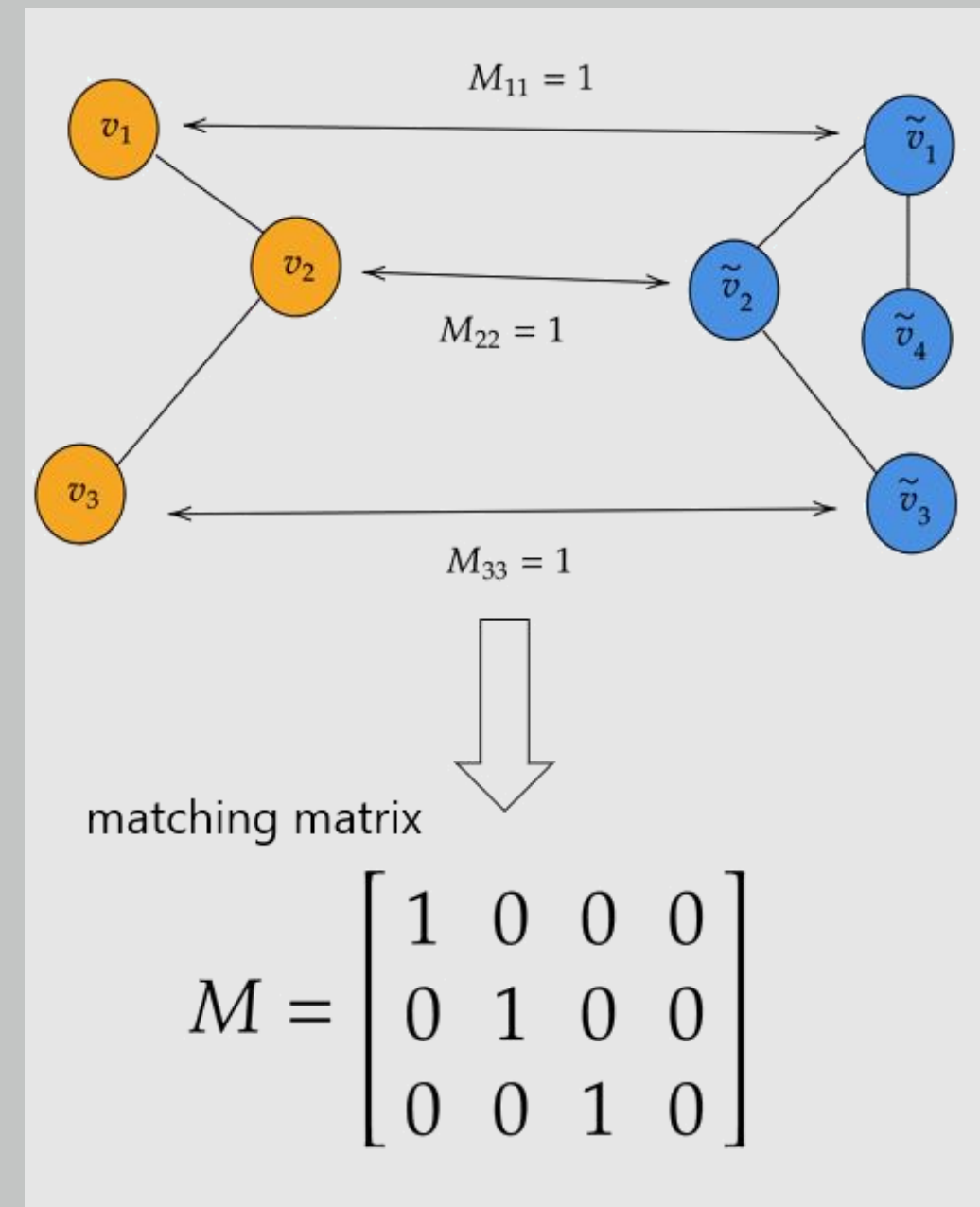


What is Graph Matching



Example



Objective Function and Method

The objective function of graph matching

$$\mathcal{Z}(M) = \frac{1}{2} \text{tr}(M^T A M \tilde{A}) + \lambda \text{tr}(M^T K).$$

The projected fixed-point method is

$$N^{(t)} = (1 - \alpha)N^{(t-1)} + \alpha D^{(t)},$$

$$D^{(t)} = \mathcal{P}(\nabla \mathcal{Z}(N^{(t-1)})).$$

$\mathcal{P}(\cdot)$ projects the gradient onto a feasible set, such as a convex hull of the original domain, using the doubly stochastic projection (DSP):

$$\mathcal{P}_{\mathcal{D}}(X) = \arg \min_{D \in \mathcal{D}_{n \times n}} \|D - X\|_F.$$

$$\mathcal{D}_{n \times n} := \{Y : Y\mathbf{1} = \mathbf{1}, Y^T \mathbf{1} = \mathbf{1}, Y \geq 0\}.$$

Challenges

Loss of scale invariance property

$$\arg \max \mathcal{Z}(M) = \arg \max w \mathcal{Z}(M), \quad w > 0.$$

$$\mathcal{P}_{\mathcal{D}}(X) \neq \mathcal{P}_{\mathcal{D}}(wX), \quad X \in \mathbb{R}_+^{n \times n}.$$

Projection-relaxation may cause deviation from original domain.

Why DSP is Sensitive to Scaling Changes?

$$\mathcal{P}_{\mathcal{D}}(wX) = \arg \max_{D \in \mathcal{D}_{n \times n}} \langle D, X \rangle - \frac{1}{2w} \langle D, D \rangle.$$

Referring back to the updating formula, X corresponds to the gradient $\nabla \Phi(N^{(t)})$:

$$\mathcal{P}_{\mathcal{D}}(w \nabla \Phi(N^{(t)})) = \arg \max_{D \in \mathcal{D}_{n \times n}} -\frac{1}{2w} \langle D, D \rangle + \text{tr}(D^T A N^{(t)} \tilde{A}) + \lambda \text{tr}(D^T K)$$

As w increases, the projection process emphasizes optimizing the objective assignment score.

Frobenius-Regularized Assignment (FRA)

Turn the uncontrollable problem's scale constant w into a controllable modeling parameter θ .

Theorem. DSP with a parameter θ

$$D_X^\theta = \arg \min_{D \in \mathcal{D}_{n \times n}} \|D - \frac{\theta}{2} X\|_F^2$$

can be rewritten as

$$D_X^\theta = \arg \max_{D \in \mathcal{D}_{n \times n}} \langle D, X \rangle - \frac{1}{\theta} \langle D, D \rangle.$$

The new formulation allows input normalization by $\frac{X}{\max(X)}$ to eliminate scaling variations (i.e., w).

Effect of θ

What is the distance between D_X^θ and D_X^∞ ?

Proposition. For a matrix $X \in \mathbb{R}_+^{n \times n}$,

$$\frac{1}{n} (\langle D_X^\infty, X \rangle - \langle D_X^\theta, X \rangle) \leq \frac{1}{\theta}.$$

How θ suppresses the bias introduced by relaxation?

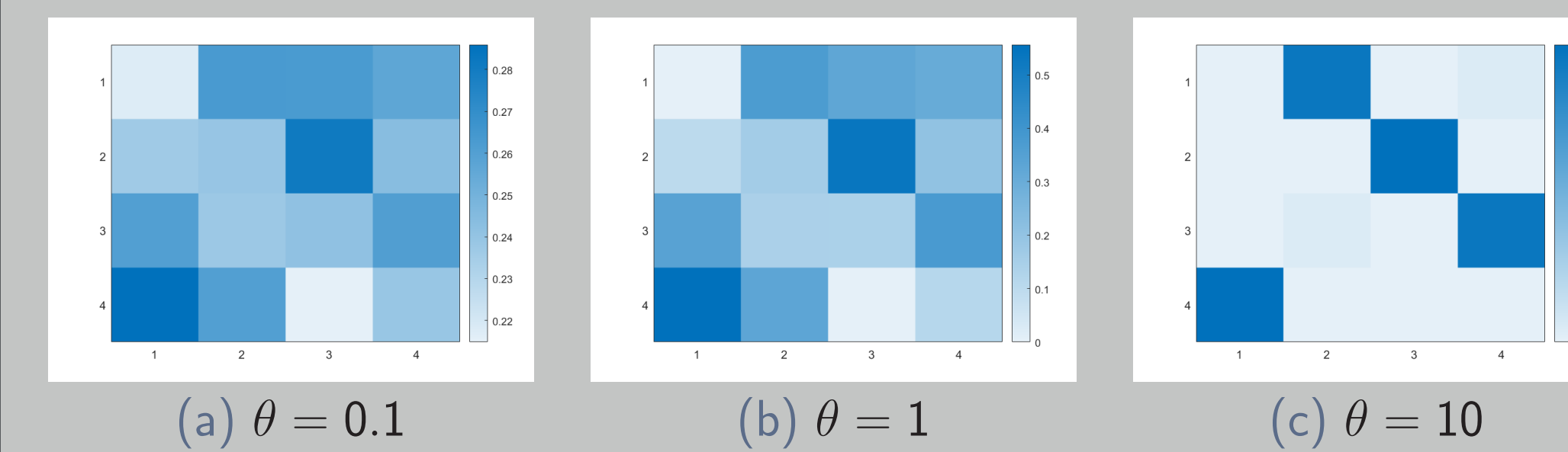


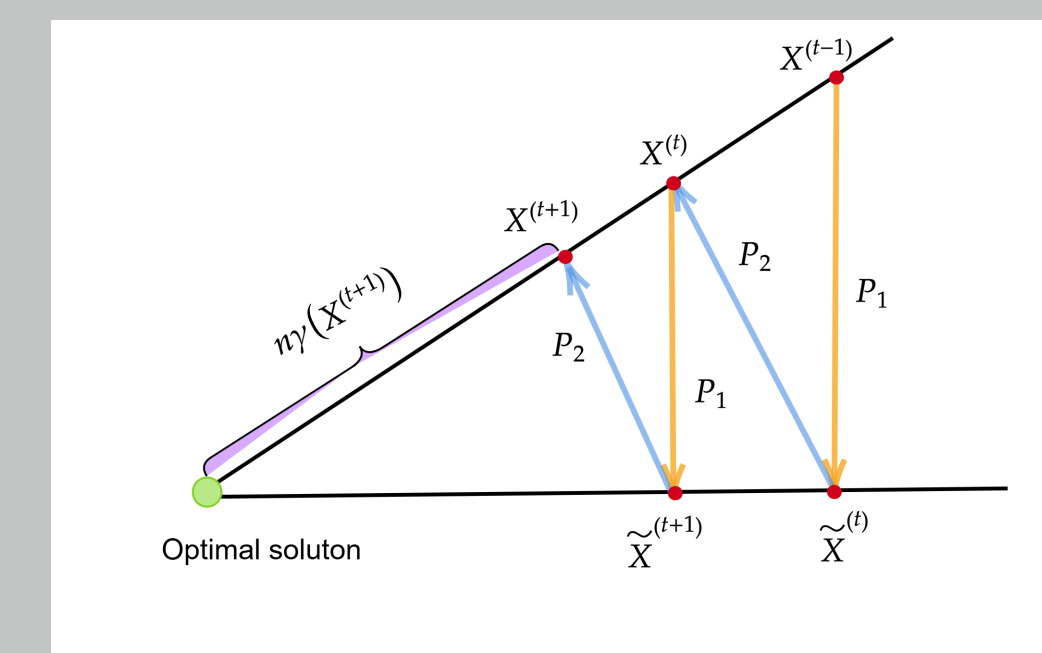
Figure: Visualization of D_X^θ under different θ . The color of each cell represents the matrix entry, with darker shades indicating larger values.

Solve FRA

Scaling Doubly Stochastic Normalization (SDSN):

$$X^{(0)} = \frac{\theta X}{\max(X)}, \quad \tilde{X}^{(k)} = \mathcal{P}_1(X^{(k-1)}), \quad X^{(k)} = \mathcal{P}_2(\tilde{X}^{(k)}),$$

$$\mathcal{P}_1(X) = \arg \min_{Y \mathbf{1} = Y^T \mathbf{1} = 1} \|X - Y\|_F, \quad \mathcal{P}_2(X) = \arg \min_{Y \geq 0} \|X - Y\|_F^2.$$



Robustness to Rounding Error

Theorem Given that $X_k = \hat{X}_k + \Delta X_k$ is the k -th iterate of SDSN and ΔX_k is the rounding error, both X_k and \hat{X}_k have the same limit under subsequent SDSN iterations.

This property prevents accumulation of rounding error arising from the gradient matrix computation and SDSN (corresponding to ΔX_0 and $\{\Delta X_k\}_{k>1}$).

Algorithm with Mixed-Precision

Algorithm FRAM

- 1: **Require** $A, \tilde{A}, K, \lambda, \alpha, \theta, \delta_{th}$
- 2: Initial $X^{(0)} = \mathbf{0}_{n \times n}$
- 3: $c = \max(A, \tilde{A}, K)$ ▷ FP64
- 4: $A = A/\sqrt{c}, \tilde{A} = \tilde{A}/\sqrt{c}, K = K/\sqrt{c}$ ▷ FP64
- 5: **While** $\delta^{(t)} > \delta_{th}$
- 6: $X^{(t)} = A N^{(t-1)} \tilde{A} + \lambda K$ ▷ TF32
- 7: $D^{(t)} = \text{SDSN}(X^{(t)}, \theta)$ ▷ FP32
- 8: $N^{(t)} = (1 - \alpha)N^{(t-1)} + \alpha D^{(t)}$ ▷ FP64
- 9: $\delta^{(t)} = \|N^{(t)} - N^{(t-1)}\|_F / \|N^{(t)}\|_F$ ▷ FP64
- 10: *Discretize* N to obtain M ▷ FP64
- 11: **Return** Matching matrix M

Experiments on Facebook Networks

Social network	5% noise		15% noise		25% noise	
	Methods	Acc	Time	Acc	Time	Acc
ucsf500	S-GWL	26.4%	1204.1s	18.3%	1268.2s	17.9%
	GWL	78.1%	3721.6s	68.4%	4271.3s	60.8%
	DSPFP	79.7%	151.3s	68.3%	154.2s	62.2%
	GA	35.5%	793.2s	21.4%	761.7s	16.0%
	GRASP	37.9%	63.6s	20.3%	67.4s	15.7%
House500	ASM	91.1%	387.2s	88.4%	391.7s	85.7%
	AIPFP	68.6%	2705.5s	55.1%	2552.7s	47.8%
	FRAM	94.7%	211.1s	91.1%	221.6s	89.5%

Acceleration of Mixed-Precision Design

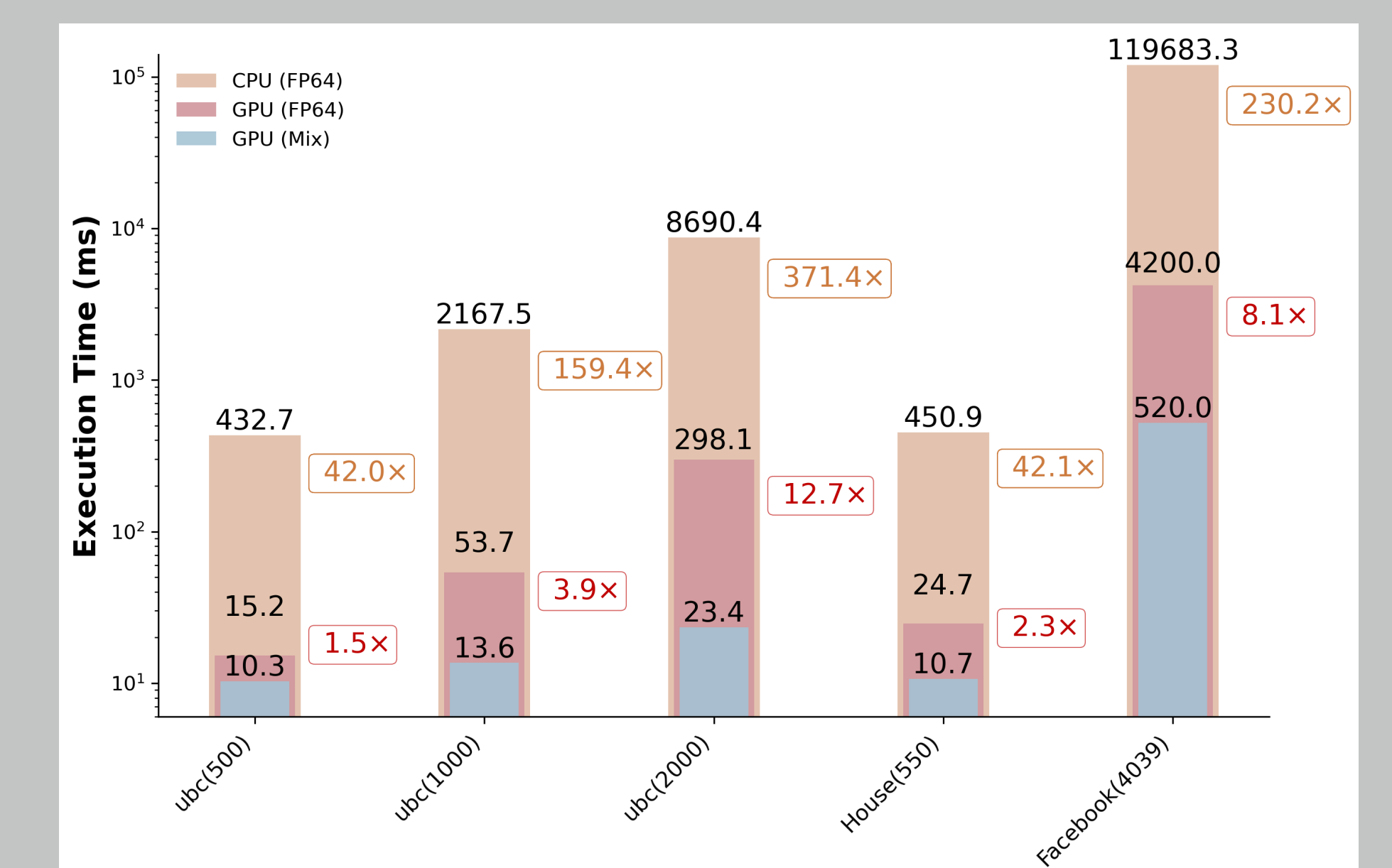


Figure: Red boxed numbers show the speedup of GPU mixed-precision over GPU double precision, and yellow boxed numbers show the speedup over CPU double precision.