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Topology-Aware Learning of Tubular Manifolds via SE(3)-Equivariant Network on Ball B-Spline Curve

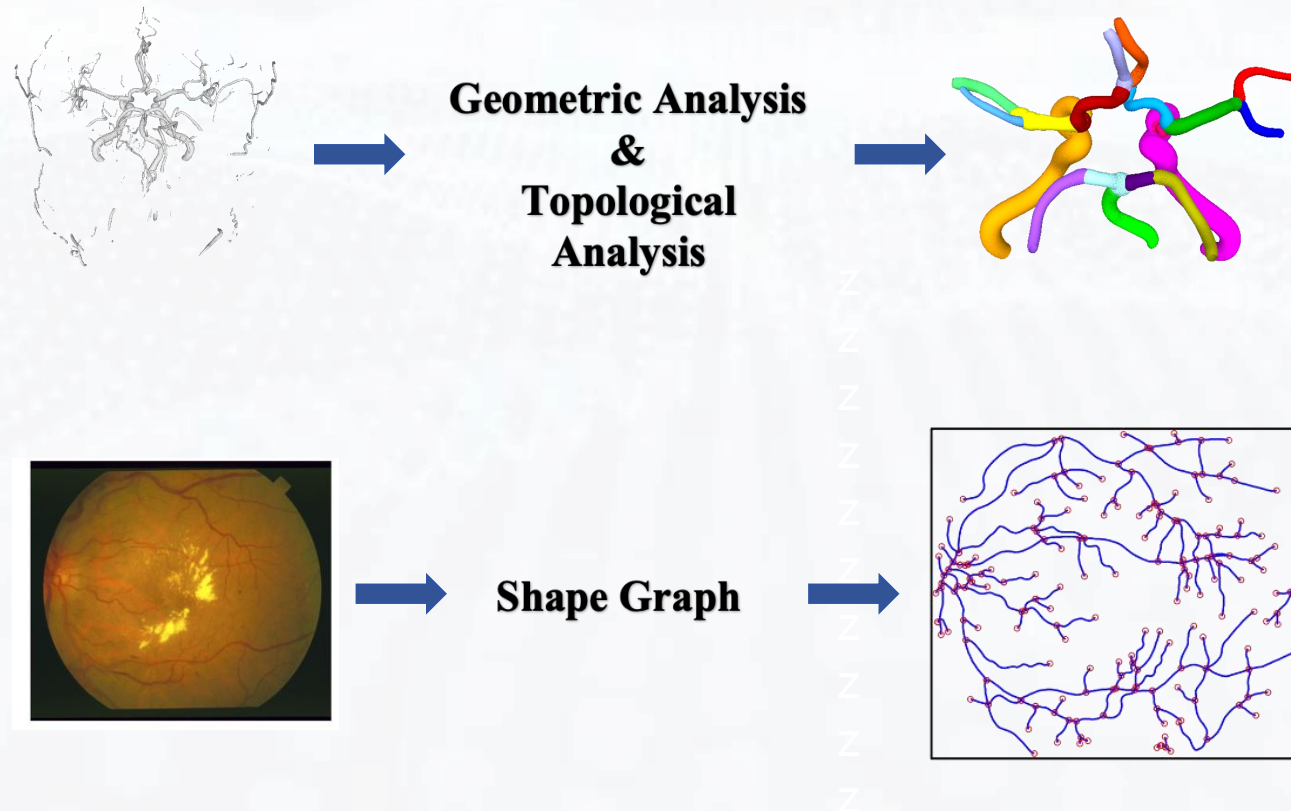
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Background of Tubular Structure Analysis

- Medical image processing (2D & 3D images)
 - Local geometric feature analysis (arc length, normal, curvature)
 - Topological relationship analysis

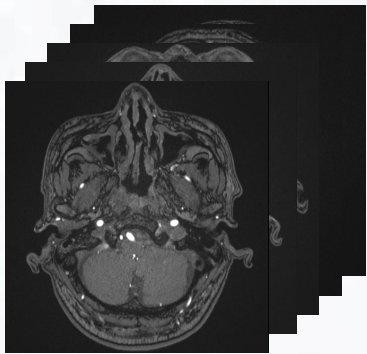


Challenge & Motivation

- Data discretization (Pixels, voxels, point clouds, meshes)
 - Loss of local geometric details
 - High-precision geometric features require large scale, high-resolution data



- Parameterized manifolds
 - Continuously and differentiable, allowing for the determination of precise geometric properties
 - Low storage and computing costs
 - Rigorous theoretical analysis can be performed



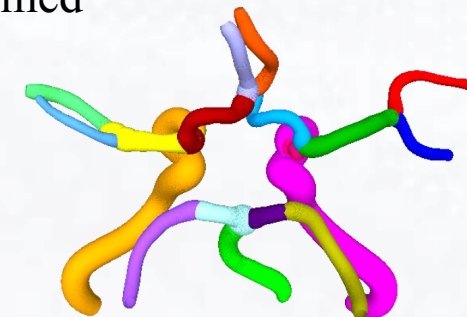
Voxel



Point cloud



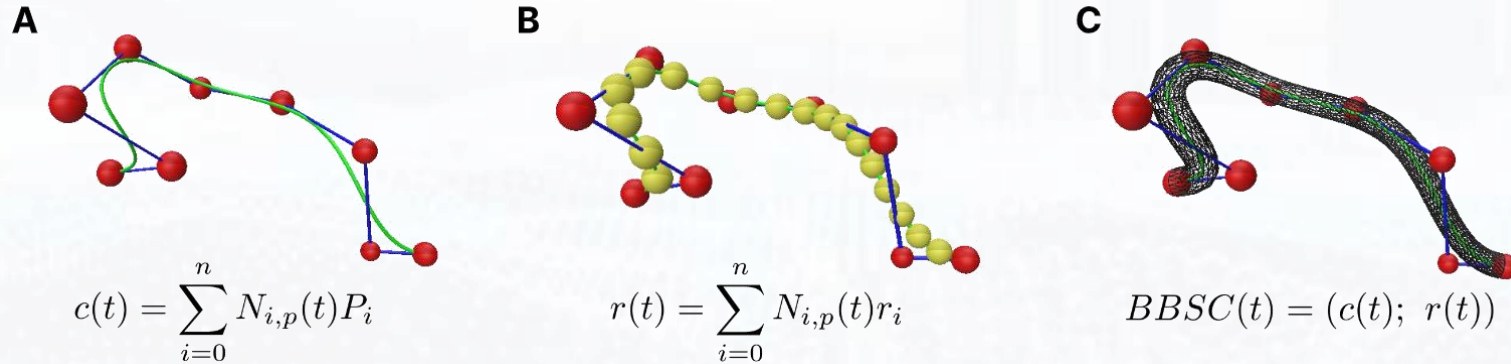
Mesh



Ball B-Spline Curve

- Ball B-Spline Curve (BBSC)

$$BBSC(t) = \sum_{i=0}^n N_{i,p}(t) C_i = \sum_{i=0}^n N_{i,p}(t) (P_i ; r_i) = \left(\sum_{i=0}^n N_{i,p}(t) P_i ; \sum_{i=0}^n N_{i,p}(t) r_i \right) \quad (\text{Abbreviated as } \beta)$$



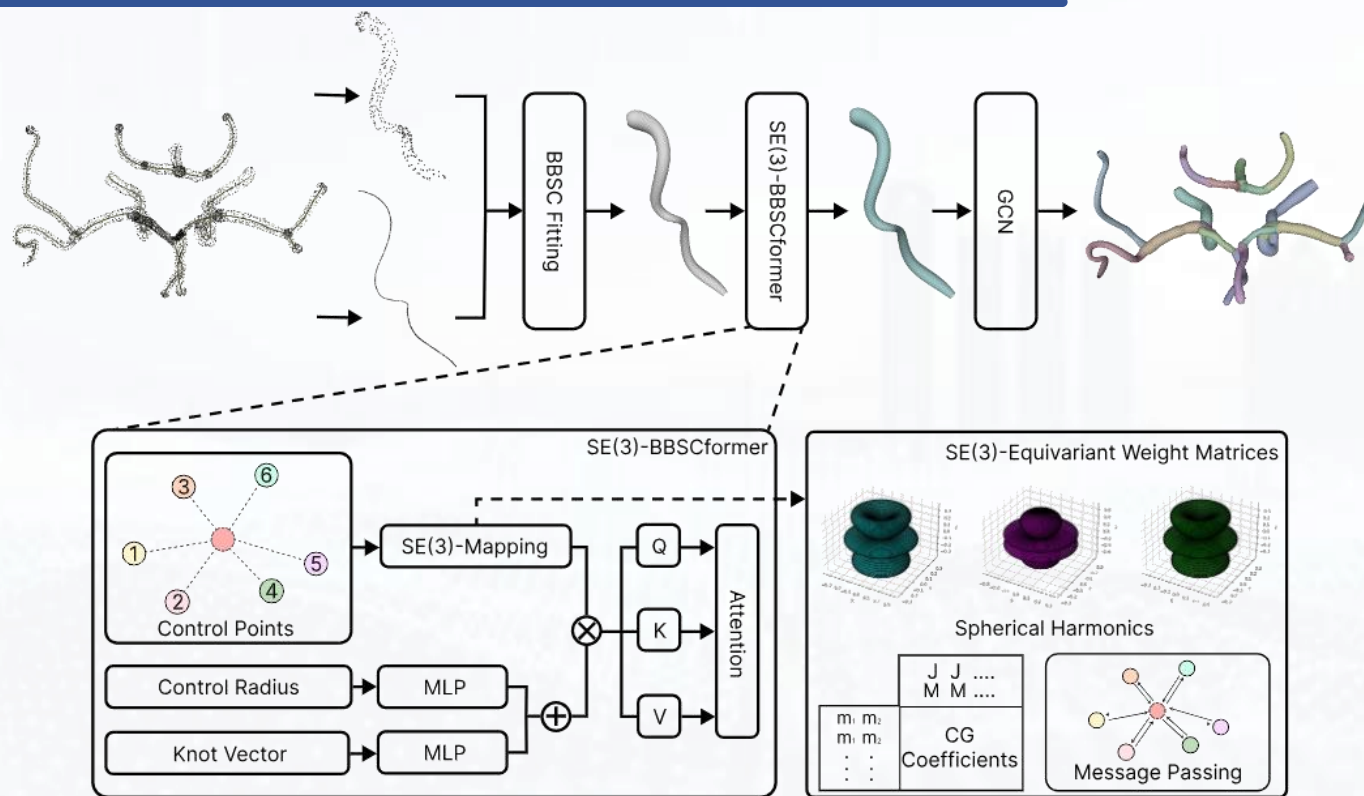
A smooth tubular surface, which can be viewed as a 2D manifold coordinated by u and v.

- Ball B-Spline Curve functional space

$$\mathcal{M}_p = \{\beta(P, r, \tau) \mid (P, r, \tau) \in \Theta\}, \quad \Theta = \{P \in \mathbb{R}^{3 \times n}, r \in \mathbb{R}_{>0}, \tau \in \mathbb{T}\}$$

- Ball B-Spline Curve topological structure

$$\mathcal{GM} = \left(\bigsqcup_{i \in I} \beta_i \right) / \sim, \quad \sim \subseteq \bigsqcup_{i \in I} \beta_i \times \bigsqcup_{i \in I} \beta_i$$



- BBSC fitting

- Input: surface point, centerline
- Output: control parameters, knot vectors
(Fitting scattered data points with ball b-spline curves using particle swarm optimization)

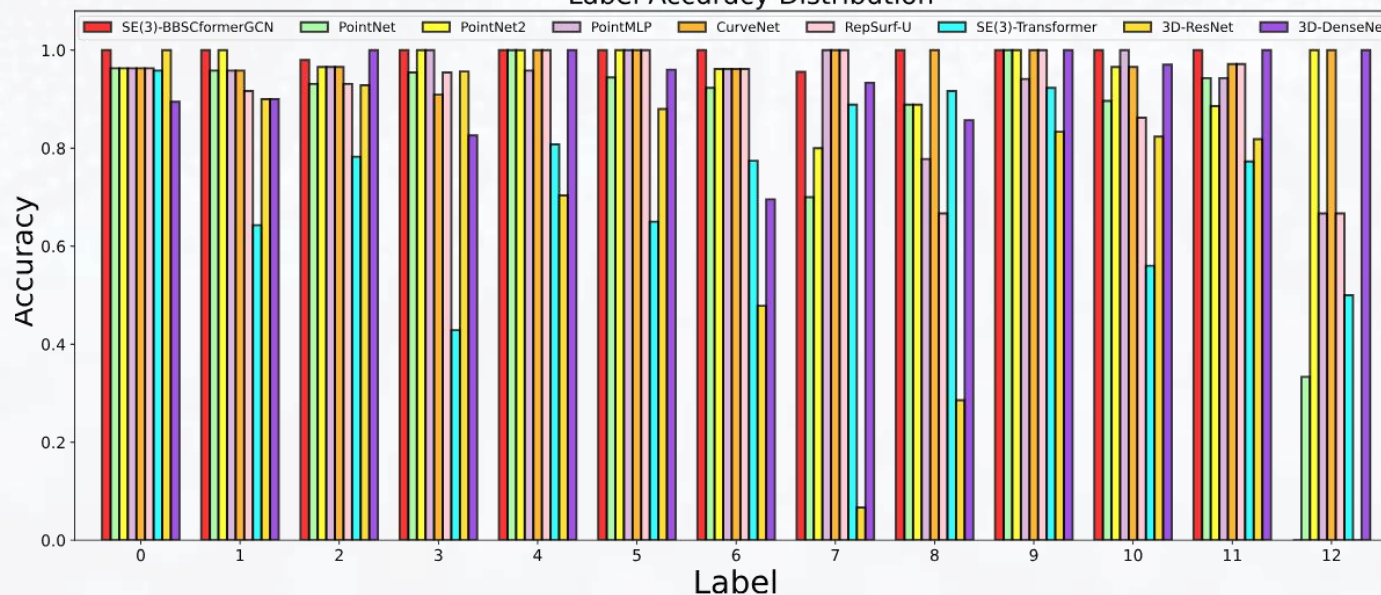
- SE(3)-BBSCformer

- Input: $f_{in}^{c_{i0}} = (MLP(r), MLP(\tilde{r}))$, $\tilde{r} = ((t_1, \dots, t_{p+1}), \dots, (t_n, \dots, t_{n+p+1})) \in \mathbb{R}^{n \times (p+1)}$
- Output: $\vec{q}_i = \bigoplus_{c_o} \sum_{c_i} W_Q^{c_o c_i} f_{in,i}^{c_i}$, $\vec{k}_j = \bigoplus_{c_o} \sum_{c_i} W_K^{c_o c_i} (P_j - \bar{P}) f_{in,j}^{c_i}$, $\alpha_{ij} = \frac{\exp(\vec{q}_i^T \vec{k}_j)}{\sum_{j=1}^n \exp(\vec{q}_i^T \vec{k}_j)}$

$$f_{out,i}^{c_o} = W_V^{c_o c_o} f_{in,i}^{c_o} + \sum_k \alpha_{i,j} W_V^{c_o c_i} (P_i - \bar{P}) f_{in,j}^{c_i}$$

Per-class classification accuracy

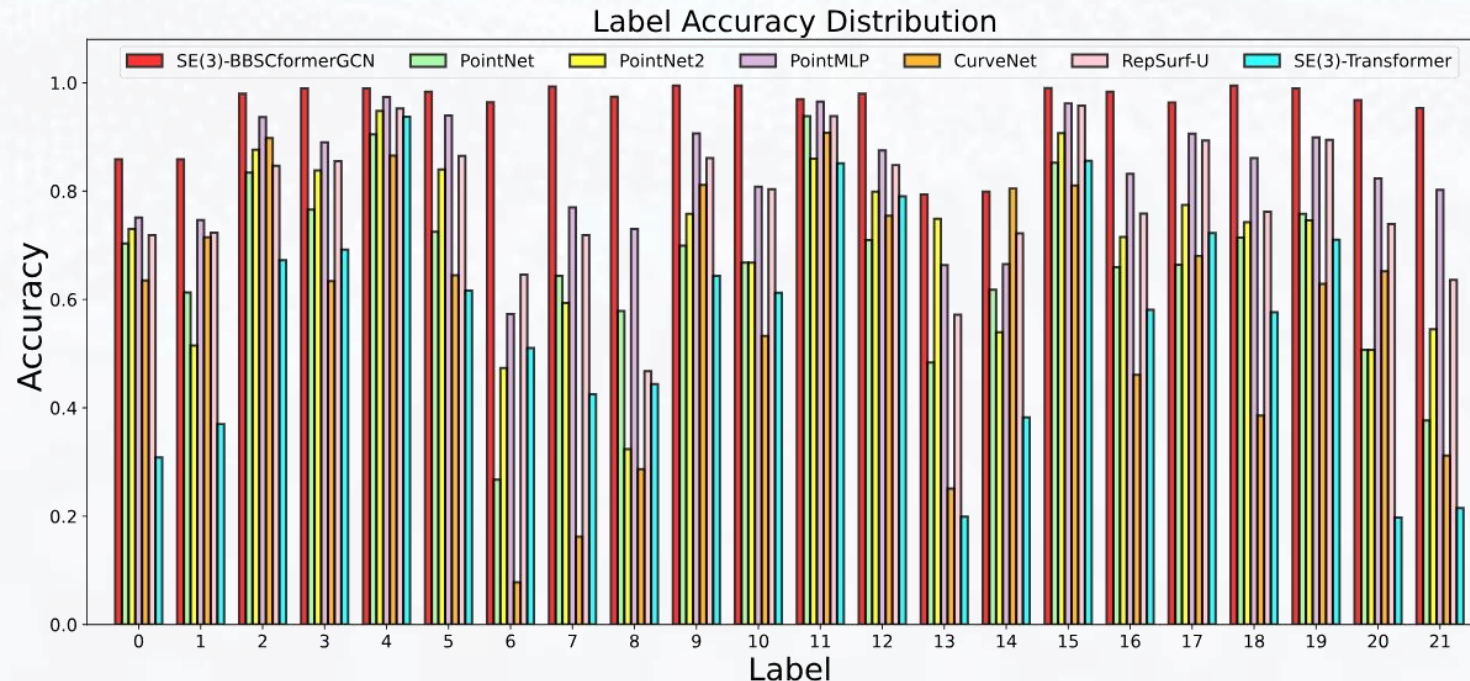
Label Accuracy Distribution



Classification performance

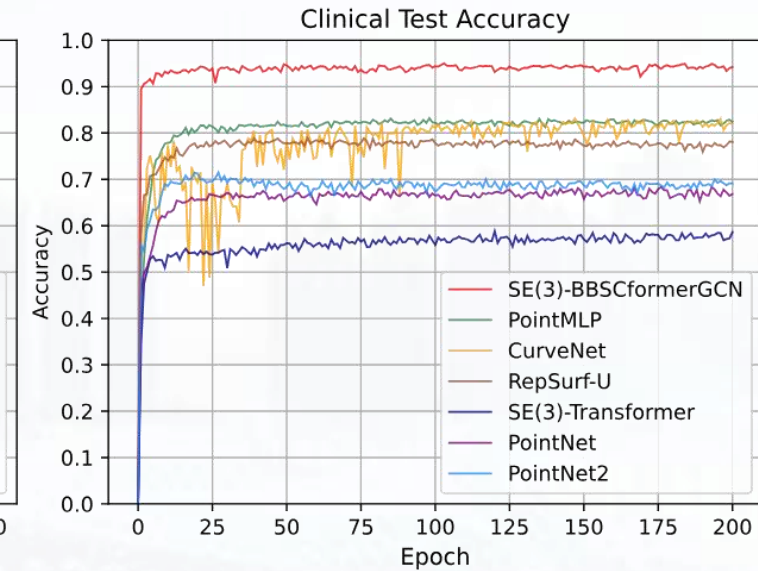
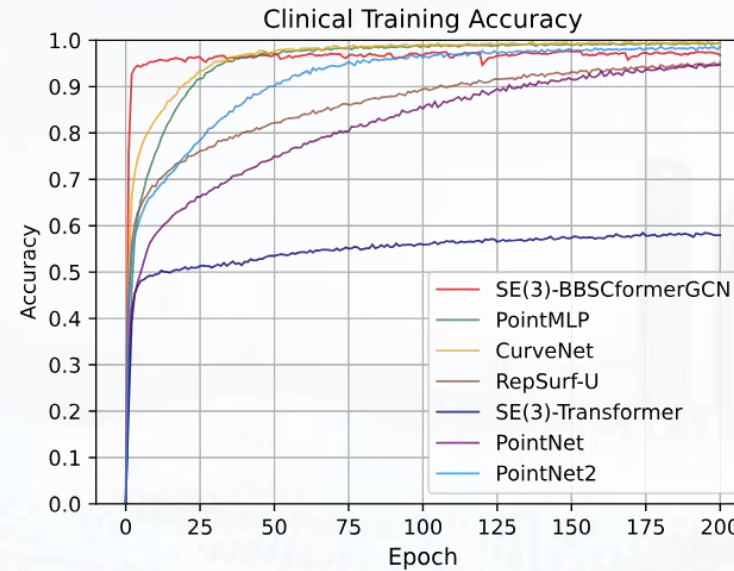
Method	Accuracy%	AUC-ROC%	Precision%	Recall%	F1 Score%
PointNet [24]	69.20 \pm 0.98	96.50 \pm 0.24	70.02 \pm 0.77	69.17 \pm 0.96	68.90 \pm 1.02
PointNet++ [55]	70.27 \pm 0.16	96.60 \pm 0.17	70.82 \pm 0.43	70.28 \pm 0.20	70.05 \pm 0.14
CurveNet [56]	81.91 \pm 0.14	93.80 \pm 1.13	62.92 \pm 3.14	60.13 \pm 4.25	58.51 \pm 4.58
RepSurf-U [57]	78.22 \pm 0.17	98.40 \pm 0.11	78.34 \pm 0.28	77.99 \pm 0.29	78.00 \pm 0.25
PointMLP [58]	82.70 \pm 0.10	98.66 \pm 0.06	82.86 \pm 0.14	82.70 \pm 0.10	82.67 \pm 0.14
SE(3)-Transformer [30]	61.96 \pm 1.45	92.32 \pm 0.96	61.05 \pm 2.07	61.94 \pm 1.47	60.77 \pm 2.57
SE(3)-BBSCformer	71.06 \pm 1.39	93.25 \pm 0.60	70.25 \pm 1.16	71.04 \pm 1.39	70.45 \pm 1.21
BBSCformerGCN	95.45 \pm 1.09	99.34 \pm 0.21	95.10 \pm 1.48	95.38 \pm 1.13	95.23 \pm 1.29
SE(3)-BBSCformerGCN	96.11 \pm 1.01	99.38 \pm 0.19	96.11 \pm 0.93	96.08 \pm 0.97	96.02 \pm 1.05

Per-class classification accuracy



Training Efficiency, Stability, and Computational Cost

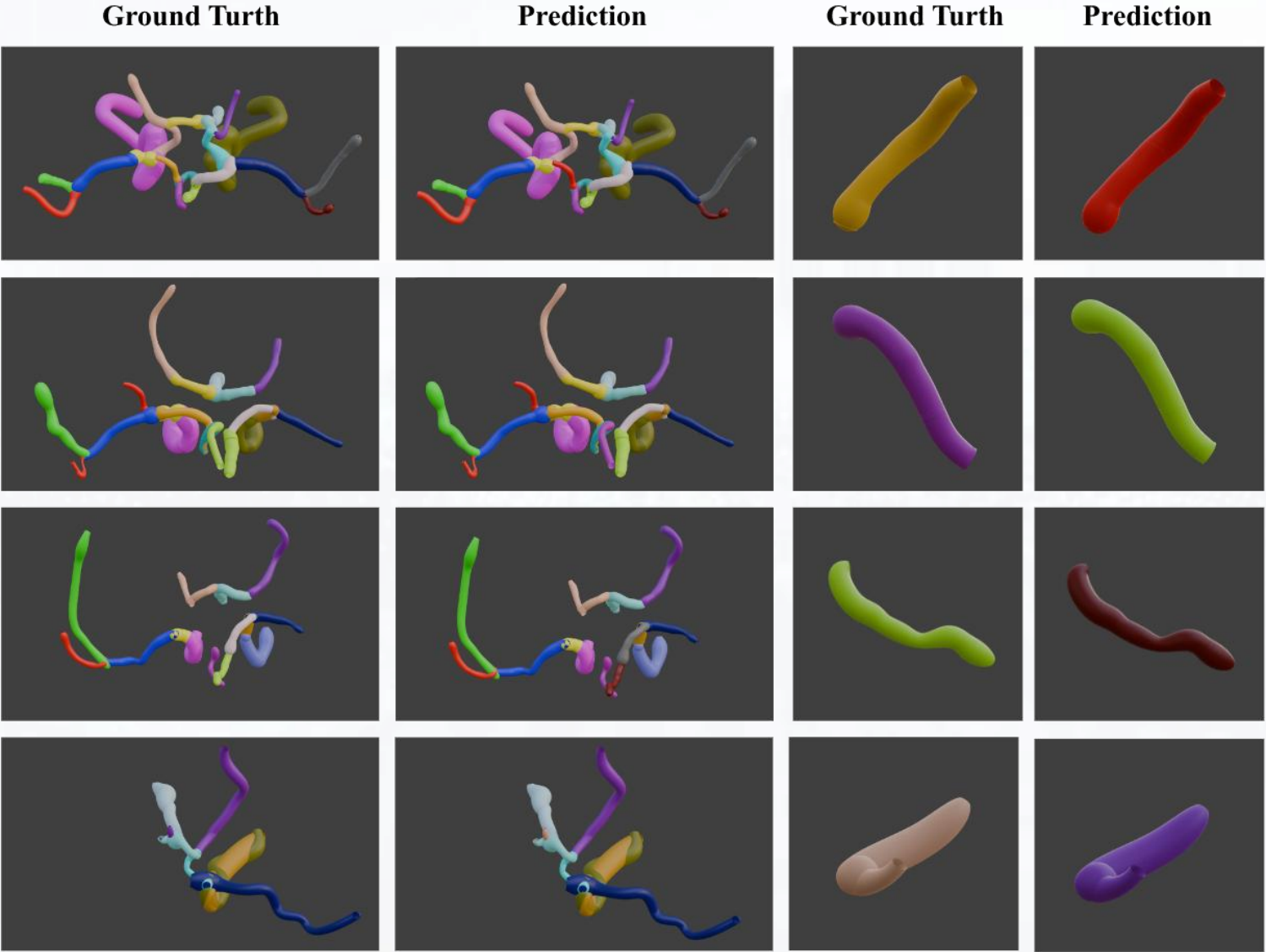
- Training
 - Convergence speed
 - Training stability
 - Resistance to overfitting



- Computational Cost
 - Evaluation time (ms)
 - FLOPS
 - Model parameters

Method	Evaluation Time(ms)	FLOPs(M)	Parameters(M)
3D DenseNet [53]	8.03	9743.76	18.56
3D ResNet [54]	10.95	11463.08	85.23
PointNet [24]	0.88	450.38	3.46
PointNet++ [55]	1.54	4067.53	1.74
CurveNet [56]	81.95	269.56	2.13
RepSurf-U [57]	59.84	911.32	1.48
PointMLP [58]	38.39	15733.95	13.23
SE(3)-Transformer [30]	19.03	456.33	0.12
SE(3)-BBSCformer	1.92	1.72	0.35
BBSCformerGCN	1.14	88.98	3.60
SE(3)-BBSCformerGCN	3.02	59.01	2.70

Case Study and Failure Case



- Conclusion
 - Using BBSC to analyze tubular structure, and a functional space is constructed for this type of tubular manifold.
 - An analytical method is constructed that uses $SE(3)$ isovariant mapping to analyze BBSC and graph convolution to process the topology of tubular topological manifolds.
 - Achieves superior accuracy in Circle of Willis branch classification.
- Acknowledgements
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