

# How does PDE order affect the convergence of PINNs?

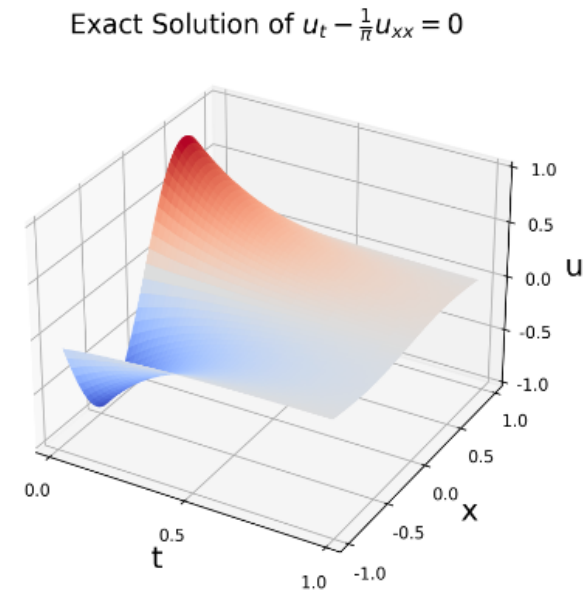
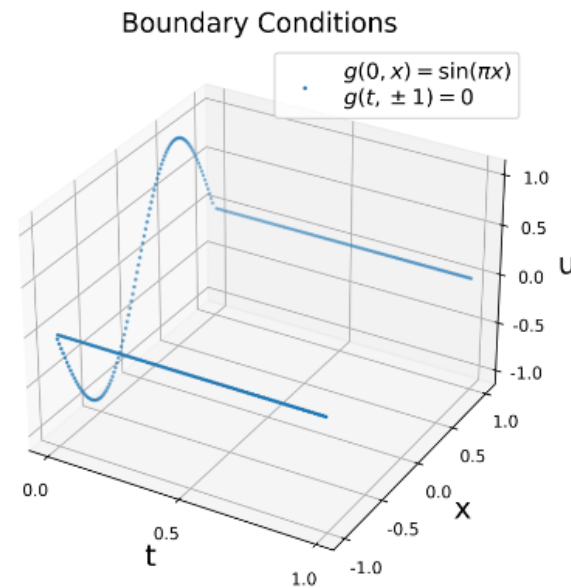
Changhoon Song, Yesom Park, Myungjoo Kang

# Partial Differential Equations

A partial differential equation(PDE) is an equation that computes a function between various partial derivatives of a multivariate function.

Examples:

- $\frac{\partial^2}{\partial x^2} u(x, y) + \frac{\partial^2}{\partial y^2} u(x, y) = 0.$
- $\frac{\partial}{\partial t} u(t, x) - \frac{\partial^2}{\partial x^2} u(t, x) = 0.$



# Physics-Informed Neural Networks

A neural network  $u_\theta$  is a solution of PDE if it satisfies

$$\begin{cases} \mathcal{N} [u_\theta, Du_\theta, D^2 u_\theta] (\mathbf{x}) = f (\mathbf{x}), & \mathbf{x} \in \Omega, \\ u_\theta (\mathbf{x}) = g (\mathbf{x}), & \mathbf{x} \in \partial\Omega, \end{cases}$$

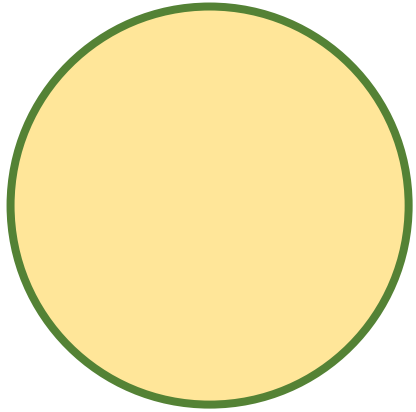
## Physics-Informed Neural Networks (PINNs) [DPT94, RPK19]

PINNs learn a solution by minimizing the residual of the PDE:

$$\mathcal{L} (u_\theta) := \|\mathcal{N} [u_\theta] - f\|_{L^2(\Omega)} + \|u_\theta - g\|_{L^2(\partial\Omega)}.$$

# Physics-Informed Neural Networks

## Theoretical Setting



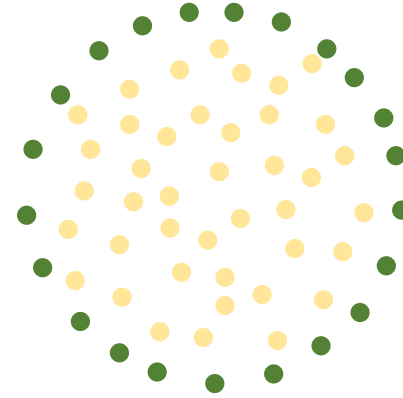
$$\mathcal{N}[u_\theta] = f, \quad x \in \Omega$$

$$\mathcal{B}[u_\theta] = g, \quad x \in \partial\Omega$$

$$\mathcal{L}(u_\theta) = \|\mathcal{N}[u_\theta] - f\|_{L^2(\Omega)} + \|\mathcal{B}[u_\theta] - g\|_{L^2(\partial\Omega)}$$

$$\theta = \arg \min_{\theta} \mathcal{L}(u_\theta)$$

## Practical Setting



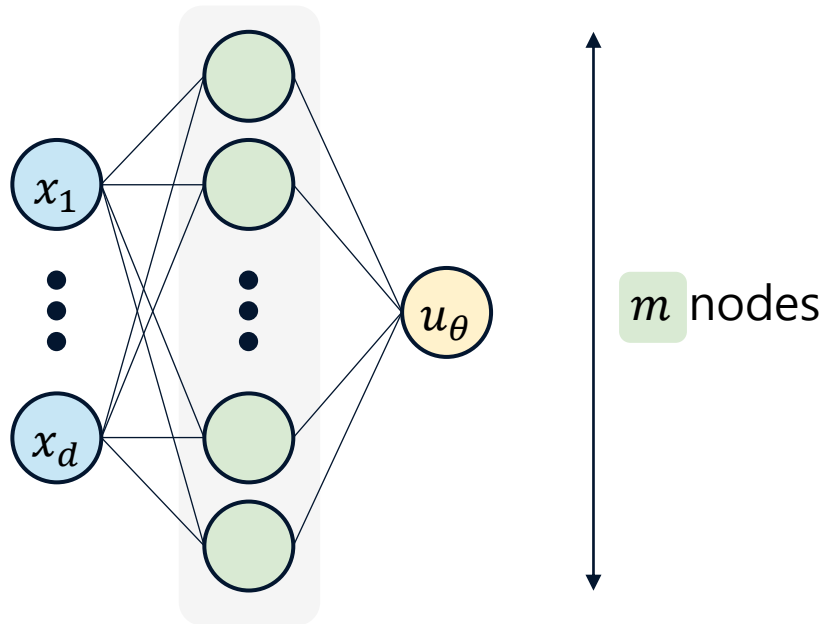
$$\mathcal{N}[u_\theta](x_i) = f(x_i), \quad x_i \in \Omega$$

$$\mathcal{B}[u_\theta](\tilde{x}_j) = g(\tilde{x}_j), \quad \tilde{x}_j \in \partial\Omega$$

$$\mathcal{L}(u_\theta) = \sum_i (\mathcal{N}[u_\theta](x_i) - f(x_i))^2 + \sum_j (\mathcal{B}[u_\theta](\tilde{x}_j) - g(\tilde{x}_j))^2$$

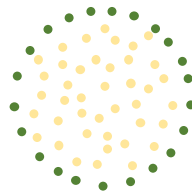
$$\dot{\theta}(t) = -\nabla \mathcal{L}(u_{\theta(t)})$$

# Training Convergence of PINNs



$$u_\theta = \frac{1}{\sqrt{m}} \sum_{r=1}^m a_r \sigma(W_{ij} x_j + b_i)$$

$$\sigma(x) = \max\{0, x\}^p$$



$$\mathcal{N}[u_\theta](x_i) = f(x_i), \quad x_i \in \Omega$$

$$u_\theta(\tilde{x}_j) = g(\tilde{x}_j), \quad \tilde{x}_j \in \partial\Omega$$

$$\mathcal{N}[u] = \sum_{|\alpha| \leq k} a_\alpha(x) \frac{\partial^\alpha}{\partial x^\alpha} u(x), \quad \mathcal{B}[u] = \sum_{|\alpha| \leq 1} \tilde{a}_\alpha(x) \frac{\partial^\alpha}{\partial x^\alpha} u(x)$$

$$\mathcal{L}(u_\theta) = \sum_i (\mathcal{N}[u_\theta](x_i) - f(x_i))^2 + \sum_j (\mathcal{B}[u_\theta](\tilde{x}_j) - g(\tilde{x}_j))^2$$

## Theorem (Brief)

$$m = \Omega \left( \log \frac{m}{\delta} \right)^{4p} \implies P \left( \lim_{t \rightarrow \infty} \mathcal{L}(u(t)) = 0 \right) \geq 1 - \delta.$$

# Main result 1

## Theorem (Special Case)

*There exists a constant  $C$ , independent of  $d$ ,  $k$ , and  $p$ , such that for any  $\delta \ll 1$ , if*

$$m > C \binom{d+k}{d}^{14} p^{7k+4} 2^{6p} \left( \log \frac{md}{\delta} \right)^{4p}$$

*then with probability of at least  $1 - \delta$  over the initialization, we have*

$$\mathcal{L}_{PINN}(\mathbf{w}(t), \mathbf{v}(t)) \leq \exp(-\lambda_0 t) \mathcal{L}_{PINN}(\mathbf{w}(0), \mathbf{v}(0)), \quad \forall t \geq 0.$$

# Main result 1

## Theorem (Special Case)

There exists a constant  $C$ , independent of  $d$ ,  $k$ , and  $p$ , such that for any  $\delta \ll 1$ , if

$$\boxed{m} \underset{\text{Width}}{>} C \binom{d+k}{d}^{14} \overset{\text{PDE order}}{p^{7\boxed{k}+4}} 2^{6p} \left( \log \frac{md}{\delta} \right)^{4p}$$

then with probability of at least  $1 - \delta$  over the initialization, we have

$$\boxed{\mathcal{L}_{PINN}(\mathbf{w}(t), \mathbf{v}(t))} \leq \exp(-\lambda_0 t) \boxed{\mathcal{L}_{PINN}(\mathbf{w}(0), \mathbf{v}(0))}, \quad \forall t \geq 0.$$

Loss at time  $t$

Initial loss

- Higher  $k$  and  $p$  requires exponentially wide width.
- $p = k + 1$  is optimal order for RePU, since  $p \geq k + 1$ .

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Width ReLU power

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Loss at time  $t$

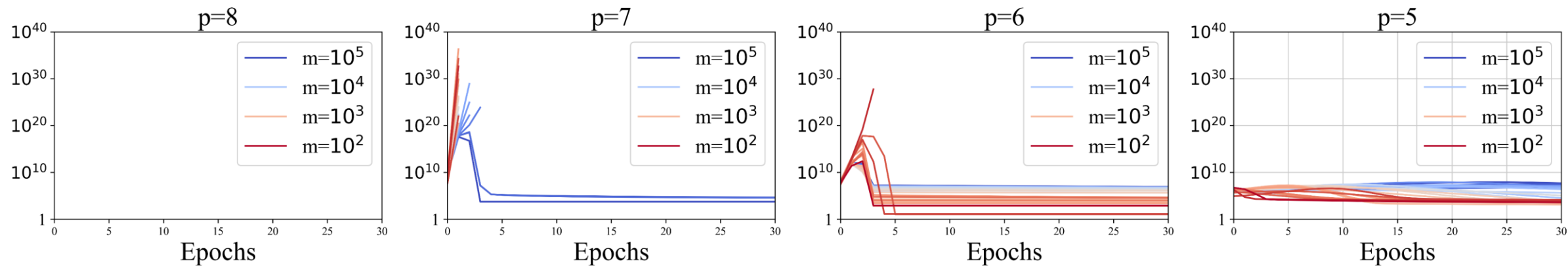
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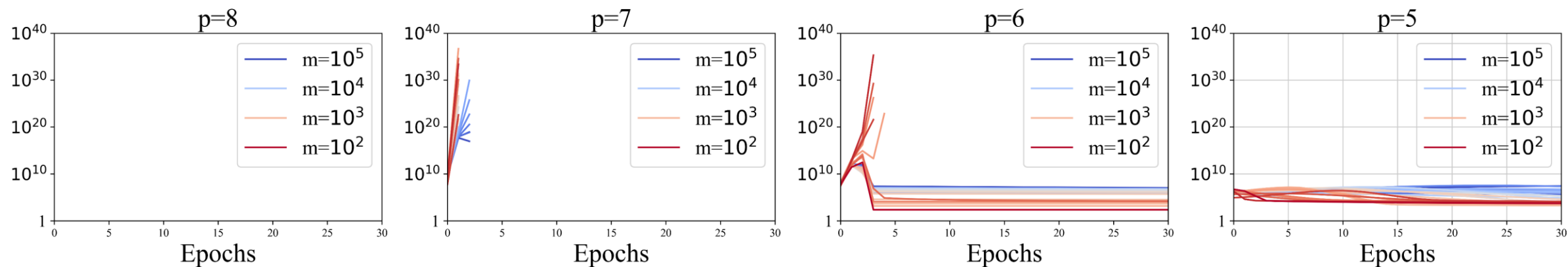


# Experiment 1

Harmonic equation:  $u_{xx} + u_{yy} = f_1$

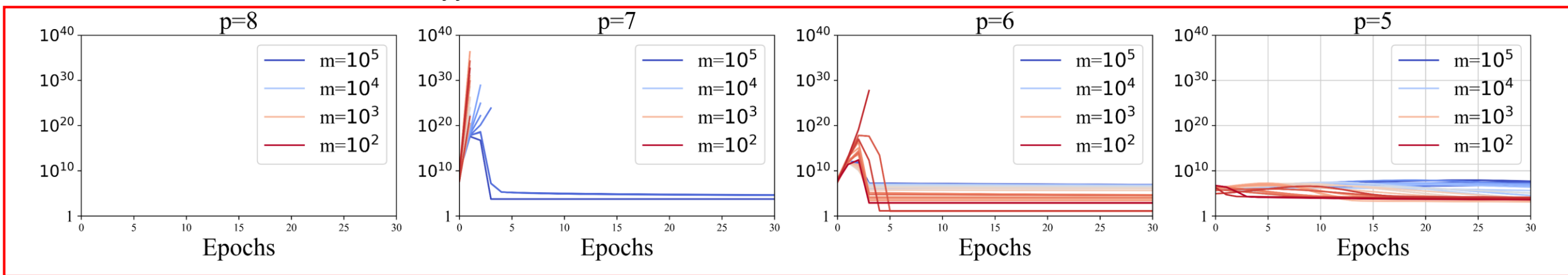


Biharmonic equation:  $u_{xxxx} + 2u_{xxyy} + u_{yyyy} = f_2$



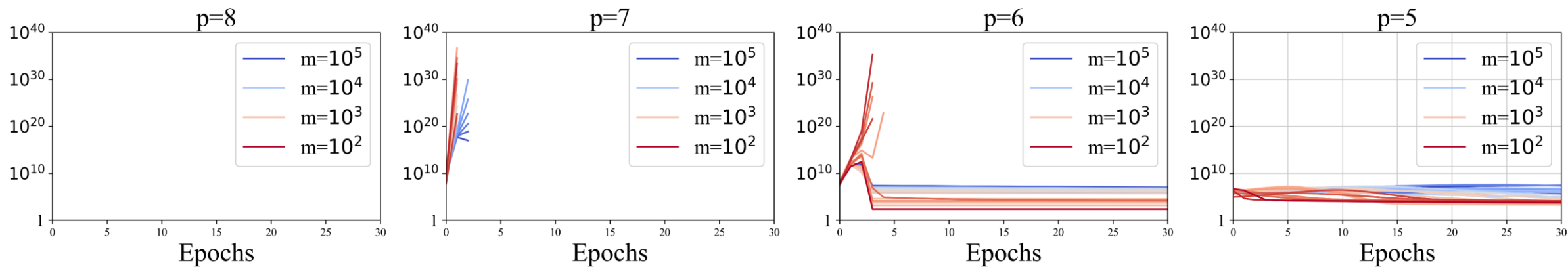
# Experiment 1

Harmonic equation:  $u_{xx} + u_{yy} = f_1$



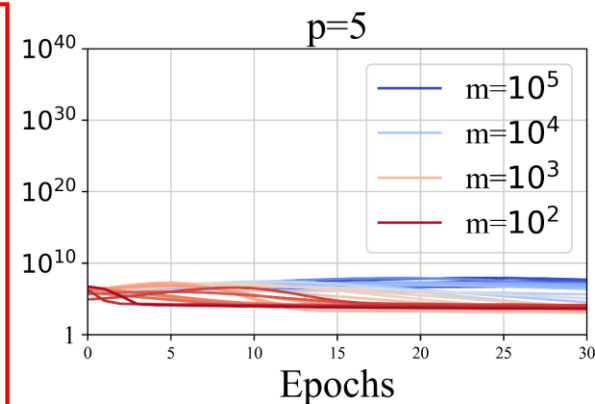
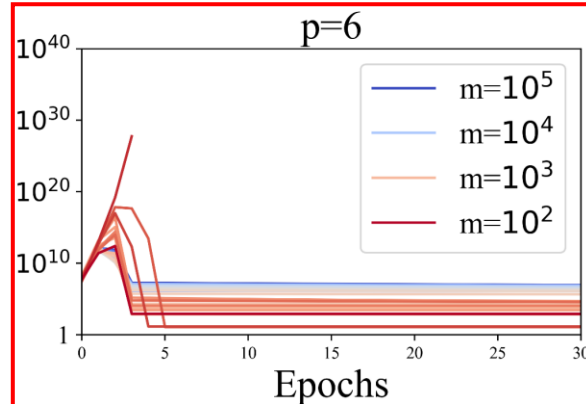
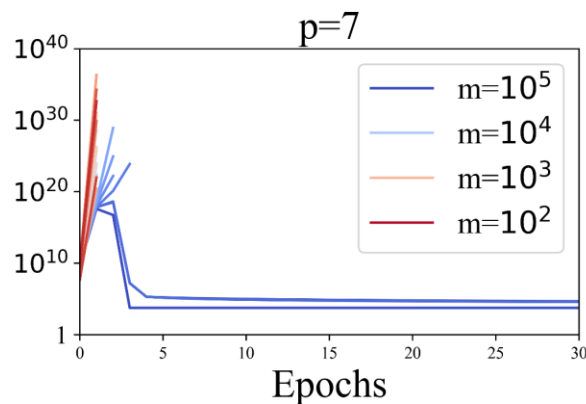
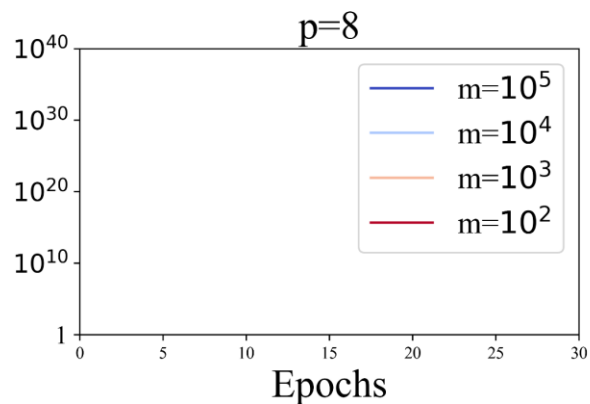
Larger  $p$  requires larger  $m$

Biharmonic equation:  $u_{xxxx} + 2u_{xxyy} + u_{yyyy} = f_2$

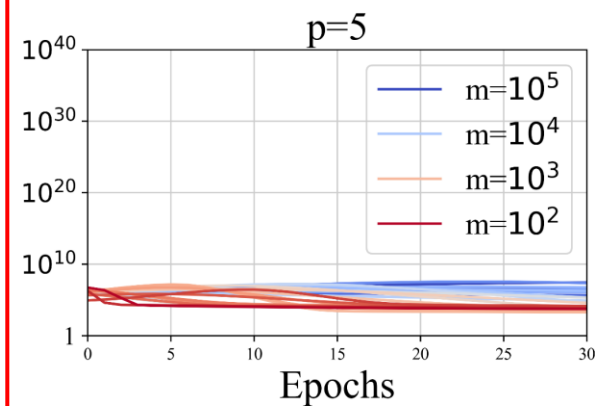
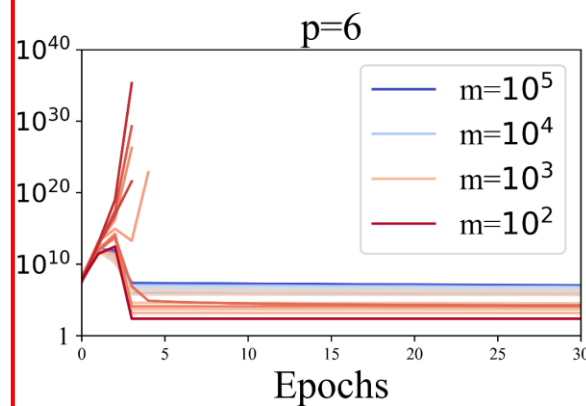
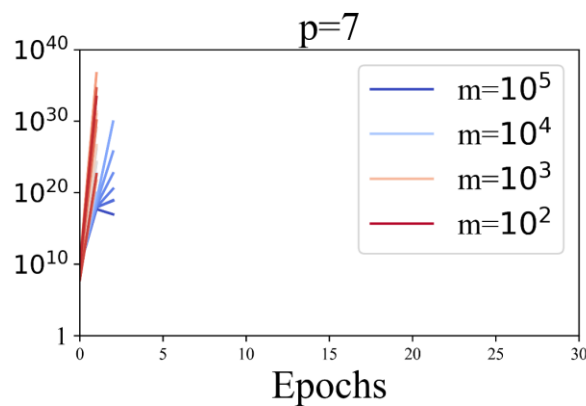
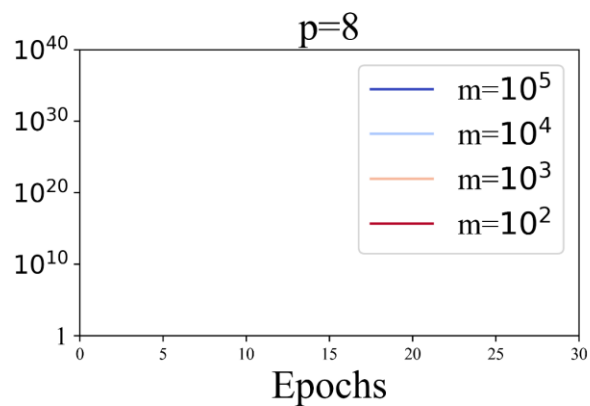


# Experiment 1

Harmonic equation:  $u_{xx} + u_{yy} = f_1$



Biharmonic equation:  $u_{xxxx} + 2u_{xxyy} + u_{yyyy} = f_2$



Larger  $k$  requires larger  $m$

# Variable Splitting

$$\Delta \mathbf{u} = f$$

primary variable

## Higher-order PDEs

$$\begin{cases} \mathcal{N}[u](\mathbf{x}) = f(\mathbf{x}), \\ \mathcal{B}[u](\mathbf{x}) = g(\mathbf{x}), \end{cases}$$

$$\mathcal{N}[u] = \sum_{|\alpha| \leq k} a_\alpha \frac{\partial^\alpha}{\partial \mathbf{x}^\alpha} u$$

Auxiliary variable

$$\begin{cases} \nabla \cdot \mathbf{V} = f \\ \mathbf{V} = \nabla u \end{cases}$$

## System of lower-order PDEs

$$\begin{cases} \hat{\mathcal{N}}[\phi_0, \dots, \phi_L](\mathbf{x}) = f(\mathbf{x}), \\ \frac{\partial^\beta}{\partial \mathbf{x}^\beta} (\phi_{\ell-1})_\alpha(\mathbf{x}) = (\phi_\ell)_{\alpha+\beta}(\mathbf{x}) \\ \mathcal{B}[\phi_0](\mathbf{x}) = g, \end{cases}$$

$$\mathcal{N}[u] = \sum_{\ell} \sum_{|\alpha| \leq \xi_\ell} \sum_{|\beta| \leq \Delta \xi_{\ell+1}} \hat{a}_{\ell, \alpha, \beta} \frac{\partial^{\Delta \xi_{\ell+1}}}{\partial \mathbf{x}^\beta} (\phi_\ell)_\alpha$$

# Main result 2

## Theorem (General Case)

There exists a constant  $C$ , independent of  $d$ ,  $k$ ,  $|\xi|$ , and  $p$ , such that for any  $\delta \ll 1$ , if

$|\xi|$ : maximal order in system of PDEs

$$m > C \binom{d+k}{d}^6 \binom{d+|\xi|}{d}^8 p^{7|\xi|+4} 2^{6p} \left( \log \frac{md}{\delta} \right)^{4p},$$

then with probability of at least  $1 - \delta$  over the initialization, we have

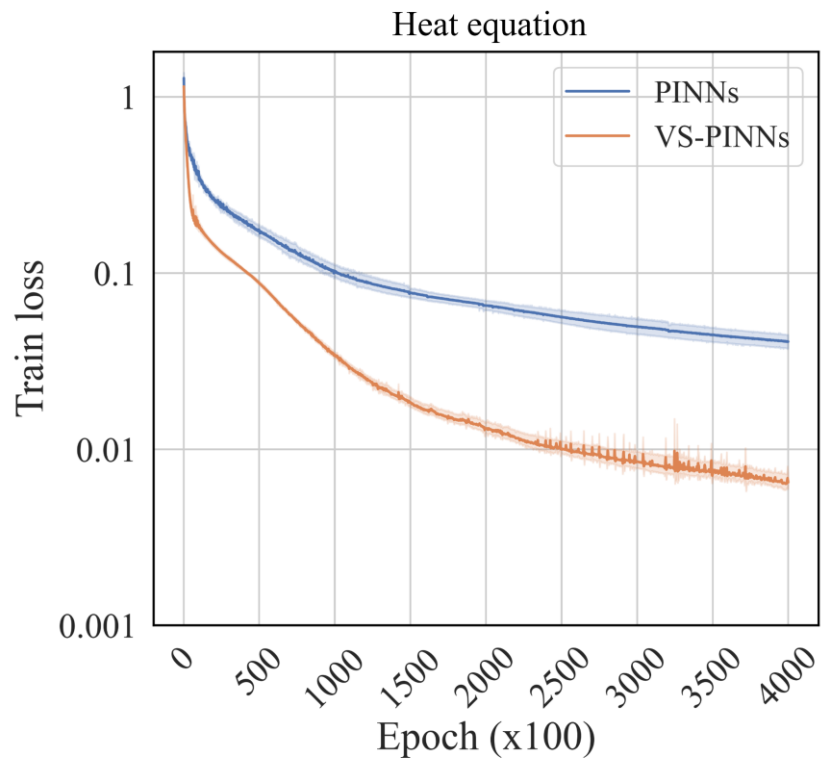
$$\mathcal{L}_{PINN}^{VS}(\mathbf{w}(t), \mathbf{v}(t)) \leq \exp(-\lambda_0 t) \mathcal{L}_{PINN}^{VS}(\mathbf{w}(0), \mathbf{v}(0)), \quad \forall t \geq 0.$$

- Lower  $|\xi|$  reduces width requirement.
- $p = |\xi| + 1$  is optimal order for RePU.

# Experiment 2

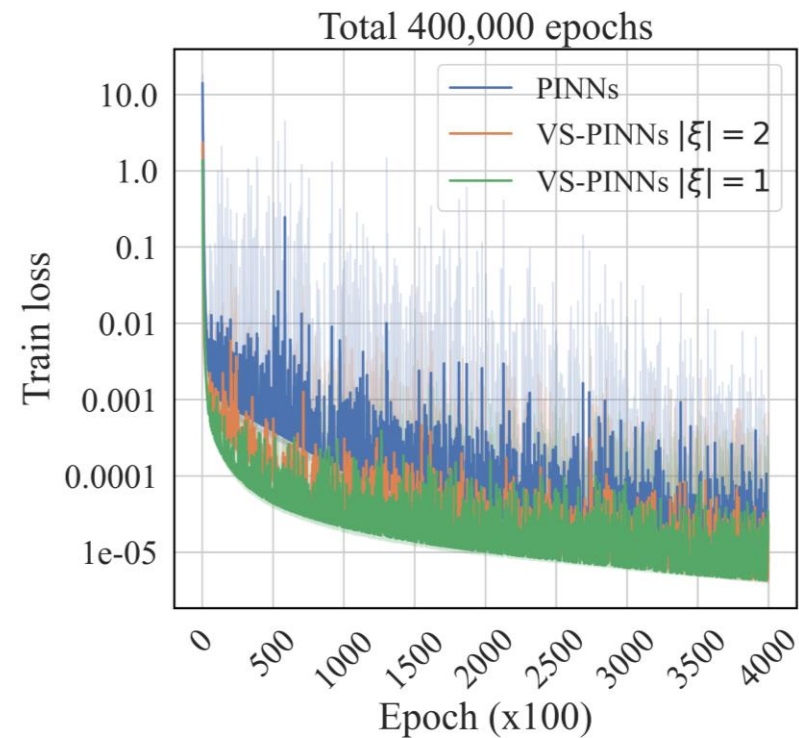
## Heat equation (GD)

$$\begin{cases} u_t = u_{xx} \\ u(t, -1) = u(t, 1) = 0 \\ u(0, x) = \sin(\pi x) \end{cases}$$



## Elastic beam equation (Adam)

$$\begin{cases} u_t + u_{xxxx} = 0 \\ u(t, 0) = u(t, \pi) = u_{xx}(t, 0) = u_{xx}(t, \pi) = 0 \\ u(0, x) = 2 \sin(x) \end{cases}$$



# Summary

- The PINNs converge to global minimizer, provided enough network size.
- The higher the PDE order, the larger the network should be.
- Re-formulating high-order PDE as system of lower-order PDEs enhance the convergence condition.

Thank you