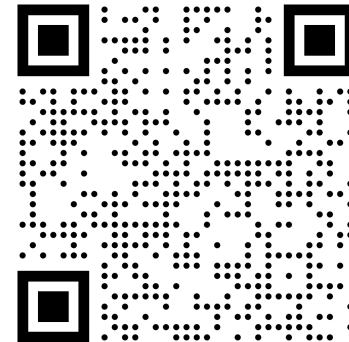




Model based inference of synaptic plasticity rules

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James Fitzgerald*, Jan Funke*

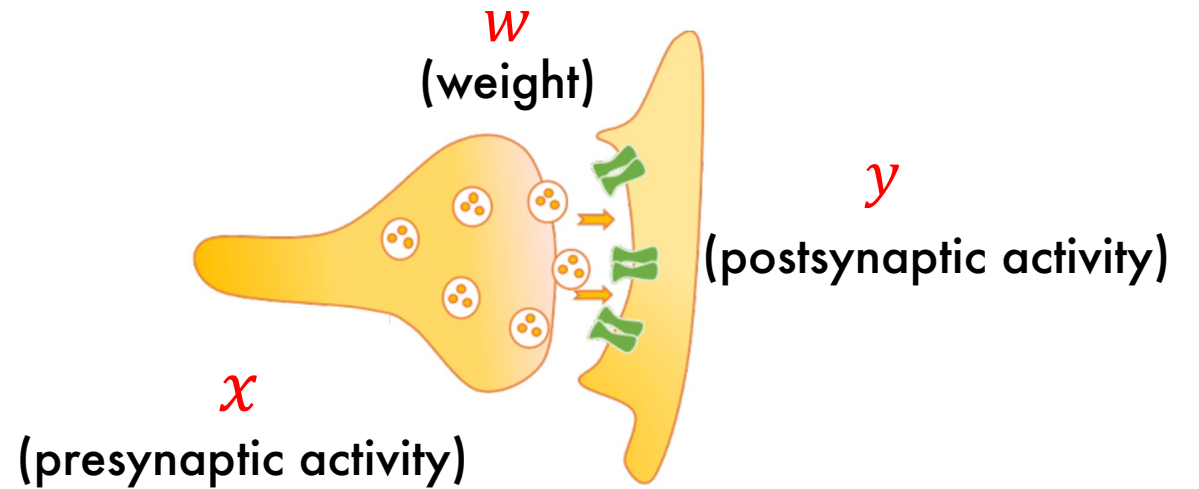


Paper Website



Standard forms of synaptic plasticity

	Δw
Hebbian.....	xy
Anti-Hebbian	$-xy$
Oja's	$xy - y^2w$
Dopamine-based?.....	xr



$$\Delta w = g_{\theta}(x, y, w, r) = ?$$




$$g_{\theta}^{\text{Taylor}} = \sum_{\alpha, \beta, \gamma=0}^2 \theta_{\alpha, \beta, \gamma} x_i^{\alpha} y_j^{\beta} w_{ij}^{\gamma}.$$

Note,

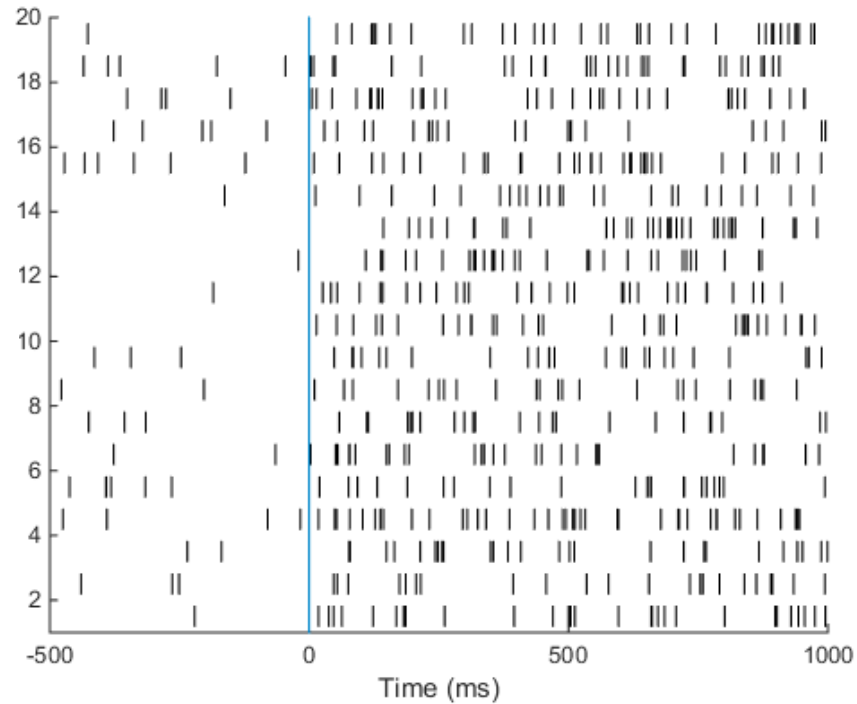
Hebbian.....	xy	$\theta_{110} = 1,$	$\theta_{rest} = 0$
Anti-Hebbian	$-xy$	$\theta_{110} = -1,$	$\theta_{rest} = 0$
Oja's	$xy - y^2w$	$\theta_{110} = 1,$	$\theta_{021} = -1, \quad \theta_{rest} = 0$



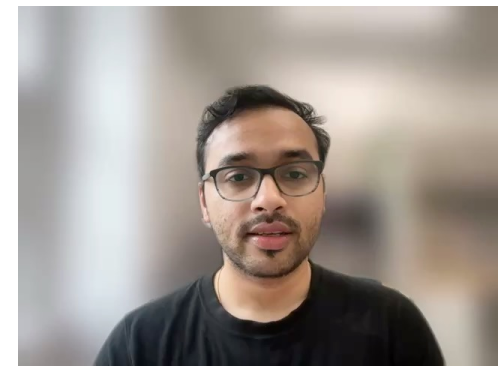
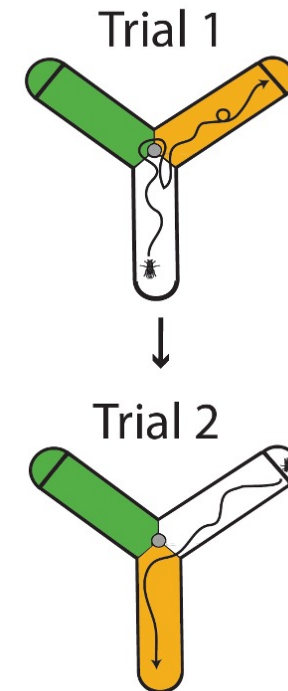
 We can't directly measure the changes in synaptic weights during learning!

Obtainable measurements:

A. Neural activity

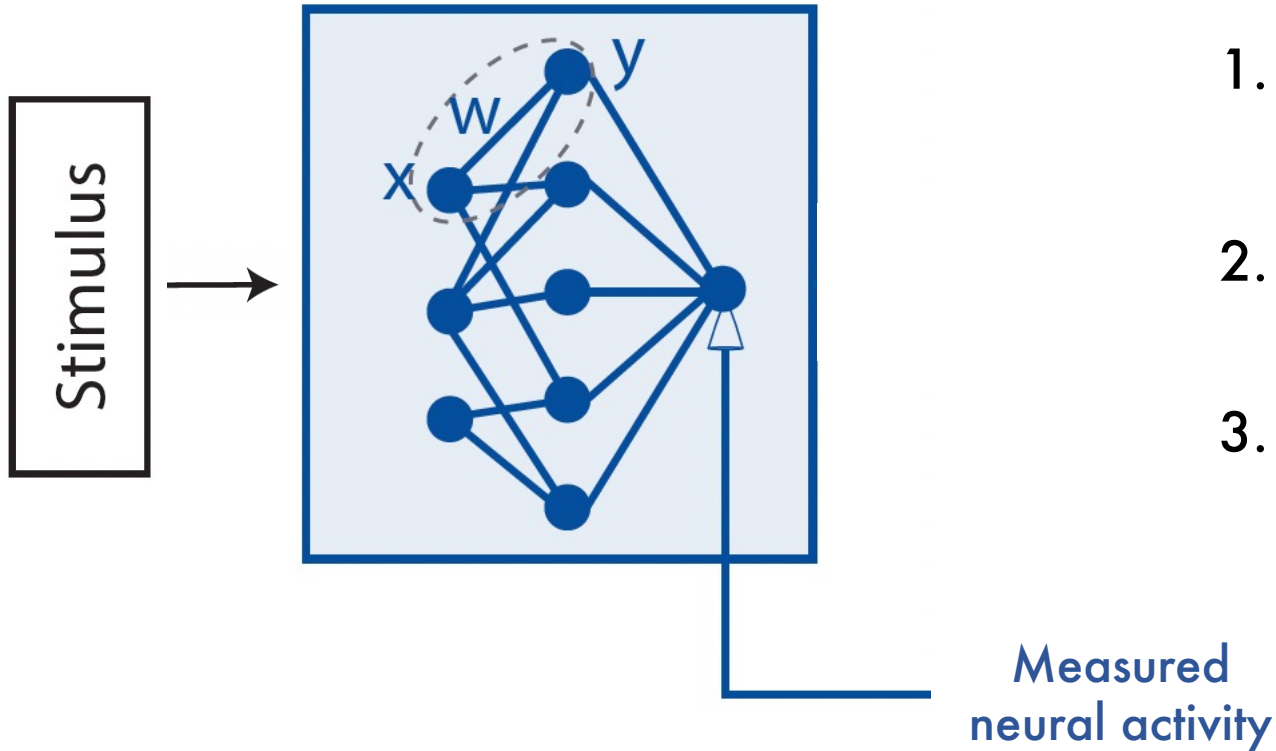


B. Behavior



Model (plasticity from neural activity)

$$\Delta w_{ij} = g_{\theta}(x_j, y_i, w_{ij}, r_j)$$

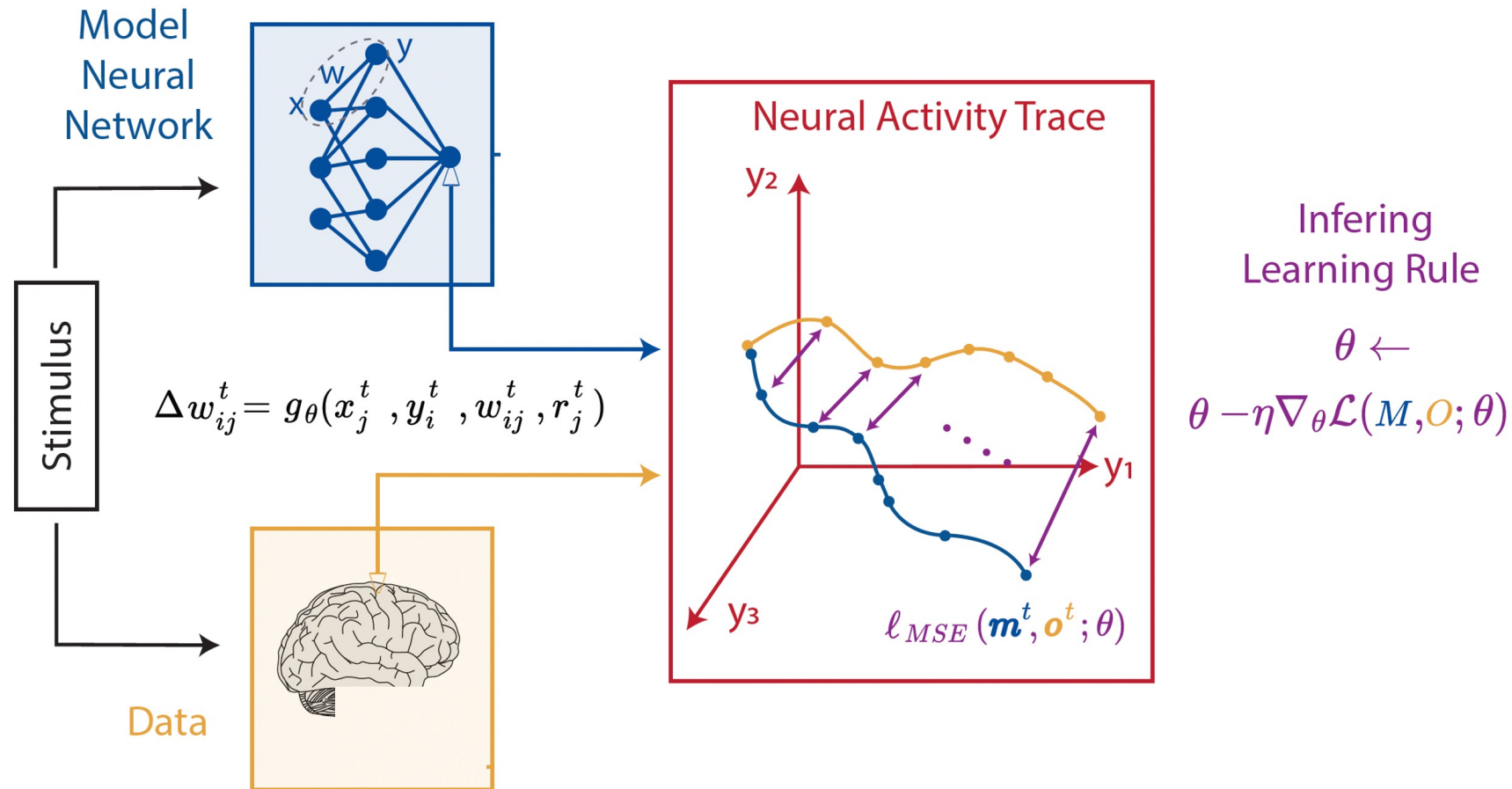


Assumptions

1. Single layer of feed forward neural network with plasticity
2. All weights evolve according to same plasticity rule, g_{θ}
3. Plasticity (g_{θ}) depends only on state (x, y, w, r) of the current time step

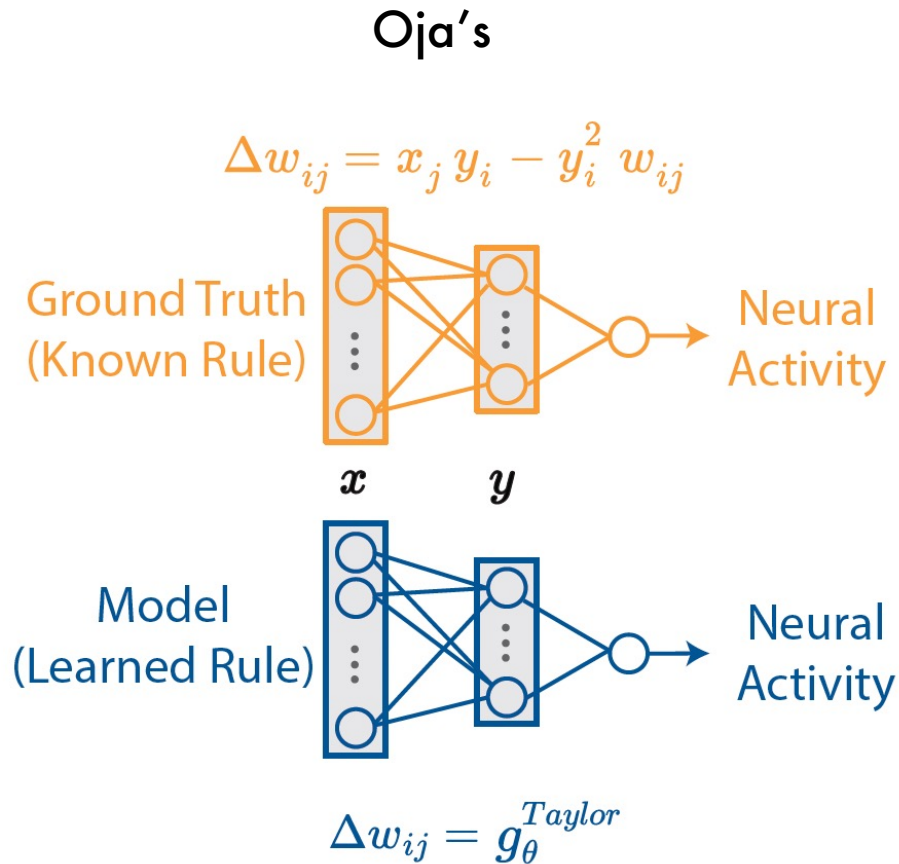


Method overview (neural activity)

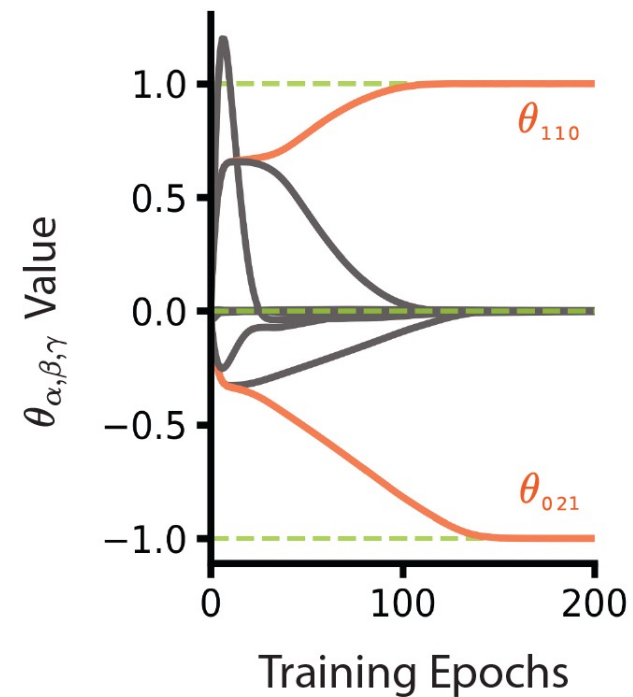


Method validation: simulated data

💡 Generate a trajectory with a known plasticity rule, then try to infer it.



$$xy - y^2 w$$
$$\theta_{110} = 1, \quad \theta_{021} = -1, \quad \theta_{rest} = 0$$

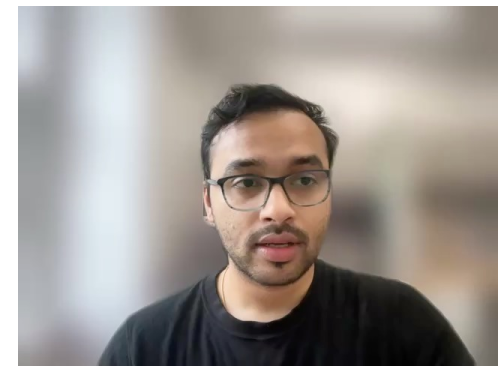
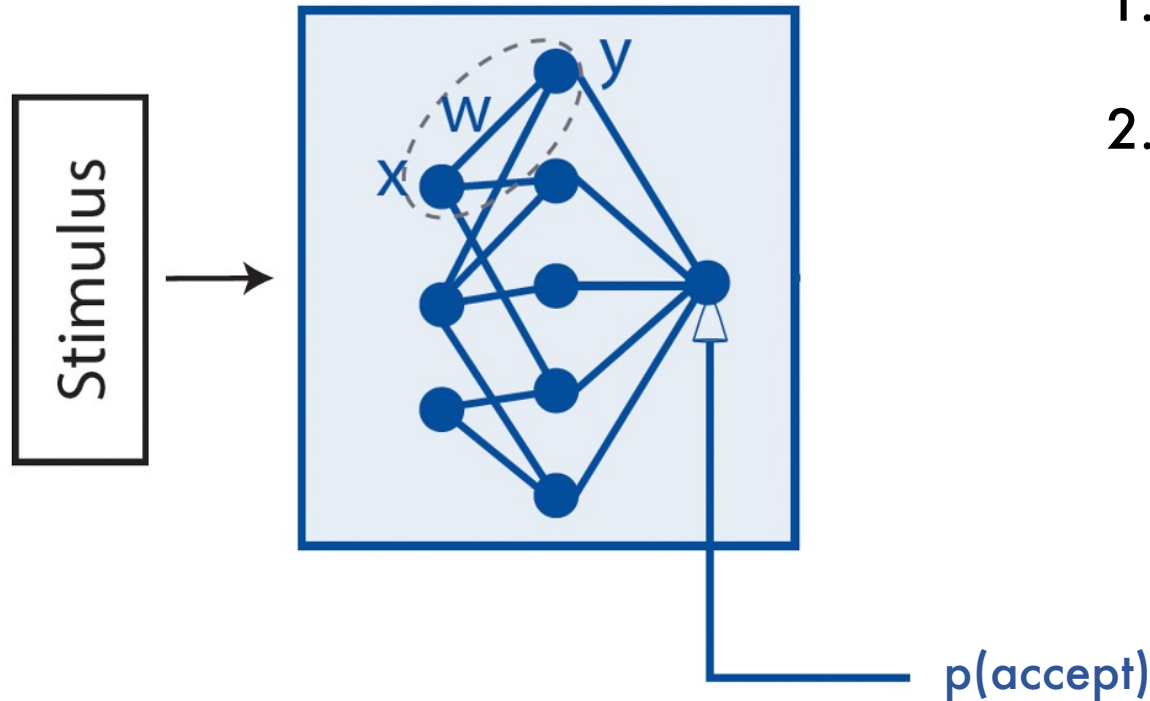


Model (plasticity from behavior)

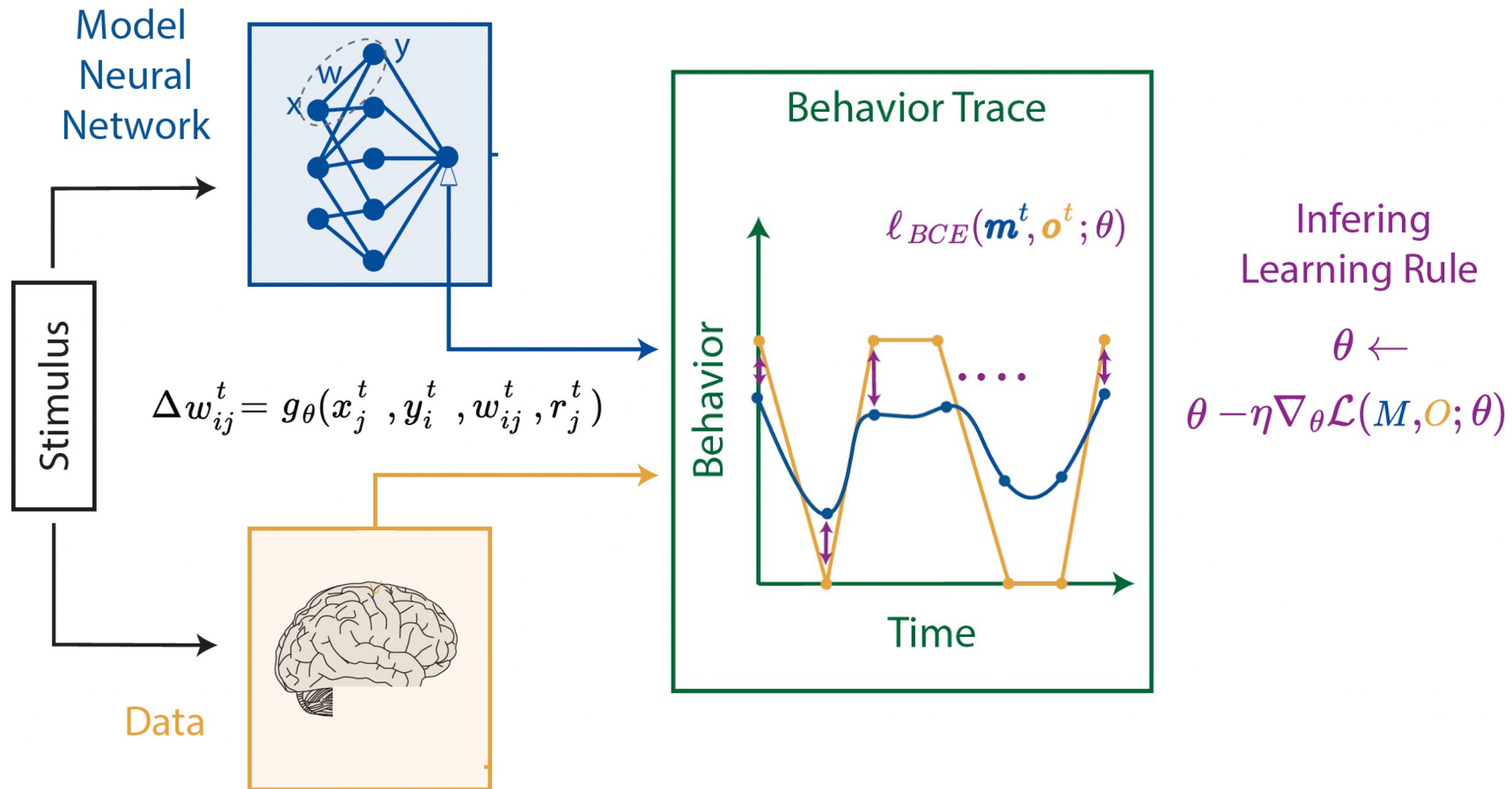
$$\Delta w_{ij} = g_{\theta}(x_j, y_i, w_{ij}, r_j)$$

Assumptions

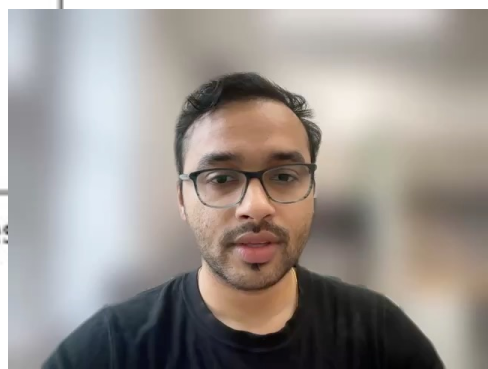
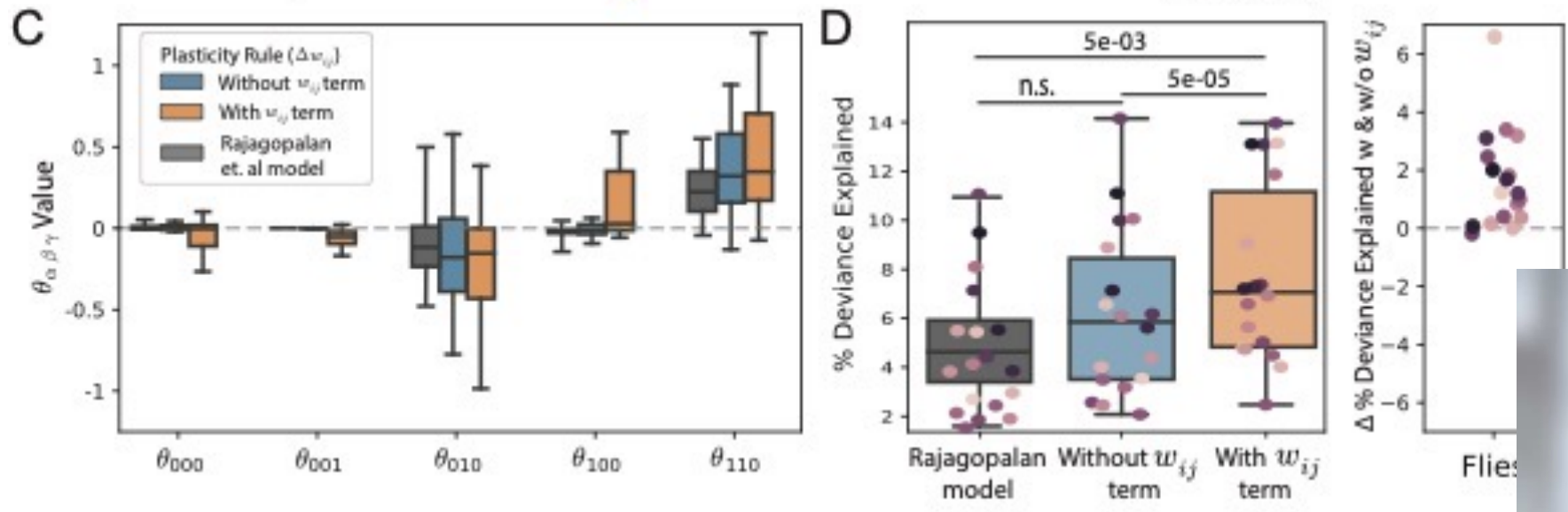
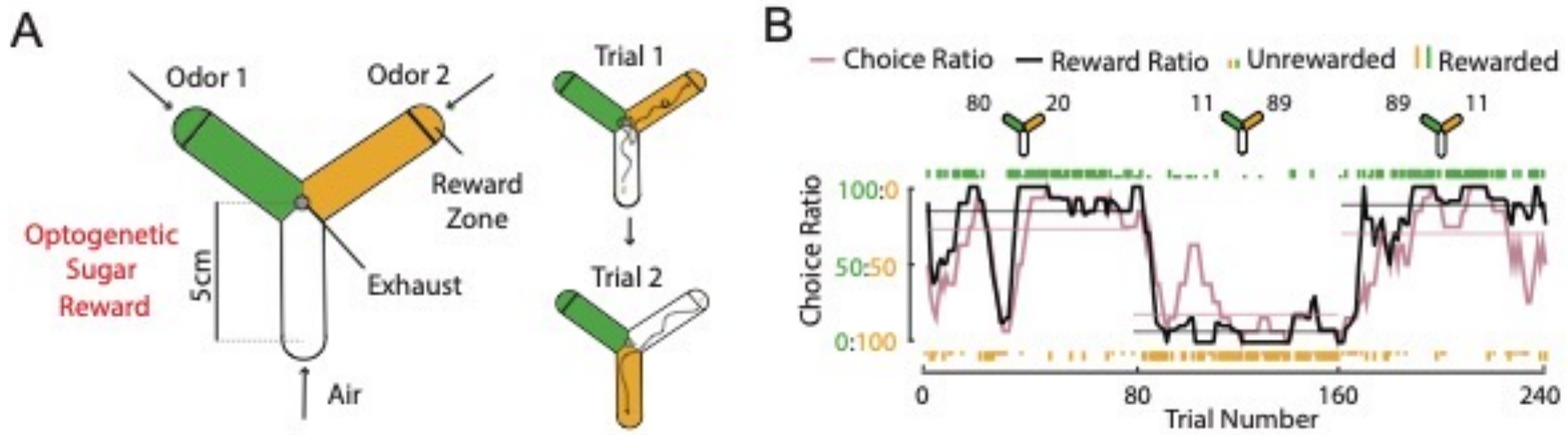
1. Behavior: accept, reject decisions.
Given by network output
2. Plasticity happens in the first layer, last layer is fixed (averages neural activity)



Method overview (behavior)



Fly experimental setup





Yash Mehta,
Cognitive Science PhD student,
Johns Hopkins



Paper Website



GitHub Repo

