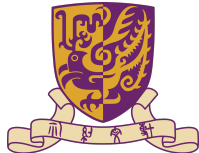


Think or Not? Selective Reasoning via Reinforcement Learning for Vision-Language Models

Jiaqi Wang^{1†}, Kevin Qinghong Lin^{2†}, James Cheng¹, Mike Zheng Shou²

¹The Chinese University of Hong Kong

²Show Lab, National University of Singapore





Motivation

- **Reinforcement Learning (RL)** enhances reasoning in vision-language models (**VLMs**) but often generates **unnecessarily long reasoning traces**.
- Prior works (e.g., GRPO) always force VLMs to perform complete reasoning, increasing computation cost.
- Inspired by humans: sometimes we answer **directly** (no reasoning), sometimes we think **carefully**.
- **Key Question:** Can VLMs learn to decide **when reasoning is necessary**?

	wo think correct	wo think incorrect
w think correct	52.1%	25.6%
w think incorrect	14.5%	7.69%

Figure 1: Accuracy comparison of “with” vs. “without” explicit thinking. Skipping unnecessary reasoning saves tokens without hurting accuracy.



Related Work

- **RL for VLMs:** PPO, DPO, GRPO—focus on **reward-driven** improvement, but always generate full explanations.
- Recent solutions: heuristic penalties for long explanations, separate control modules.
- **Reasoning in LMs:** Early works focus on reasoning quality/length, new works begin to address efficiency.
- **Gap:** Few address **when to skip reasoning altogether** for efficiency and human-likeness.

We propose: **TON** (**T**hink-**o**r-**N**ot) — allows selective, task-adaptive reasoning.



Method Overview: TON Framework

- **TON** enables VLMs to decide: *Think, or not?*
- **Two-stage Training:**
 - 1 **Supervised Fine-Tuning (SFT)** with **Thought Dropout** — trains a cold-start format for skipping reasoning.
 - 2 **Group Relative Policy Optimization (GRPO)** — lets model explore “think or not” to maximize rewards.

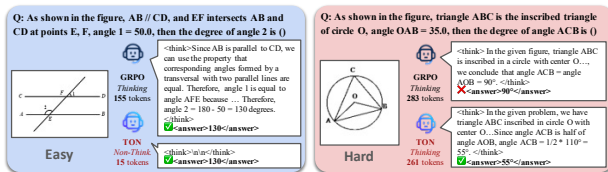


Figure 2: TON learns to skip reasoning for easy questions, while fully reasoning on complex ones.



Method: SFT with Thought Dropout

- **Standard SFT:** All samples have full reasoning traces ().
- **Thought Dropout:** Randomly **remove reasoning traces** during SFT.
- Skipped samples use just `<answer>...</answer>`.
- **Benefit:** Introduces the possibility for the model to “skip thinking”.

Pseudo-code for Thought Dropout

```
if random() < dropout_prob: thought = "\n\n"
```



Method: Reverse Thinking for Thought Data

- How to get high-quality “thoughts” for SFT?
- **Reverse Thinking:** Let the model generate its own reasoning traces by prompting it with inputs AND ground truth answer.
- No external models needed; self-consistent.

Reverse Thinking Prompt

Given (image, question, answer) → generate reasoning process for deriving the answer, but **do not output the answer itself**.



Method: RL via Group Relative Policy Optimization (GRPO)

- **In RL phase:** Let model explore **when to skip reasoning**.
- Sample diverse responses, some with, some without thoughts.
- Use group reward statistics to encourage **short, correct answers** when “thinking” isn’t needed.
- **Reward:** Correctness + Format.

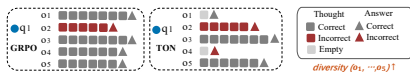


Figure 3: GRPO with TON: Promotes diverse outputs by allowing both “think” and “skip” responses.



Experimental Method

■ Questions:

- Q1 Does skipping reasoning improve efficiency and performance?
- Q2 How does the skip ratio evolve during training? Any trend with model or task difficulty?
- Q3 Is SFT with dropout necessary, or can prompting alone suffice?

■ Benchmarks: (see next slide)

- Counting—CLEVR, Super-CLEVR
- Math—GeoQA, GSM8K
- Mobile Navigation—AITZ



Experimental Setting

■ Datasets:

- **Counting:** CLEVR, Super-CLEVR
- **Math:** GeoQA, GSM8K
- **Navigation:** AITZ (incl. OOD splits)

■ Models: Qwen-2.5-VL-Instruct-3B/7B

■ Environments: 8 NVIDIA H20 GPUs, vLLM acceleration.

■ Evaluation Metrics: Accuracy, output/completion length, training time, exact match/type match for navigation.

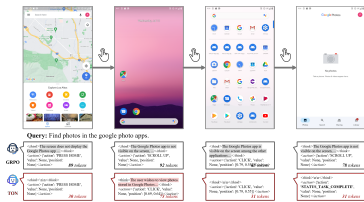


Figure 4: AITZ multi-step mobile navigation task illustration.



Dataset Summary

Benchmark	Model	OOD	Type	Difficulty	Answer	Thought len.
GSM8K	LLM		Math	Hard	Number	939
CLEVR	VLM		Counting	Easy	Integrate	586
Super-CLEVR	VLM	✓	Counting	Easy	Integrate	–
GeoQA	VLM		Math	Hard	Number	1652
AITZ	Agent		GUI	Medium	Action	283

Table 1: Benchmarks used in our evaluation.



Experimental Results: Efficiency and Accuracy

- **TON** achieves massive reduction in output length.
- **No loss in accuracy**, some cases even improve!
- Works across tasks and model sizes.

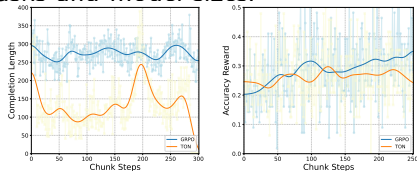


Figure 5: TON shortens answers (left), keeps reward high (right).

	CLEVR			GeoQA		
	Acc.	Time	Len.	Acc.	Time	Len.
Baseline	64.0	-	306	36	-	924
GRPO	93.5	1h44m	227	37	2h50m	272
TON	98.5	57m	28	51	2h04m	96

Table 2: TON vs. GRPO: output length drops by up to 90%; accuracy improves.



Experimental Results: Multi-Step Navigation (AITZ)

- **TON** generalizes to OOD GUI domains, saves tokens, maintains accuracy.
- **Token-saving**: Reduces task-level output from 3.6K to 0.9K tokens.
- Improves exact/action accuracy in several OOD domains.

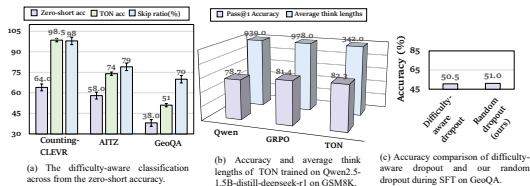
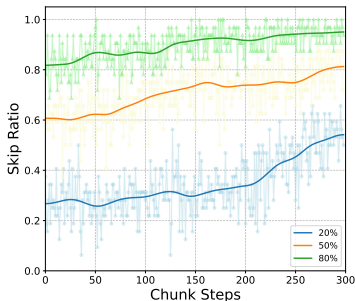


Figure 6: TON adapts to task difficulty; high skip for easy, low skip for hard.



Ablation Study: Thought Dropout and Prompting

- **Skip-think Ratio:** Increases as reward rises—model **learns when to skip**.
- **Dropout Ratio:** Different ratios examined (20%, 50%, 80%); all work, low ratios give rapid skip increase.
- **Prompting vs. SFT:** Prompting alone insufficient—SFT with dropout is crucial.





Deficiencies & Discussion

- Only tested on open-source VLMs at moderate scale (3B, 7B).
- Large proprietary VLMs (GPT-4o, etc.) not evaluated due to access limitation.
- Some hard tasks (e.g., AIME, coding) left for future study.
- Potential bias/noise in “difficulty-aware” dropout; random dropout preferred for generalization.



Future Work

- **Scale up:** Apply TON to larger VLMs and more hard tasks (e.g., code, AIME).
- **Domain generalization:** More OOD evaluations.
- **Reward design:** Explore richer reward schemes for selective reasoning.
- **Application:** Deploy in real-time systems needing fast, efficient reasoning (e.g., mobile agents).

Code: <https://github.com/kokolerk/TON>

Thank you!

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