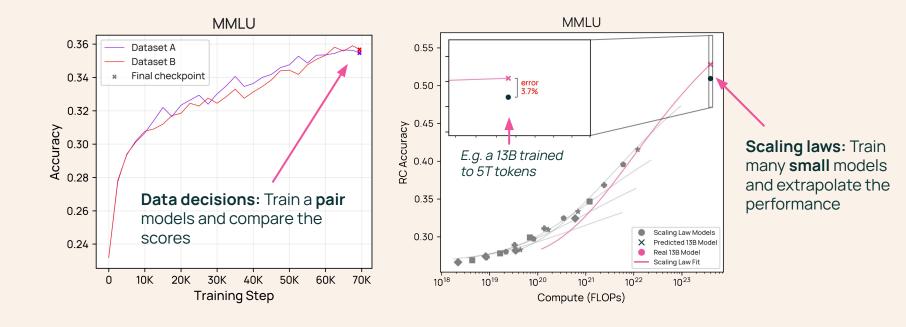


# Signal and Noise: A Framework for Reducing Uncertainty in Language Model Evaluation

David Heineman, Valentin Hofmann, Ian Magnusson, Yuling Gu, Noah A. Smith, Hannaneh Hajishirzi, Kyle Lo, Jesse Dodge



### Building Language Models means making decisions

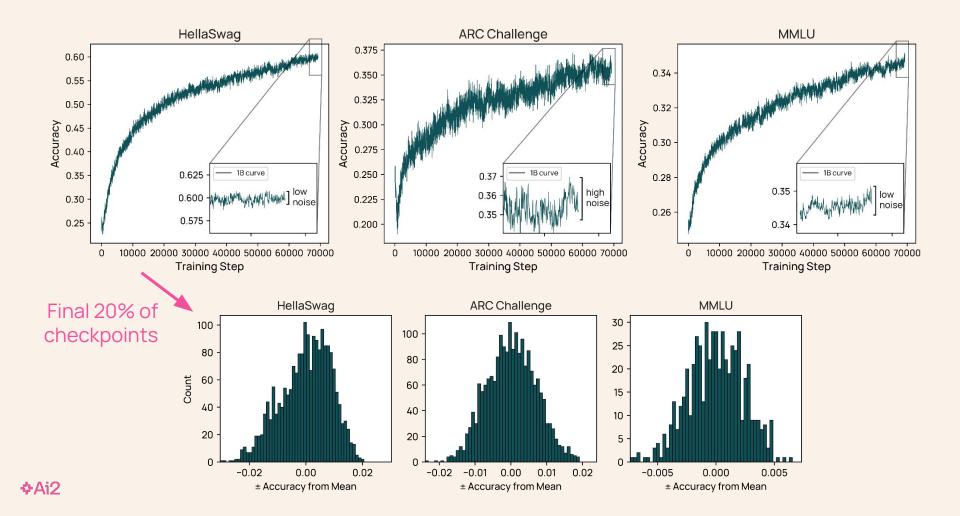


#### <u>Downstream tasks</u> are now core to building models ...

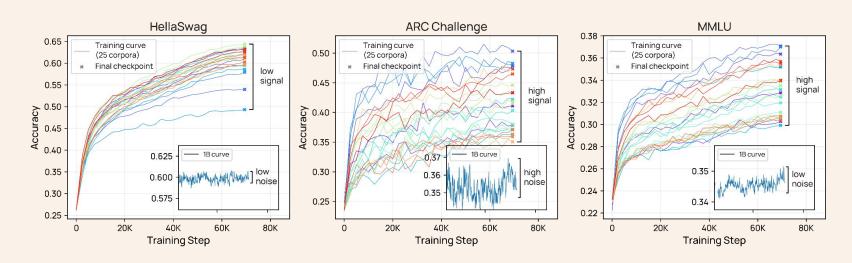
... some tasks aren't predictable ... some metrics hide real capability ... some tasks are useful! Are Emergent Abilities of Large Language Models a Language models scale reliably with over-training and on The Llama 3 Herd of Models Mirage? downstream tasks Llama Team, Al @ Meta A detailed contributor list can be found in the appendix of this paper Samir Yitzhak Gadre<sup>1,2</sup> Georgios Smyrnis<sup>3</sup> Vaishaal Shankar<sup>4</sup> Rylan Schaeffer, Brando Miranda, and Sanmi Koveic Modern artificial intelligence (AI) systems are powered by foundation models. This paper presents a Suchin Gururangan<sup>5</sup> Mitchell Wortsman<sup>5</sup> Rulin Shao<sup>5</sup> Jean Mercat<sup>2</sup> new set of foundation models, called Llama 3. It is a herd of language models that natively support Alex Fang<sup>5</sup> Jeffrey Li<sup>5</sup> Sedrick Keh<sup>2</sup> Rui Xin<sup>5</sup> Marianna Nezhurina<sup>6</sup> Computer Science, Stanford University multilinguality, coding reasoning and tool usage. Our largest model is a dense Transformer with Igor Vasiljevic<sup>2</sup> Jenia Jitsev<sup>6,7</sup> Luca Soldaini<sup>8</sup> Alexandros G. Dimakis<sup>3</sup> Gabriel Ilharco<sup>5</sup> Pang Wei Koh<sup>5,8</sup> Shuran Song<sup>9</sup> Thomas Kollar<sup>2</sup> ampirical analysation of Llama 3. We find that Llama 3 delivers comparable quality to leading language models such as GPT-4 on a plethora of tasks. We publicly release Llama 3, including pre-trained and Yair Carmon<sup>10\*</sup> Achal Dave<sup>2\*</sup> Reinhard Heckel<sup>11\*</sup> Niklas Muennighoff<sup>12\*</sup> Ludwig Schmidt<sup>5\*</sup> Abstract post-trained versions of the 405B parameter language model and our Llama Guard 3 model for input and output safety. The paper also presents the results of experiments in which we integrate image Scaling Law Models 1.375 Llama 2 Models Scaling Law Predicti Liama 3 405B 1.325 ₫ 1.300 2 1.275 1.250 A N = 0.011B ○ 1.200 ■ N = 0.079B — Interpolation # N = 0.154B --- Extrapolation 1020 1021 1022 1023 1024 1025 1.40 1.30 N = 0.411B
 M = 20 ♦ N = 1.4B \* N = 6.9B M = 640 Figure 4 Scaling law forecast for ARC Challenge. Left: Normalized negative log-likelihood of the correct answer on the 5.0 ARC Challenge benchmark as a function of pre-training FLOPs. Right: ARC Challenge benchmark accuracy as a Compute (6ND, D = MN) [FLOPs] function of the normalized negative log-likelihood of the correct answer. This analysis enables us to predict model performance on the ARC Challenge benchmark before pre-training commences. See text for details. Figure 1: Reliable scaling with over-training and on downstream error prediction. (left) We fit a scaling law for model validation loss, parameterized by (i) a token multiplier M = N/D, ruality of the data we use for pre-training and post-training. These improvements include the develop gigure 2: Emergent abilities of large language models are created by the researcher's chosen of more careful pre-processing and curation pipelines for pre-training data and the development of more which is the ratio of training tokens D to parameters N and (ii) the compute C in FLOPs used to metrics, not unpredictable changes in model behavior with scale. (A) Suppose the per-token rigorous quality assurance and filtering approaches for post-training data. We pre-train Llama 3 on a train a model, approximated by C = 6ND. Larger values of M specify more over-training. We are cross-entropy loss decreases monotonically with model scale, e.g.,  $\mathcal{L}_{CE}$  scales as a power law. (B) corpus of about 15T multilingual tokens, compared to 1.8T tokens for Llama 2. . Scale. We train a model at far larger scale than previous Llama models: our flagship language model was able to extrapolate, in both N and M, the validation performance of models requiring more than The per-token probability of selecting the correct token asymptotes towards 1, (C) If the researcher pre-trained using 3.8 × 10<sup>25</sup> FLOPs, almost 50× more than the largest version of Llama 2. Specifically scores models' outputs using a nonlinear metric such as Accuracy (which requires a sequence of 300× the training compute used to construct the scaling law. (right) We also fit a scaling law to we pre-trained a flagship model with 405B trainable parameters on 15.6T text tokens. As expected petokens to all be correct), the metric choice nonlinearly scales performance, causing performance predict average downstream top-1 error as a function of validation loss. We find that fitting scaling to change sharply and unpredictably in a manner that qualitatively matches published emergent laws for downstream error benefits from using more expensive models when compared to fitting for abilities (inset). (D) If the researcher instead scores models' outputs using a discontinuous metric such as Multiple Choice Grade (akin to a step function), the metric choice discontinuously scales loss prediction. We predict the average error over 17 downstream tasks for models trained with over performance, again causing performance to change sharply and unpredictably. (E) Changing from a 20× the compute. For this figure, we train all models on RedPajama [112]. nonlinear metric to a linear metric such as Token Edit Distance, scaling shows smooth, continuous and predictable improvements, ablating the emergent ability. (F) Changing from a discontinuous metric to a continuous metric such as Brier Score again reveals smooth, continuous and predictable improvements in task performance. Consequently, emergent abilities are created by the researcher's choice of metrics, not fundamental changes in model family behavior on specific tasks with scale.

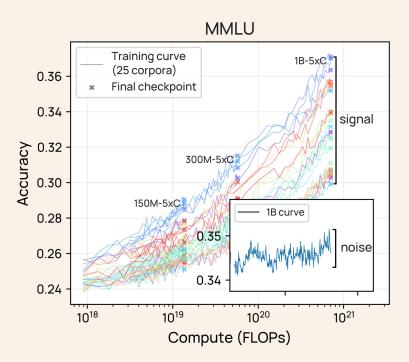
The Llama 3 Herd of Models (preprint, 2024)
Language models scale reliably with over-training and on downstream tasks (ICLR, 2025)
Are Emergent Abilities of Large Language Models a Mirage? (NeurlPS, 2023)

# Why do so many predictions fail - but some don't?



## ... but inter-checkpoint variance is not the whole story! We need to measure both signal and noise





#### signal:

Rel. Dispersion(M) =  $\max_{j,k} |m_j - m_k|/\bar{m}$ 

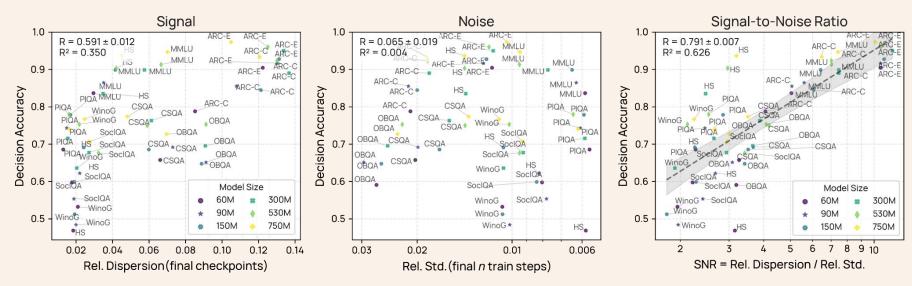
#### noise:

Rel. Std.
$$(m) = \sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (m_i - \bar{m})^2 / \bar{m}}$$

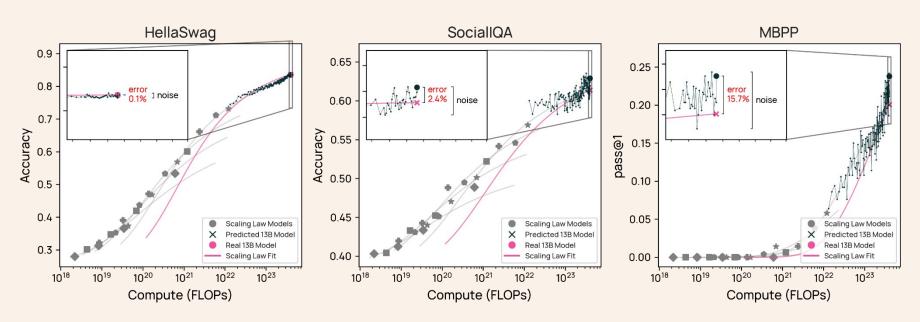
Signal-to-Noise Ratio =

Rel. Dispersion(final train checkpoint)
Rel. Std.(final n train checkpoints)

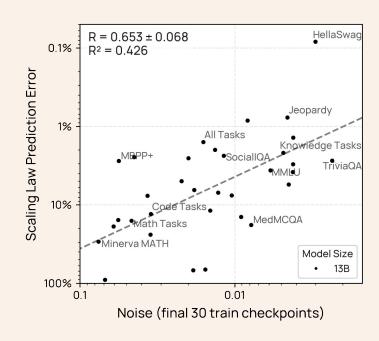
## Only signal or noise alone do not explain rank agreement from small to large scale... ... but the signal-to-noise ratio does!



## Predicting task performance using scaling laws is sensitive to noise!

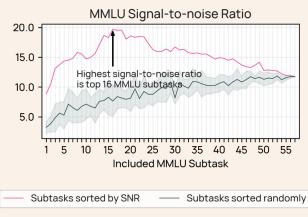


### Predicting task performance using scaling laws is sensitive to noise!



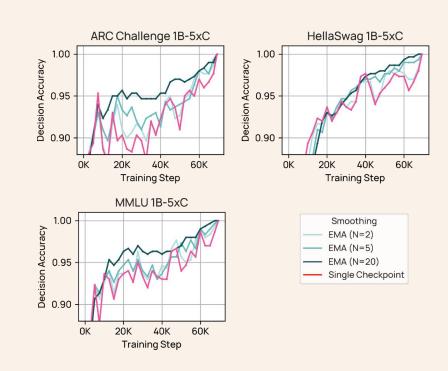
### We can use the signal-to-noise ratio to improve our benchmarks

- intervention 1: filter subtasks with high SNR
- intervention 2: smooth intermediate checkpoints
- intervention 3: select metrics



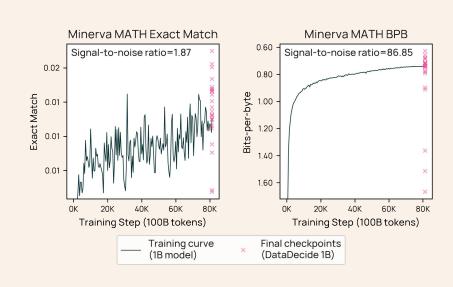
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### Thank you!

Learn more at our poster:

Wednesday, Dec 3 at 4:30 in Hall C,D,E.

Contact: davidh@allenai.org

























