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Meta-Learning Universal Priors Using Non-Injective Change of Variables

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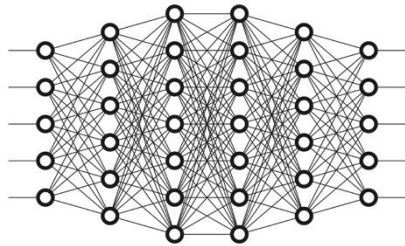
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Motivating context of meta-learning

Challenge in deep learning: large-scale model vs. limited training data

Ex. ResNet-50 [He et al'15]

>23M parameters



HE-vs-MPM dataset [Han et al'23]

116 breast cancer images



VS.

□ Conventional supervised learning

$$\min_{\phi} \mathcal{L}(\phi; \mathcal{D}^{\text{trn}}) + \mathcal{R}(\phi)$$

- Model parameter $\phi \in \mathbb{R}^d$, training data $\mathcal{D}^{\text{trn}} = \{(\mathbf{x}^n, y^n)\}_{n=1}^{N^{\text{trn}}}$
- Loss $\mathcal{L}(\phi; \mathcal{D}^{\text{trn}}) = -\log p(\mathbf{y}^{\text{trn}} | \phi; \mathbf{X}^{\text{trn}})$, regularizer $\mathcal{R}(\phi) = -\log p(\phi)$ empirical prior
- Overfitting if $d \gg N^{\text{trn}}$ ➤ Rely on informative $\mathcal{R}(\phi)$

Remedy: extract and transfer **task-invariant prior** from related tasks

learnable prior

Meta-learning in a nutshell

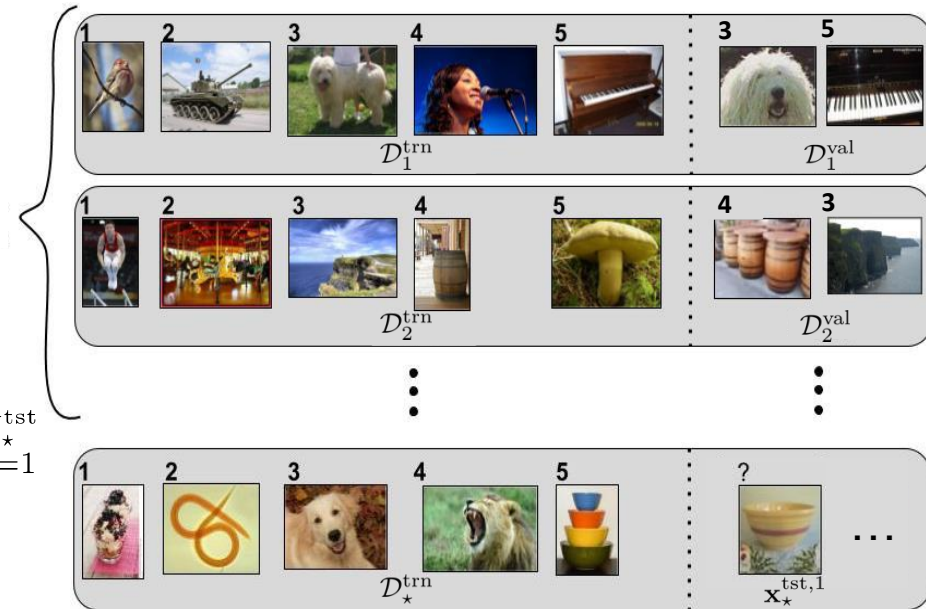
Supervised meta-learning

Given:

Tasks $t = 1, \dots, T$, each with $\mathcal{D}_t^{\text{trn}}, \mathcal{D}_t^{\text{val}}$

New task \star with **limited** $\mathcal{D}_\star^{\text{trn}}$ and $\{\mathbf{x}_\star^{\text{tst},n}\}_{n=1}^{N_\star^{\text{tst}}}$

To-do: predict $\{y_\star^{\text{tst},n}\}_{n=1}^{N_\star^{\text{tst}}}$



✓ **Goal:** learn **task-invariant** prior from given tasks, with which new task can be solved

➤ Bilevel problem: **task-specific** parameter $\phi_t \in \mathbb{R}^d$, **task-invariant** meta-parameter $\theta \in \mathbb{R}^D$

$$\min_{\theta} \sum_{t=1}^T \mathcal{L}(\phi_t^*(\theta); \mathcal{D}_t^{\text{val}})$$

$$\text{s.t. } \phi_t^*(\theta) = \arg \min_{\phi_t} \mathcal{L}(\phi_t; \mathcal{D}_t^{\text{trn}}) + \mathcal{R}(\phi_t; \theta), \forall t$$

$$\phi_t^*(\theta) = \arg \min_{\phi_t} \mathcal{L}(\phi_t; \mathcal{D}_t^{\text{trn}}, \theta), \forall t$$

outer/meta-level

inner/task-level

alternative: implicit prior

Expressiveness challenge in prior selection

Q. Which prior/regularizer to choose?

□ Implicit prior via initialization

- MAML [Finn et al'17]: **Task-invariant** initialization + GD

$$\phi_t^0 = \phi^{\text{init}} = \theta, \forall t \quad \phi_t^k = \phi_t^{k-1} - \alpha \nabla \mathcal{L}(\phi_t^{k-1}; \mathcal{D}_t^{\text{trn}}), k = 1, \dots, K$$

Lemma [Grant et al'18]. Under second-order approximation, MAML satisfies

$$\phi_t^K(\theta) \approx \phi_t^*(\theta) = \arg \min_{\phi_t} \mathcal{L}(\phi_t; \mathcal{D}_t^{\text{trn}}) + \frac{1}{2} \|\phi_t - \theta\|_{\Lambda_t}^2$$

where Λ_t is determined by $\alpha, K, \nabla^2 \mathcal{L}(\theta; \mathcal{D}_t^{\text{trn}})$

➤ Implicit **Gaussian** prior $p(\phi_t; \theta) = \mathcal{N}(\theta, \Lambda_t^{-1})$

□ Explicit prior via regularization

- Isotropic Gaussian [Rajeswaran et al'19] $\mathcal{R}(\phi_t; \theta) = \frac{\lambda}{2} \|\phi_t - \phi^{\text{init}}\|_2^2, \theta := \{\phi^{\text{init}}, \lambda\}$
- Diagonal Gaussian [Li et al'17], block-diagonal Gaussian [Park et al'19], ...
- Sparse [Tian et al'20], factorable + degenerate [Bertinetto et al'18, Lee et al'19], ...

Challenge: preselected priors have limited **expressiveness**

Data-driven priors via transform

Goal: data-driven prior $p(\phi_t; \theta)$ of sufficient expressiveness

Key idea: transform a known prior into the sought one

➤ Learning prior boils down to learning transform

□ Conventional approaches:

- GAN, VAE, diffusion model: tailored to nature signals
- Normalizing flow (NF)

Change-of-variable formula. Let $\mathbf{Z} \in \mathbb{R}^d$ be a continuous random vector, and $f : \mathbb{R}^d \mapsto \mathbb{R}^d$ a bijection. Then $\mathbf{Z}' := f(\mathbf{Z})$ has analytical pdf

$$p_{\mathbf{Z}'}(\mathbf{z}') = p_{\mathbf{Z}}(f^{-1}(\mathbf{z}')) |\det J_{f^{-1}}(\mathbf{z}')| = \frac{p_{\mathbf{Z}}(f^{-1}(\mathbf{z}'))}{|\det J_f(\mathbf{z}')|} \text{ (a.e.)}.$$

- Probability integral transform (PIT): if $d=1$, the optimal $f^* = Q^{-1} \circ P_Z$
- If $d>1$, f^* may not exist [Kong et al'20, Sec. 4] P_Z, Q : source, target cdfs

➤ Limited expressiveness especially in high-dimensional spaces

Learning universal prior via non-injective change-of-variables

□ **Our approach:** non-injective change-of-variable (NCoV)

Theorem 1 (Multivariate PIT). Let $\mathbf{Z} \in \mathbb{R}^d$ be a continuous random vector with mutually independent entries. For any differentiable a.e. cdf $Q : \mathbb{R}^d \mapsto [0, 1]$, there exists $f^* : \mathbb{R}^d \mapsto \mathbb{R}^d$ for which $\mathbf{Z}' := f^*(\mathbf{Z})$ has cdf

$$P_{\mathbf{Z}'} = Q \text{ (a.e.)}.$$

- Q is arbitrary (even discrete), and f^* can be non-injective
- Limitation: transformed pdf may be intractable

$$p_{\mathbf{Z}'}(\mathbf{z}') = \int_{\mathbb{R}^d} p_{\mathbf{Z}}(\mathbf{z}) \delta(\mathbf{z}' - f^*(\mathbf{z})) d\mathbf{z}$$

Alternative: numerical integration when d is small

□ Meta-learning with NCoVs

Target pdf q is $p(\phi_t; \theta)$; use parametric $f(\cdot; \theta)$; task-level optimizes latent variable \mathbf{z}_t

$$\begin{aligned} \min_{\theta} \sum_{t=1}^T \mathcal{L}_t^{\text{val}}(f(\mathbf{z}_t^*(\theta); \theta)) \\ \text{s.t. } \mathbf{z}_t^*(\theta) = \arg \min_{\mathbf{z}_t} \mathcal{L}_t^{\text{trn}}(f(\mathbf{z}_t; \theta)) - \log p_{\mathbf{Z}}(\mathbf{z}_t), \forall t \end{aligned}$$

Ex. $p_{\mathbf{Z}} = \mathcal{N}(\mathbf{0}_d, \mathbf{I}_d)$

$$\begin{aligned} \rightarrow -\log p_{\mathbf{Z}}(\mathbf{z}_t) &= \frac{1}{2} \|\mathbf{z}_t\|_2^2 \\ \mathbf{z}_t^0 &= \mathbf{0}_d \end{aligned}$$

Side benefit: inherent initialization $\mathbf{z}_t^0 = \arg \max_{\mathbf{z}_t} p_{\mathbf{Z}}(\mathbf{z}_t)$ via **maximum a priori**

Numerical tests

□ Few-shot classification

Method	Prior model	5-class miniImageNet	
		1-shot (%)	5-shot (%)
Meta-LSTM [41]	RNN-based	43.44 \pm 0.77	60.60 \pm 0.71
MAML [10]	implicit Gaussian	48.70 \pm 1.84	63.11 \pm 0.92
MetaSGD [29]	diagonal Gaussian	50.47 \pm 1.87	64.03 \pm 0.94
R2D2 [3]	degenerate body & Gaussian head	51.8 \pm 0.2	68.4 \pm 0.2
MC [37]	block-diagonal Gaussian	54.08 \pm 0.93	67.99 \pm 0.73
Warp-MAML [12]	Gaussian	52.3 \pm 0.8	68.4 \pm 0.6
MAML + L2F [2]	implicit Gaussian	52.10 \pm 0.50	69.38 \pm 0.46
MeTAL [1]	implicit Gaussian	52.63 \pm 0.37	70.52 \pm 0.29
Minimax-MAML [58]	inverted Gaussian & entropy	51.70 \pm 0.42	68.41 \pm 1.28
MAML + MetaNCoV	NCoV-based	57.74 \pm 1.47	70.72 \pm 0.70
MetaSGD + MetaNCoV		59.10 \pm 1.52	71.48 \pm 0.68

□ Cross-domain generalization

Method	5-class TieredImageNet		5-class CUB		5-class Cars	
	1-shot (%)	5-shot (%)	1-shot (%)	5-shot (%)	1-shot (%)	5-shot (%)
MAML [10]	51.61 \pm 0.20	65.76 \pm 0.27	40.51 \pm 0.08	53.09 \pm 0.16	33.57 \pm 0.14	44.56 \pm 0.21
ANIL [38]	52.82 \pm 0.29	66.52 \pm 0.28	41.12 \pm 0.15	55.82 \pm 0.21	34.77 \pm 0.31	46.55 \pm 0.29
BOIL [35]	53.23 \pm 0.41	69.37 \pm 0.23	44.20 \pm 0.15	60.92 \pm 0.11	36.12 \pm 0.29	50.64 \pm 0.22
SparseMAML+ [56]	53.91 \pm 0.67	69.92 \pm 0.21	43.43 \pm 1.04	62.02 \pm 0.78	37.14 \pm 0.77	53.18 \pm 0.44
GAP [19]	58.56 \pm 0.93	72.82 \pm 0.77	44.74 \pm 0.75	64.88 \pm 0.72	38.44 \pm 0.77	55.04 \pm 0.77
MetaNCoV	61.50 \pm 1.49	73.10 \pm 0.74	47.84 \pm 1.49	65.27 \pm 0.73	41.66 \pm 1.48	57.19 \pm 0.75

□ Check our paper for additional analytical and experimental results

Thank you!