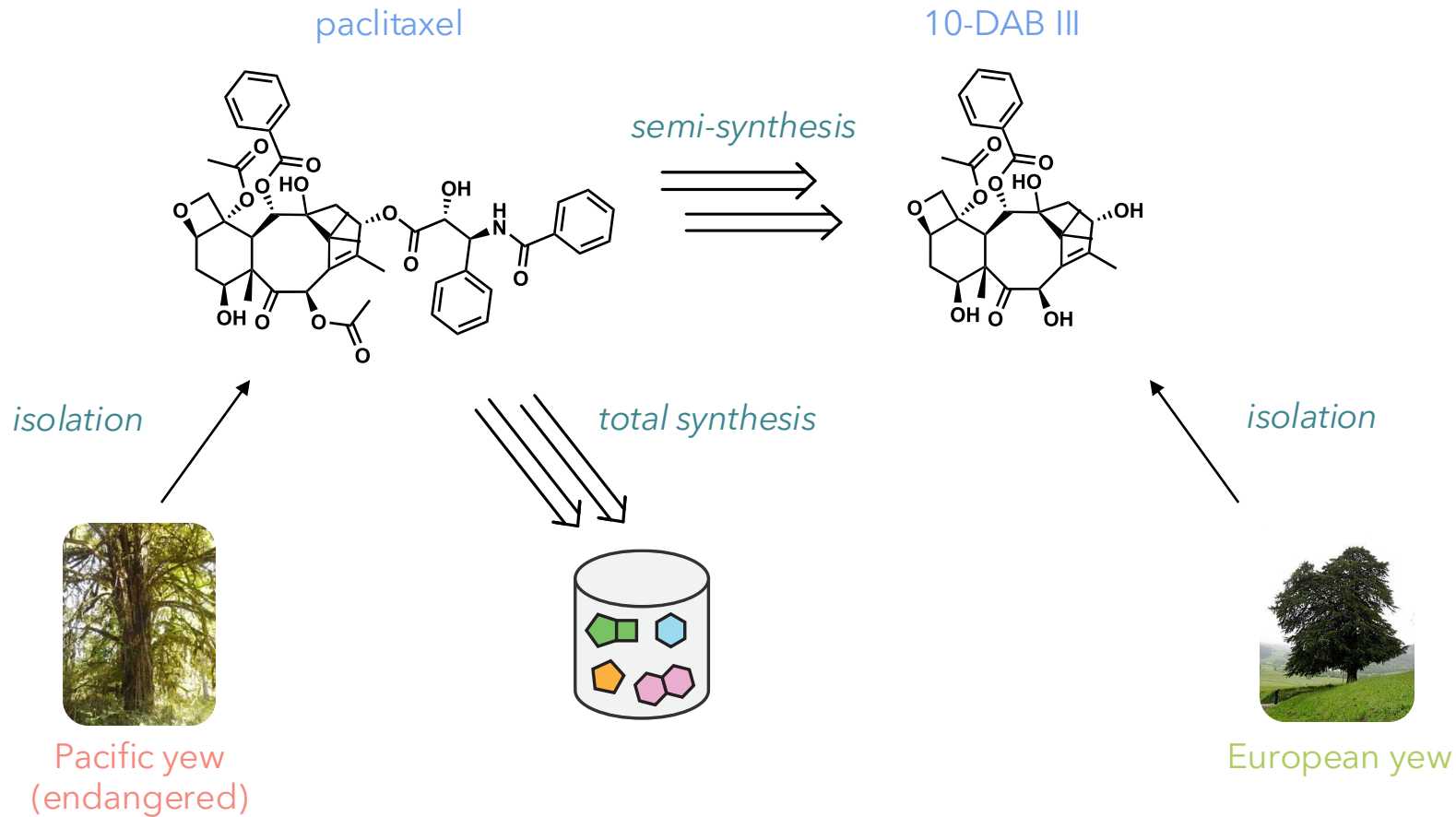


Double-Ended Synthesis Planning with Goal-Constrained Bidirectional Search

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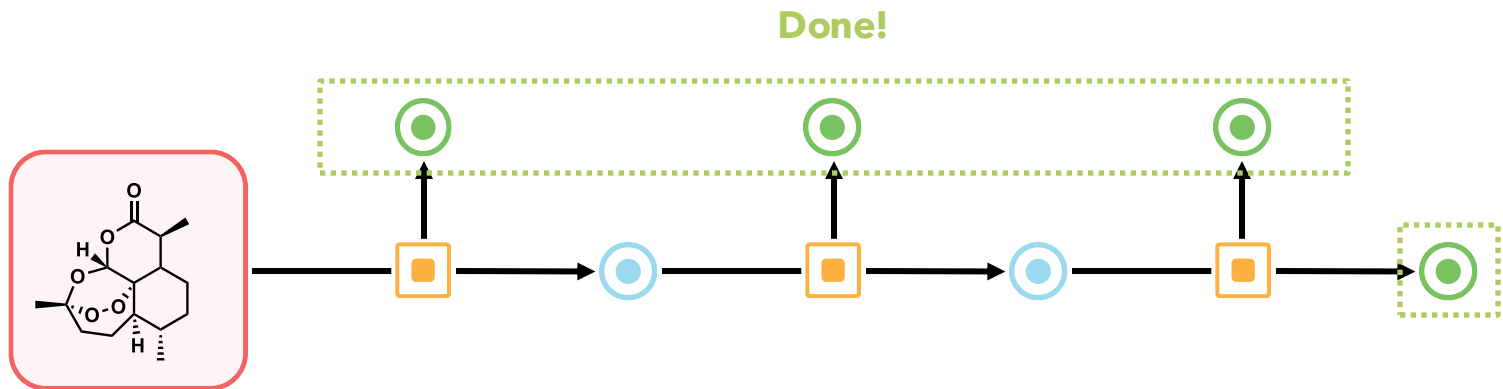
Molecules can be obtained by a variety of means



Synthesis planning problem formulation

Given: target molecule t + set of purchasable building blocks \mathcal{B} ,

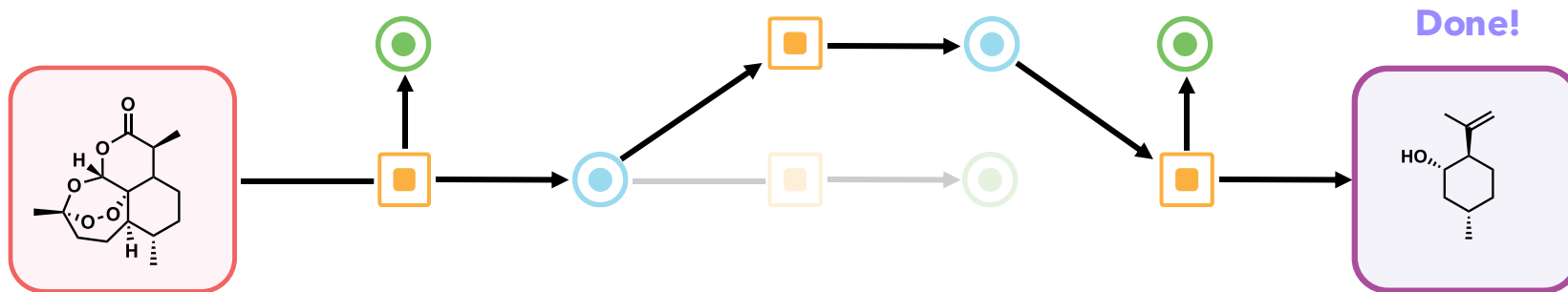
Construct: a sequence of valid chemical reactions forming a synthesis tree with root node t such that all leaf nodes are members of \mathcal{B}



The problem can be redefined to include structure goals (“starting material-constrained planning”)

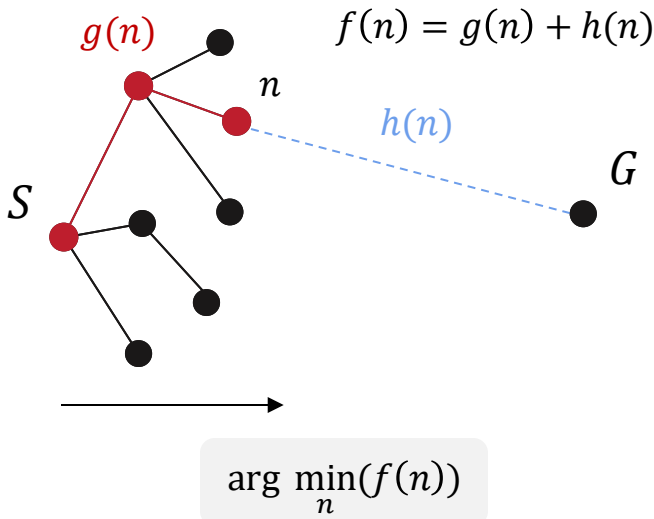
Given: target molecule t and starting material s + set of purchasable building blocks \mathcal{B} ,

Construct: a sequence of chemical reactions forming a synthesis tree with root node t such that one leaf node is s and all other leaf nodes are members of \mathcal{B}

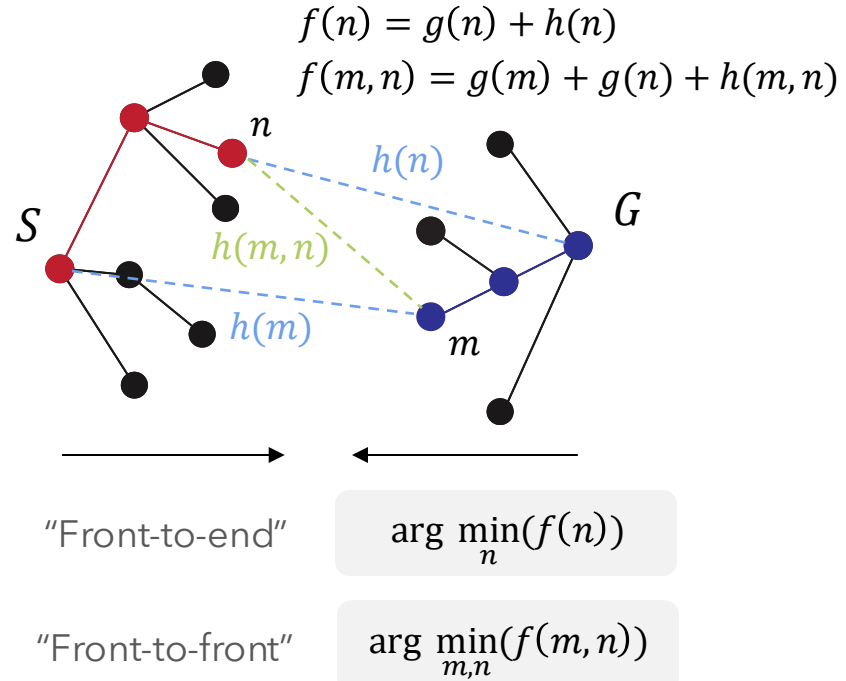


Bidirectional search algorithms are naturally suited for goal-constrained planning

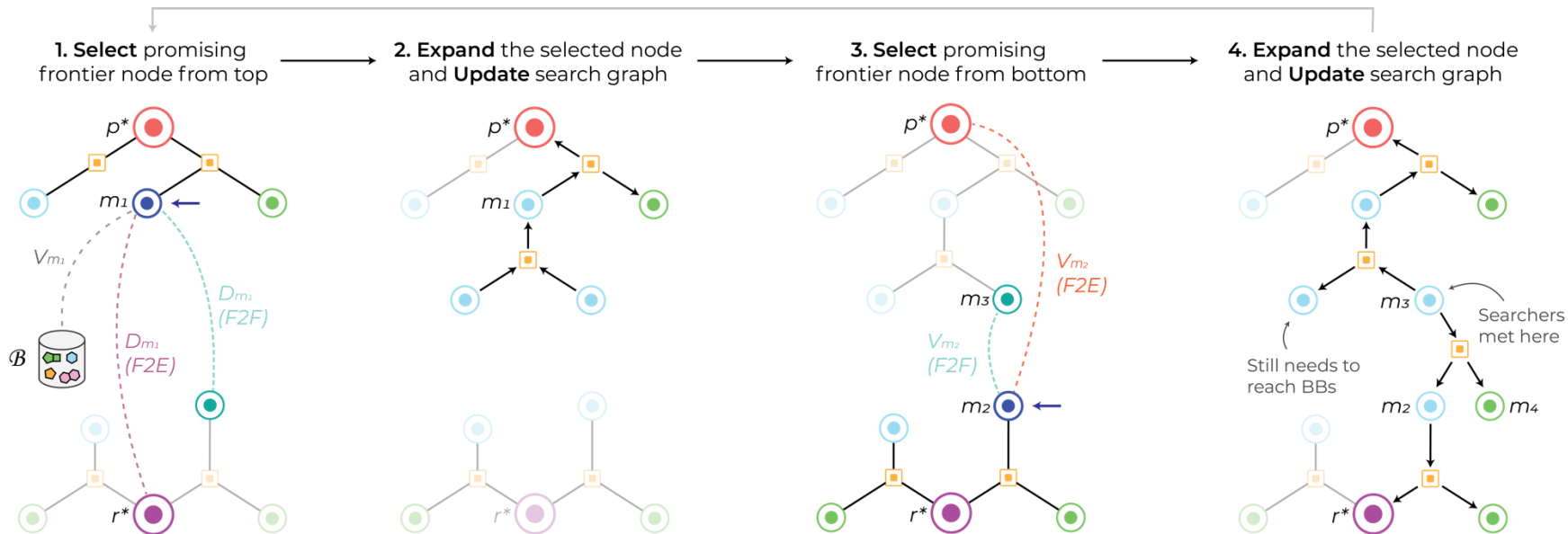
Unidirectional A* search



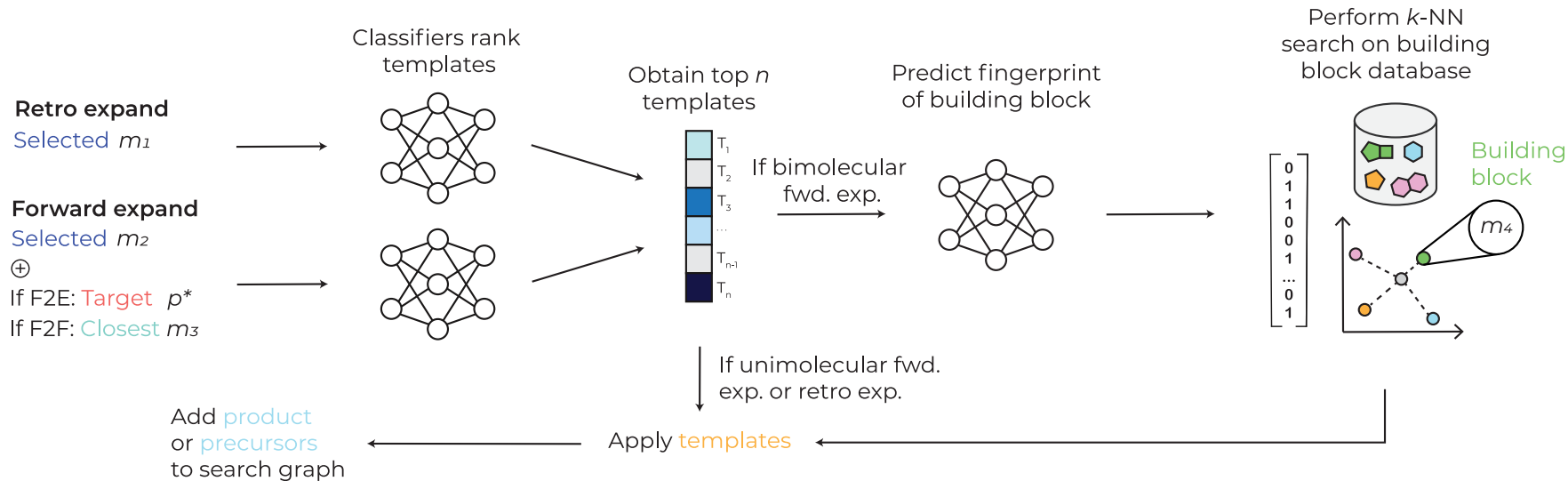
Bidirectional A* search



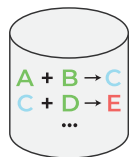
DESP (Double-ended Synthesis Planning) plans syntheses with bidirectional A*-like search



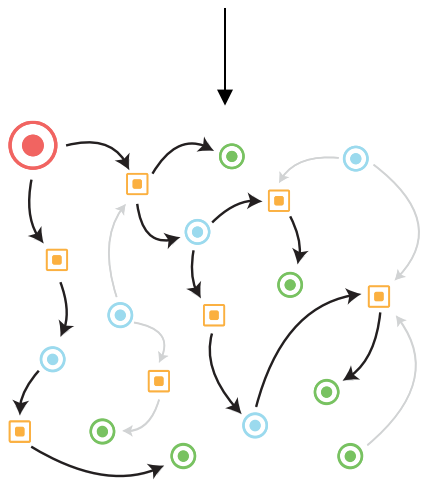
DESP utilizes a conditional forward expansion policy



Bidirectional A* cost function and forward expansion policy can be learned from extracted multi-step reaction data

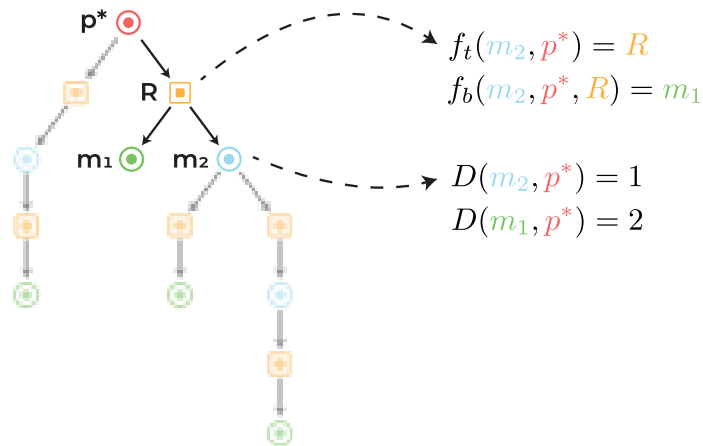


USPTO-Full
~1m reactions
from 1976-2016



Perform enumerative search on non-buyable molecules in synthesis knowledge graph

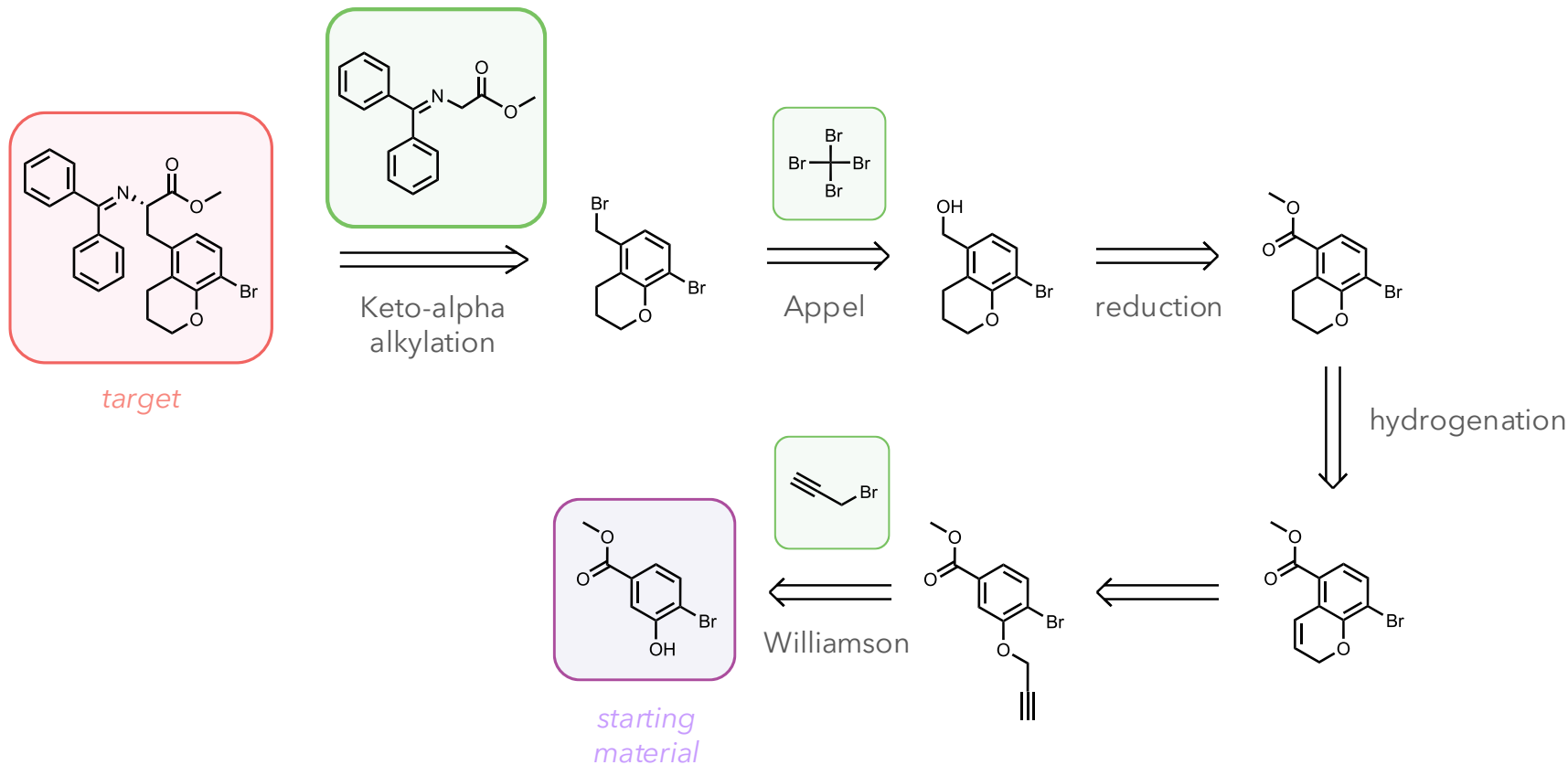
Obtain training examples for "synthetic distance" and conditional forward expansions



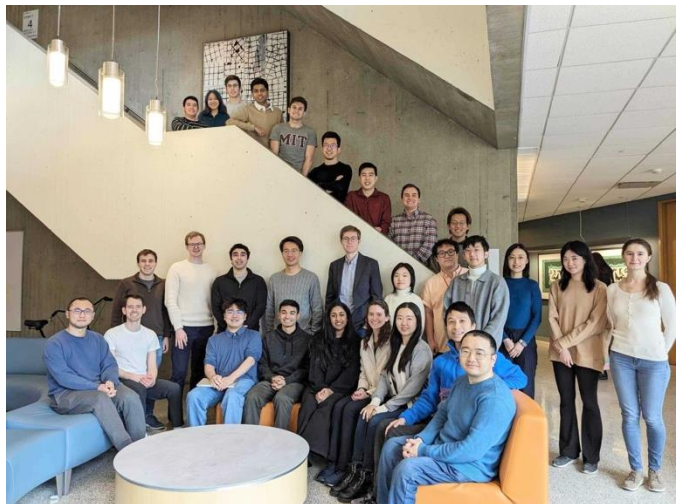
DESP outperforms baseline methods on the starting material-constrained synthesis planning task

Algorithm	USPTO-190				Pistachio Reachable				Pistachio Hard			
	Solve Rate (%) \uparrow			\bar{N} \downarrow	Solve Rate (%) \uparrow			\bar{N} \downarrow	Solve Rate (%) \uparrow			\bar{N} \downarrow
	$N=100$	300	500		50	100	300		100	300	500	
Random	4.2	4.7	4.7	479	16.0	26.7	40.7	325	6.0	12.0	13.0	452
BFS	12.1	20.0	24.2	413	48.7	57.3	74.0	169	16.0	26.0	29.0	390
MCTS	20.5	32.1	35.3	364	52.0	72.7	85.3	111	27.0	31.0	32.0	361
Retro*	25.8	33.2	35.8	351	70.7	78.0	92.7	73	32.0	35.0	37.0	342
GRASP	15.3	21.1	23.7	410	46.7	51.3	66.7	198	14.0	22.0	29.0	402
Retro*+D	27.4	32.6	37.4	348	77.3	87.3	96.0	49	31.0	40.0	42.0	323
DESP-F2E	30.0	35.3	39.5	340	84.0	90.0	96.0	41	35.0	44.0	50.0	300
DESP-F2F	29.5	34.2	39.5	336	84.5	88.9	97.3	38	39.0	45.0	48.0	293

DESP can find routes for targets where single-ended search cannot



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