

Online Robust Locally Differentially Private Learning for Nonparametric Regression

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Online Private Nonparametric Regression

Motivation

- Streaming data in autonomous systems, wearables, and healthcare require **real-time, privacy-preserving models**.
- Batch-based nonparametric methods are **unsuitable for large-scale or continuous data**.
- **Outliers and heavy-tailed noise** in streaming data hinder model reliability.
- Achieving **local differential privacy (LDP)** remains difficult beyond centralized or low-dimensional settings.

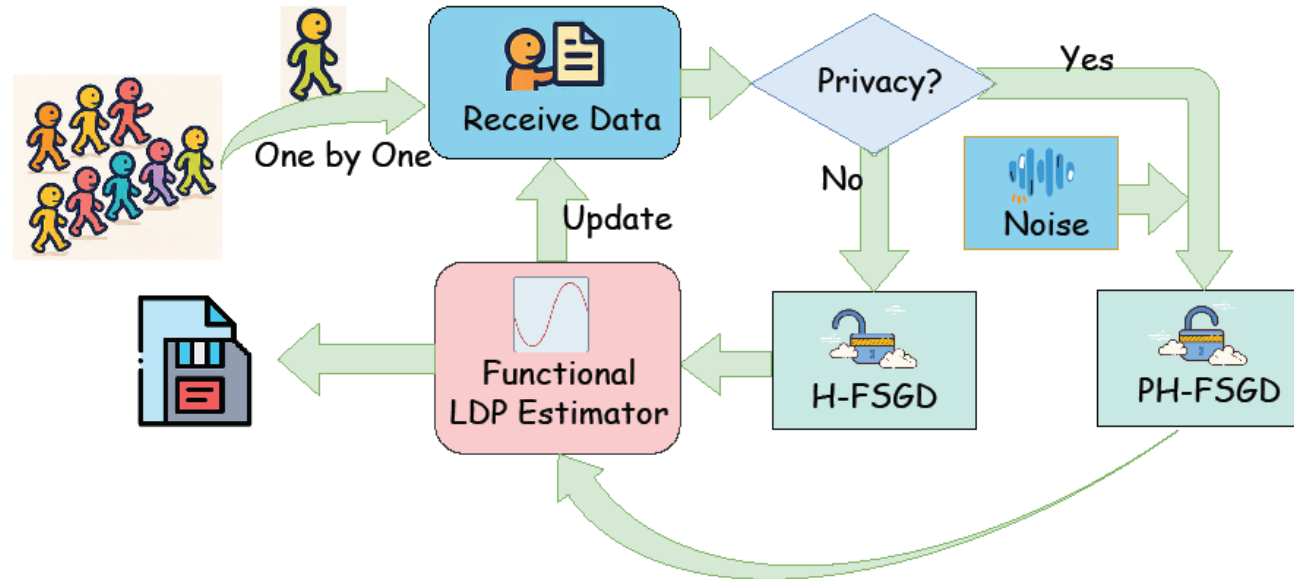
Table 1: A comparison of recent results on nonparametric regression.

| Method | Online | One-pass | Robust | Optimal rate | Privacy |
|----------------------------|--------|----------|--------|--------------|---------|
| Hall et al. [2013] | ✗ | ✗ | ✗ | ? | ✓ |
| Dieuleveut and Bach [2016] | ✓ | ✓ | ✗ | ✓ | ✗ |
| Liu et al. [2023] | ✓ | ✓ | ✗ | ✓ | ✗ |
| Quan and Lin [2024] | ✓ | ✓ | ✗ | ✓ | ✗ |
| Proposed | ✓ | ✓ | ✓ | ✓ | ✓ |

Models and Problem Formulation



Goal



- Develop an **online**, **private**, nonparametric regression framework that is **robust** to heavy-tailed noise and satisfies **LDP**.
- Study **non-asymptotic convergence** guarantees and identify **optimal step-size** schedules.

Models and Problem Formulation



Setup

- The observed data are streaming samples $\{(X_n, Y_n)\}_{n=1}^{\infty}$ generated from the model $Y_n = f^*(X_n) + e_n$.

- The best reproducing kernel Hilbert space (RKHS) approximation:

$$f_{\mathcal{H}} := \operatorname{argmin}_{f \in \bar{\mathcal{H}}} \mathbb{E} \left[(Y - f(X))^2 \right].$$

- Our objective is to develop a computationally efficient, single-pass sequence of estimators for $f_{\mathcal{H}}$.
- To address robustness in the presence of heavy-tailed noises and to facilitate private updates, consider the Huber regression in an RKHS:

$$\min_{f \in \mathcal{H}} \mathbb{E} L_{\tau}(Y - f(X)),$$

where $L_{\tau}(u) = \frac{1}{2}u^2 \mathbb{I}\{|u| \leq \tau\} + (\tau|u| - \frac{1}{2}\tau^2) \mathbb{I}\{|u| > \tau\}$.

Methodology



Private Huber Functional SGD

Algorithm 1 PH-FSGD

- 1: **Input:** The streaming data $\{(X_n, Y_n)\}_{n \in \mathbb{N}}$, the initial estimates $\bar{f}(\cdot) = \hat{f}(\cdot) = 0$, the step size sequences $\{\gamma_n\}_{n \in \mathbb{N}}$, the tuning parameter $\tau > 0$, the reproducing kernel K , the bounded parameter $B > 0$, the privacy parameters $\{\varepsilon_n\}_{n \in \mathbb{N}}$, $\{\delta_n\}_{n \in \mathbb{N}}$, and the function grids $\{t_j\}_{j=1}^J$.
- 2: **for** $n = 1, 2, \dots$ **do**
- 3: Generate the noise $\{\xi_n(t_j)\}_{j=1}^J$ from $N_J(\mathbf{0}, \frac{8\tau^2 B^2 \log(2/\delta_n)}{\varepsilon_n^2} K^{(t)})$, where $K^{(t)}$ is a $J \times J$ matrix with its components $(K^{(t)})_{ij} = K(t_i, t_j)$.
- 4: Calculate the residual: $\text{res}_n = Y_n - \langle \hat{f}_{n-1}, K_{X_n} \rangle_{\mathcal{H}}$.
- 5: Perform the noisy gradient descent at each function grid t_j for $j = 1, \dots, J$ as follows.
- 6: **if** $|\text{res}_n| \leq \tau$
- 7: **then** $\hat{f}_n(t_j) = \hat{f}_{n-1}(t_j) + \gamma_n \text{res}_n K(X_n, t_j) + \gamma_n \xi_n(t_j)$.
- 8: **elseif** $\text{res}_n > \tau$
- 9: **then** $\hat{f}_n(t_j) = \hat{f}_{n-1}(t_j) + \gamma_n \tau K(X_n, t_j) + \gamma_n \xi_n(t_j)$.
- 10: **else** $\hat{f}_n(t_j) = \hat{f}_{n-1}(t_j) - \gamma_n \tau K(X_n, t_j) + \gamma_n \xi_n(t_j)$.
- 11: Update \bar{f}_n at each function grid:

$$\bar{f}_n(t_j) = \frac{n-1}{n} \bar{f}_{n-1}(t_j) + \frac{1}{n} \hat{f}_n(t_j), j = 1, \dots, J.$$

- 12: **end for**
 - 13: **Output:** The estimators $\{\bar{f}_n(t_j)\}_{j=1}^J$ at each function grid t_j and each iteration n .
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Theory



Constant Step Size Scheme

Table 3: Constant step size: optimal ζ and convergence rates.

| r range | Optimal ζ in $\gamma_i \asymp n^{-\zeta}$ | Private / non-private convergence rate |
|-------------------------------|---|--|
| $(0, (\alpha - 1)/(2\alpha)]$ | 0 | $O(n^{-2r})$ |
| $((\alpha - 1)/(2\alpha), 1]$ | $(2r\alpha + 1 - \alpha)/(2r\alpha + 1)$ | $O(n^{-2r\alpha/(2r\alpha+1)})$ |
| $(1, (\alpha + 2)/2]$ | $(\alpha + 1)/(2r\alpha + 1)$ | $O(n^{-(2r\alpha-2r+2)/(2r\alpha+1)})$ |
| $((\alpha + 2)/2, \infty)$ | $1/(1 + \alpha)$ | $O(n^{-\alpha/(1+\alpha)})$ |



Non-constant Step Size Scheme

Table 4: Non-constant step size: optimal ζ and convergence rates.

| r range | Optimal ζ in $\gamma_i \asymp n^{-\zeta}$ | Private / non-private convergence rate |
|--|---|---|
| $(0, (\alpha - 1)/(2\alpha)]$ | 0 | $O(n^{-2r})$ |
| $((\alpha - 1)/(2\alpha), (1 + \alpha)/(2\alpha))$ | $(2r\alpha + 1 - \alpha)/(2r\alpha + 1 + \alpha)$ | $O(n^{-(2r\alpha+\alpha-1)/(2r\alpha+1+\alpha)})$ |
| $[(1 + \alpha)/(2\alpha), \infty)$ | $1/(1 + \alpha)$ | $O(n^{-\alpha/(1+\alpha)})$ |

Experiment



Non-Private Synthetic Data

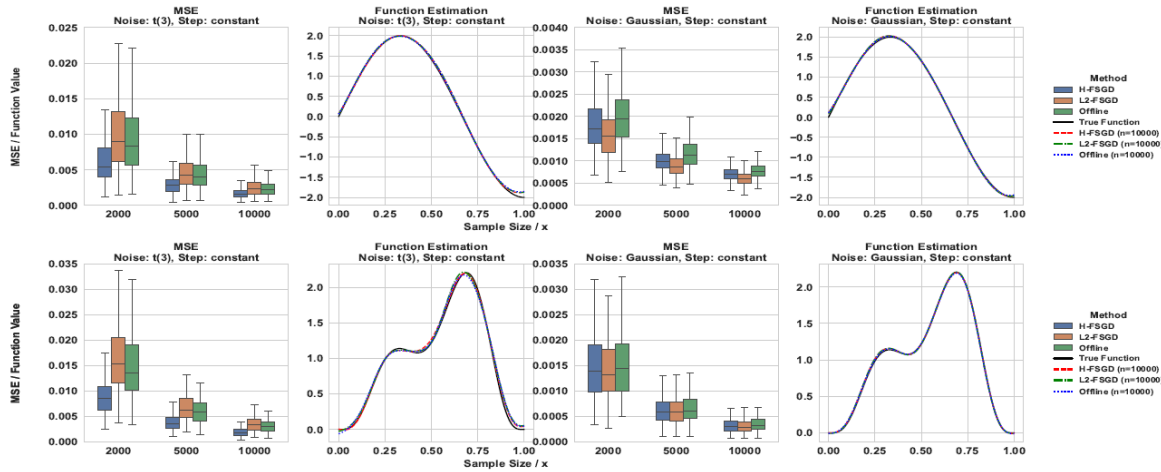


Figure 2: Box-plots and function fitting plots for Case 1 (top panels) and Case 2 (bottom panels) with the constant step size scheme in Example 5.1.



Private Synthetic Data

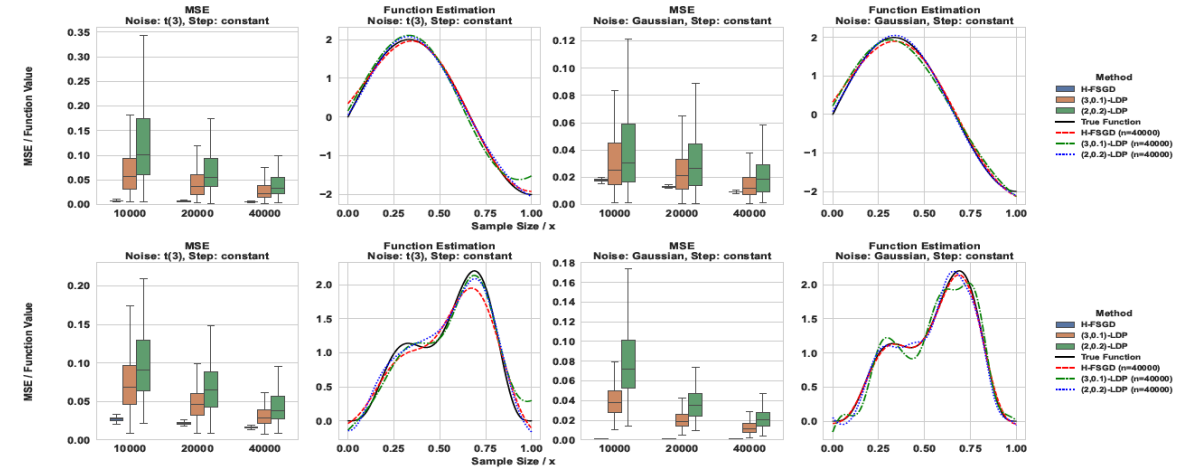


Figure 3: Box-plots and function fitting plots for Case 1 (top panels) and Case 2 (bottom panels) with the constant step size scheme in Example 5.2.

- The proposed H-FSGD method significantly outperforms the least-squares-based FSGD under heavy-tailed noises.
- PH-FSGD can still recover the true function shape well, even under strong privacy constraints.
- Stronger privacy enhances protection but also leads to greater estimation error and slower convergence.

Takeaway Notes

- **Online Robust LDP Estimation Framework**

Develop an online robust LDP framework enabling per-iteration privacy guarantees and outlier-resistant real-time nonparametric regression in dynamic environments.

- **One-pass Algorithms**

Propose two one-pass algorithms, H-FSGD and PH-FSGD, that achieve $O(1)$ time and space complexity per iteration without storing past observations.

- **Non-asymptotic Analysis**

Establish comprehensive non-asymptotic convergence guarantees and identify optimal step-size schedules that achieve minimax-optimal rates.

Thank You!