

Balanced Active Inference

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Outline

- 1 Introduction
- 2 Methodology
- 3 Theoretical Results
- 4 Experiments
- 5 Conclusion

The Labeling Bottleneck

- Limited labeling budget impedes data-driven researches:
 - Medical analysis (Kononenko, 2001)
 - Remote sensing (Jean et al., 2016)
 - Population census (Cochran, 1977)
- Core challenge: Abundance of unlabeled data vs. scarcity of annotations (Traugott, 2011)
- Conventional approaches lack statistical efficiency:
 - Random sampling: Ignores instance informativeness
 - Heuristic-based selection: Lacks systematic prioritization

- Active learning selects uncertain instances to maximize label efficiency (Settles, 2009; Gal et al., 2017; Li et al., 2024)
- **Active inference** extends active learning to **statistical inference** by querying labels where the model exhibits high uncertainty using **independent sampling** (Angelopoulos et al., 2023; Zrnic and Candes, 2024)
- Balancing ideas from **survey sampling** may help to **improve statistical efficiency**

Core Problem

How to achieve **higher statistical efficiency** given **fixed labeling cost**?

- Balanced sampling (Hájek, 1964; Royall and Herson, 1973) :
 - Enforce structural representativeness in selected instances through auxiliary variable alignment
 - Improve statistical efficiency without increasing labeling cost
- Cube method to implement balanced sampling (Deville and Tillé, 2004; Tillé, 2011) :
 - **Flight phase** adjusts inclusion probabilities to approximate target distributions
 - **Landing phase** resolves residual imbalances via constrained optimization

- **Active inference** leverages both model-derived uncertainty estimates and strategically acquired sample labels to **maximize statistical information**.
- The **cube method** optimizes sampling through balancing constraints, reconciling **variance reduction** with asymptotic normality.

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Problem Setup

- Datasets:
 - Labeled: $\mathcal{D}_l = \{(X_j, Y_j)\}_{j=1}^m$
 - Unlabeled: $\mathcal{D}_u = \{X_i\}_{i=1}^n$ (labels unobserved)
- Target parameter: Population mean of unobserved labels in \mathcal{D}_u

$$\theta^* = \frac{1}{n} \sum_{i=1}^n Y_i$$

Active Inference Framework

- Resources:

- Labeling budget: Acquire n_b labels from \mathcal{D}_u

$$\xi_i = \mathbb{I}(\text{label } Y_i \text{ acquired}), \quad \mathbb{E} \left[\sum_{i=1}^n \xi_i \right] = n_b$$

- $\hat{f}(\cdot)$: predictive model of label trained on labeled \mathcal{D}_l
- $\hat{u}(X_i)$: the model's estimated uncertainty measure for instance i , typically approximating $|Y_i - \hat{f}(X_i)|$
- Label strategy: Normalized sampling probabilities for each instance

$$\pi(X_i) = \frac{n_b}{n} \cdot \frac{\hat{u}(X_i)}{\frac{1}{n} \sum_{j=1}^n \hat{u}(X_j)}$$

- **Balanced constraint:** Enforce uncertainty balancing

$$\sum_{i=1}^n \frac{\hat{u}(X_i)\xi_i}{\pi(X_i)} = \sum_{i=1}^n \hat{u}(X_i)$$

- Employ the cube method for sampling to satisfy the balancing constraint
- Estimate the mean of unobserved labels through a Generalized Difference estimator (Cassel et al., 1976):

$$\tilde{\theta} = \frac{1}{n} \sum_{i=1}^n \left[\hat{f}(X_i) + \{Y_i - \hat{f}(X_i)\} \frac{\xi_i}{\pi(X_i)} \right]$$

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Asymptotic Normality

- The theorem establishes the asymptotic normality of the balanced active inference estimator

Theorem

Under regularity conditions, for the balanced active sampling scheme, the estimator $\tilde{\theta}$ satisfies:

$$\sqrt{n}(\tilde{\theta} - \theta^*) \xrightarrow{d} \mathcal{N}(0, V_0)$$

where $V_0 = \mathbb{E}(\varepsilon_1^2/\pi_1) + \text{Var}[f(X_1)]$.

- The asymptotic variance includes the scaled noise variance and the intrinsic variance of $f(X_1)$

Theorem

Under regularity conditions, for traditional active inference with independent $\{\xi_i\}_{i=1}^n$, the estimator $\hat{\theta}$ satisfies:

$$\sqrt{n}(\hat{\theta} - \theta^*) \xrightarrow{d} \mathcal{N} \left(0, V_0 + \mathbb{E} \left[\left(f(X_1) - \hat{f}(X_1) \right)^2 \left(\frac{1}{\pi(X_1)} - 1 \right) \right] \right).$$

- We can show that the asymptotic variance V_1 of the traditional active inference estimator with $\{\xi_i\}_{i=1}^n$ being independent ([Poisson sampling in survey sampling](#)) satisfies

$$V_1 - V_0 \succcurlyeq 0$$

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Stabilization via mixed sampling

- Direct implementation of $\pi(X_i) \propto \hat{u}(X_i)$ may be statistically inefficient due to variance inflation from **near-zero $\pi(X_i)$'s**.
- A τ -mixed rule is proposed (Zrnic and Candes, 2024):

$$\pi^{(\tau)}(X_i) = \tau \cdot \frac{n_b \hat{u}(X_i)}{\sum_{j=1}^n \hat{u}(X_j)} + (1 - \tau) \cdot \frac{n_b}{n}$$

- $\tau \in [0, 1]$ controls the trade-off between uncertainty prioritization and robustness.
- τ defaults to 0.5 in implementation.

Algorithm

- 1 Split data into training/test sets
- 2 Train two XGBoost models:
 - $\hat{f}(\cdot)$: Label predictor
 - $\hat{u}(X_i)$: Uncertainty estimator ($|\hat{f}(X_i) - Y_i|$)
- 3 Compute blended sampling probabilities:

$$\pi^{(\tau)}(X_i) = \tau \cdot \frac{n_b \hat{u}(X_i)}{\sum_{j=1}^n \hat{u}(X_j)} + (1 - \tau) \cdot \frac{n_b}{n}$$

- 4 Apply the cube method to obtain $\{\xi_i\}$ with balancing:

$$\sum_{i=1}^n \frac{\hat{u}(X_i) \xi_i}{\pi^{(\tau)}(X_i)} = \sum_{i=1}^n \hat{u}(X_i)$$

- 5 Compute balanced GD estimator $\tilde{\theta}$

- **Datasets:**

- Synthetic: Linear, Nonlinear, Friedman
- Real: 6 regression (Bike, Communities, Concrete, Energy, Life, Superconductor)
2 classification (Credit Fraud Detection, Post-election)

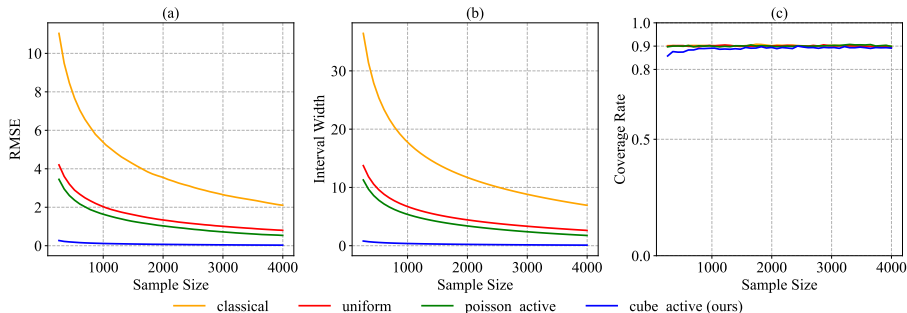
- **Baselines:**

- Classical: Simple random sampling
- Uniform: Active inference with uniform sampling
- Traditional-active: Active inference with independent sampling

- **Evaluation:**

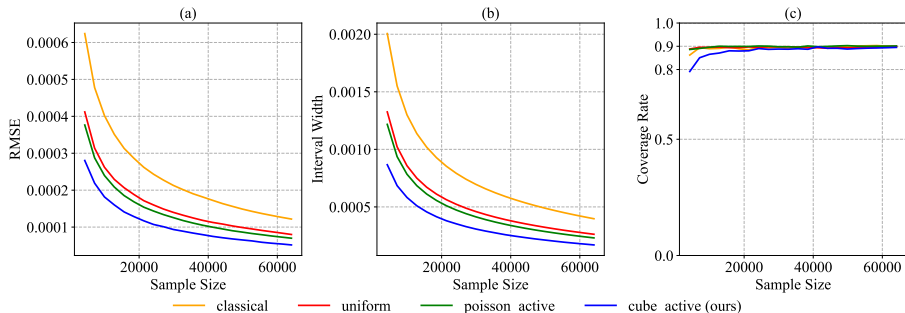
- RMSE, CI width, coverage rate (90% nominal)
- $T = 10,000$ Monte Carlo repetitions

Performance: Bike Sharing Dataset



- 17k hourly rentals (weather/temporal features)
- ↓30-50% RMSE vs alternatives
- **Tighter inference:** Narrowest intervals achieved
- **Reliable coverage:** Coverage aligns with nominal 90% target

Performance: Credit Fraud Dataset



- 492 frauds / 284k transactions (PCA features)
- **Best precision:** Tightest CIs + accurate coverage
- **Superior RMSE:** Outperforms all benchmarks
- Robust in high-imbalance scenarios and Classification problems

Accuracy Improvement (Label Budget = 0.1)

Table 1: Comparison of Confidence Interval Width with 0.1 Label Budget across Methods (Partial Results)

Dataset	Classical	Uniform	Traditional-active	Cube-active
Linear	0.3171	0.1690	0.1443	0.0722
Nonlinear	0.7786	0.3626	0.2963	0.1370
Communities	0.0722	0.0516	0.0509	0.0466
Concrete	7.1217	3.9367	3.7415	2.6406
Life	3.0828	1.4509	1.3050	0.7265
Post-election	0.0571	0.0426	0.0403	0.0381
Superconductor	3.2664	1.6711	1.5950	1.1680

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Conclusion

- We propose balanced active inference, integrating balanced sampling with active inference to address variance inflation and dataset imbalance in label-scarce settings.
- Theoretical guarantees establish the estimator's asymptotic normality and statistical efficiency.
- Experiments across datasets demonstrate RMSE reduction, label savings, and reliable coverage versus traditional active inference.

Thank you for your attention!

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