

Directional Smoothness and Gradient Methods

Convergence and Adaptivity

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- We use directional smoothness to derive path-dependent sub-optimality bounds for GD.
- We prove that the Polyak step-size and Normalized GD match the fast rates of GD with strongly adapted step-sizes.

Background on L-Smoothness

Setting: minimize a convex, differentiable function f using GD:

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- To hold globally, the Lipschitz constant must reflect the **worst-case** growth of f ,

$$L = \sup_{x,y} \frac{\|\nabla f(x) - \nabla f(y)\|_2}{\|x - y\|_2}.$$

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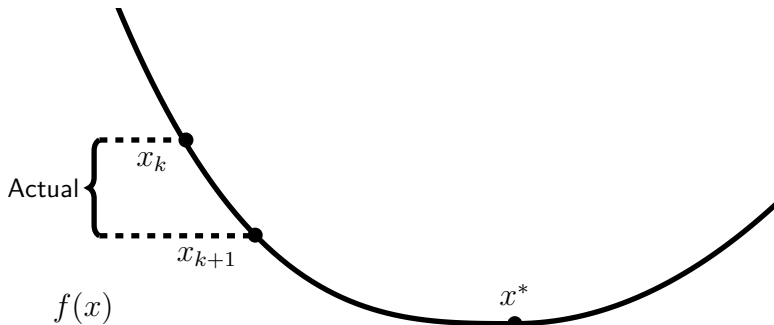
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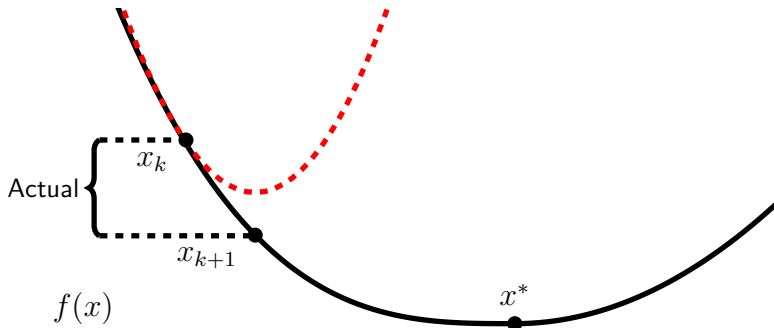


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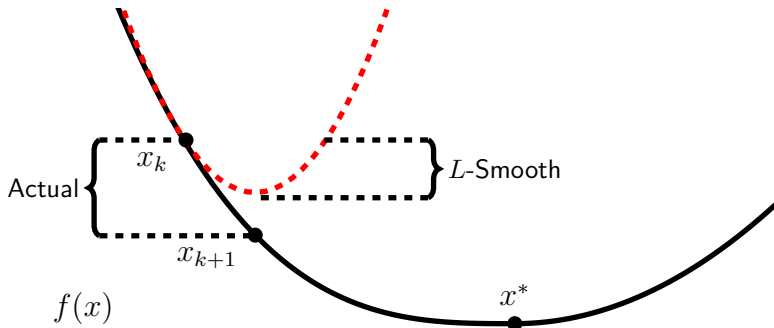


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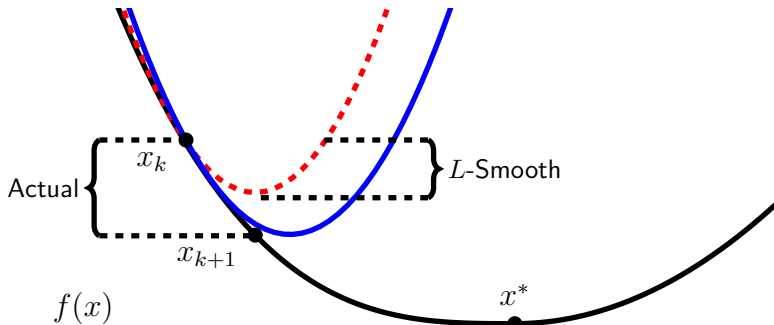


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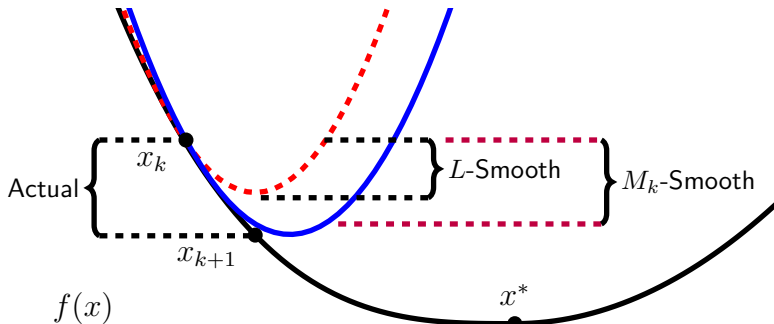


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- **Exact Smoothness:**

$$H(y, x) = \frac{2(f(y) - f(x) - \langle \nabla f(x), y - x \rangle)}{\|y - x\|_2}.$$

Path-Dependent Convergence Rates

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- If $\eta_k = 1/M(x_{k+1}(\eta_k), x_k)$ is strongly adapted, then we get **path-dependent** rates:

$$\min_{k \in [K]} f(x_k) - f(x^*) \leq \left[\frac{\sum_{i=0}^K M_i}{K+1} \right] \frac{\|x_0 - x^*\|_2^2}{K+1}$$

Strongly Adapted Step-Sizes

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Does any method obtain match the strongly-adapted rate without knowing M ?

The Polyak Step-Size

Polyak Step-size: assuming knowledge of $f(x^*)$, set $\gamma \geq 1$ and

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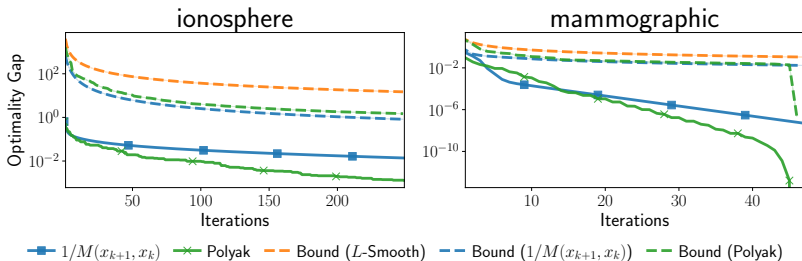
$$\min_{k \in [K]} f(x_k) - f(x^*) \leq \frac{3 \|x_0 - x^*\|_2^2}{K} \left[\frac{\sum_{i=0}^{K-1} M(x_{i+1}, x_i)}{K} \right],$$

Directional Smoothness: Tighter Rates in Practice

How does this **path-dependent** theory compare to standard **L -smooth** rates?

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Learn more at our poster!

Thursday Dec. 12 at 4:30 p.m



References I
