

## Interactive Cross-modal Learning for Text-3D Scene Retrieval

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**Time:** Thu, Dec 4 · 2:40–3:00 a.m. CST **Location:** Upper Level – Ballroom 6CDEF



### **Contents**



- 1 Overview of Our Work
- 2 Background
- **3** Method: Interactive Text-3D Scene Retrieval Method
  - > Interactive Retrieval Refinement framework (IRR)
  - Interaction Adaptation Tuning strategy (IAT)
- 4 Experiments



### **Contents**



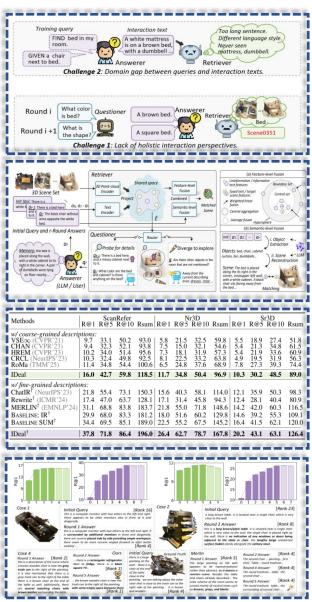
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### Overview of Our Work



- We propose a novel Interactive Text-3D Scene Retrieval Method (IDeal), which actively enhances alignment between text queries and 3D scenes through ongoing interactions.
- An Interactive Retrieval Refinement framework (IRR) is presented to enable a deep interaction for comprehensive scene exploration, leading to progressively improved retrieval.
- An Interaction Adaptation Tuning strategy (IAT) is proposed, which facilitates the transfer of the retriever to the interaction text domain, promoting improved interaction.
- We conduct extensive comparison experiments on text-3D scene datasets. Our IDeal remarkably outperforms the existing methods, demonstrating its superiority.



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### Text-3D Scene Retrieval





Text-3D Scene Retrieval (T3SR) requires methods to establish semantic correspondence between 3D scenes and texts, enabling the matching of the most relevant 3D scene instance from a comprehensive 3D scene set or atlas solely based on textual queries.







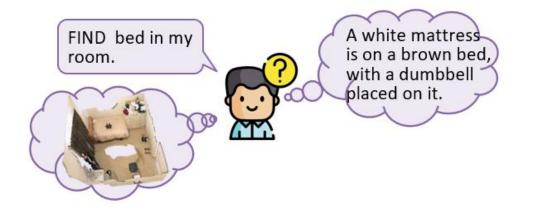
Retrieval-Enhanced Semantic Alignment in Robotic Navigation



Text-Driven Indexing for the Emerging 3D Data Ecosystem



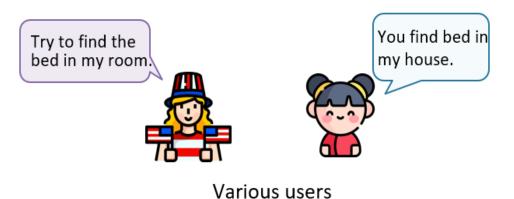




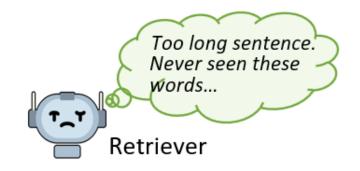
❖ Incomplete one-shot descriptions of user intent



Ambiguous descriptions

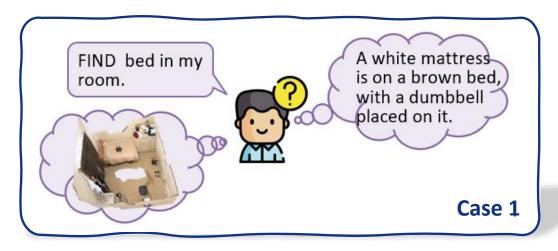


Domain shifts









Incomplete one-shot descriptions of user intent



Ambiguous descriptions



Domain shifts





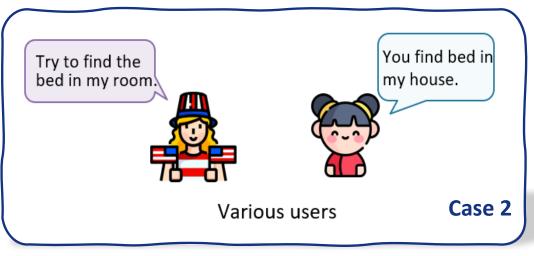




Incomplete one-shot descriptions of user intent



Ambiguous descriptions



Domain shifts

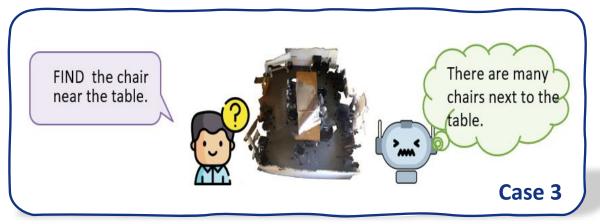




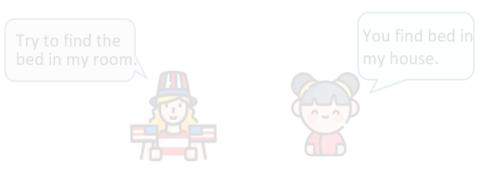




Incomplete one-shot descriptions of user intent



Ambiguous descriptions



Various users

Domain shifts







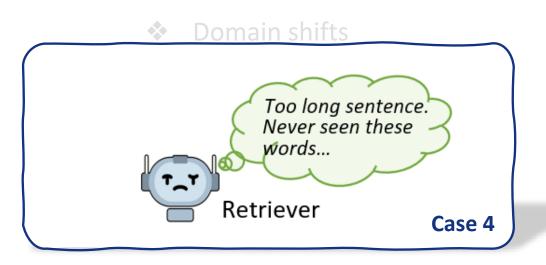


Incomplete one-shot descriptions of user intent



Ambiguous descriptions





Limited generalization of the models

Information-complete queries and static model limitations!

### Motivation





We can explore leveraging interactive retrieval with external agents (such as users or LLMs) to achieve a general solution for the above issues.

However, there are two key challenges in adapting existing interactive methods to Text-3D Scene retrieval.

### Motivation

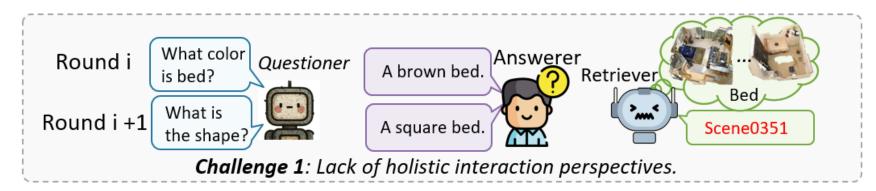




We can explore leveraging interactive retrieval with external agents (such as users or LLMs) to achieve a general solution for the above issues.

However, there are two key challenges in adapting existing interactive methods to Text-3D Scene retrieval.

Challenges in applying existing interactive methods.



### Motivation

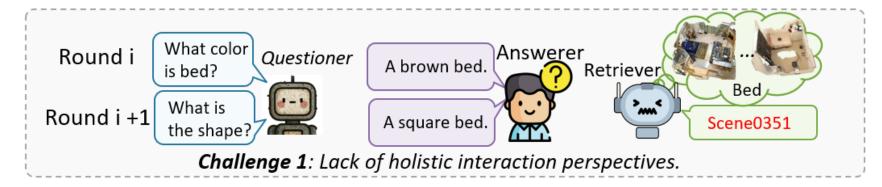




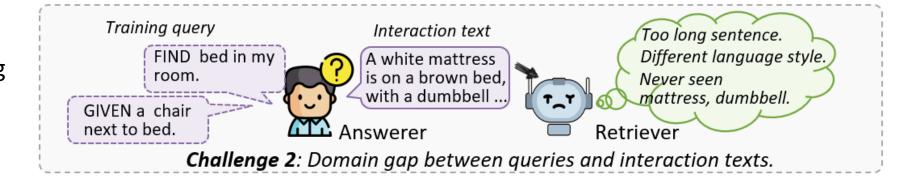
We can explore leveraging interactive retrieval with external agents (such as users or LLMs) to achieve a general solution for the above issues.

However, there are two key challenges in adapting existing interactive methods to Text-3D Scene retrieval.

Challenges in applying existing interactive methods.



Challenges in making existing static methods interactive.

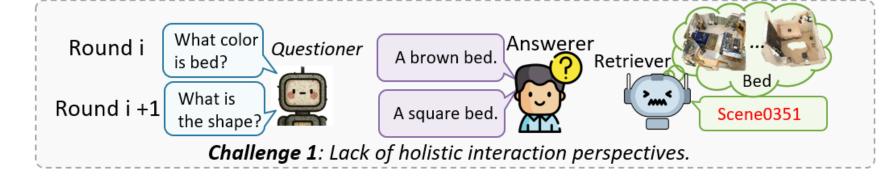


# Motivation: Challenge 1





Challenges in applying existing interactive methods



Diverge

Comparison between existing and ideal interactive descriptions:

#### **Existing interactive method**

**A1**: Locate a room that has a white bed with a black curtain beside it.

**A2**: Locate a room that has a white wooden bed with a dumbbell on it, and a black Limited wrinkled curtain beside it.

A3:Locate a room that has a big white wooden bed with a dumbbell on it, and d black wrinkled curtain next to it.

#### Ideal interaction

A1: Locate a room that has a white bed with a black curtain beside it.

**A2**: Locate a room that has a white wooden bed with a dumbbell on it, and a black wrinkled w elsewherecurtain beside it.

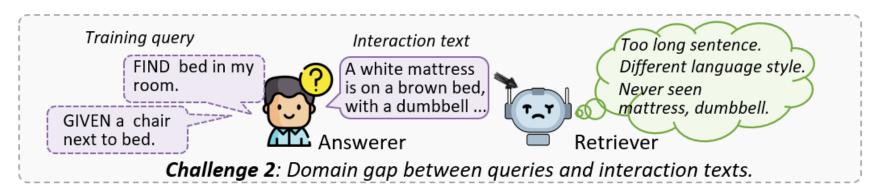
> A3: Locate a room that has a white wooden **bed** with **a dumbbell** on it, and **a black** wrinkled curtain beside it. Opposite the bed, there is a black chair next to a dressing table with a suitcase next to it.

# Motivation: Challenge 2

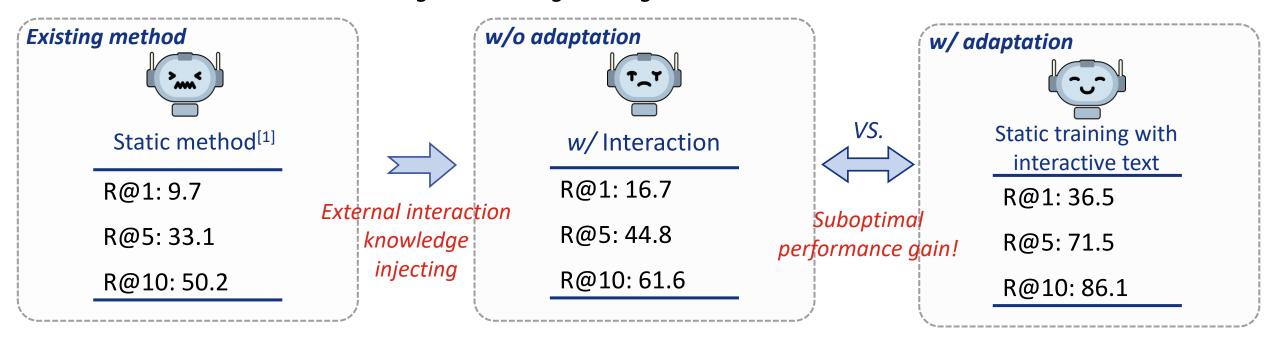




Challenges in making existing static methods interactive



### Challenges in making existing static methods interactive:



[1] Feng Y, Qin Y, Peng D, et al. Pointcloud-text matching: Benchmark dataset and baseline

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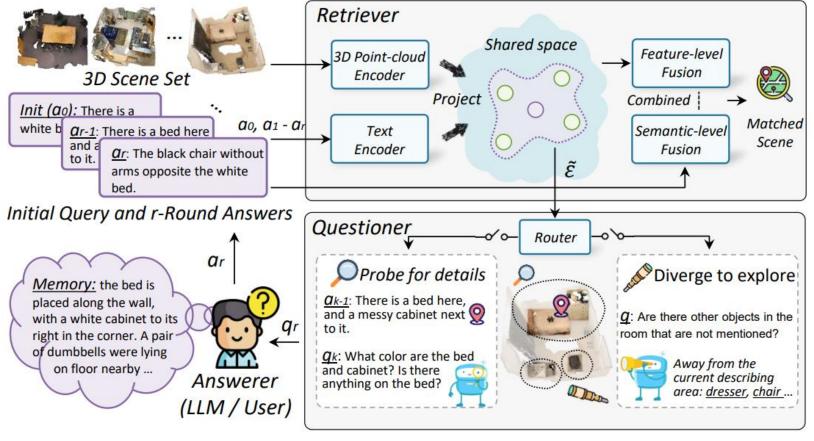


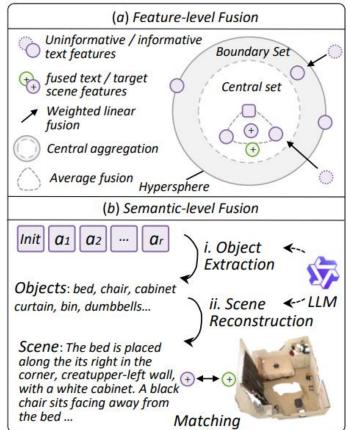






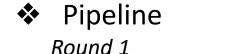






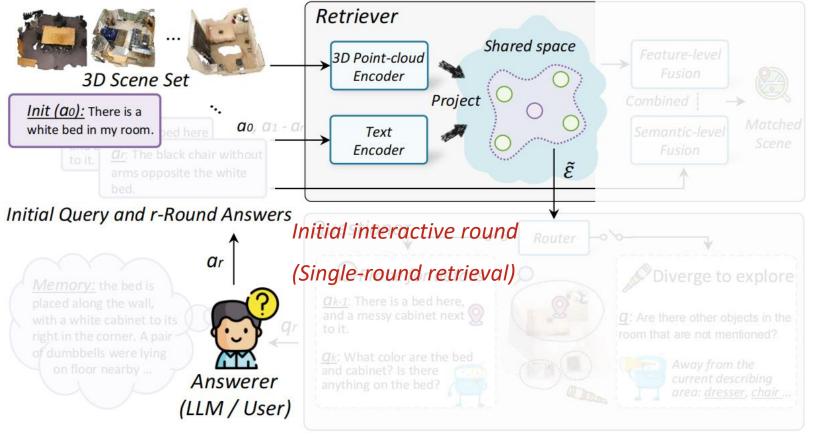


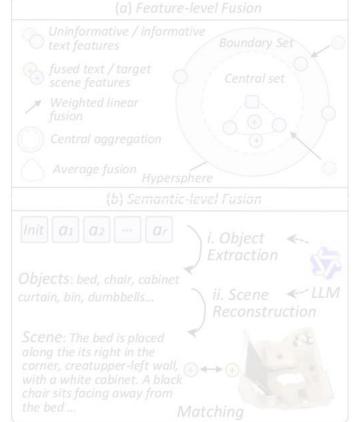




Questioner  $\xrightarrow{Ask}$  Answerer  $\xrightarrow{Answer}$  Retriever  $\xrightarrow{Matching}$ 

Round N



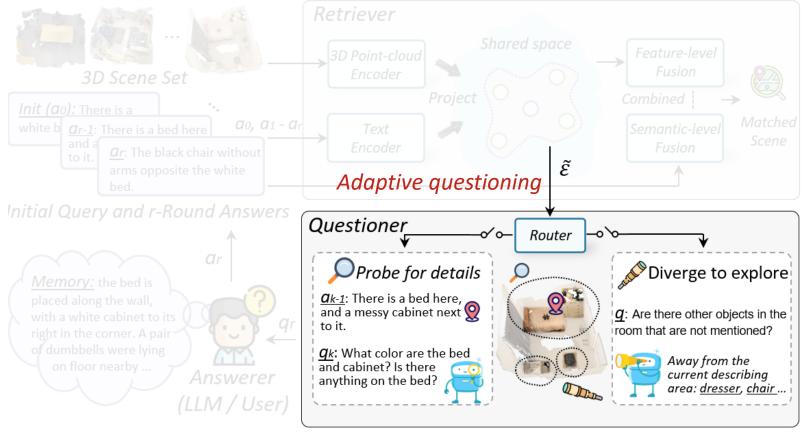


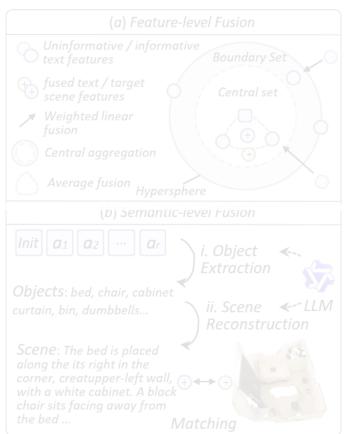
















### Questioner

#### Router

**Initial Query**: Locate a room that has a white bed with a black curtain beside it.

Density Compensated Affinity Entropy

$$\tilde{\mathcal{E}} \ \mathcal{E}(\boldsymbol{u}_i^{r-1}) = -\sum_{j \in N_k(\boldsymbol{u}_i^{r-1})} p(\boldsymbol{u}_i^{r-1}, \boldsymbol{v}_j) \log p(\boldsymbol{u}_i^{r-1}, \boldsymbol{v}_j)$$

Formulate response features whether aligned with the scene features.

$$\tilde{\mathcal{E}} > \beta$$

$$\tilde{\mathcal{E}} \leq \beta$$

### **Questioning**

# Probe for details $\mathcal{Q}_1$

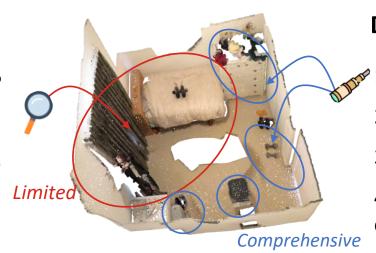


- 1) What material is the bed made of?
- 2) What's on the bed?
- 3) What are the characteristics of the curtains?





- 1) What object is in the distance from the bed?
  - 2) What object is opposite the bed?
  - 3) What object is to the right of the curtains?
  - 4) What are the characteristics of each of these objects?

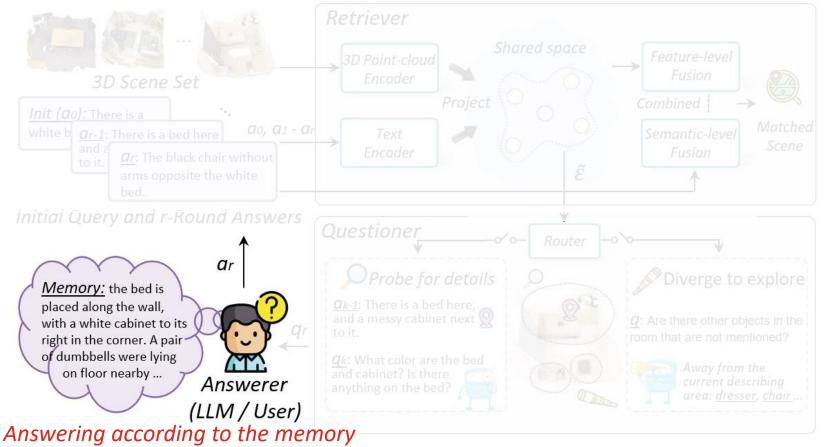


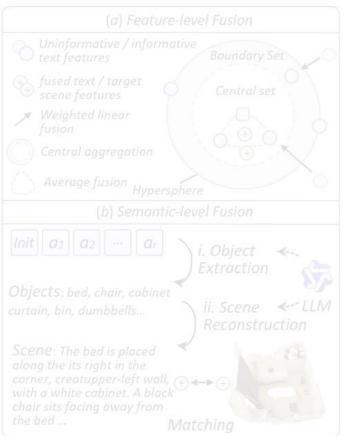




### Pipeline







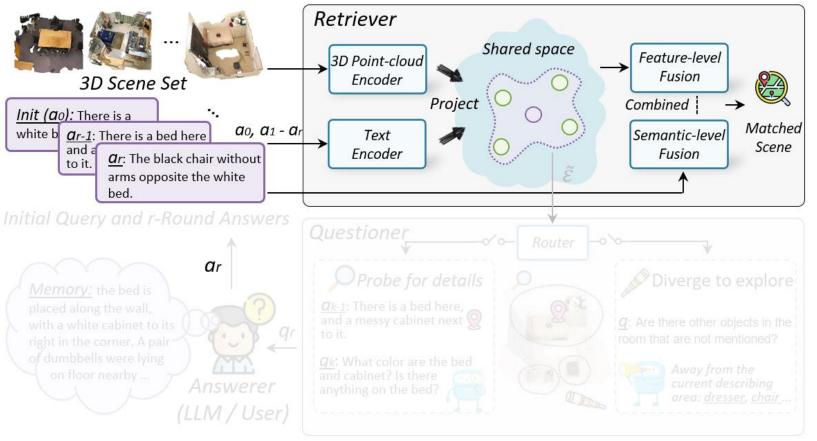


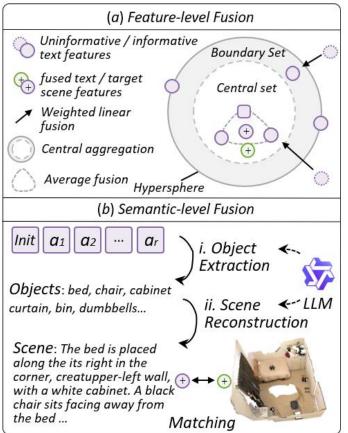






Framework Matching the result with multi-round descriptions.









Retriever

$$\hat{\boldsymbol{p}}_c(\boldsymbol{u}_i) = \lambda_1 \hat{\boldsymbol{p}}_1(\boldsymbol{u}_i) + \lambda_2 \hat{\boldsymbol{p}}_2(\bar{\boldsymbol{u}}_i) + \lambda_3 \hat{\boldsymbol{p}}_3(\boldsymbol{s}_i)$$

From three perspectives.





### Retriever

$$\hat{\boldsymbol{p}}_c(\boldsymbol{u}_i) = \lambda_1 \hat{\boldsymbol{p}}_1(\boldsymbol{u}_i) + \lambda_2 \hat{\boldsymbol{p}}_2(\bar{\boldsymbol{u}}_i) + \lambda_3 \hat{\boldsymbol{p}}_3(\boldsymbol{s}_i)$$

From three perspectives.

### 1. Initial Retrieval

$$\hat{\boldsymbol{p}}(\boldsymbol{u}_i) = \left[\hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_1), \hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_2), \dots, \hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_{n_c})\right]^{\top} \qquad \hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_j) = \exp(\mathcal{S}(\boldsymbol{u}_i, \boldsymbol{v}_j)) / \sum_{l=1}^{n_c} \exp(\mathcal{S}(\boldsymbol{u}_i, \boldsymbol{v}_l))$$







$$\hat{\boldsymbol{p}}_c(\boldsymbol{u}_i) = \lambda_1 \hat{\boldsymbol{p}}_1(\boldsymbol{u}_i) + \lambda_2 \hat{\boldsymbol{p}}_2(\bar{\boldsymbol{u}}_i) + \lambda_3 \hat{\boldsymbol{p}}_3(\boldsymbol{s}_i)$$

From three perspectives.

### 1. Initial Retrieval

$$\hat{\boldsymbol{p}}(\boldsymbol{u}_i) = \left[\hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_1), \hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_2), \dots, \hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_{n_c})\right]^{\top}$$

### 2. Retrieval after Feature-level Fusion

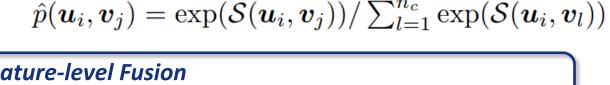
i) Answers from  $Q_1$ : (Weighted linear fusion)

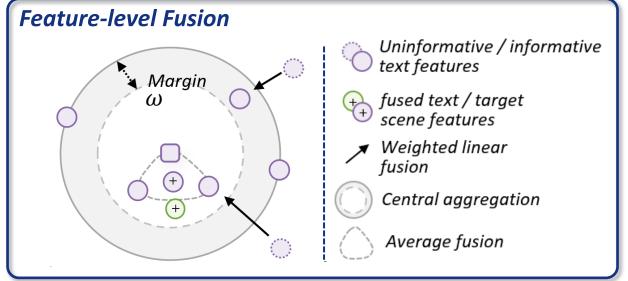
$$\boldsymbol{u}_i^j = \alpha \boldsymbol{u}_i^j + (1 - \alpha) \boldsymbol{u}_i^{j-1}$$

ii) Answers from  $\mathcal{Q}_2$  : (*Central fusion*)

$$(\boldsymbol{o}_{i}^{*}, R_{i}^{*}) = \arg\min_{\boldsymbol{o}_{i}, R_{i}} \left\{ R_{i} : \boldsymbol{u}_{i}^{j} \boldsymbol{o}_{i}^{\top} \leq R_{i}, \forall j \right\}$$

$$\bar{\boldsymbol{u}}_{i} = \frac{1}{2} \left( \boldsymbol{o}_{i}^{*} + \frac{1}{|\mathcal{U}_{i}^{2}|} \sum_{\boldsymbol{u}_{i}^{j} \in \mathcal{U}_{i}^{2}} \boldsymbol{u}_{i}^{j} \right)$$









Retriever

$$\hat{\boldsymbol{p}}_c(\boldsymbol{u}_i) = \lambda_1 \hat{\boldsymbol{p}}_1(\boldsymbol{u}_i) + \lambda_2 \hat{\boldsymbol{p}}_2(\bar{\boldsymbol{u}}_i) + \lambda_3 \hat{\boldsymbol{p}}_3(\boldsymbol{s}_i)$$

### 1. Initial Retrieval

$$\hat{\boldsymbol{p}}(\boldsymbol{u}_i) = \left[\hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_1), \hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_2), \dots, \hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_{n_c})\right]^{\top}$$

### 2. Retrieval after Feature-level Fusion

i) Answers from  $\mathcal{Q}_1$ : (Weighted linear fusion)

$$\boldsymbol{u}_i^j = \alpha \boldsymbol{u}_i^j + (1 - \alpha) \boldsymbol{u}_i^{j-1}$$

ii) Answers from  $\mathcal{Q}_2$  : (Central fusion)

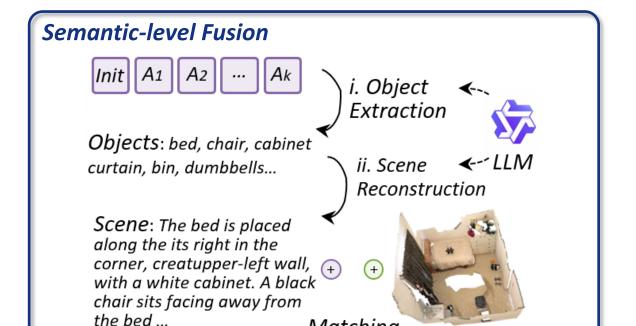
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### 3) Retrieval after Semantic-level Fusion

From three perspectives.

 $\hat{p}(\boldsymbol{u}_i, \boldsymbol{v}_i) = \exp(\mathcal{S}(\boldsymbol{u}_i, \boldsymbol{v}_i)) / \sum_{l=1}^{n_c} \exp(\mathcal{S}(\boldsymbol{u}_i, \boldsymbol{v}_l))$ 



Matching

i) Object extraction from answers; ii) Scene text reconstruction by LLMs.

## Ideal - Interaction Adaptation Tuning strategy (IAT)





Motivation: To facilitate the transformation of existing static models into interaction-friendly models.

## Ideal - Interaction Adaptation Tuning strategy (IAT)





- Motivation: To facilitate the transformation of existing static models into interaction-friendly models.
- 1. Generate interaction-domain-like text. Target domain data.

## Ideal - Interaction Adaptation Tuning strategy (IAT)





- Motivation: To facilitate the transformation of existing static models into interaction-friendly models.
- 1. Generate interaction-domain-like text. -> Target domain data.
- 2. Source-free domain adaptation —> Adapting model to target domain.

$$\textit{Criterion}^{[2]} \colon \quad \mathcal{R}(\boldsymbol{\theta}) = \mathcal{R}_{dis}(\boldsymbol{\theta}) + \mathcal{R}_{div}(\boldsymbol{\theta}) = \mathbb{E}_{\tilde{\mathcal{U}}} \left[ \left( -\mathbb{E}_{\tilde{\mathcal{U}}^+} \left\{ \mathcal{S}(\tilde{\boldsymbol{u}}_i^+, \tilde{\boldsymbol{u}}_i) \right\} \right) + \left( \mathbb{E}_{\tilde{\mathcal{U}}^-} \left\{ \mathcal{S}(\tilde{\boldsymbol{u}}_i^-, \tilde{\boldsymbol{u}}_i) \right\} \right) \right]$$

$$\textit{Discriminability} \qquad \qquad \textit{Diversity}$$

$$\textit{Criterion}^{[2]} \colon \quad \mathcal{R}(\boldsymbol{\theta}) = \mathcal{R}_{dis}(\boldsymbol{\theta}) + \mathcal{R}_{div}(\boldsymbol{\theta}) = \mathbb{E}_{\tilde{\mathcal{U}}} \left[ \left( -\mathbb{E}_{\tilde{\mathcal{U}}^+} \left\{ \mathcal{S}(\tilde{\boldsymbol{u}}_i^+, \tilde{\boldsymbol{u}}_i) \right\} \right) \right] + \left( \mathbb{E}_{\tilde{\mathcal{U}}^-} \left\{ \mathcal{S}(\tilde{\boldsymbol{u}}_i^-, \tilde{\boldsymbol{u}}_i) \right\} \right) \right]$$

$$\mathcal{L} = \lambda \mathcal{L}_{dis} + (1 - \lambda) \mathcal{L}_{div} \qquad \qquad \textit{risk}$$

$$\textit{Implement} \qquad \mathcal{R} \qquad \qquad \textit{Implement} \qquad \mathcal{R}$$

 $\mathcal{L}_{dis} = -\sum_{i=1}^{b} \sum_{j=1}^{n_c} y_{ij} \log \mathcal{S}(\tilde{\boldsymbol{u}}_i, \boldsymbol{v}_j) \quad \mathcal{L}_{div} = \sum_{i=1}^{b} \sum_{j\neq i}^{b} \underbrace{\exp\left(-\max\left(0, \mathcal{S}(\tilde{\boldsymbol{u}}_i, \tilde{\boldsymbol{u}}_j) - \gamma\right)\right)}_{\text{Weighting term}} \underbrace{\log\left(1 - \mathcal{S}(\tilde{\boldsymbol{u}}_i, \tilde{\boldsymbol{u}}_j)\right)}_{\text{Complementary contrastive term}}$ 

Ensure the adapted model outputs discriminative features.

Ensure the adapted model keeps unrelated features well-separated.

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## **Comparative Experiments**





Table: 1 Performance comparison on ScanRefer, Nr3D, and Sr3D in terms of R@1, R@5, R@10, and their sum (Rsum). † denotes the use of coarsegrained descriptions as memory

Surpass static cross-modal retrieval methods in combating inherent data incompleteness.

Methods	ScanRefer			Nr3D			Sr3D				
Methods	R@1	R@5	R@10	Rsum   R@1	R@5	R@10	Rsum	R@1	R@5	R@10	Rsum
w/ coarse-grained descriptions:											
VSE∞ (CVPR'21)	9.7	33.1	50.2	93.0 + 5.8	21.5	32.5	59.8	5.5	18.9	27.4	51.8
CHAN (CVPR'23)	9.4	32.3	52.1	93.8 7.5	15.0	32.1	54.6	5.4	21.3	34.8	61.5
HREM (CVPR'23)	10.2	34.0	51.4	95.6 7.3	18.1	31.9	57.3	5.4	21.9	33.6	60.9
CRCL (NeurIPS'23)	10.3	32.4	49.8	92.5 8.1	22.5	33.2	63.8	4.9	19.5	31.9	56.3
RoMa (TMM'25)	11.4	34.8	54.4	100.6   6.5	24.8	37.6	68.9	7.8	27.3	39.3	74.4
IDeal	16.0	42.7	<b>59.8</b>	118.5   11.7	34.8	50.4	96.9	10.3	30.2	48.5	89.0
w/ fine-grained descriptions:											
ChatIR <sup>†</sup> (NeurIPS'23)	21.8	55.4	73.1	150.3   15.6	40.3	58.1	114.0	12.1	35.9	50.3	98.3
Rewrite <sup>†</sup> (ICMR'24)	17.4	47.0	63.7	128.1 17.1	31.4	45.8	94.3	12.4	28.1	40.4	80.9
MERLIN <sup>†</sup> (EMNLP'24)	31.1	68.8	83.8	183.7 21.8	55.0	71.8	148.6	14.2	42.0	60.3	116.5
BASELINE: IR <sup>†</sup>	29.9	68.0	83.3	181.2   18.0	51.6	60.2	129.8	14.6	39.2	55.3	109.1
Baseline SUM <sup>†</sup>	34.4	69.5	85.1	189.0   22.5	55.2	67.5	145.2	16.4	41.5	62.1	120.0
IDeal <sup>†</sup>	37.8	71.8	86.4	196.0   26.4	62.7	78.7	167.8	20.2	43.1	63.1	126.4

Outperforming general text-to-2D interactive retrieval.



The advancement of the interactive methods~

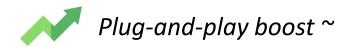


Table 2: Performance comparison on ScanRefer and Nr3D in terms of R@1, R@5, R@10, and their sum. +Ideal indicates plugging the model into our IDeal. † denotes the use of fine-grained descriptions as memory.

Methods			nRefer		Nr3D				
	R@1	R@5	R@10	Rsum	R@1	R@5	R@10	Rsum	
$VSE\infty$	9.7	33.1	50.2	93.0	5.8	21.5	32.5	59.8	
+IDeal	13.3	38.9	57.6	109.8	8.7	27.5	42.1	78.3	
${ m VSE}\infty^\dagger$	14.9	42.3	61.5	118.7	16.4	47.5	55.2	119.1	
+IDeal <sup>†</sup>	35.8	70.6	85.0	191.4	21.2	52.1	68.4	141.7	
CRCL	10.3	32.4	49.8	92.5	8.1	22.5	33.2	63.8	
+IDeal	13.4	35.5	56.1	105.0	7.4	25.4	38.3	71.1	
$CRCL^{\dagger}$	17.5	45.1	58.3	120.9	13.4	44.5	51.5	109.4	
+IDeal <sup>†</sup>	31.7	66.9	83.5	182.1	15.8	50.4	64.4	130.6	
RoMa	9.7	33.1	50.2	93.0	8.3	27.9	37.2	73.4	
+IDeal	16.0	42.7	59.8	118.5	11.7	34.8	50.4	96.9	
RoMa <sup>†</sup>	16.7	44.8	61.6	123.1	17.4	48.5	57.5	123.4	
+IDeal <sup>†</sup>	37.8	71.8	86.4	196.0	25.4	60.7	75.7	161.8	

# **Ablation Study**



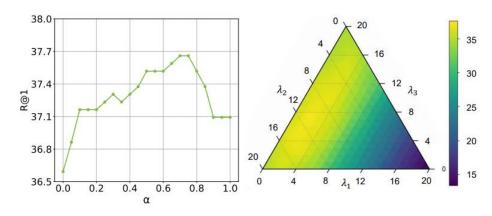


### Ablation study

Table 3: Ablation studies for components of our IDeal on ScanRefer. RSum is the sum of R@1, R@5, R@10. w/o stands for without use.

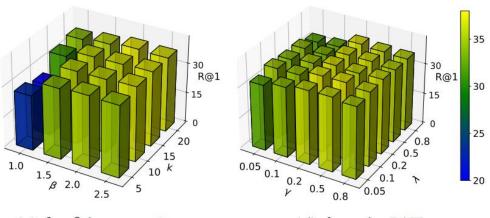
	boost Config	configurations			Refer R@10	Rsum
performance	Questioner	w/o Q <sub>1</sub> w/o Q <sub>2</sub>	36.0 26.3	71.2 61.5	86.7 77.3	193.9 165.1
	Retriever must adapt to tive domain to	$egin{array}{l} w \hspace{-0.1cm} / \hspace{-0.1cm} w \hspace{-0.1cm} / \hspace{-0.1cm} \hat{oldsymbol{p}}_1(oldsymbol{u}_i) \ w \hspace{-0.1cm} / \hspace{-0.1cm} o \hspace{-0.1cm} \hat{oldsymbol{p}}_2(oldsymbol{ar{u}}_i) \ w \hspace{-0.1cm} / \hspace{-0.1cm} o \hspace{-0.1cm} \text{CoT} \end{array}$	35.2 28.1 31.8 35.7	70.1 63.3 67.8 71.5	86.5 80.6 84.2 85.9	191.8 172.0 183.8 193.1
exploit inte	Adaptation	$w/o$ IAT $w/o$ $\mathcal{L}_{dis}$ $w/o$ $\mathcal{L}_{div}$	16.6 34.9 35.1	48.4 69.5 69.4	64.4 84.4 84.1	129.4 188.8 191.7
	Full	IDeal	37.8	71.8	86.4	196.0

### Parameter analysis



(a)  $\alpha$  in retriever.

(b)  $\lambda_1$ ,  $\lambda_2$ ,  $\lambda_3$  in retriever.



(c) k,  $\beta$  in questioner.

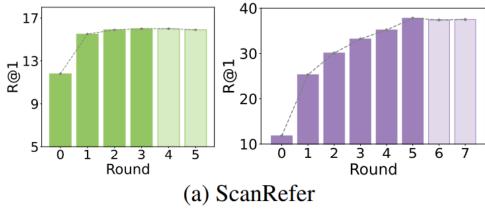
(d)  $\lambda$ ,  $\gamma$  in IAT.

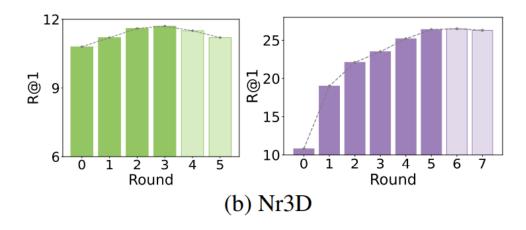
## Visualization Experiments





Interaction **Analysis** 





### Case Analysis





#### **Initial Query**

[Rank 16]

this is a computer monitor with two others to the left and right. there appears to be other monitors also in front of it and diagonally.

#### Round 1 Answer

this is a computer monitor with two others to the left and right. it is surrounded by additional monitors in front and diagonally. there are screens placed side by side providing ample workspace. there seem to be more screens angled forward to offer better [*Rank 4*] visibility ...

[Rank 1]





#### **Initial Query**

[Rank 23]

a long brown table. it is located near a single chair which is very close to the wall.

#### Round 2 Answer

[Rank 8]

this is a long brown/plain table. it is situated near a single chair which is very close to the wall, the single chair is placed right by the wall, there is no indication of any windows or doors being adjacent to the table or chair. the lengthy beige unadorned surface (table) stands alongside the solitary stool.

1) Performance boost.

**2)** Memory information exploited.

3) Superiority brought by a divergent perspective.

#### Case 4

[Rank 2] Round 1 Answer this is a description of the scene where a brown wooden chair is near the **gray** trash can to the right of the painting. it is also mentioned that there is a aray trash can to the right of the table. there is a brown chair at the end of the table as well. additionally, there are several matching chairs with

brown leather surrounding the table...

#### Round 2 Answer

... there is a rectangular refrigerator, Next to fridge, there is a black square TV... [*Rank 1*]

#### Round 5 Answer

... the brown wooden chair is near the trash can to the right of the painting, with some empty space between them

#### Ours Initial Query

there is a large painting on the wall. there is a chair at the end of the table

**Ground Truth** close to the

painting. we are talking about the other chair that is close to the trash can to the right side of the painting. it is brown [Rank 4] and wooden.

#### Merlin

Round 1 Answer [Rank 5]

The large painting on the wall appears to be representational rather than abstract, as it depicts a realistic scene. Besides the table and chairs already described... The color scheme of the room seems to consist mainly of neutral tones such as browns, grays, and blacks.

#### [Rank 4] Round 2 Answer

The second chair ... painting... first chair. Table... round trashcan...

[Rank 4] Round 4 Answer The round trashcan... table. the second chair ...

#### [*Rank 4*] Round 5 Answer

The round trashcan. table... the surrounding of second chair ...





# Thanks for Watching!

**Time:** Thu, Dec 4 · 2:40–3:00 a.m. CST **Location:** Upper Level – Ballroom 6CDEF

