### **Consistency Models for Scalable and Fast Simulation-Based Inference**

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## Introduction



- Simulation-based inference (SBI) allow us to infer the hidden parameters of complex systems by means of simulation.
- The goal of amortized **posterior estimation** is to efficiently approximate the full posterior distribution  $p(\theta|x)$  over parameters  $\theta$  for any observable x.

## Motivation

- Multi-step models (e.g., diffusion models, flow matching) are flexible, but slow.
- One-step models (e.g., normalizing flows) are constrained by invertible architectures, but fast.
- Consistency models are both **unconstrained** and **fast**.

## Method

- Explore Consistency Training to train neural posterior estimators from scratch
- Compare four methods: Affine Coupling Flows (ACF), Neural Spline Flows (**NSF**), Flow Matching Posterior Estimation (FMPE), and Consistency Model Posterior Estimation (CMPE; Ours)

**Consistency Function**: Ensure that for t = 0, function is the identity:  $f_{\boldsymbol{\theta}}(\boldsymbol{\theta}, t; \mathbf{x}) = c_{skip}(t)\boldsymbol{\theta} + c_{out}(t)F_{\boldsymbol{\theta}}(\boldsymbol{\theta}, t; \mathbf{x})$ **Optimization Objective:** 

$$\mathbb{E}\Big[\lambda(t_i) \| f_{\boldsymbol{\phi}}(\boldsymbol{\theta} + t_{i+1}\mathbf{z}, t_{i+1}; \mathbf{x}) - \underbrace{f_{\boldsymbol{\phi}^-}(\boldsymbol{\theta} + t_i\mathbf{z}, t_i; \mathbf{x})}_{\text{stop_gradient}} \| \Big],$$

where  $\lambda(t)$  is a weighting function and  $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ .

<sup>r</sup> Learning and Intelligent Systems













# Models Enable Fast tency or Approximation with strained Architectures.

**Bayesian denoising:** Denoising Fashion MNIST shows that CMPE is able to handle higher-dimensional problems as well. For the figure below, we used a U-Net architecture and 60 000 training images.

Tumor spheroid growth: A multi-scale hybrid discretecontinuum model describing the growth of a 2D tumor spheroid. The plot below shows bivariate posteriors for two parameters.













## Experiments

**Three low-dimensional benchmarks:** The tasks feature multi-modal distributions. See the center figure (bottom) for examples with sampling durations. Below on the left, we provide performance on the two moons benchmark as a function of the training budget for different methods. K # indicates K sampling steps. For C2ST, lower is better.







## Limitations

• No closed-form likelihood computation possible.

• Non-monotonic relationship between compute and sample quality.

• Slightly increased training time (25%).



