## **Model:** *Linear Transformer*

● Linear Transformer updates each layer using

 $\left(\begin{array}{c} x_{j+1}^{l+1} \ y_{j}^{l+1} \end{array}\right) := \sum_{k=1}^{h}\left|P_{k}^{l}\sum_{j=1}^{n}\left(\left(\begin{array}{c} x_{j}^{l} \ y_{j}^{l} \end{array}\right) ((x_{j}^{l})^{\top},y_{j}^{l})\right)Q_{k}^{l}\right| \ .$ 

- Each token  $e_i = (x_i, y_i) \in \mathbb{R}^{d+1}$  consists of a feature vector  $x_i \in \mathbb{R}^d$  , and its corresponding output  $y_i \in \mathbb{R}$ .
- We append a query token  $e_{n+1} = (x_t, 0)$ to the sequence, where  $x_t$  represents test data.
- The goal of in-context learning is to predict  $y_t$  for the test data  $x_t$  .



# Linear Transformers are Versatile In-Context Learners



# Key Findings



- Linear transformers can learn to solve challenging problems, like linear regression with varying levels of noise.
- **Fig.** They discover effective optimization strategies that outperform standard methods.
- **Q** These strategies include adjusting step sizes based on noise levels and rescaling the solution.

We also consider problems where the noise variance  $\sigma_{\tau}$  is sampled from a given distribution  $p(\sigma_{\tau}).$ 



$$
L(\theta) = \mathop{\mathbb{E}}_{\substack{w_{\tau} \sim N(0,I) \\ x_i \sim N(0,I) \\ \xi_i \sim N(0,\sigma_{\tau}^2)}} \left[ (y_{\theta}(\{e_1,...,e_n\},e_{n+1}) - y_t) \right]
$$

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Transformers have the potential to automatically discover new and effective algorithms for S various machine learning tasks.

- $\bullet$   $w_{xy}^l$ : how much  $y_i^l$  influences  $x_i^{l+1}$ . ○ *Adapting the step-sizes* based on the noise.
- $\bullet \;\; w_{uu}^l$ : how much  $y_i^l$  influences  $y_i^{l+1}$ . ○ *Adaptive rescaling* based on the noise.

# **Experiments**

- **Full**. Trains full parameter matrices.
- **Diag**. Trains diagonal parameter matrices
- **GD++**. An even more restricted diagonal variant that uses only  $w_{yx}^l$  and  $w_{xx}^l$  terms.









 $t\rangle.$ 

**NEURAL INFORMATION** PROCESSING SYSTEMS

#### **Problem:** *Noisy regression*  Diagonal attention matrices

- For each input sequence  $\tau$  the input is given by: • A ground-truth weight vector  $w_{\tau} \sim N(0, I)$ . We also analysed even simpler variant of linear transformer with diagonal attention matrices. Since the elements  $x$  are permutation invariant, a
- $\bullet$  *n* input data points  $x_i \sim N(0,I)$ .
- Noise  $\xi_i \sim N(0, \sigma_\tau^2)$  sampled with variance  $\sigma_{\tau} \sim p(\sigma_{\tau}).$
- Labels  $y_i = \langle w_\tau, x_i \rangle + \xi_i$ .

For a *known* noise level  $\sigma_{\tau}$ , the best estimator for  $w_{\tau}$  is provided by ridge regression:

$$
L_{\rm RR}(w) = \sum_{i=1}^n \left(y_i - \langle w, x_i \rangle\right)^2 + \sigma_{\tau}^2 \|u\|
$$

Linear transformers are restricted to maintaining a linear regression model based on the input:

**Theorem 4.1.** Suppose the output of a linear transformer at l-th layer is  $(x_1^l, y_1^l), (x_2^l, y_2^l), ..., (x_n^l, y_n^l), (x_t^l, y_t^l)$ , then there exists matrices  $M^l$ , vectors  $u^l$ ,  $w^l$  and scalars  $a^l$  such that

$$
x_i^{l+1} = M^l x_i + y_i u^l, \t x_t^{l+1} = M^l x_t,
$$
  

$$
y_i^{l+1} = a^l y_i - \langle w^l, x_i \rangle, \t y_t^{l+1} = -\langle w^l, x_t \rangle
$$

# **Conclusions**

diagonal parameterization reduces each attention heads to just four parameters:

$$
P_k^l=\left(\begin{array}{cc} p_{x,k}^l I&0\\0&p_{y,k}^l\end{array}\right);\quad Q_k^l=\left(\begin{array}{cc} q_{x,k}^l I&0\\0&q_{y,k}^l\end{array}\right).
$$

Linear transformers, even though they are simple, can be a surprisingly versatile in-context learners.  $\bigotimes$  They can discover effective optimization strategies that outperform standard methods. ● **Tuned Adaptive Ridge Regression (TunedRR)**. Same as above, but after the noise is estimated, we tuned two parameters:

Using reparametrization

$$
w_{xx}^l = \sum_{k=1}^H p_{x,k}^l q_{x,k}^l, \quad w_{xy}^l = \sum_{k=1}^H p_{x,k}^l q_{y,k}^l,
$$

$$
w_{yx}^l = \sum_{k=1}^H p_{y,k}^l q_{x,k}^l, \quad w_{yy}^l = \sum_{k=1}^H p_{y,k}^l q_{y,k}^l.
$$

leads to the following diagonal layer updates:

$$
x_i^{l+1} = x_i^l + w_{xx}^l \Sigma^l x_i^l + w_{xy}^l y_i^l \alpha^l
$$
  

$$
y_i^{l+1} = y_i^l + w_{yx}^l \langle \alpha^l, x_i^l \rangle + w_{yy}^l y_i^l \lambda^l,
$$

Each term controls a specific aspect of the updates:

- $\bullet \;\; w_{yx}^l$ : how much  $x_i^l$  influences  $y_i^{l+1}$ . ○ Controls the *gradient descent*.
- $\bullet$   $w_{xx}^l$ : how much  $x_i^l$  influences  $x_i^{l+1}$ .

○ Controls the *preconditioner* strength.

Linear Transformer-based methods:

Baselines:

- **Constant Ridge Regression (ConstRR)**. The noise variance is estimated using a single scalar value for all the sequences.
- **Adaptive Ridge Regression (AdaRR)**. Estimate the noise variance via unbiased estimator:  $\sigma_{\text{est}}^2 = \frac{1}{n-d}\sum_{j=1}^n (y_j - \hat{y}_j)^2$  , where  $\hat{y}_j$ represents the solution to the ordinary least squares.
	- a max. threshold for the estimated variance,
	- a multiplicative adj. to the noise estimator.

#### **Main Result:** Linear transformers maintain linear regression model at every layer.