

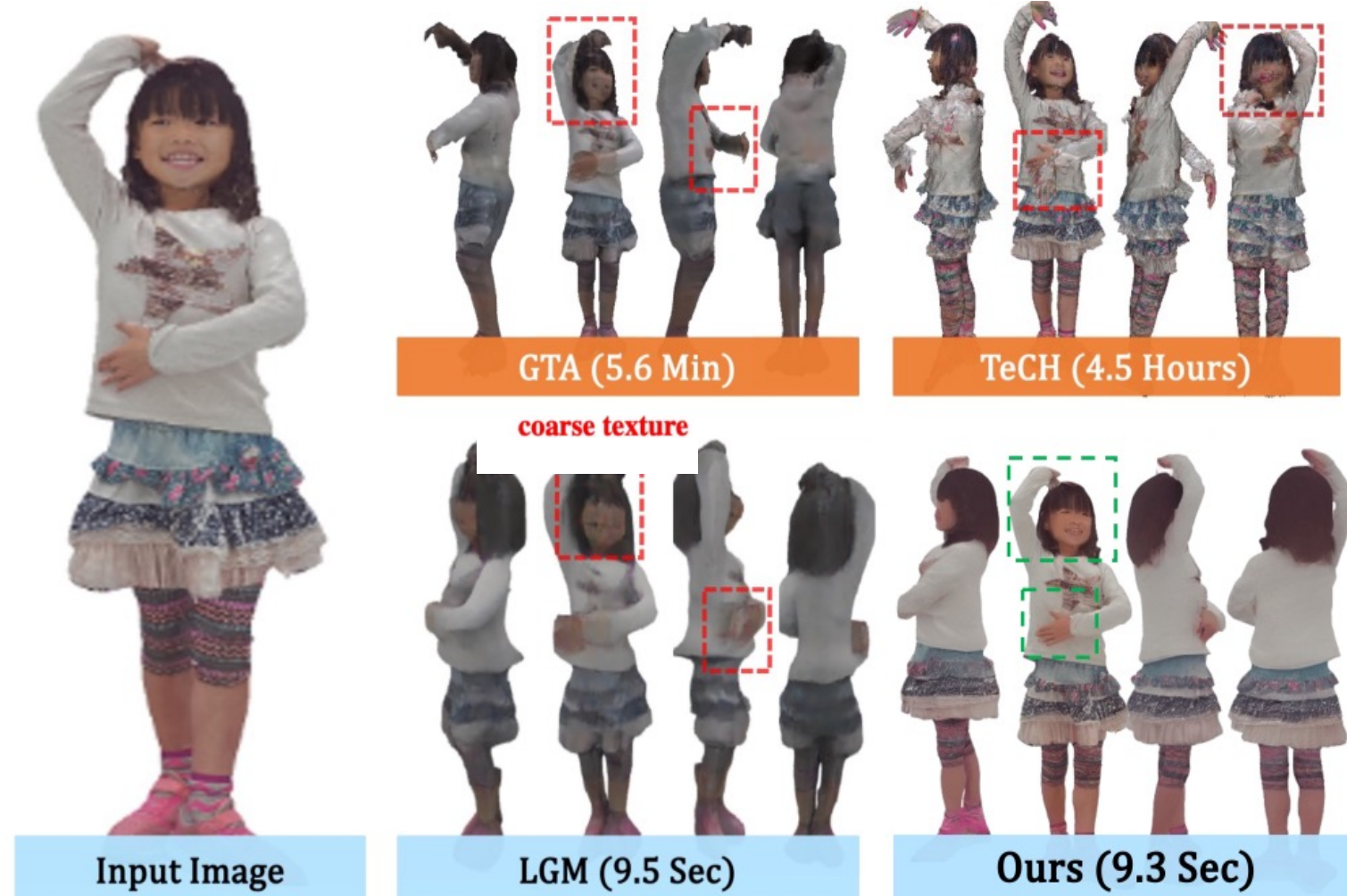
HumanSplat: Generalizable Single-Image Human Gaussian Splatting with Structure Priors

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Motivation



The Drawbacks of Related Works:

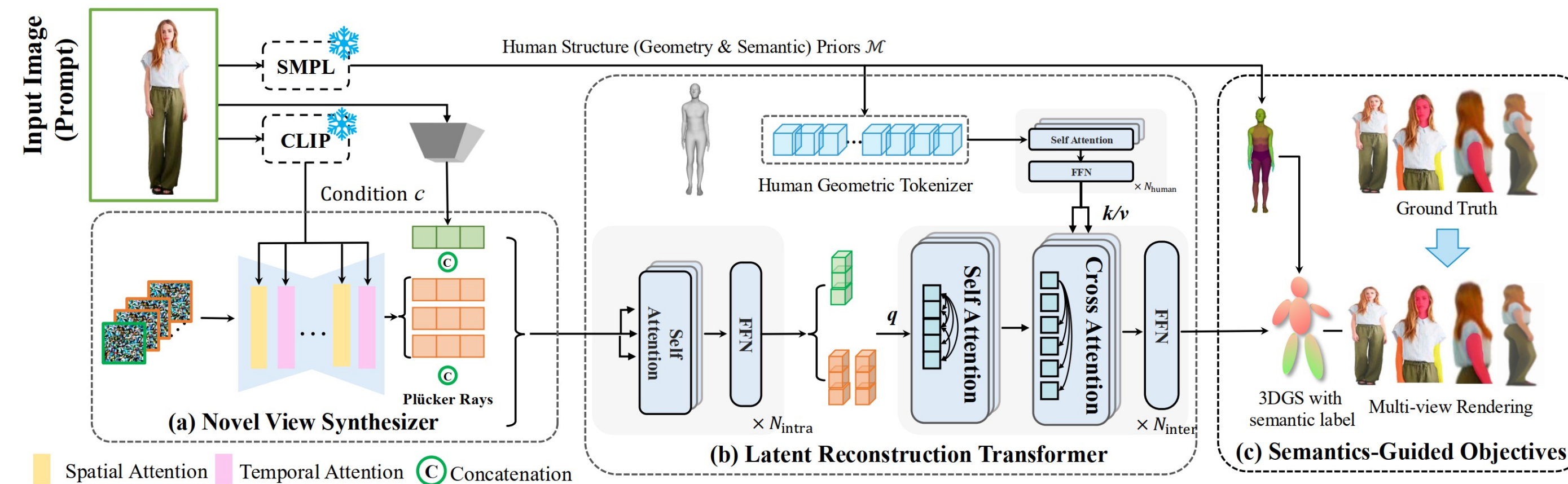
- ❖ Lack human priors as inductive biases.
- ❖ The requirements for dense input images.
- ❖ Time-consuming per-instance optimization.

Contribution

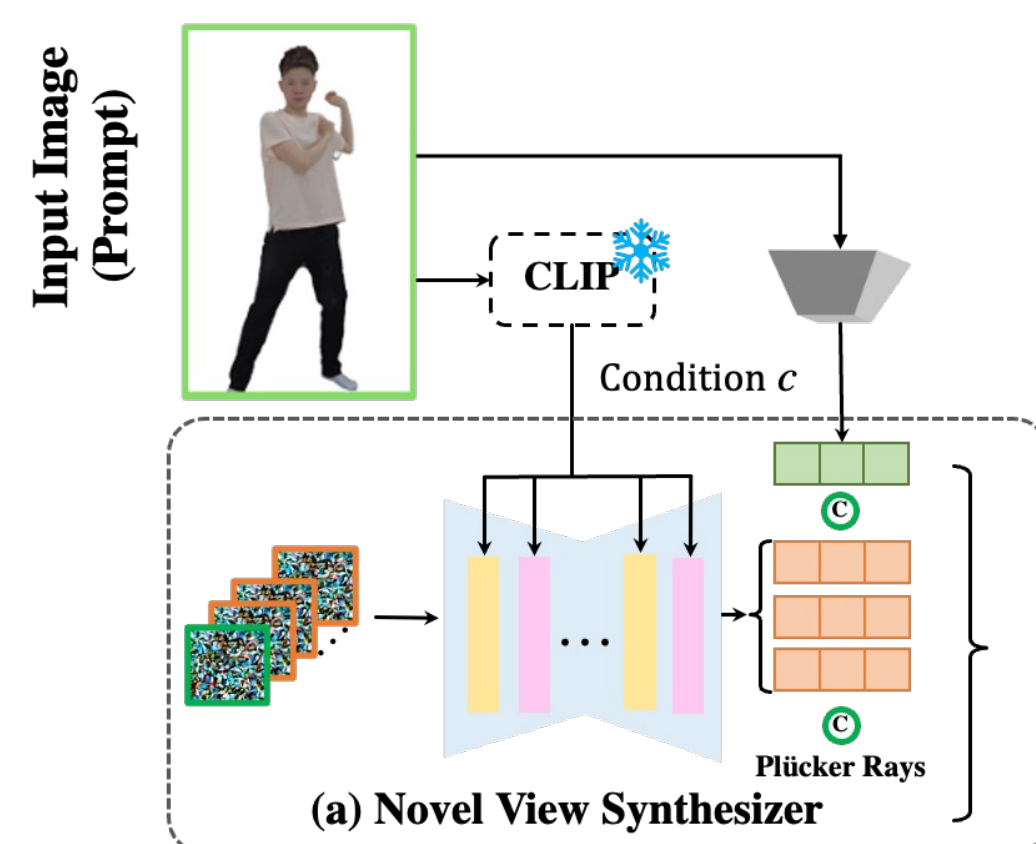
- ❖ It is the first work to propose a novel generalizable human Gaussian Splatting network for high-fidelity human reconstruction from a single image.
- ❖ We integrate a universal Transformer framework by leveraging human geometry priors and appearance priors from the 2D generative diffusion model.
- ❖ We enhance the fidelity of reconstructed human models by introducing semantic cues, hierarchical supervision, and tailored loss functions.
- ❖ Extensive experiments demonstrate that our method achieves SOTA performance.

Methodology

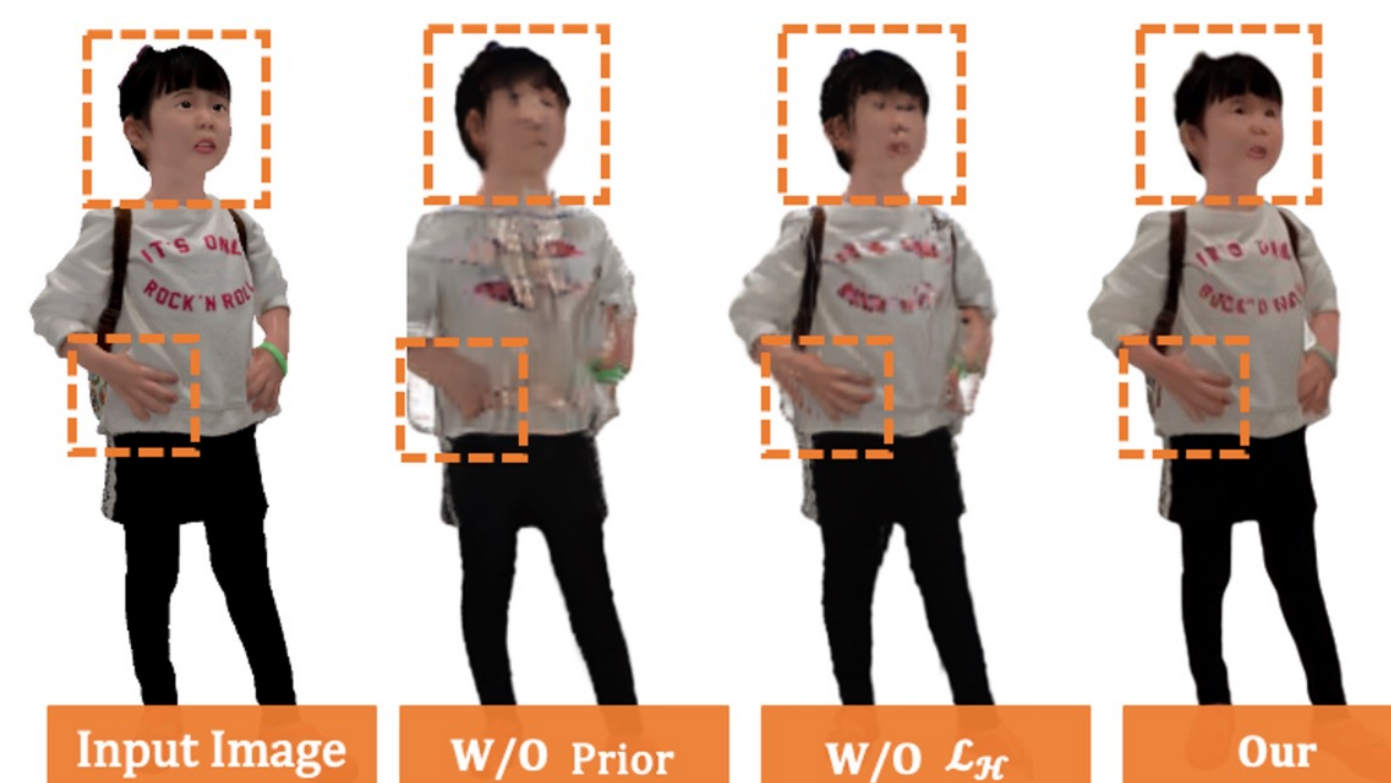
Overview of HumanSplat



Novel-view Synthesizer



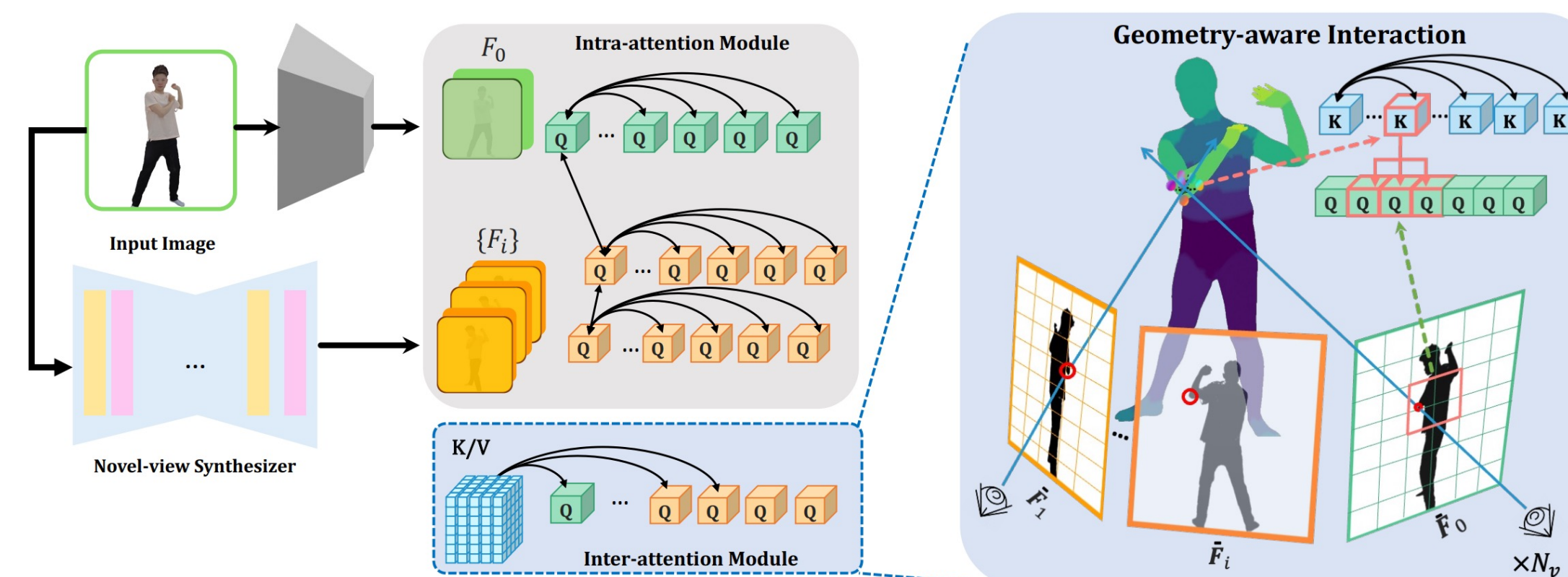
Semantics-guided Objectives



$$\mathbb{E}_{\epsilon \sim p(\epsilon)} [\lambda(\epsilon) | (D_{\theta} \{F_i^{\epsilon}\}_{i=1}^N; \{e_i, a_i\}_{i=1}^N, c, F_0, \epsilon) - \{F_i\}_{i=1}^N | |]$$

$$\mathcal{L}_H = \frac{1}{n} \frac{1}{m} \sum_{i=1}^n \sum_{j=1}^m \lambda_i \lambda_j (\mathcal{L}_{MSE}(\mathbf{I}_{i,j}, \hat{\mathbf{I}}_{i,j}) + \lambda_p \mathcal{L}_p(\mathbf{I}_{i,j}, \hat{\mathbf{I}}_{i,j})),$$

Latent Reconstruction Transformer



Experiments

Quantitative Comparison

Quantitative comparison against SOTA methods.

Method	Category		THuman2.0 [105]			Twindom [106]			Time
	Diffusion	Human Prior	PSNR↑	SSIM↑	LPIPS↓	PSNR↑	SSIM↑	LPIPS↓	
PIFu [107]	✗	✗	18.093	0.911	0.137	-	-	-	30.0s
LGM* [29]	✓	✗	20.013	0.893	0.116	19.840	0.851	0.292	9.5s
GTA [30]	✗	✓	18.050	-	-	17.669	0.741	0.418	43s
SIFU [102]	✗	✓	22.025	0.921	0.084	19.714	0.832	0.312	44s
SIFU [†] [102]	✓	✓	22.102	0.923	0.079	-	-	-	6min
Magic123 [†] [108]	✓	✗	14.501	0.874	0.145	-	-	-	1h
HumanSGD [†] [22]	✓	✓	17.365	0.895	0.130	-	-	-	7min
TeCH [†] [21]	✓	✓	25.211	0.936	0.083	21.192	0.884	0.188	4.5h
HumanSplat (Ours)	✓	✓	24.033	0.918	0.055	23.346	0.913	0.125	9.3s

Qualitative Comparison

Qualitative comparison against SOTA methods.

