

Looking forward to seeing you at our poster and we can discuss

model details

training details

experimental results

paper can be downloaded from

