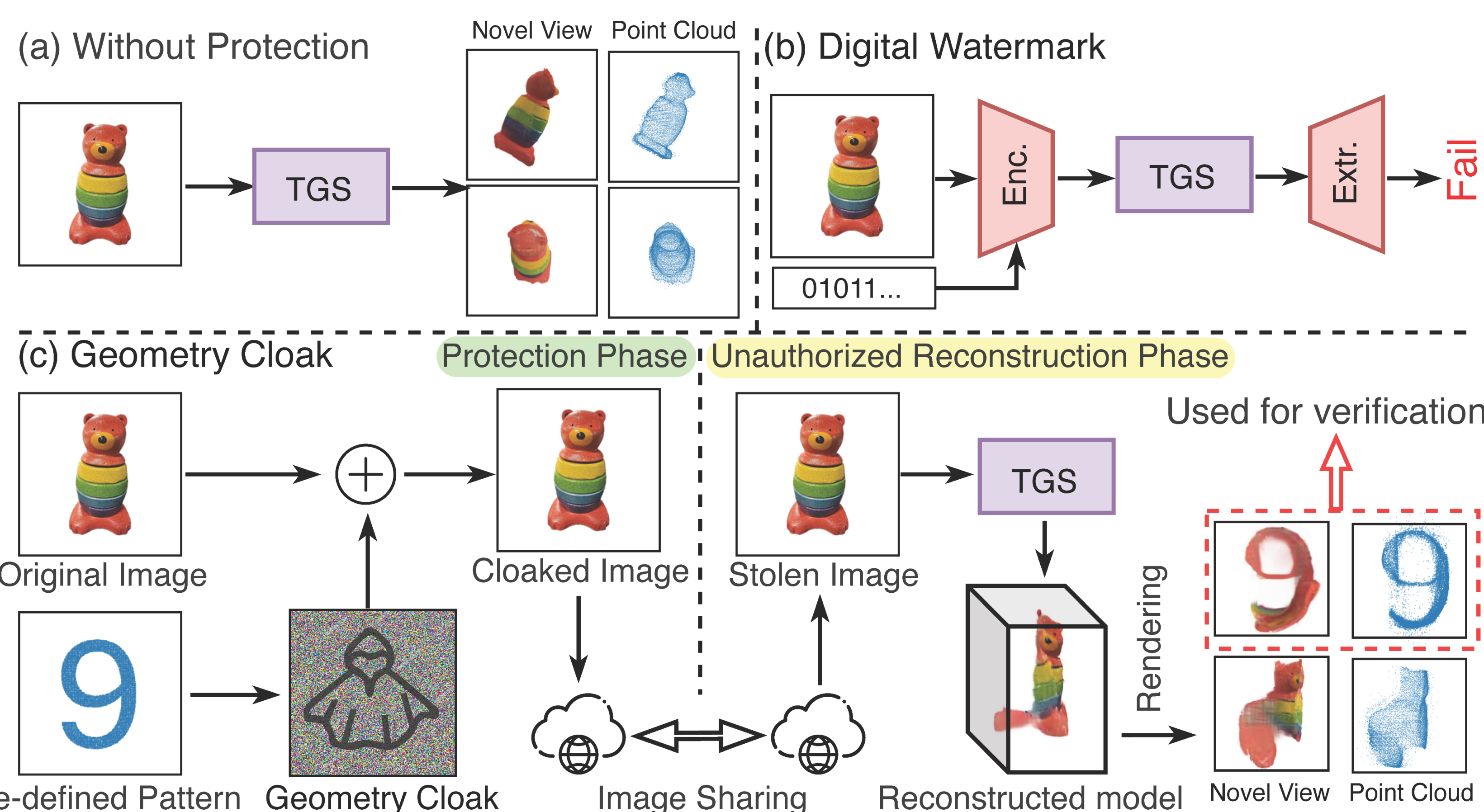


Two key objectives of Geometry Cloak:

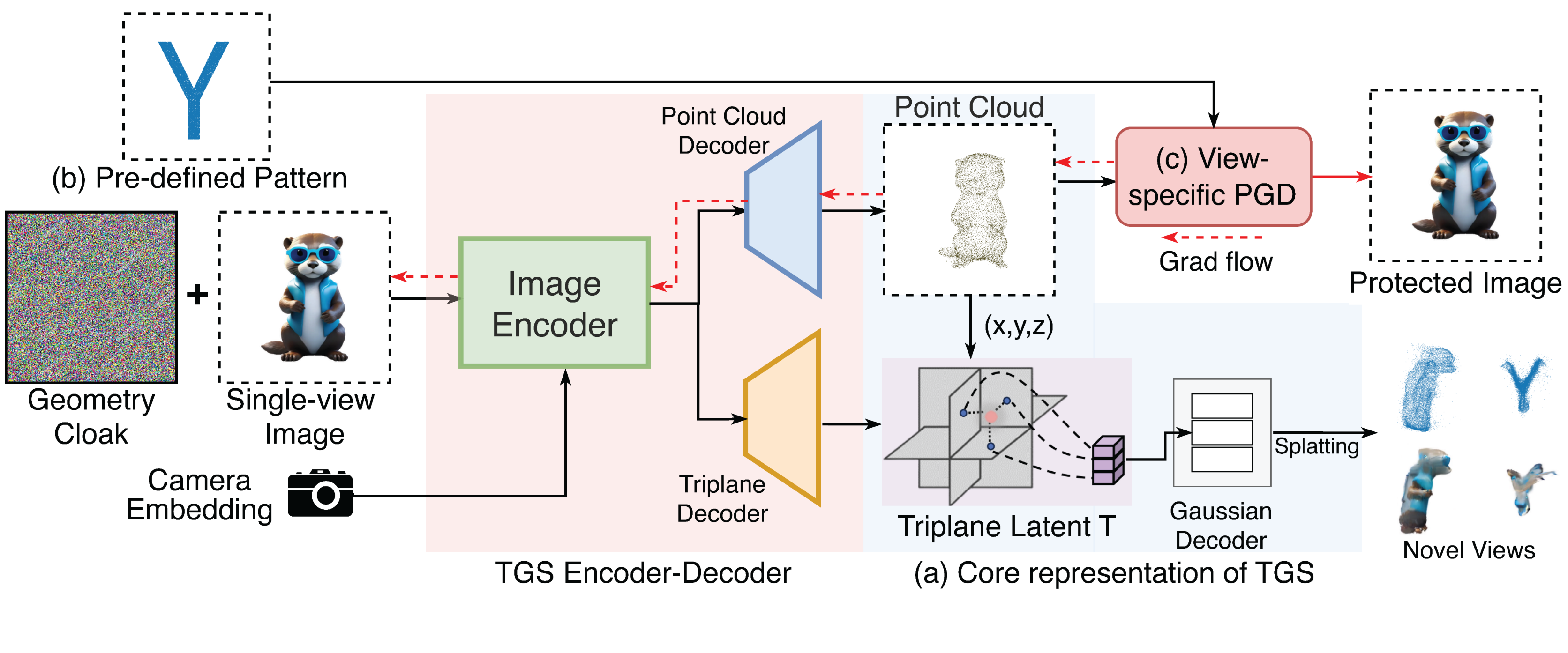
1) Comprise 3D reconstructed result

2) Reveal distinguishable patterns

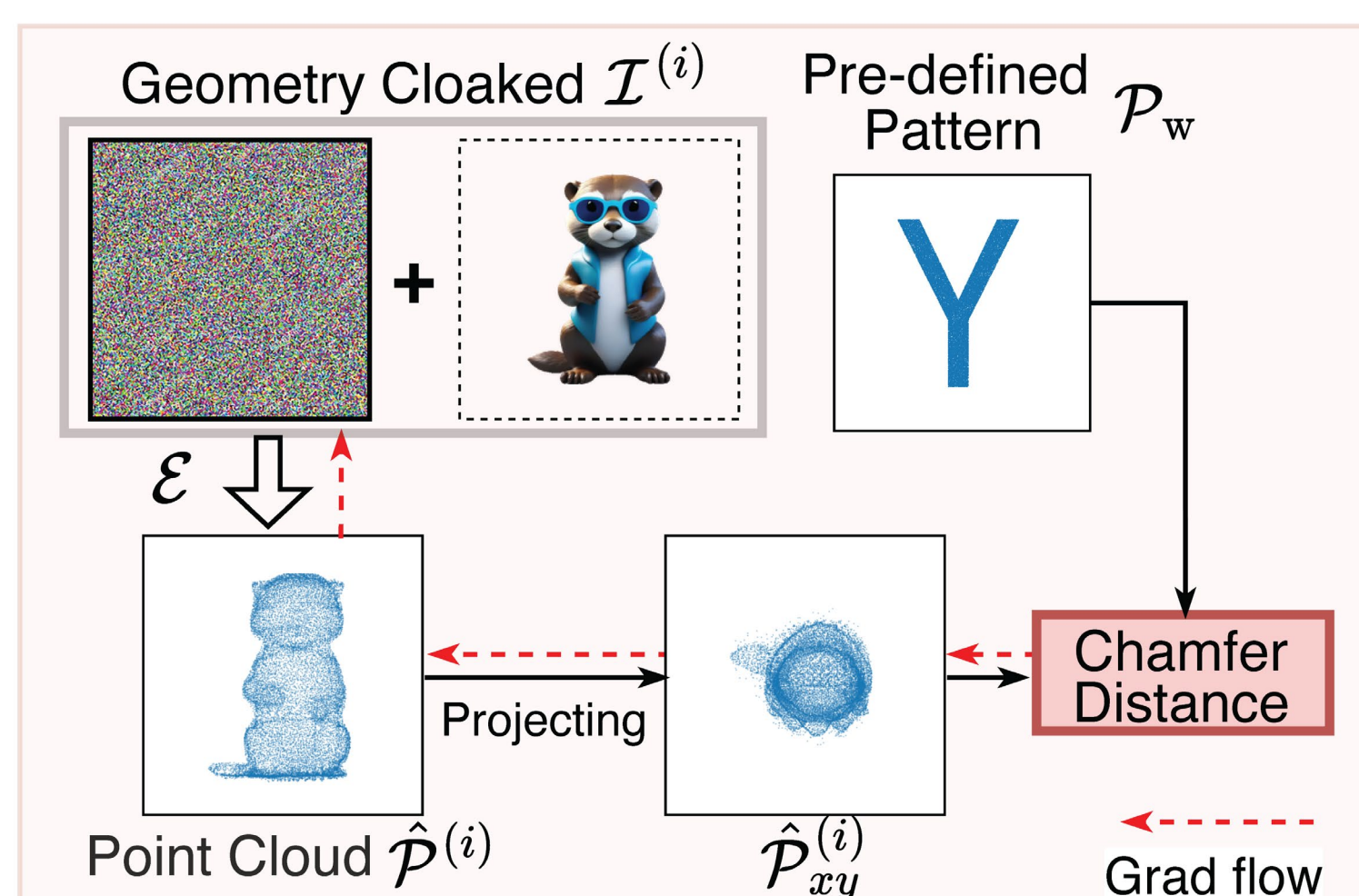
Overview of our scenario



Overview of our framework



View-specific PGD



Input: Input image \mathcal{I} , Point cloud encoder \mathcal{E} from TGS, pre-defined pattern \mathcal{P}_w , number of steps N , step size α , perturbation budget ϵ , viewing direction θ

Output: Geometry cloaked image $\hat{\mathcal{I}}$

Initialize geometry cloak $\delta \leftarrow 0$, and geometry cloaked image $\hat{\mathcal{I}} \leftarrow \mathcal{I}$

for $i \leftarrow 1$ to N do

$\hat{\mathcal{P}} \leftarrow \mathcal{E}(\hat{\mathcal{I}})$ // Estimate point cloud representations;

$\hat{\mathcal{P}}_\theta \leftarrow \text{Proj}_\theta(\hat{\mathcal{P}})$ // Project the point cloud at view direction θ ;

$Loss \leftarrow \mathcal{L}_{CD}(\hat{\mathcal{P}}_\theta, \mathcal{P}_w)$ // Calculate CD between two 2D point clouds;

$\delta \leftarrow \alpha \cdot \text{sgn}(\nabla_{\hat{\mathcal{I}}} Loss)$ // Update geometry cloak;

$\hat{\mathcal{I}} \leftarrow \hat{\mathcal{I}} + \delta$ // Update cloaked image;

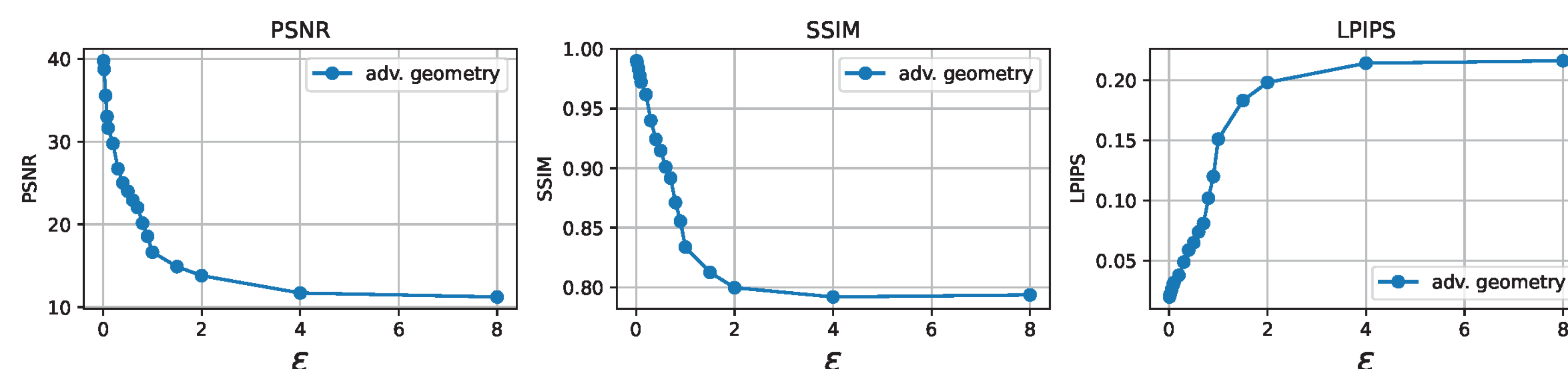
$\hat{\mathcal{I}} \leftarrow \text{clip}(\hat{\mathcal{I}}, \mathcal{I} - \epsilon, \mathcal{I} + \epsilon)$ // Clip cloaked image $\hat{\mathcal{I}}$;

end

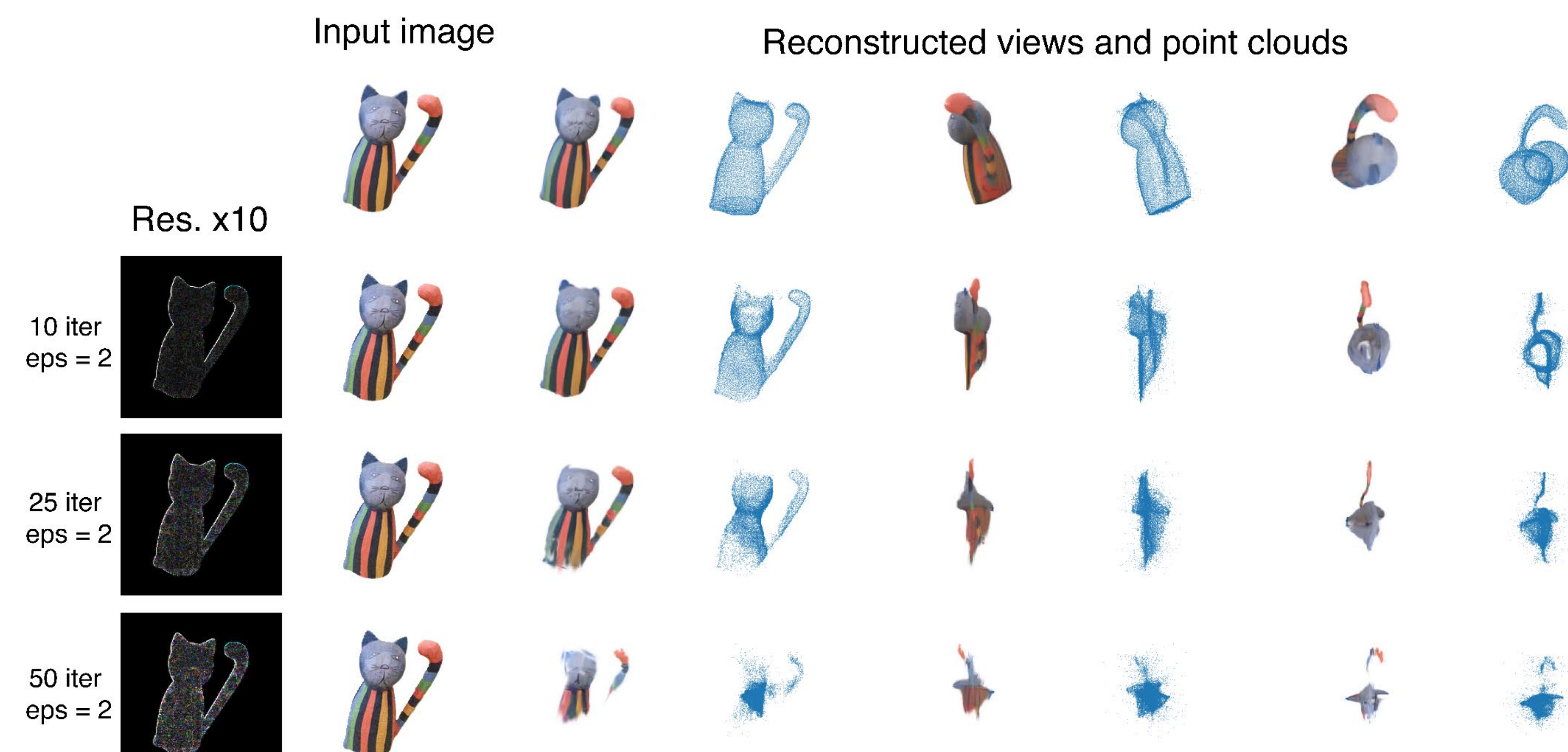
Return $\hat{\mathcal{I}}$

Results

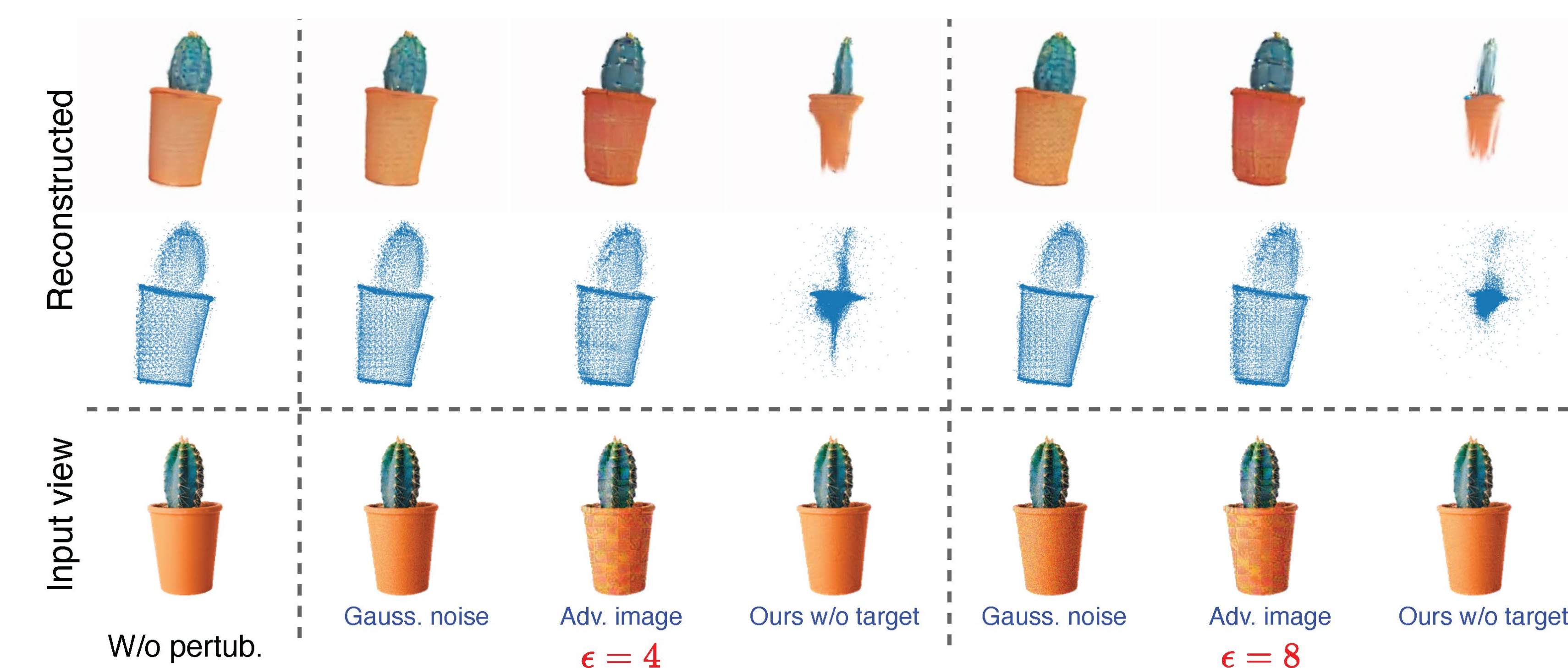
Privacy/perturbation budget



Geometry cloak w/o target



Reconstructed results with different perturbation strategy



Watermark patterns & Customized patterns

