



Causal normalizing flows: from theory to practice

Adrián Javaloy

NeurIPS 2023 - Oral

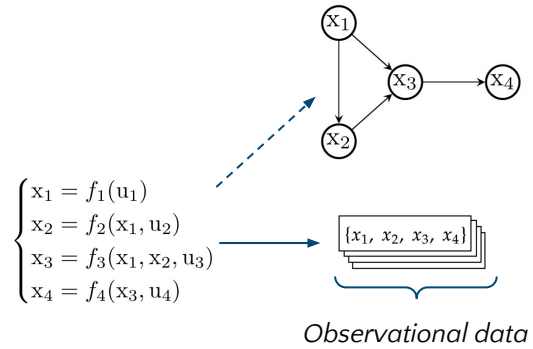
Pablo Sánchez-Martín



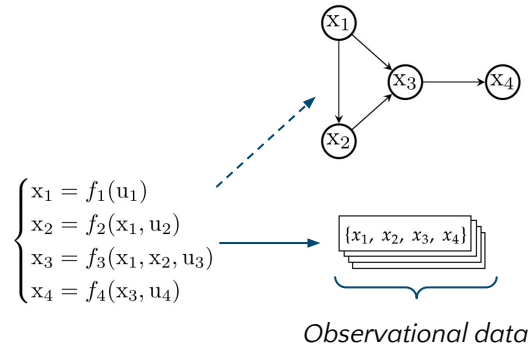
Isabel Valera



Motivation

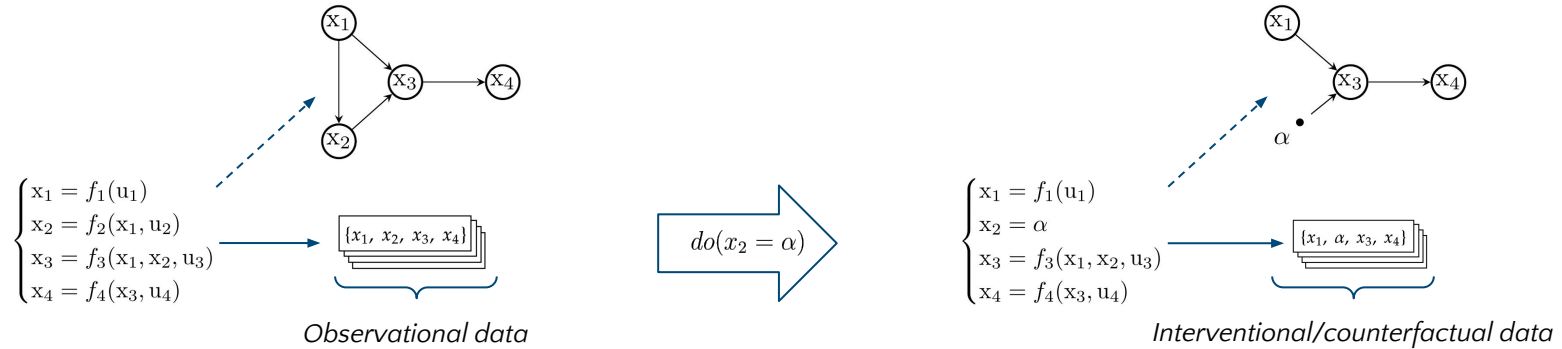


Motivation



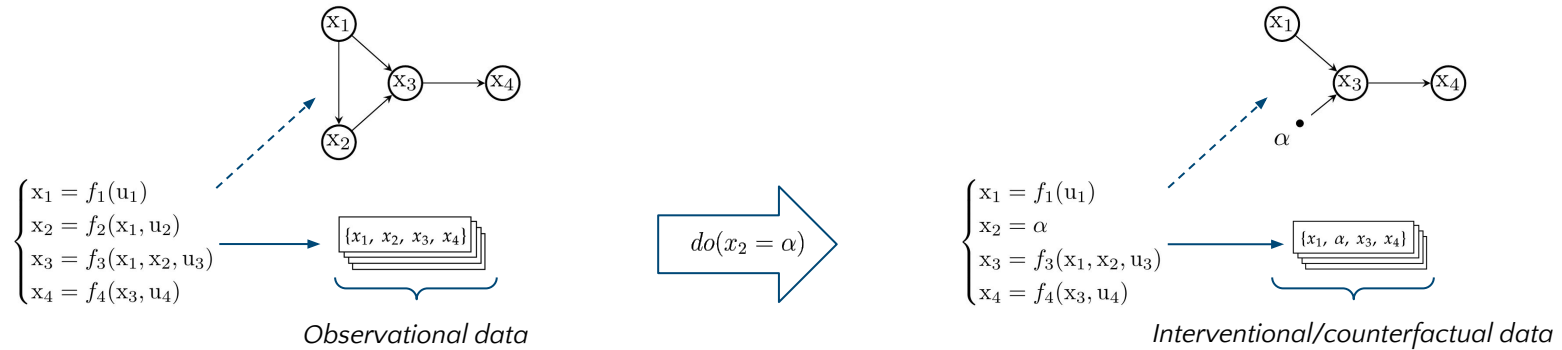
“Will I get my health insurance application approved?”

Motivation



“Will I get my health insurance application approved?”

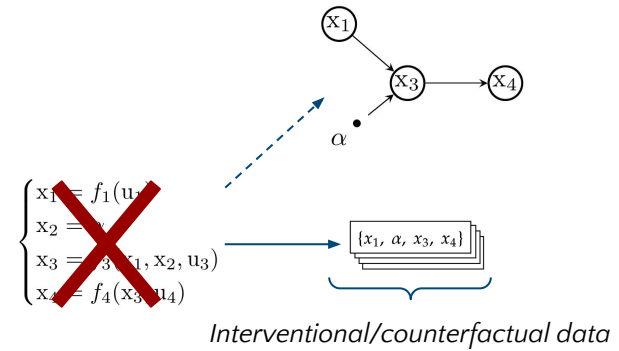
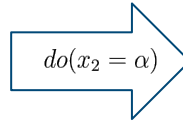
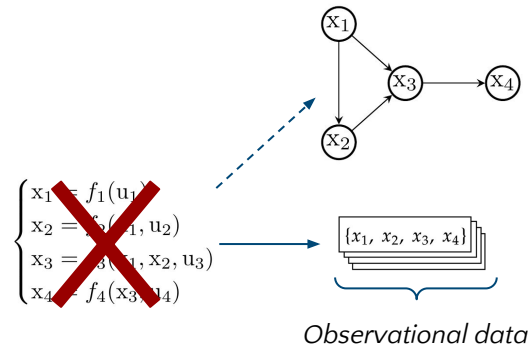
Motivation



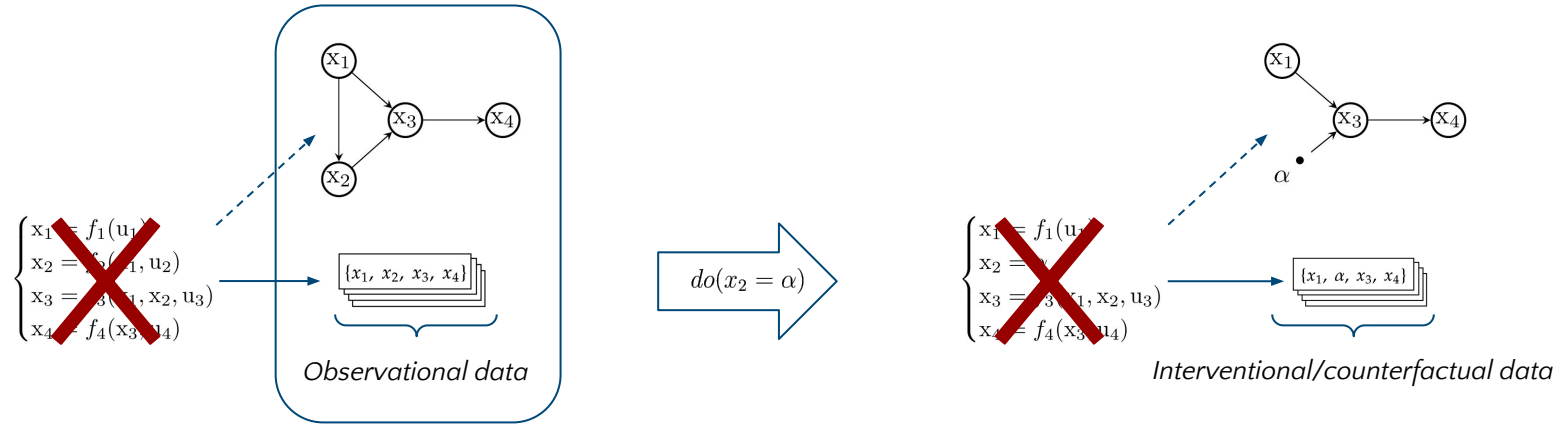
“Will I get my health insurance application approved?”

“I got my application rejected. Would I have gotten it if I were younger?”

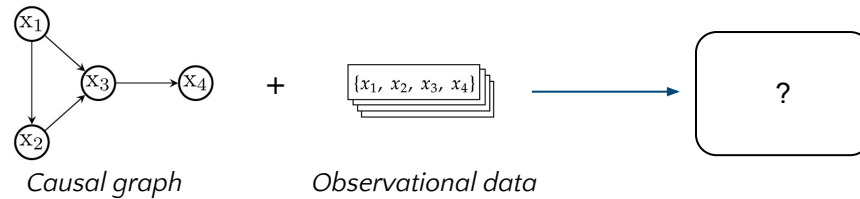
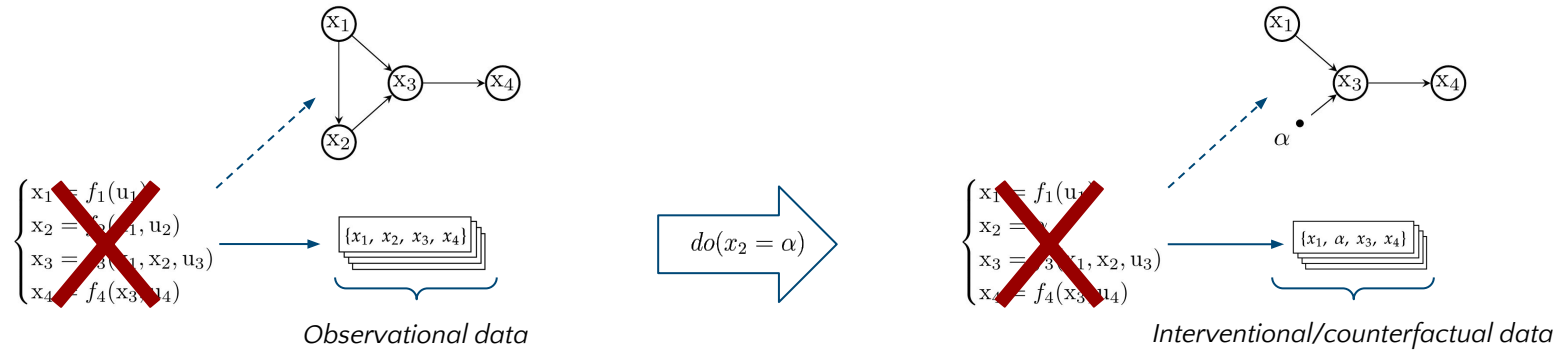
Motivation



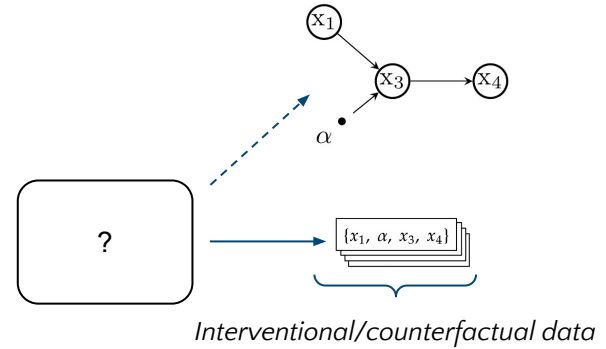
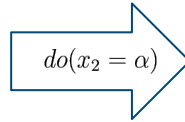
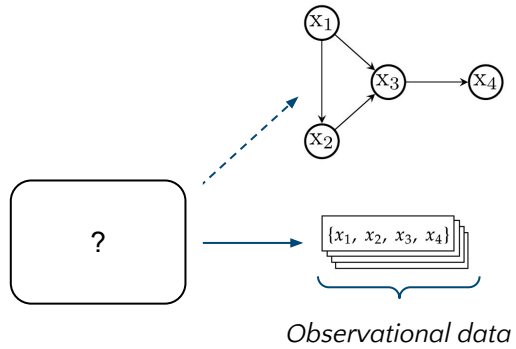
Motivation



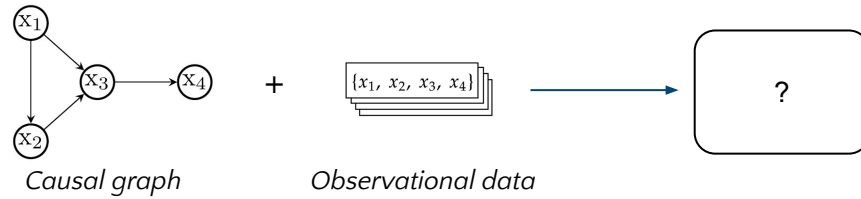
Motivation



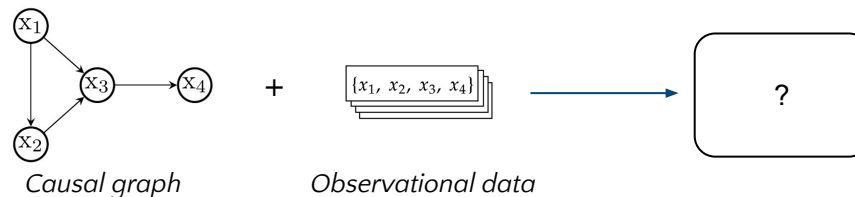
Motivation



How to approach this problem...



How to approach this problem...



1. Model each variable individually:

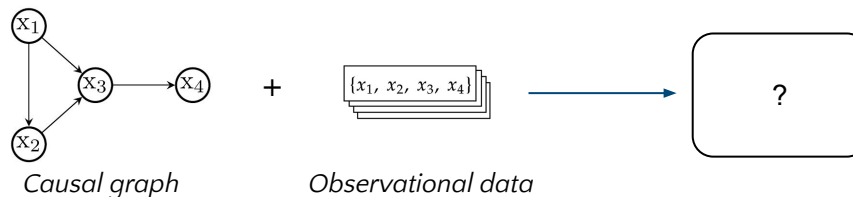
E.g.: a linear function, spline, GP¹, NN², ...

- ✗ Independent functions ✓ Straightforward
- ✗ No amortization ✓ Causally consistent
- ✗ Seq. error propagation ✓ Easy do-operator

[1] Karimi, Amir-Hossein, et al. "Algorithmic recourse under imperfect causal knowledge: a probabilistic approach." Advances in neural information processing systems 33 (2020): 265-277.

[2] Parafita, Álvaro, and Jordi Vitrià. "Estimand-Agnostic Causal Query Estimation With Deep Causal Graphs." IEEE Access 10 (2022): 71370-71386.

How to approach this problem...



1. Model each variable individually:

E.g.: a linear function, spline, GP¹, NN², ...

- ✗ Independent functions
- ✓ Straightforward
- ✗ No amortization
- ✓ Causally consistent
- ✗ Seq. error propagation
- ✓ Easy do-operator

2. Model the SCM with a Deep Neural Network.

E.g.: VACA,¹ CAREFL,² ...

- ✓ Expressive
- ✗ Without guarantees
- ✓ Parameter amortization
- ✗ Complex NN training
- ✓ Parallel computations
- ✗ Inexact do-operator

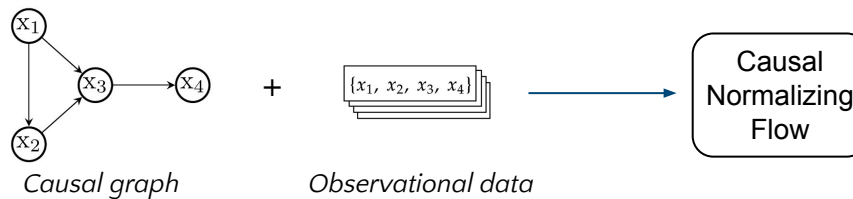
[1] Karimi, Amir-Hossein, et al. "Algorithmic recourse under imperfect causal knowledge: a probabilistic approach." Advances in neural information processing systems 33 (2020): 265-277.

[2] Parafita, Álvaro, and Jordi Vitrià. "Estimand-Agnostic Causal Query Estimation With Deep Causal Graphs." IEEE Access 10 (2022): 71370-71386.

[3] Sánchez-Martin, P., M. Rateike, and I. Valera. "VACA: Designing Variational Graph Autoencoders for Causal Queries". Proceedings of the AAAI Conference on Artificial Intelligence, vol. 36, no.

[4] Khemakhem, Ilyes, et al. "Causal autoregressive flows." International conference on artificial intelligence and statistics. PMLR, 2021.

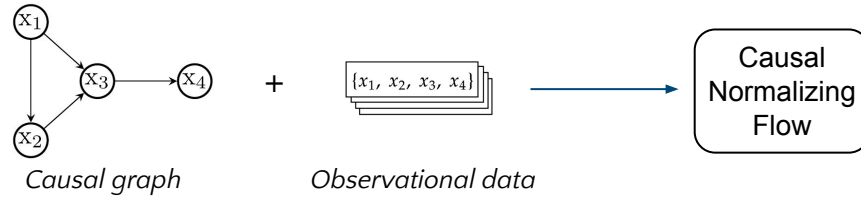
... until today



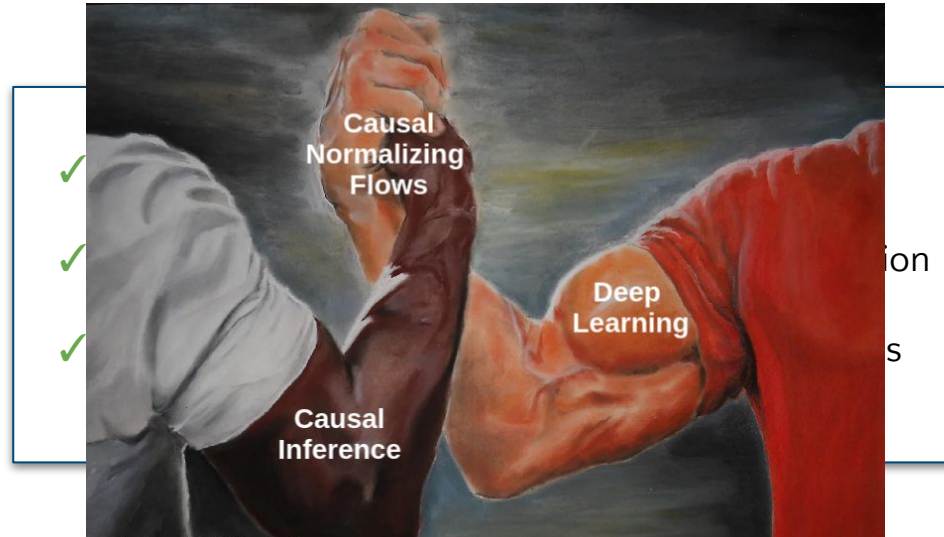
Causal Normalizing Flows:

- ✓ Straightforward
- ✓ Expressive
- ✓ Causally consistent
- ✓ Parameter amortization
- ✓ Easy do-operator
- ✓ Parallel computations

... until today



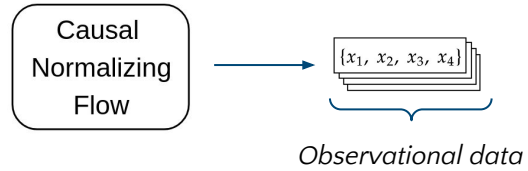
Causal Normalizing Flows:



In a nutshell

Causal
Normalizing
Flow

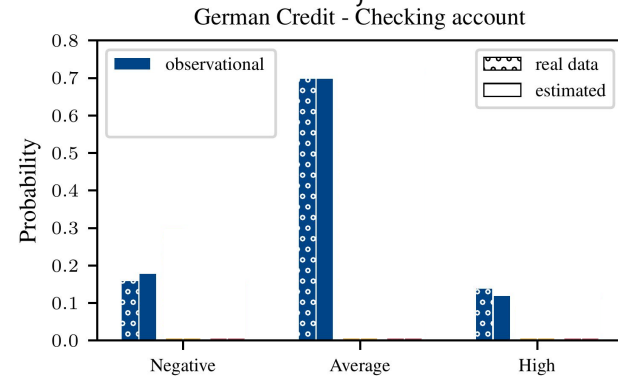
In a nutshell



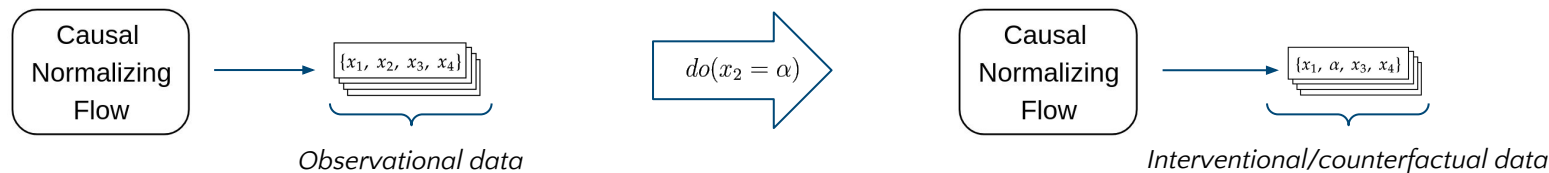
Capabilities

1. Generate observational data.

Objectives

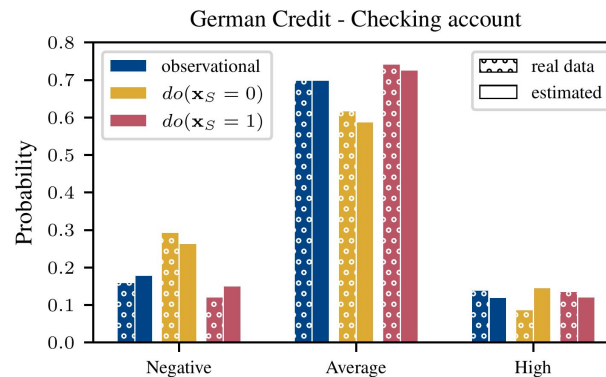


In a nutshell

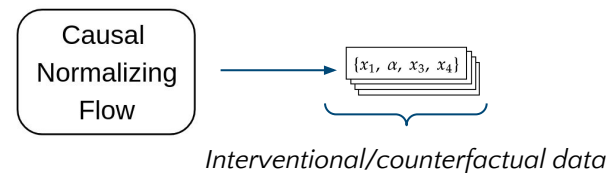
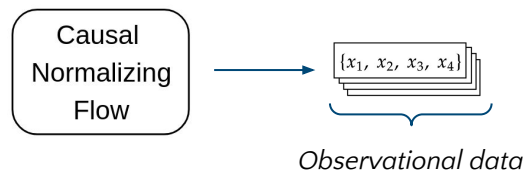


Capabilities

1. Generate observational data.
2. Generate interventional data.
3. Generate counterfactual data.

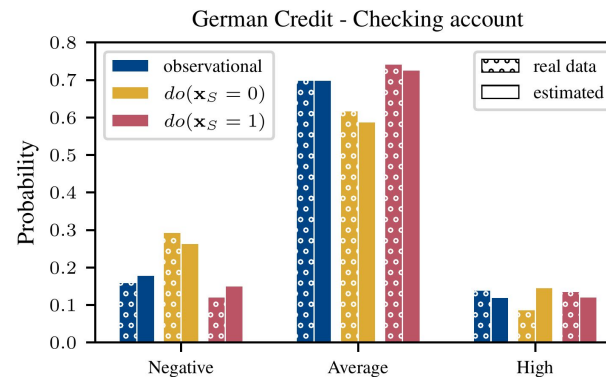


In a nutshell

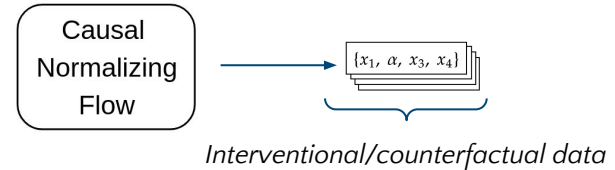
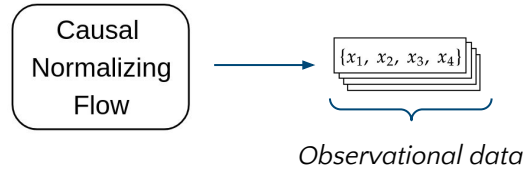


Capabilities

1. Generate observational data.
2. Generate interventional data.
3. Generate counterfactual data.



In a nutshell



Capabilities

1. Generate observational data.

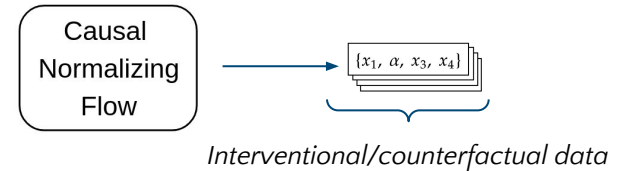
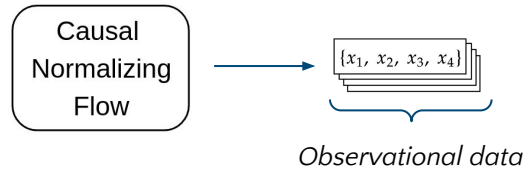
2. Generate interventional data.

3. Generate counterfactual data.

Objectives

1. Fit the observed data accurately.

In a nutshell

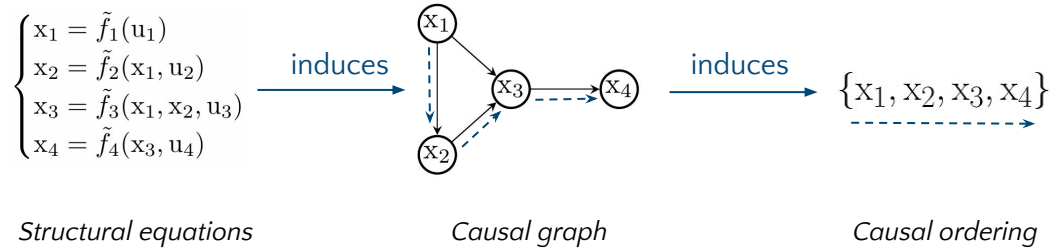


Capabilities

1. Generate observational data.
2. Generate interventional data.
3. Generate counterfactual data.

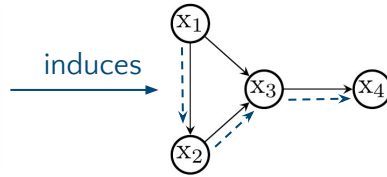
Objectives

1. Fit the observed data accurately.
2. Identify the exogenous variables.
3. Ensure causal consistency wrt. the true SCM.

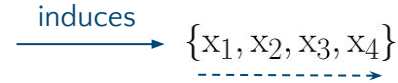


$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) \end{cases}$$

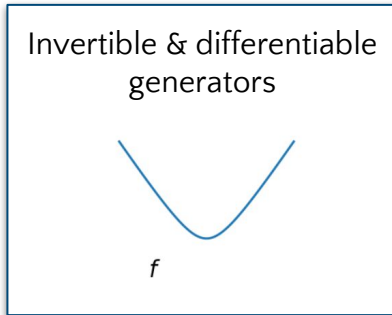
Structural equations



Causal graph

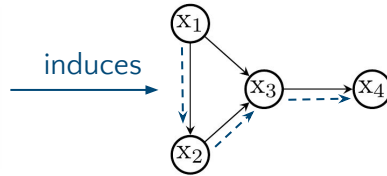


Causal ordering

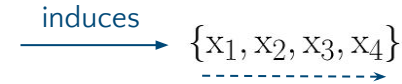


$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) \end{cases}$$

Structural equations

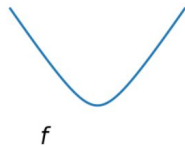


Causal graph

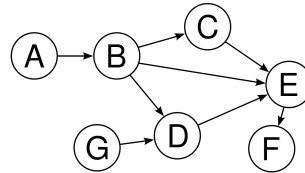


Causal ordering

Invertible & differentiable
generators

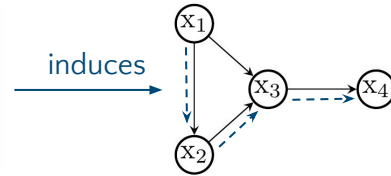


No feedback loops

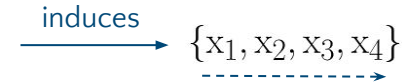


$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) \end{cases}$$

Structural equations

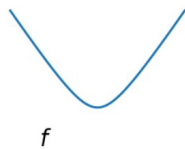


Causal graph

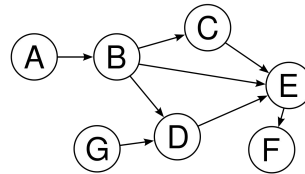


Causal ordering

Invertible & differentiable
generators



No feedback loops



Causal sufficiency

$$p(\mathbf{u}) = \prod_i p(\mathbf{u}_i)$$

ANFs and SCMs under the same umbrella

SCM→Structural Causal Model

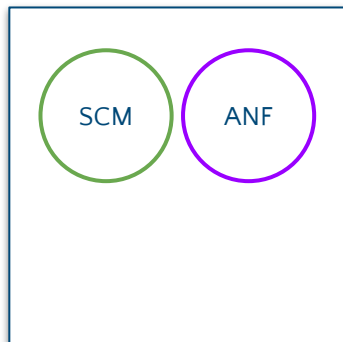
1. Fit the observed data accurately.



ANFs and SCMs under the same umbrella

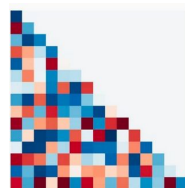
1. Fit the observed data accurately.

SCM → Structural Causal Model
ANF → Aut. Normalizing Flow



ANFs:

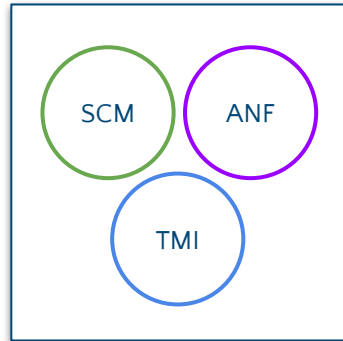
- Invertible differentiable neural networks.
- Transform random variables, $T_{\theta}(\mathbf{x}) =: \mathbf{u} \sim P_{\mathbf{u}}$.
- Autoregressive and monotonic.



ANFs and SCMs under the same umbrella

1. Fit the observed data accurately.

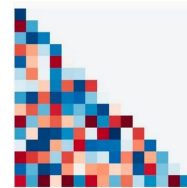
SCM→Structural Causal Model
ANF→Aut. Normalizing Flow
TMI→Triangular Monotonic Incr. Map



Triangular Monotonic Increasing (TMI) maps.

$$f(x) = \begin{bmatrix} f_1(x_1) \\ f_2(x_1, x_2) \\ \vdots \\ f_d(x_1, \dots, x_d) \end{bmatrix}$$

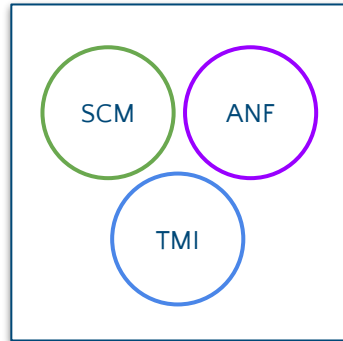
$$\partial_{x_i} f_i(x_1, x_2, \dots, x_i) \geq 0$$




ANFs and SCMs under the same umbrella

1. Fit the observed data accurately.

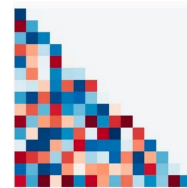
SCM→Structural Causal Model
ANF→Aut. Normalizing Flow
TMI→Triangular Monotonic Incr. Map



Triangular Monotonic Increasing (TMI) maps.

$$f(x) = \begin{bmatrix} f_1(x_1) \\ f_2(x_1, x_2) \\ \vdots \\ f_d(x_1, \dots, x_d) \end{bmatrix}$$


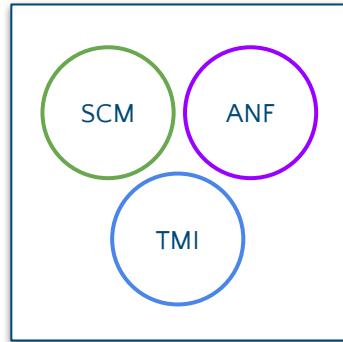
$$\partial_{x_i} f_i(x_1, x_2, \dots, x_i) \geq 0$$



ANFs and SCMs under the same umbrella

1. Fit the observed data accurately.

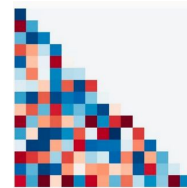
SCM→Structural Causal Model
ANF→Aut. Normalizing Flow
TMI→Triangular Monotonic Incr. Map



Triangular Monotonic Increasing (TMI) maps.

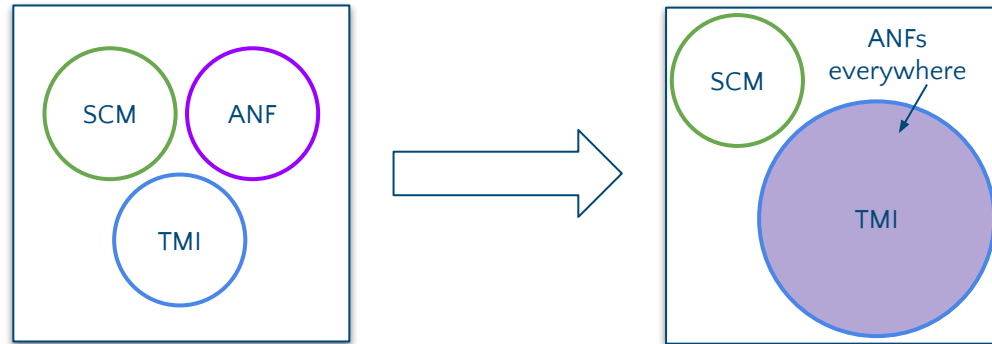
$$f(x) = \begin{bmatrix} f_1(x_1) \\ f_2(x_1, x_2) \\ \vdots \\ f_d(x_1, \dots, x_d) \end{bmatrix}$$

$$\partial_{x_i} f_i(x_1, x_2, \dots, x_i) \geq 0$$



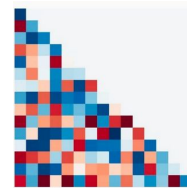
ANFs and SCMs under the same umbrella

1. Fit the observed data accurately.



SCM→Structural Causal Model
ANF→Aut. Normalizing Flow
TMI→Triangular Monotonic Incr. Map

ANFs are TMI maps
and
universal approximators of any other TMI map.

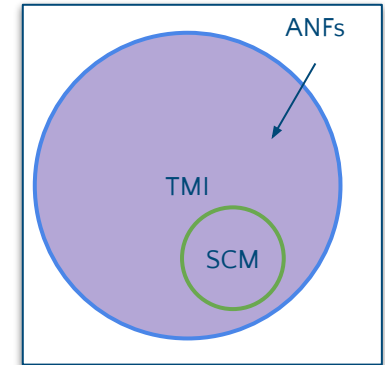
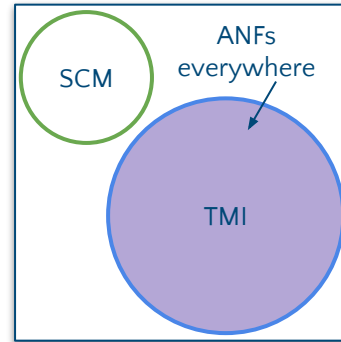
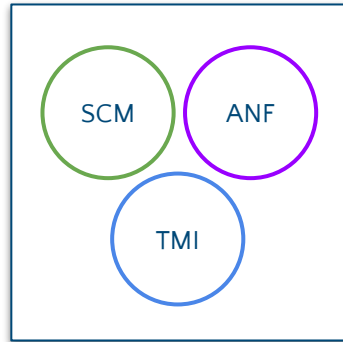


ANFs and SCMs under the same umbrella



1. Fit the observed data accurately.

SCM → Structural Causal Model
ANF → Aut. Normalizing Flow
TMI → Triangular Monotonic Incr. Map



Structural equations
can be always
unrolled & monotimized

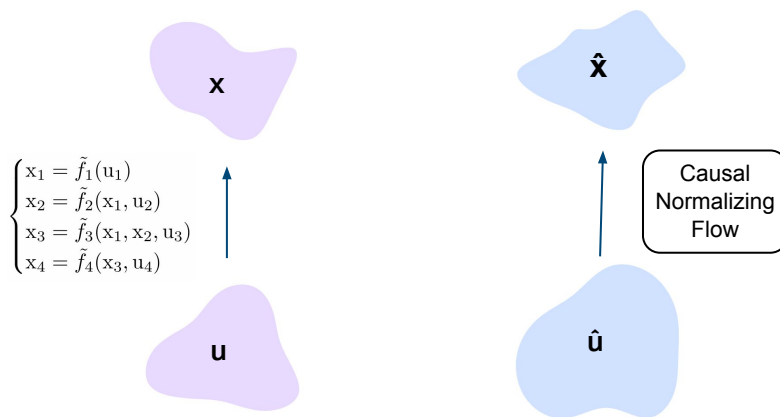
$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) = \tilde{f}_2(\tilde{f}_1(u_1), u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) = \tilde{f}_3(\tilde{f}_1(u_1), \tilde{f}_2(\tilde{f}_1(u_1), u_2), u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) = \tilde{f}_4(\tilde{f}_3(\tilde{f}_1(u_1), \tilde{f}_2(\tilde{f}_1(u_1), u_2), u_3), u_4) \end{cases}$$

Isolating the exogenous variables

2. Identify the exogenous variables.

$\mathcal{F} \times \mathcal{P}_{\mathbf{u}}$ - Family of TMI maps with fully-factorized distributions.

Theorem 1 (Identifiability). If two elements of the family $\mathcal{F} \times \mathcal{P}_{\mathbf{u}}$ (as defined above) produce the same observational distribution, then the two data-generating processes differ by an invertible, component-wise transformation of the variables \mathbf{u} .

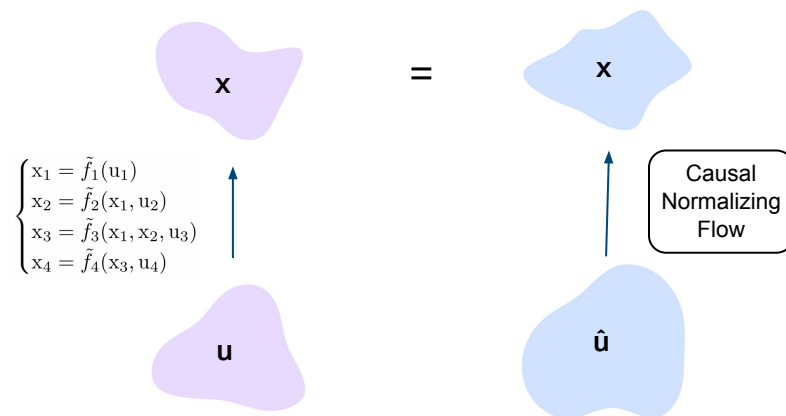


Isolating the exogenous variables

2. Identify the exogenous variables.

$\mathcal{F} \times \mathcal{P}_{\mathbf{u}}$ - Family of TMI maps with fully-factorized distributions.

Theorem 1 (Identifiability). If two elements of the family $\mathcal{F} \times \mathcal{P}_{\mathbf{u}}$ (as defined above) produce the same observational distribution, then the two data-generating processes differ by an invertible, component-wise transformation of the variables \mathbf{u} .



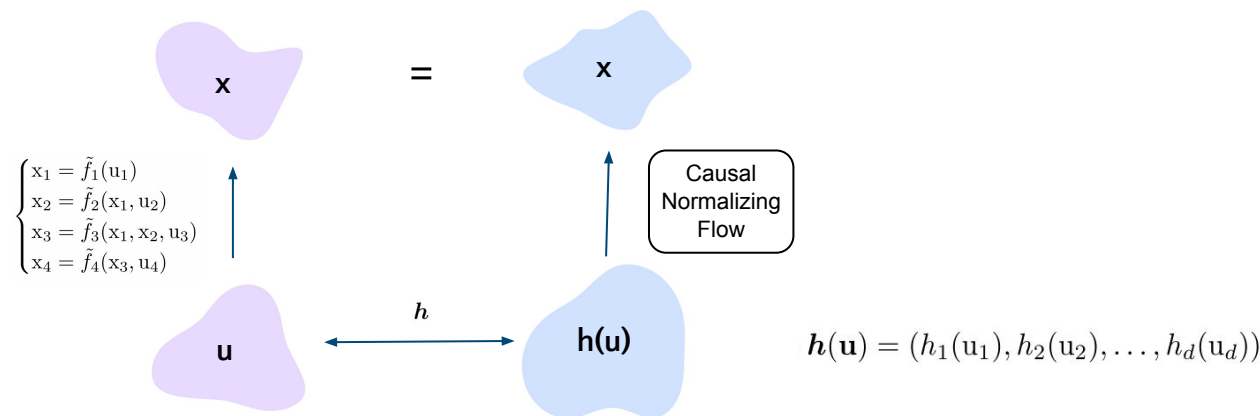
Isolating the exogenous variables



2. Identify the exogenous variables.

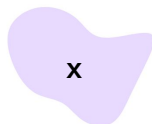
$\mathcal{F} \times \mathcal{P}_{\mathbf{u}}$ - Family of TMI maps with fully-factorized distributions.

Theorem 1 (Identifiability). If two elements of the family $\mathcal{F} \times \mathcal{P}_{\mathbf{u}}$ (as defined above) produce the same observational distribution, then the two data-generating processes differ by an invertible, component-wise transformation of the variables \mathbf{u} .

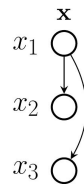


3. Ensure causal consistency wrt. the true SCM.

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, u_3) \end{cases}$$

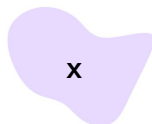


Recursive

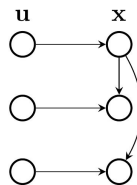


3. Ensure causal consistency wrt. the true SCM.

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, u_3) \end{cases}$$

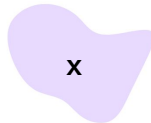


Recursive

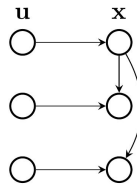


3. Ensure causal consistency wrt. the true SCM.

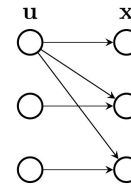
$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, u_3) \end{cases}$$



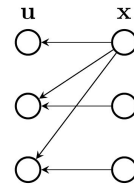
Recursive



Generative

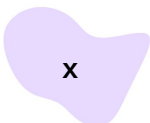


Abductive

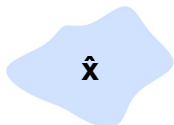


3. Ensure causal consistency wrt. the true SCM.

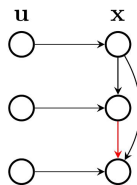
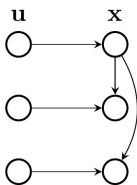
$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, u_3) \end{cases}$$



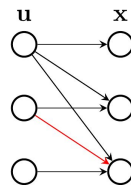
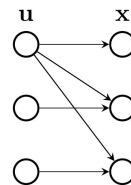
Causal
Normalizing
Flow



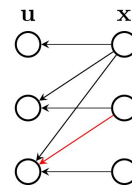
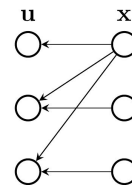
Recursive



Generative



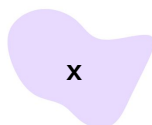
Abductive



3. Ensure causal consistency wrt. the true SCM.

Corollary 2 (Causal consistency). If a causal NF T_θ isolates the exogenous variables of an SCM \mathcal{M} , then $\nabla_{\mathbf{x}} T_\theta(\mathbf{x}) \equiv \mathbf{I} - \mathbf{A}$ and $\nabla_{\mathbf{u}} T_\theta^{-1}(\mathbf{u}) \equiv \mathbf{I} + \sum_{n=1}^{\text{diam}(\mathbf{A})} \mathbf{A}^n$, where \mathbf{A} is the causal adjacency matrix of \mathcal{M} . In other words, T_θ is causally consistent with the true data-generating process, \mathcal{M} .

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, u_3) \end{cases}$$

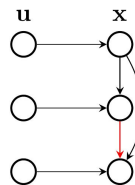
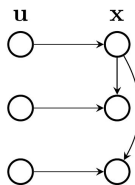


||

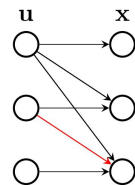
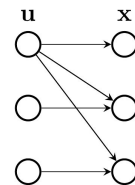


Causal
Normalizing
Flow

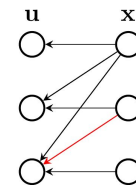
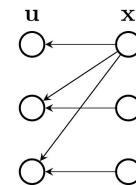
Recursive



Generative



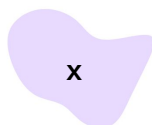
Abductive



3. Ensure causal consistency wrt. the true SCM.

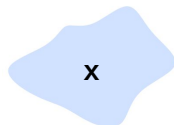
Corollary 2 (Causal consistency). If a causal NF T_θ isolates the exogenous variables of an SCM \mathcal{M} , then $\nabla_{\mathbf{x}} T_\theta(\mathbf{x}) \equiv \mathbf{I} - \mathbf{A}$ and $\nabla_{\mathbf{u}} T_\theta^{-1}(\mathbf{u}) \equiv \mathbf{I} + \sum_{n=1}^{\text{diam}(\mathbf{A})} \mathbf{A}^n$, where \mathbf{A} is the causal adjacency matrix of \mathcal{M} . In other words, T_θ is causally consistent with the true data-generating process, \mathcal{M} .

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, u_3) \end{cases}$$

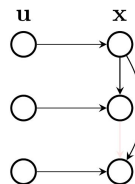
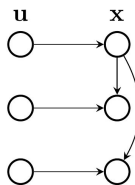


||

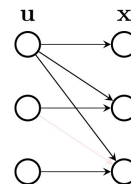
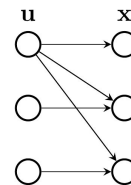
Causal
Normalizing
Flow



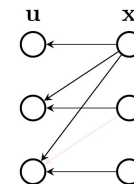
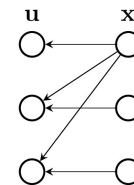
Recursive



Generative



Abductive

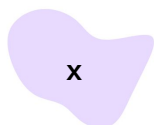




3. Ensure causal consistency wrt. the true SCM.

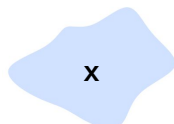
Corollary 2 (Causal consistency). If a causal NF T_θ isolates the exogenous variables of an SCM \mathcal{M} , then $\nabla_{\mathbf{x}} T_\theta(\mathbf{x}) \equiv \mathbf{I} - \mathbf{A}$ and $\nabla_{\mathbf{u}} T_\theta^{-1}(\mathbf{u}) \equiv \mathbf{I} + \sum_{n=1}^{\text{diam}(\mathbf{A})} \mathbf{A}^n$, where \mathbf{A} is the causal adjacency matrix of \mathcal{M} . In other words, T_θ is causally consistent with the true data-generating process, \mathcal{M} .

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, u_3) \end{cases}$$

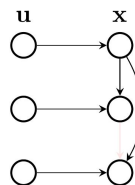
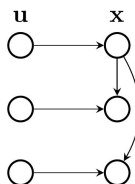


||

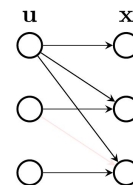
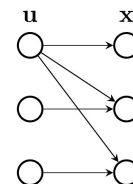
Causal
Normalizing
Flow



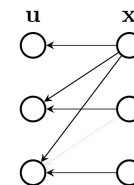
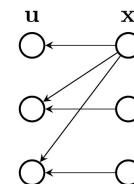
Recursive



Generative

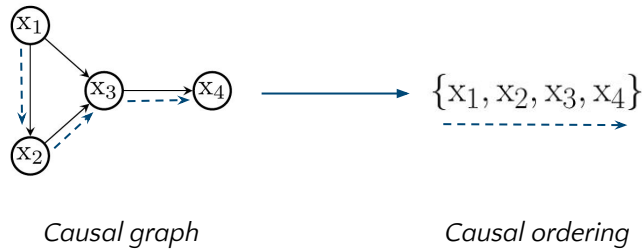


Abductive



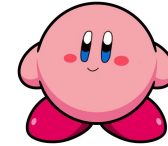
Theory vs. practice

In theory...
ANF + causal ordering is enough.



Theory vs. practice

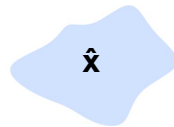
In theory...
ANF + causal ordering is enough.



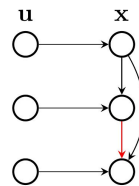
... but in practice ...
Neural networks ♥ local optima.



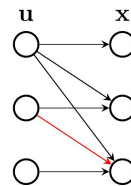
Causal
Normalizing
Flow



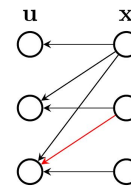
Recursive



Generative



Abductive



Theory vs. practice

In theory...
ANF + causal ordering is enough.



... but in practice ...
Neural networks ♥ local optima.



Wait!
With **G** we can design a causally consistent network!



3. Ensure causal consistency wrt. the true SCM.

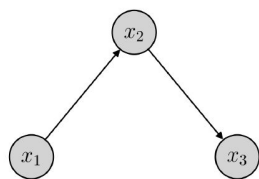
		Design Choices		Model Properties		Time Complexity	
		Network Type	Causal Assumption	Causal Consistency		Sampling	Evaluation
				$\mathbf{u} \rightarrow \mathbf{x}$	$\mathbf{x} \rightarrow \mathbf{u}$		
Flow direction	$\mathbf{u} \rightarrow \mathbf{x}$	Generative	Ordering	\times	\times	$\mathcal{O}(L)$	$\mathcal{O}(dL)$
		Generative	Graph \mathbf{G}	\checkmark	\times	$\mathcal{O}(L)$	$\mathcal{O}(dL)$
	$\mathbf{x} \rightarrow \mathbf{u}$	Abductive	Ordering	\times	\times	$\mathcal{O}(dL)$	$\mathcal{O}(L)$
		Abductive ($L > 1$)	Graph \mathbf{G}	\times	\times	$\mathcal{O}(dL)$	$\mathcal{O}(L)$
		Abductive ($L = 1$)	Graph \mathbf{G}	\checkmark	\checkmark	$\mathcal{O}(dL)$	$\mathcal{O}(L)$



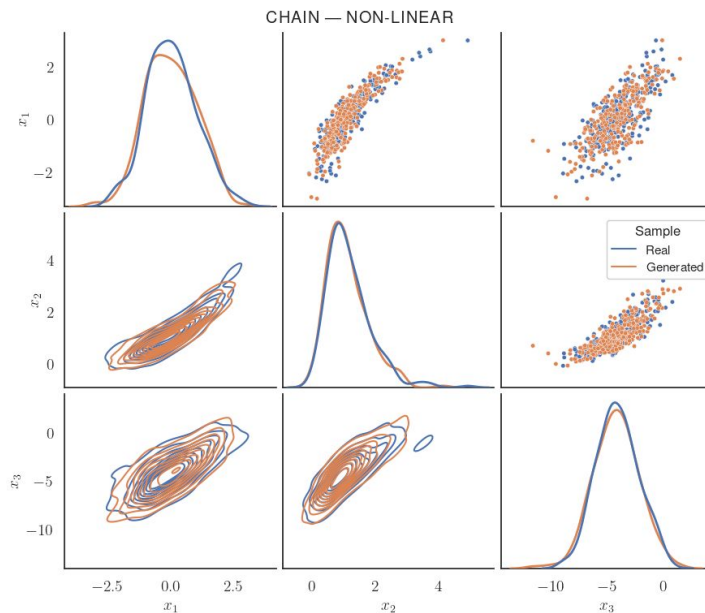
3. Ensure causal consistency wrt. the true SCM.

		Design Choices		Model Properties		Time Complexity	
		Network Type	Causal Assumption	Causal Consistency		Sampling	Evaluation
				$\mathbf{u} \rightarrow \mathbf{x}$	$\mathbf{x} \rightarrow \mathbf{u}$		
Flow direction	$\mathbf{u} \rightarrow \mathbf{x}$	Generative	Ordering	\times	\times	$\mathcal{O}(L)$	$\mathcal{O}(dL)$
		Generative	Graph \mathbf{G}	\checkmark	\times	$\mathcal{O}(L)$	$\mathcal{O}(dL)$
	$\mathbf{x} \rightarrow \mathbf{u}$	Abductive	Ordering	\times	\times	$\mathcal{O}(dL)$	$\mathcal{O}(L)$
		Abductive ($L > 1$)	Graph \mathbf{G}	\times	\times	$\mathcal{O}(dL)$	$\mathcal{O}(L)$
		Abductive ($L = 1$)	Graph \mathbf{G}	\checkmark	\checkmark	$\mathcal{O}(dL)$	$\mathcal{O}(L)$

Qualitative results

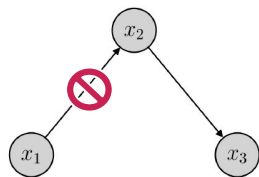


(a) 3-CHAIN

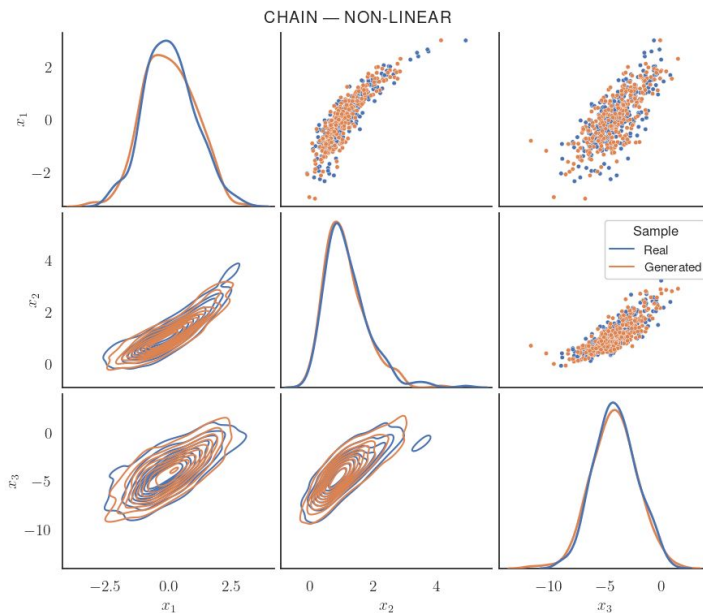


(a) Observational distribution.

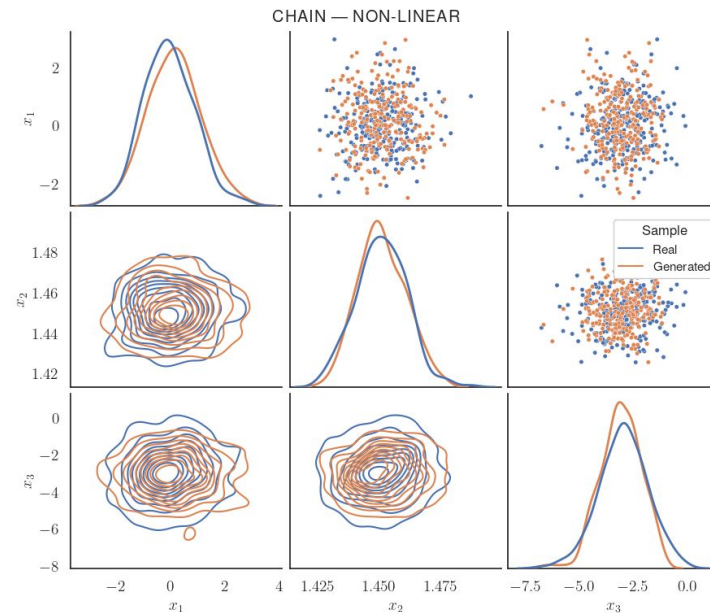
Qualitative results



(a) 3-CHAIN

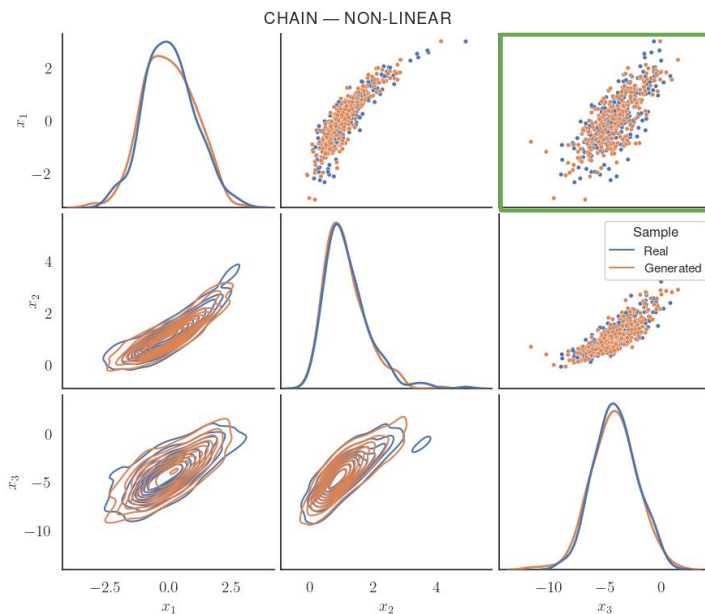
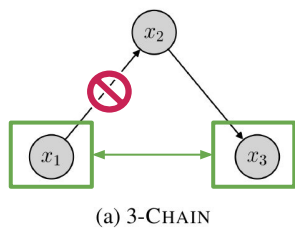


(a) Observational distribution.

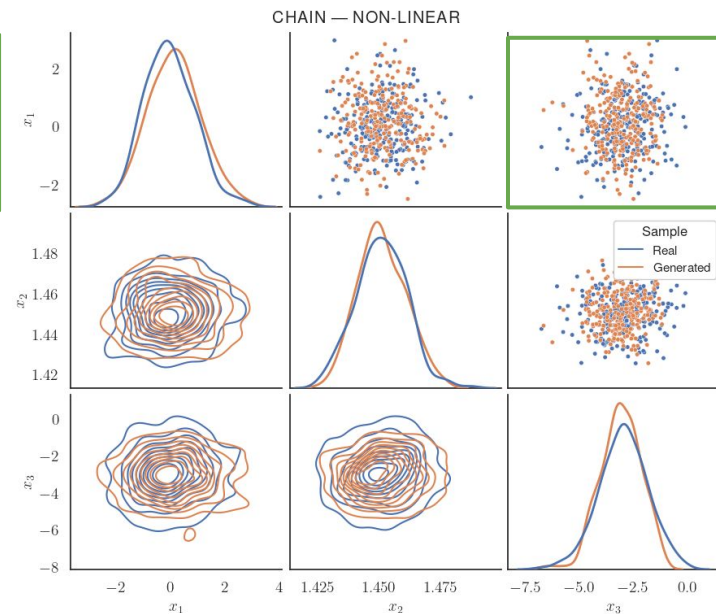


(b) Interventional distribution

Qualitative results



(a) Observational distribution.



(b) Interventional distribution

Quantitative results

Dataset	Model	Performance			Time Evaluation (μ s)		
		Observ.	Interv.	Counter.	Training	Evaluation	Sampling
Fork LIN	CausalNF	0.00 _{0.00}	0.03 _{0.01}	0.01 _{0.00}	0.52 _{0.05}	0.59 _{0.08}	1.57 _{0.57}
	CAREFL [†]	0.00 _{0.00}	0.04 _{0.01}	0.02 _{0.00}	0.60 _{0.17}	0.78 _{0.16}	2.39 _{1.06}
	VACA	8.75 _{0.73}	0.87 _{0.02}	1.43 _{0.02}	45.84 _{4.64}	34.66 _{2.39}	73.29 _{4.70}
LargeBD NLIN	CausalNF	1.51 _{0.04}	0.02 _{0.00}	0.01 _{0.00}	0.52 _{0.10}	0.60 _{0.17}	3.05 _{0.66}
	CAREFL [†]	1.51 _{0.05}	0.05 _{0.01}	0.08 _{0.01}	0.84 _{0.47}	1.18 _{0.17}	8.25 _{1.29}
	VACA	53.66 _{2.07}	0.39 _{0.00}	0.82 _{0.02}	164.92 _{11.10}	137.88 _{15.72}	167.94 _{25.75}
Simpson SYMPROD	CausalNF	0.00 _{0.00}	0.07 _{0.01}	0.12 _{0.02}	0.59 _{0.17}	0.60 _{0.11}	1.51 _{0.30}
	CAREFL [†]	0.00 _{0.00}	0.10 _{0.02}	0.17 _{0.04}	0.49 _{0.15}	0.81 _{0.19}	1.91 _{0.33}
	VACA	13.85 _{0.64}	0.89 _{0.00}	1.50 _{0.04}	49.26 _{4.09}	37.78 _{3.41}	79.20 _{14.60}

12 datasets in the paper!

Quantitative results

Dataset	Model	Performance			Time Evaluation (μ s)		
		Observ.	Interv.	Counter.	Training	Evaluation	Sampling
Fork LIN	CausalNF	0.00 _{0.00}	0.03 _{0.01}	0.01 _{0.00}	0.52 _{0.05}	0.59 _{0.08}	1.57 _{0.57}
	CAREFL [†]	0.00 _{0.00}	0.04 _{0.01}	0.02 _{0.00}	0.60 _{0.17}	0.78 _{0.16}	2.39 _{1.06}
	VACA	8.75 _{0.73}	0.87 _{0.02}	1.43 _{0.02}	45.84 _{4.64}	34.66 _{2.39}	73.29 _{4.70}
LargeBD NLIN	CausalNF	1.51 _{0.04}	0.02 _{0.00}	0.01 _{0.00}	0.52 _{0.10}	0.60 _{0.17}	3.05 _{0.66}
	CAREFL [†]	1.51 _{0.05}	0.05 _{0.01}	0.08 _{0.01}	0.84 _{0.47}	1.18 _{0.17}	8.25 _{1.29}
	VACA	53.66 _{2.07}	0.39 _{0.00}	0.82 _{0.02}	164.92 _{11.10}	137.88 _{15.72}	167.94 _{25.75}
Simpson SYMPROD	CausalNF	0.00 _{0.00}	0.07 _{0.01}	0.12 _{0.02}	0.59 _{0.17}	0.60 _{0.11}	1.51 _{0.30}
	CAREFL [†]	0.00 _{0.00}	0.10 _{0.02}	0.17 _{0.04}	0.49 _{0.15}	0.81 _{0.19}	1.91 _{0.33}
	VACA	13.85 _{0.64}	0.89 _{0.00}	1.50 _{0.04}	49.26 _{4.09}	37.78 _{3.41}	79.20 _{14.60}

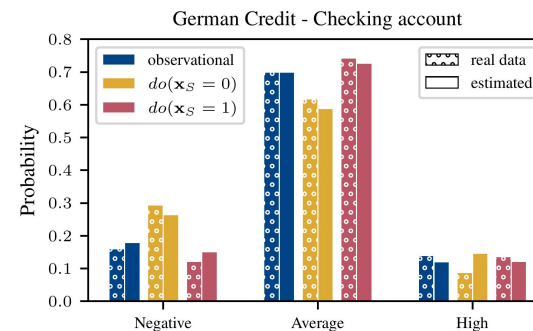
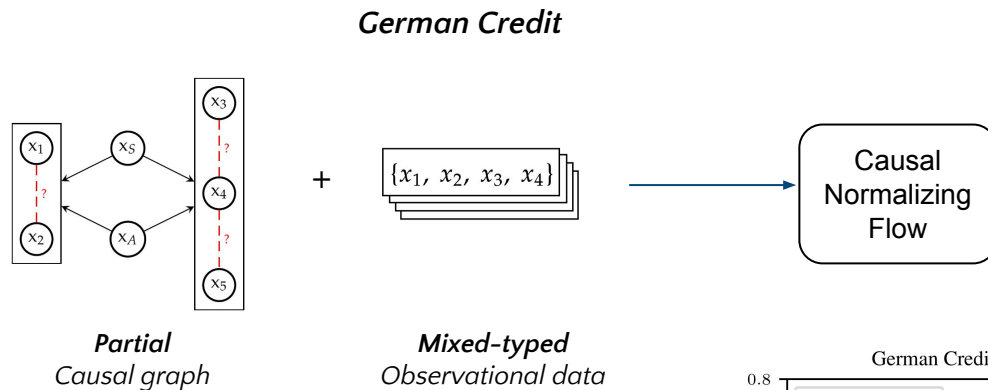
12 datasets in the paper!

Quantitative results

Dataset	Model	Performance			Time Evaluation (μ s)		
		Observ.	Interv.	Counter.	Training	Evaluation	Sampling
Fork LIN	CausalNF	0.00 _{0.00}	0.03 _{0.01}	0.01 _{0.00}	0.52 _{0.05}	0.59 _{0.08}	1.57 _{0.57}
	CAREFL [†]	0.00 _{0.00}	0.04 _{0.01}	0.02 _{0.00}	0.60 _{0.17}	0.78 _{0.16}	2.39 _{1.06}
	VACA	8.75 _{0.73}	0.87 _{0.02}	1.43 _{0.02}	45.84 _{4.64}	34.66 _{2.39}	73.29 _{4.70}
LargeBD NLIN	CausalNF	1.51 _{0.04}	0.02 _{0.00}	0.01 _{0.00}	0.52 _{0.10}	0.60 _{0.17}	3.05 _{0.66}
	CAREFL [†]	1.51 _{0.05}	0.05 _{0.01}	0.08 _{0.01}	0.84 _{0.47}	1.18 _{0.17}	8.25 _{1.29}
	VACA	53.66 _{2.07}	0.39 _{0.00}	0.82 _{0.02}	164.92 _{11.10}	137.88 _{15.72}	167.94 _{25.75}
Simpson SYMPROD	CausalNF	0.00 _{0.00}	0.07 _{0.01}	0.12 _{0.02}	0.59 _{0.17}	0.60 _{0.11}	1.51 _{0.30}
	CAREFL [†]	0.00 _{0.00}	0.10 _{0.02}	0.17 _{0.04}	0.49 _{0.15}	0.81 _{0.19}	1.91 _{0.33}
	VACA	13.85 _{0.64}	0.89 _{0.00}	1.50 _{0.04}	49.26 _{4.09}	37.78 _{3.41}	79.20 _{14.60}

12 datasets in the paper!

Use-case: fairness auditing and classification



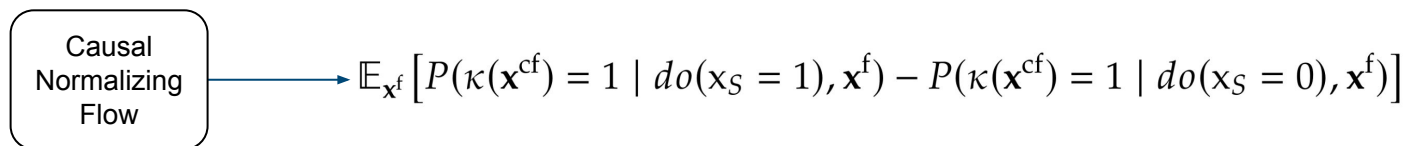
Use-case: fairness auditing and classification

	Logistic classifier			SVM classifier		
	full	unaware	fair x	full	unaware	fair x
F1-score	72.28 _{6.16}	72.37 _{4.90}	59.66 _{8.57}	76.04 _{2.86}	76.80 _{5.82}	68.28 _{5.74}
Accuracy	67.00 _{3.83}	66.75 _{2.63}	54.75 _{5.91}	69.50 _{3.11}	71.00 _{3.83}	59.25 _{2.99}

[1] Kusner, Matt J., et al. "Counterfactual fairness." Advances in neural information processing systems 30 (2017).

Use-case: fairness auditing and classification

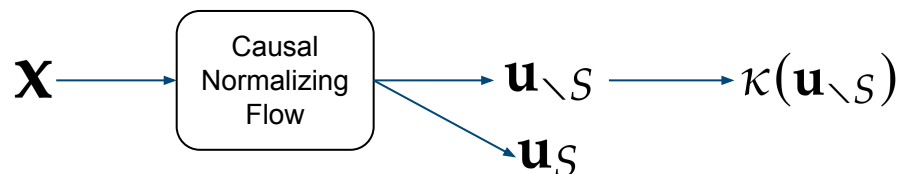
	Logistic classifier			SVM classifier		
	full	unaware	fair x	full	unaware	fair x
F1-score	72.28 _{6.16}	72.37 _{4.90}	59.66 _{8.57}	76.04 _{2.86}	76.80 _{5.82}	68.28 _{5.74}
Accuracy	67.00 _{3.83}	66.75 _{2.63}	54.75 _{5.91}	69.50 _{3.11}	71.00 _{3.83}	59.25 _{2.99}
Unfairness	5.84 _{2.93}	2.81 _{0.72}	0.00 _{0.00}	6.65 _{2.45}	2.78 _{0.40}	0.00 _{0.00}



[1] Kusner, Matt J., et al. "Counterfactual fairness." Advances in neural information processing systems 30 (2017).

Use-case: fairness auditing and classification

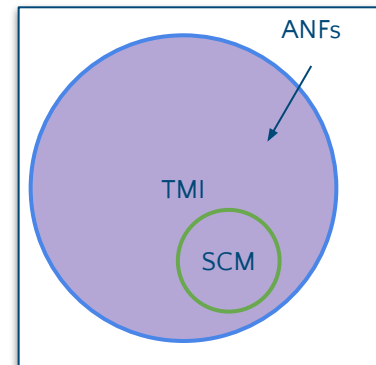
	Logistic classifier				SVM classifier			
	full	unaware	fair x	fair u	full	unaware	fair x	fair u
F1-score	72.28 _{6.16}	72.37 _{4.90}	59.66 _{8.57}	73.08 _{4.38}	76.04 _{2.86}	76.80 _{5.82}	68.28 _{5.74}	77.39 _{1.52}
Accuracy	67.00 _{3.83}	66.75 _{2.63}	54.75 _{5.91}	66.50 _{3.70}	69.50 _{3.11}	71.00 _{3.83}	59.25 _{2.99}	69.75 _{1.26}
Unfairness	5.84 _{2.93}	2.81 _{0.72}	0.00 _{0.00}	0.00 _{0.00}	6.65 _{2.45}	2.78 _{0.40}	0.00 _{0.00}	0.00 _{0.00}

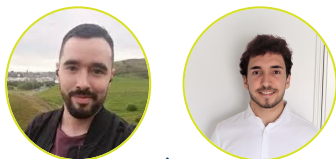


[1] Kusner, Matt J., et al. "Counterfactual fairness." Advances in neural information processing systems 30 (2017).

Concluding remarks

- Causal normalizing flows are a **natural choice** to learn SCMs.
- We provide **theoretical** results, and practical ways to:
 - **efficiently** capture a causal model, and
 - **exactly** perform causal inference.
- Lots of interesting future work! **Get in touch!**
 - Confounders?
 - Non-bijective generators?
 - Better loss functions?
 - Misspecifications?
 - Applications?





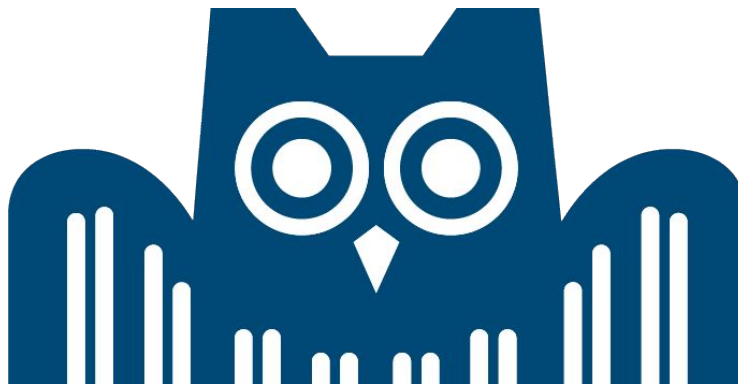
About to graduate!


Today at Poster **#822**
5:15 p.m. – 7:15 p.m




Hiring!

Questions?



 [arxiv: 2306.05415](https://arxiv.org/abs/2306.05415)

 [psanch21/causal-flows](https://github.com/psanch21/causal-flows)

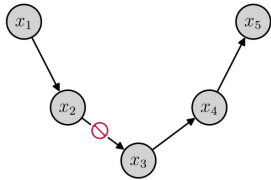
Does it work?



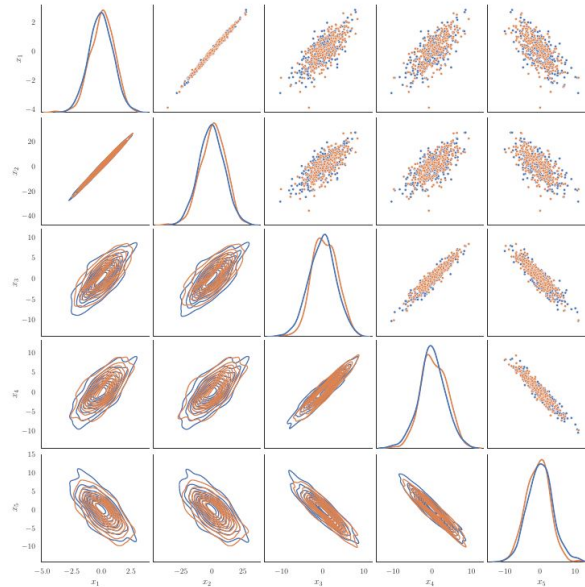
Theoretically: App. C \Rightarrow Intuition: the u_i of the intervened value is set to cancel out the influence of its parents.



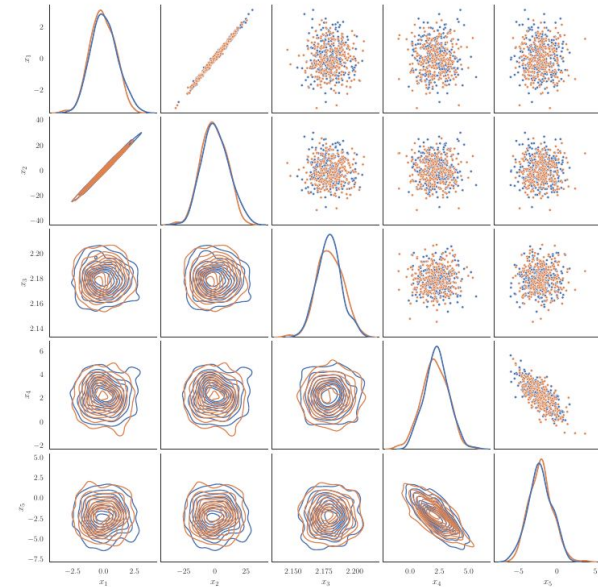
Empirically:



(c) 5-CHAIN



(a) Observational distribution.



(b) Interventional distribution $do(x_3 = 2.18)$.

Structural Causal Models

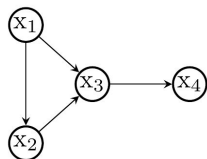
causal generator exogenous distribution

An SCM is a tuple $\mathcal{M} = (\tilde{\mathbf{f}}, P_{\mathbf{u}})$ describing a data-generating process to transform exogenous variables \mathbf{u} into (observed) endogenous variables \mathbf{x} .

$$\mathbf{u} := (u_1, u_2, \dots, u_d) \sim P_{\mathbf{u}}, \quad x_i = \tilde{f}_i(\mathbf{x}_{\text{pa}_i}, u_i), \quad \text{for } i = 1, 2, \dots, d.$$

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) \end{cases} \longrightarrow \{x_1, x_2, x_3, x_4\}$$

- Causal graph
- Adj. matrix
- Causal ordering



$$\mathbf{G} := \nabla_{\mathbf{x}} \tilde{\mathbf{f}} \neq \mathbf{0}$$

$$\mathbf{G} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$\pi = (1 \ 2 \ 3 \ 4)$$

We can use SCMs for causal inference, i.e., reason about what-if questions:
How the world would have been if X happened.

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \alpha \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) \end{cases} \longrightarrow \{x_1, \alpha, x_3, x_4\}$$

We can always write an SCM as a TMI map.

1. Unroll the SCM.



$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) = \tilde{f}_2(\tilde{f}_1(u_1), u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) = \tilde{f}_3(\tilde{f}_1(u_1), \tilde{f}_2(\tilde{f}_1(u_1), u_2), u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) = \tilde{f}_4(\tilde{f}_3(\tilde{f}_1(u_1), \tilde{f}_2(\tilde{f}_1(u_1), u_2), u_3), u_4) \end{cases}$$

2. “Monotonize” the SCM.

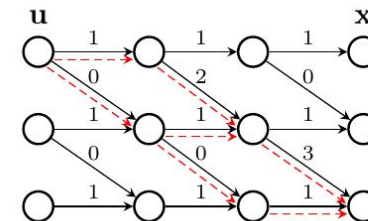
Always possible. How? Apply a Knöthe-Rosenblatt (KR) transport following the causal graph:

$$K_m(x_{1:m-1}, x_m) = F_\nu^{-1}\{F_\mu(x_m|x_{1:m-1}) \mid K_1(x_1), \dots, K_{m-1}(x_{1:m-1})\}$$

If $P_{\mathbf{u}}$ is a standard uniform distribution \Rightarrow Darmois construction.

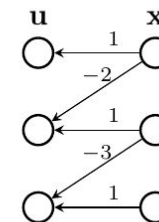
- Generative networks:
 - Defined from \mathbf{u} to \mathbf{x} .
 - The conditioner only takes the input according to \mathbf{G} .

$$\mathbf{z}_i^{l-1} = \tau_i(\mathbf{z}_i^l; \mathbf{h}_i^{l-1}), \quad \text{where } \mathbf{h}_i^{l-1} = c_i(\mathbf{z}_{\text{pa}_i}^l)$$



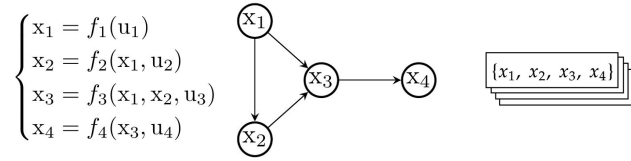
- Abductive networks:
 - Defined from \mathbf{x} to \mathbf{u} .
 - The conditioner only takes the input according to \mathbf{G} .

$$\mathbf{z}_i^l = \tau_i(\mathbf{z}_i^{l-1}; \mathbf{h}_i^l), \quad \text{where } \mathbf{h}_i^l = c_i(\mathbf{z}_{\text{pa}_i}^{l-1})$$

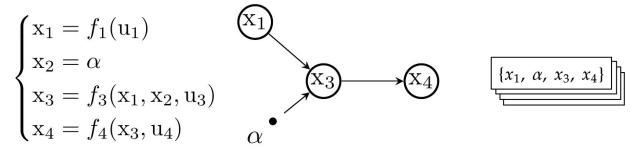


Usual implementation

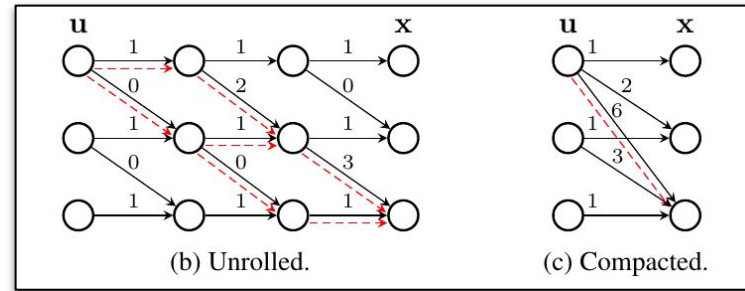
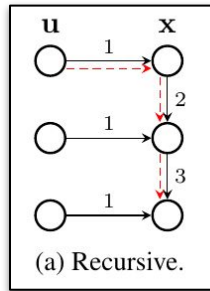
The do-operator simulates an *external intervention* in the system, breaking any causal relationships going to the intervened node.



The usual implementation yields an intervened SCM with a new set of equations, $\mathcal{M}^I = (\tilde{\mathbf{f}}^I, P_{\mathbf{u}})$



However, it only works for the recursive formulation.



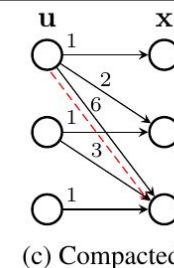
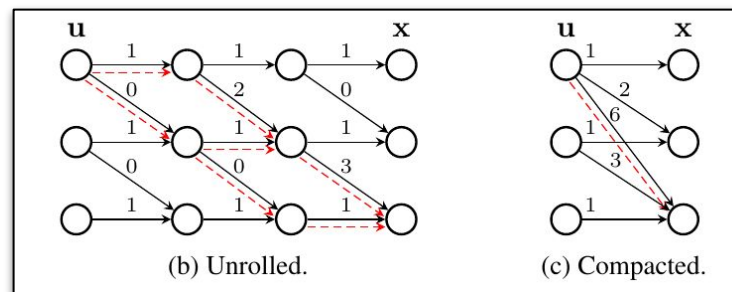
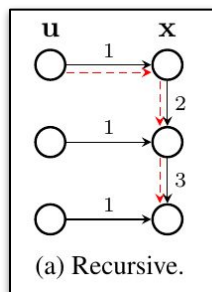
Our implementation

We propose to instead update $P_{\mathbf{u}}$ to put mass only on those values of \mathbf{u} that yield the intervened value, $\mathcal{M}^{\mathcal{I}} = (\mathbf{f}, P_{\mathbf{u}}^{\mathcal{I}})$.

$$p^{\mathcal{I}}(\mathbf{u}) = \delta\left(\left\{ \tilde{f}_i(\mathbf{x}_{\text{pa}_i}, \mathbf{u}_i) = \alpha \right\}\right) \cdot \prod_{j \neq i} p_j(\mathbf{u}_j)$$

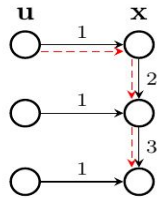
```

1: function SAMPLEINTERVENEDDIST( $i, \alpha$ )
2:    $\mathbf{u} \sim P_{\mathbf{u}}$ 
3:    $\mathbf{x} \leftarrow T_{\theta}^{-1}(\mathbf{u})$ 
4:    $x_i \leftarrow \alpha$ 
5:    $\mathbf{u}_i \leftarrow T_{\theta}(\mathbf{x})_i$ 
6:    $\mathbf{x} \leftarrow T_{\theta}^{-1}(\mathbf{u})$ 
7:   return  $\mathbf{x}$ 
8: end function
    
```



The multiple representations of SCMs

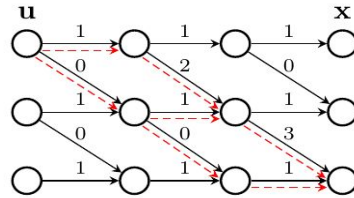
$$\mathbf{x} = \mathbf{G}\mathbf{x} + \mathbf{I}\mathbf{u}$$



(a) Recursive.

$$\begin{cases} x_1 = u_1 \\ x_2 = 2x_1 + u_2 \\ x_3 = 3x_2 + u_3 \end{cases}$$

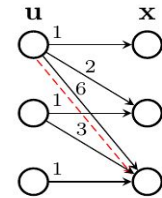
$$\mathbf{x} = \mathbf{G}_3(\mathbf{G}_2(\mathbf{G}_1\mathbf{u}))$$



(b) Unrolled.

$$\begin{cases} z_1^1 = u_1 \\ z_2^1 = u_2 \\ z_3^1 = u_3 \end{cases} \Rightarrow \begin{cases} z_1^2 = z_1^1 \\ z_2^2 = 2z_1^1 + z_2^1 \\ z_3^2 = z_3^1 \end{cases} \Rightarrow \begin{cases} x_1 = z_1^2 \\ x_2 = z_2^2 \\ x_3 = 3z_2^2 + z_3^2 \end{cases}$$

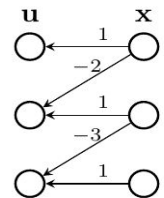
$$\mathbf{x} = (\mathbf{G}^2 + \mathbf{G} + \mathbf{I})\mathbf{u}$$



(c) Compacted.

$$\begin{cases} x_1 = u_1 \\ x_2 = 2u_1 + u_2 \\ x_3 = 6u_1 + 3u_2 + u_3 \end{cases}$$

$$\mathbf{u} = (\mathbf{I} - \mathbf{G})\mathbf{x}$$



(d) Inverted.

$$\begin{cases} u_1 = x_1 \\ u_2 = x_2 - 2x_1 \\ u_3 = x_3 - 3x_2 \end{cases}$$

