Exponential Convergence Guarantees for Iterative Markovian Fitting

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- This work: first quantitative, exponential convergence bounds.

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Dynamical Formulation

Minimize $\mathrm{KL}(P|\mathbf{R})$ over $P \in \mathcal{P}(C([0,T]))$ s.t. $P_0 = \mu$, $P_T = \nu$.

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Theorem: Under mild assumptions, there exists a unique solution π^* , called Schrödinger Bridge, which can be expressed as

$$\pi^{\star}(\mathrm{d}x,\mathrm{d}y) = \exp\left(-\varphi(x) - \psi(y)\right) \mathrm{R}_{0,T}(\mathrm{d}x,\mathrm{d}y) ,$$

for some $\varphi, \psi : \mathbb{R}^d \to (-\infty, +\infty]$ known as Sinkhorn potentials.

Idea: Alternate between Stochastic Interpolants and Markovian Projections.

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Fixed point of IMF

The Schrödinger Bridge π^* is the **unique measure** consistent with both constraints.

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Remarks:

- Exponential convergence still holds under a weaker convexity assumption, but at a slower rate;
- ullet Exponential convergence still holds when replacing R with a Langevin-type reference measure under mild structural assumptions on it.

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Propagation of assumptions under Sinkhorn.