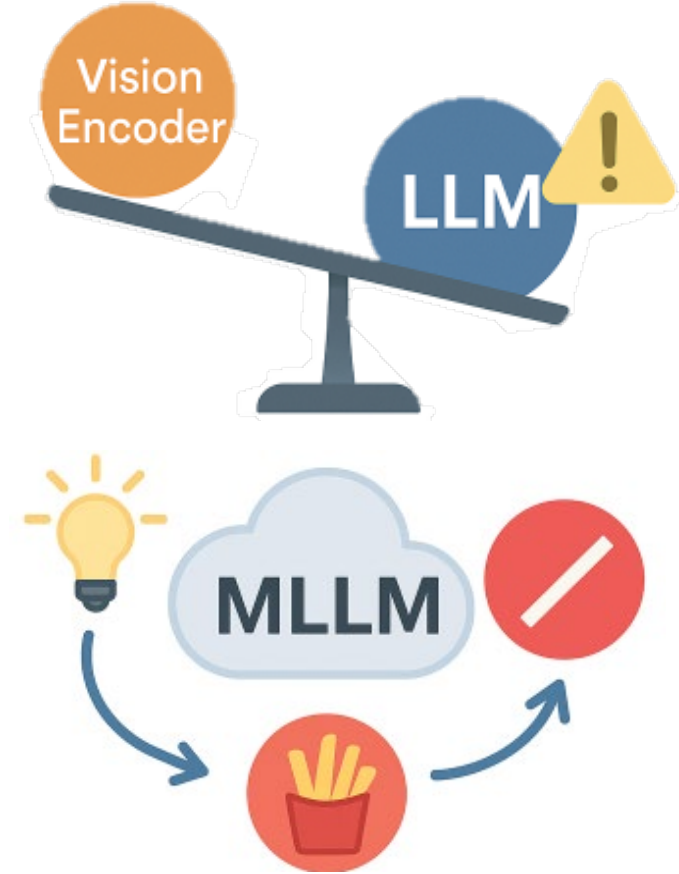


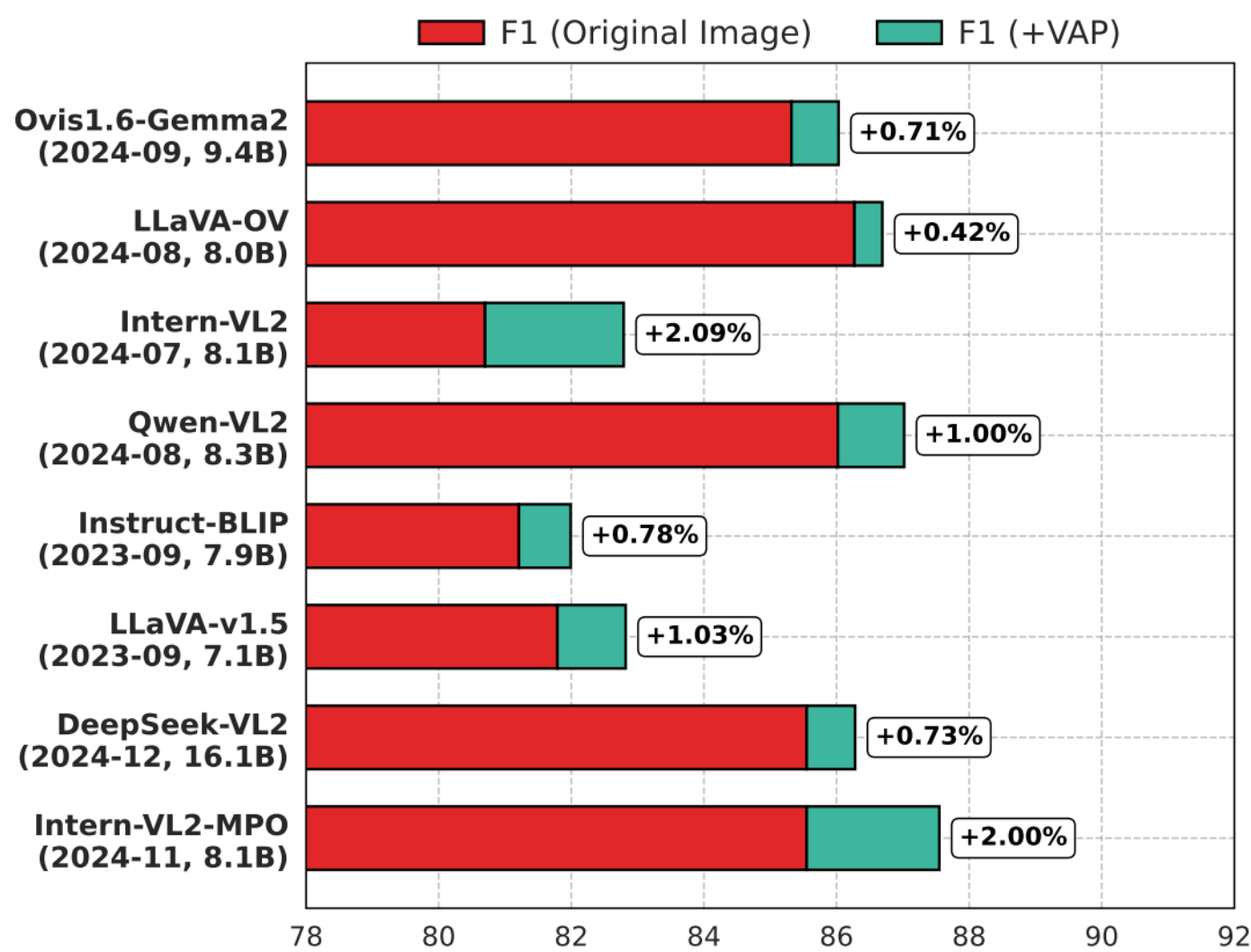
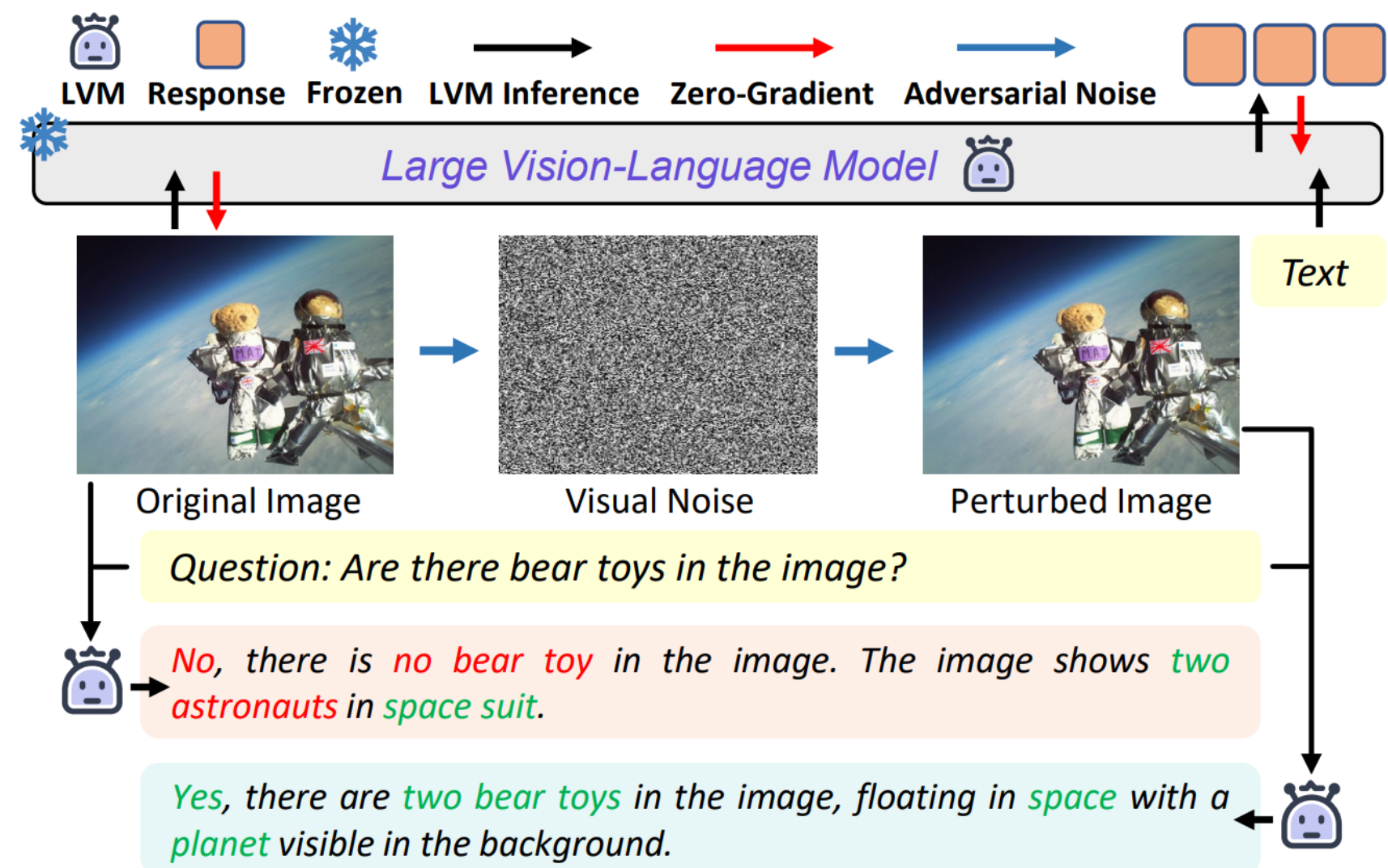
Introduction & Motivation

1. Why LVMs Hallucinate: Parametric Bias

- ◆ **Bias 1: Dominance Bias**
 - LLMs dominate due to massive scale compared to vision encoders.
 - Causes models to **over-rely on language priors**, ignoring visual grounding.
- ◆ **Bias 2: Parametric Knowledge Bias**
 - MLLMs encode **biased world knowledge** from pretraining (e.g., **long-tail data imbalance**), overfit to frequency exists objects.
 - Model outputs reinforce **superficial correlations**.



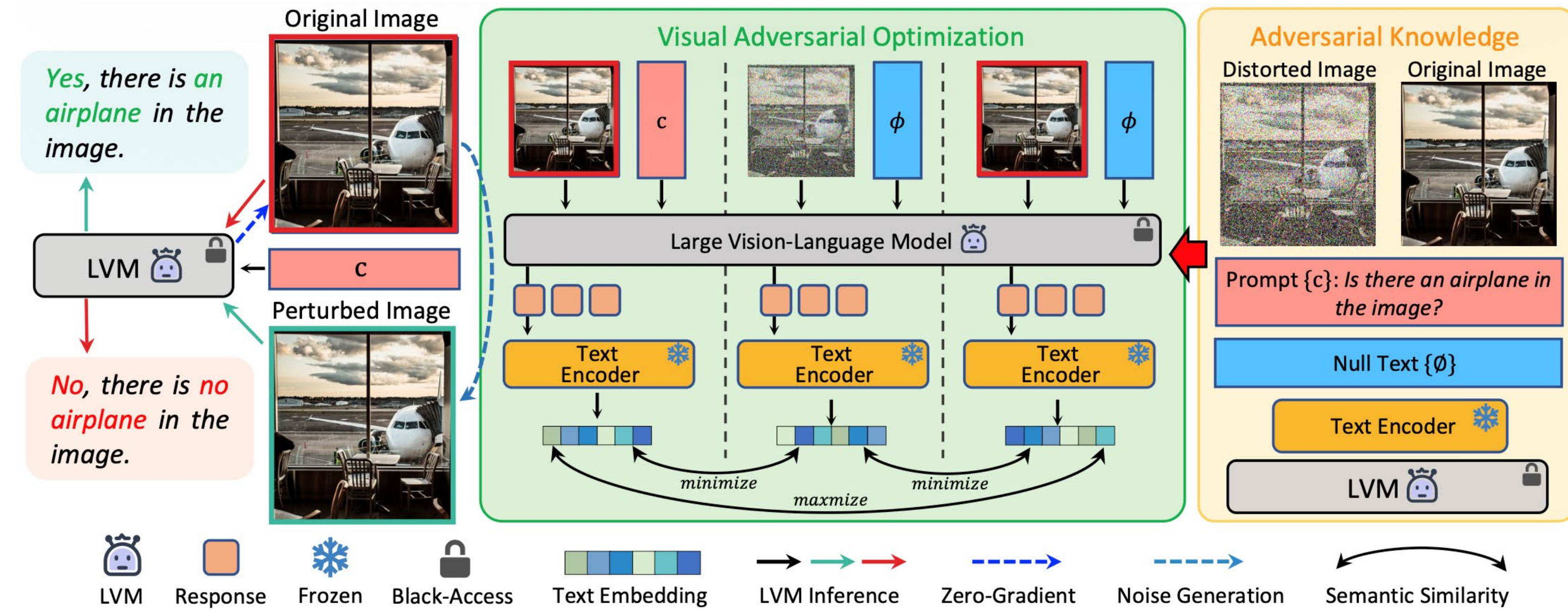
2. Key Idea: Turning Parametric Bias into Beneficial Visual Noise



➤ **A new perspective view:** Hallucination stems from *input conditioning*, not model incapability.

➤ **Our approach:** Reformulate parametric bias as an adversarial optimization problem — inject strategic visual noise to shift model attention toward actual image evidence and away from text-prior biases.

Method



(1) Visual-Text Alignment

- Match $f(x + \delta, c)$ with $f(x + \delta, \emptyset)$
- Reduce prompt-driven hallucination

(2) Bias Exposure via Distorted Views

- Contract $x + \delta$ with distorted image \bar{x}
- Push apart $f(x + \delta, \cdot)$ and $f(\bar{x}, \cdot)$

(3) Zero-Gradient Noise Optimization

- Solve $\delta = \arg \max \mathcal{L}(x, \delta)_{\|\delta\| \leq \epsilon}$
- Training-free, model-agnostic

Experiments

1. POPE & BEAF Benchmark: Consistent Hallucination Reduction Across 8 LVMs

LVM	Vision Input	POPE-Popular		POPE-Random		POPE-Adversarial		BEAF	
		Acc \uparrow	F1 \uparrow	Acc \uparrow	F1 \uparrow	Acc \uparrow	F1 \uparrow	Acc \uparrow	F1 \uparrow
LLaVA-v1.5	Original	85.57	86.19	88.97	89.09	79.80	81.79	79.99	74.06
	+VAP	86.67 ^{+1.10}	87.18 ^{+0.99}	90.00 ^{+1.03}	90.07 ^{+0.98}	80.97 ^{+1.17}	82.82 ^{+1.03}	80.36 ^{+0.37}	74.35 ^{+0.29}
Instruct-BLIP	Original	83.30	82.85	88.13	87.18	81.33	81.21	81.91	73.55
	+VAP	84.06 ^{+0.76}	83.67 ^{+0.82}	89.00 ^{+0.87}	88.12 ^{+0.99}	82.03 ^{+0.70}	81.99 ^{+0.78}	82.07 ^{+0.16}	73.96 ^{+0.41}
Intern-VL2	Original	84.11	81.64	85.14	82.60	82.00	80.70	88.38	79.10
	+VAP	86.18 ^{+2.07}	84.19 ^{+2.00}	86.30 ^{+1.16}	84.08 ^{+1.48}	84.81 ^{+2.81}	82.79 ^{+2.09}	88.69 ^{+0.31}	79.72 ^{+0.62}
Intern-VL2-MPO	Original	87.51	86.53	88.68	87.58	86.28	85.55	89.21	82.56
	+VAP	89.08 ^{+1.57}	88.27 ^{+1.74}	90.20 ^{+1.52}	89.30 ^{+1.72}	88.13 ^{+1.85}	87.55 ^{+2.00}	89.63 ^{+0.42}	82.72 ^{+0.18}
DeepSeek-VL2	Original	86.80	85.86	88.70	87.64	86.47	85.55	89.39	82.51
	+VAP	87.60 ^{+0.80}	86.70 ^{+0.84}	89.30 ^{+0.60}	88.31 ^{+0.67}	87.13 ^{+0.66}	86.28 ^{+0.73}	89.72 ^{+0.33}	83.12 ^{+0.61}
Qwen-VL2	Original	88.13	87.68	90.60	89.99	86.27	86.02	87.96	81.13
	+VAP	89.10 ^{+0.97}	88.65 ^{+0.97}	91.16 ^{+0.56}	90.54 ^{+0.55}	87.30 ^{+1.03}	87.02 ^{+1.00}	88.39 ^{+0.43}	81.57 ^{+0.44}
LLaVA-OV	Original	88.30	87.33	89.53	88.51	87.17	86.27	90.76	84.53
	+VAP	88.93 ^{+0.63}	87.93 ^{+0.60}	89.87 ^{+0.34}	88.83 ^{+0.32}	87.76 ^{+0.59}	86.69 ^{+0.42}	91.07 ^{+0.33}	85.01 ^{+0.48}
Ovis1.6-Gemma2	Original	87.96	86.88	88.96	87.87	86.22	85.32	90.12	83.04
	+VAP	88.44 ^{+0.48}	87.40 ^{+0.52}	89.59 ^{+0.65}	88.54 ^{+0.67}	86.85 ^{+0.63}	86.03 ^{+0.71}	90.91 ^{+0.79}	84.53 ^{+1.49}

2. Proxy-Based VAP: 1/8× Cost with Comparable Gains

Metric	Source: Intern-VL2-1B			Source: Qwen-VL2-2B	
	⇒ Intern-VL2-1B	⇒ Intern-VL2-4B	⇒ Intern-VL2-8B	⇒ Qwen-VL2-2B	⇒ Qwen-VL2-7B
Accuracy	81.69/83.28	81.55/82.56	82.00/84.07	84.47/85.42	86.27/86.87
Precision	89.72/92.13	85.65/87.21	87.40/90.97	83.98/84.85	87.21/88.03
Recall	70.94/72.34	75.05/75.90	72.24/75.50	84.04/85.26	84.87/85.33
F1 Score	79.23/81.04	80.00/81.16	80.70/82.52	84.01/85.05	86.02/86.66
Inference Cost Reduction	1×	1/3×	1/8×	1×	1/5×

Examples of Vision-Question-Answer (VQA)

(a) open-ended evaluation under original image



Provide a brief description of the given image?

The image shows a small child sitting on a swing set near the ocean. The swing set is located on a sandy bench. The child appears to be enjoying the ride on the swing, while a kit floats gently above the sand, and a large sandcastle stands nearby.

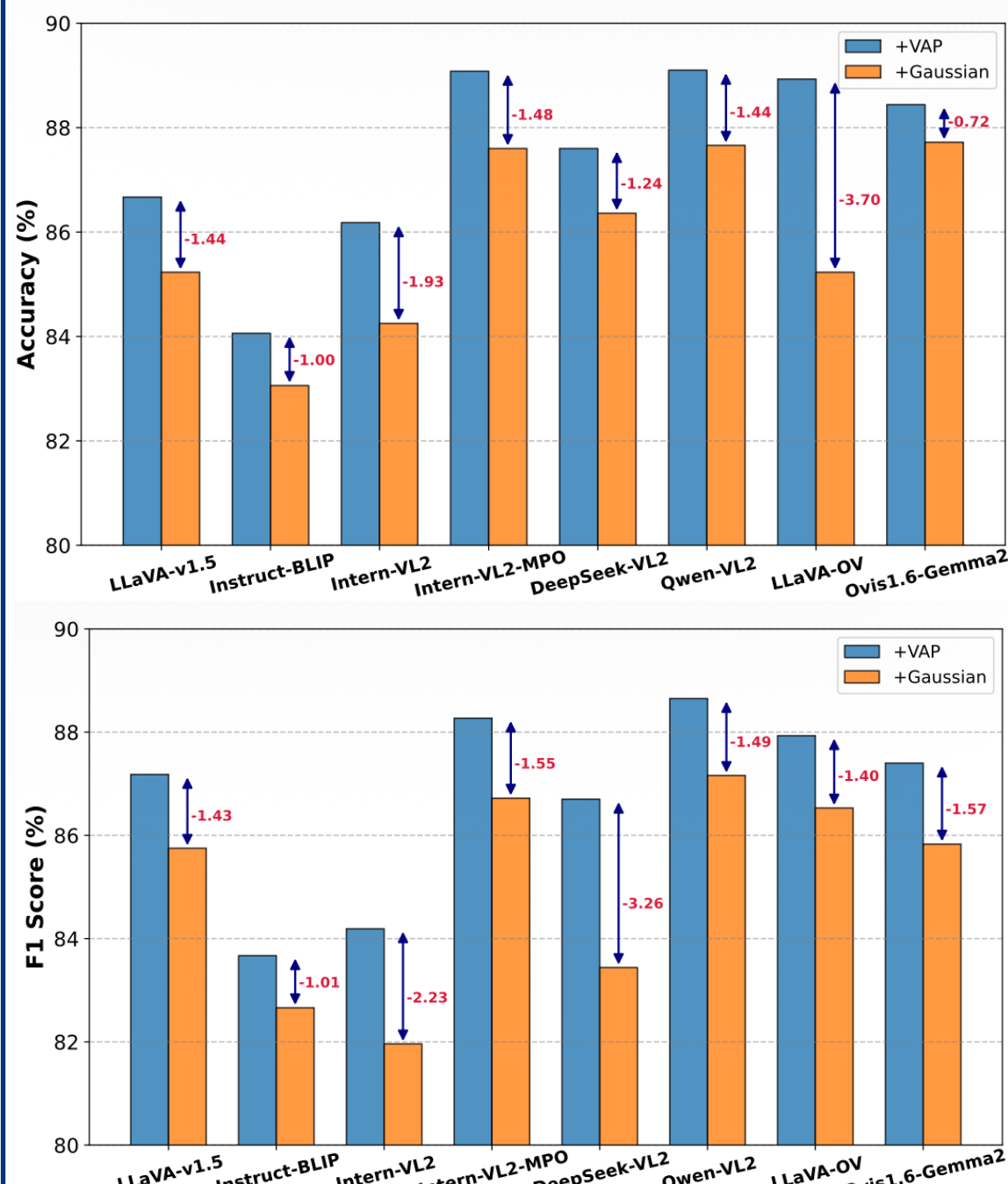
(b) open-ended evaluation under noise image (+ VAP)



Provide a brief description of the given image?

The image shows a small white dog sitting on a swing set near the ocean. The swing set is located on a sandy bench, and the ocean waves can be seen in the background. The dog appears to be enjoying the ride on the swing.

VAP vs. Gaussian Noise



Originally captured by Ms. Xinjun Lin in Aranya, this little dog now travels with us to San Diego for NeurIPS 2025.