

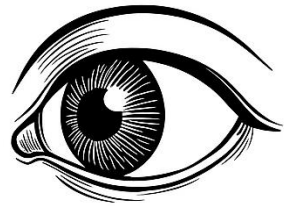
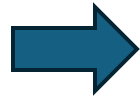
Neurons as Detectors of Coherent Sets in Sensory Dynamics

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Problem Statement



sparse measurements

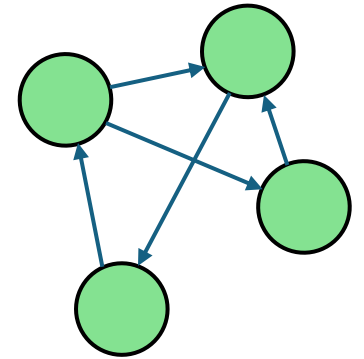


$\{f_1(\mathbf{x}), f_2(\mathbf{x}), \dots, f_N(\mathbf{x})\}$

neurons

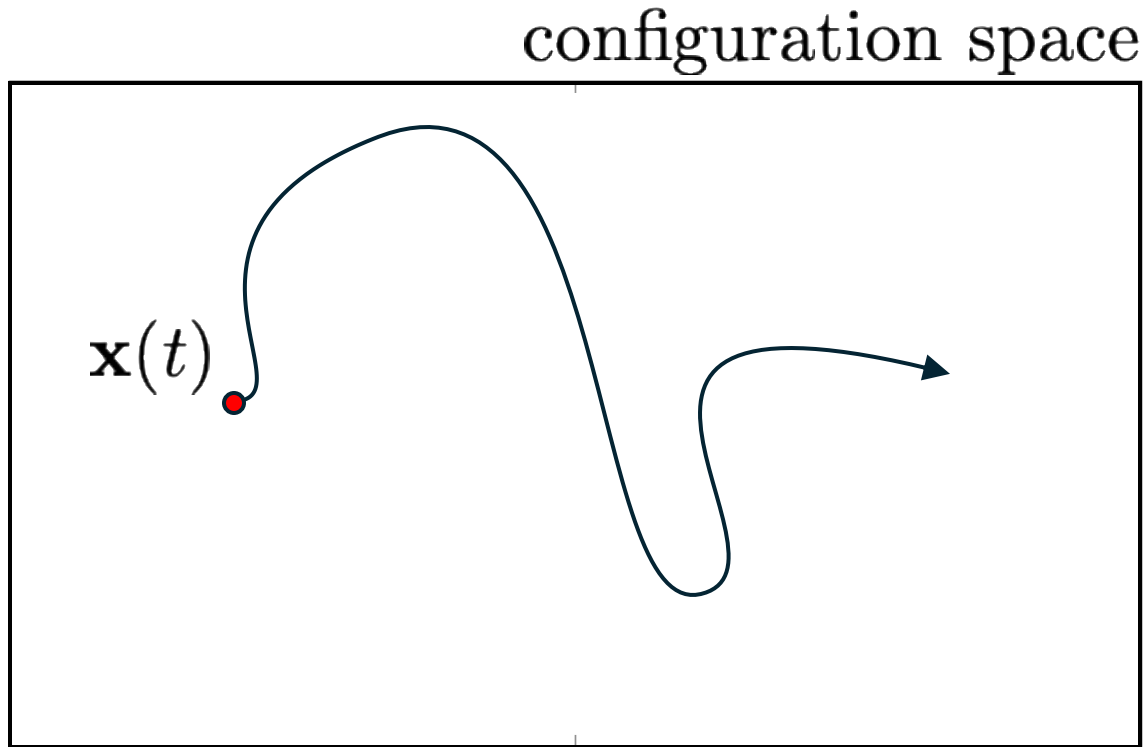


Internal
Representation



dynamic!

Stochastic Processes



$$d\mathbf{X}(t) = \underbrace{\phi(\mathbf{X}(t))dt}_{\text{deterministic}} + \underbrace{d\mathbf{W}(t)}_{\text{stochastic}}$$

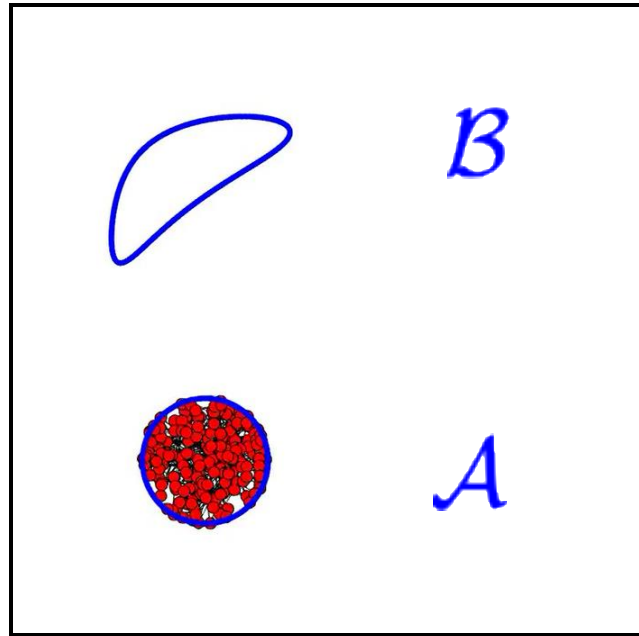
deterministic

stochastic

$$\{f_1(\mathbf{x}), f_2(\mathbf{x}), \dots, f_N(\mathbf{x})\}$$

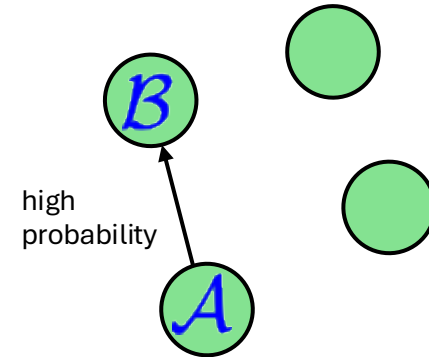
Coherent Set

$$C_\tau(\mathcal{A}, \mathcal{B}) = \mathbb{P}[\mathbf{X}(t + \tau) \in \mathcal{B} \mid \mathbf{X}(t) \in \mathcal{A}] \approx 1$$



configuration space

Internal
Representation



Coherent Set Identification

$$C_\tau(\mathcal{A}, \mathcal{B}) = \frac{\langle 1_{\mathcal{A}}, K_\tau 1_{\mathcal{B}} \rangle}{\langle 1_{\mathcal{A}}, 1_{\mathcal{A}} \rangle}$$

**Rayleigh Quotient = easy to solve
maximization problem**

$$[K_\tau f](\mathbf{x}) = \mathbb{E}[f(\mathbf{X}(t + \tau)) | \mathbf{X}(t) = \mathbf{x}]$$

$$\mathbb{E}[f_i(\mathbf{X}) f_j(\mathbf{X})] \longrightarrow K$$

**computed from covariances,
utility well established**

Coherent Set Identification

$$K_{\tau}^{\dagger} K_{\tau} \vec{a} = \lambda \vec{a}$$

Neural output



Neural input



$$1_{\mathcal{A}}(\mathbf{x}) \approx \begin{cases} 1 & \sum_i a_i f_i(\mathbf{x}) > 0 \\ 0 & \text{else} \end{cases}$$

Problem Solution

Coherent set Identifier

