



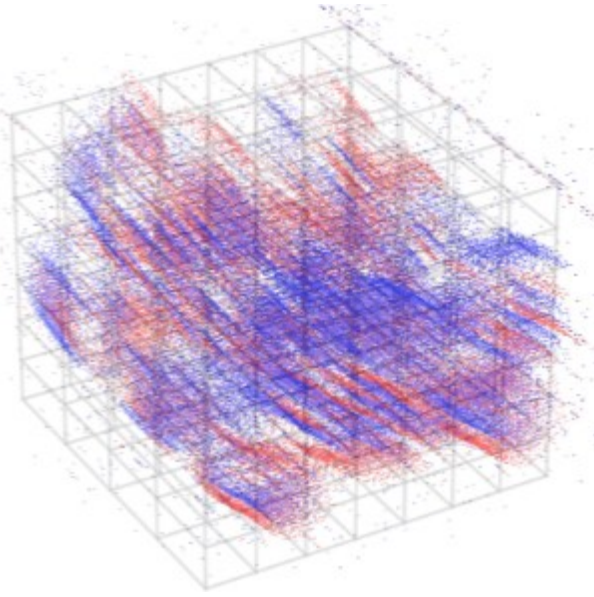
PASS: Path-selective State Space Model for Event-based Recognition

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Project Page: https://jiazhou-garland.github.io/PASS_Homepage/

Background: Event Camera



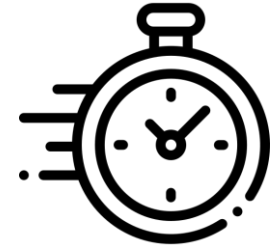
Event camera
perceive the **per-pixel
brightness** changes
asynchronously.

$$\varepsilon = \sum e_i(x_i, y_i, t_i, p_i)$$

ε encodes three critical
pieces of information:

- **time** t_i
- **pixel location** (x_i, y_i)
- **polarity of intensity
changes** p_i .

- It advances in:



High Temporal
Resolution

- Being resilient to:



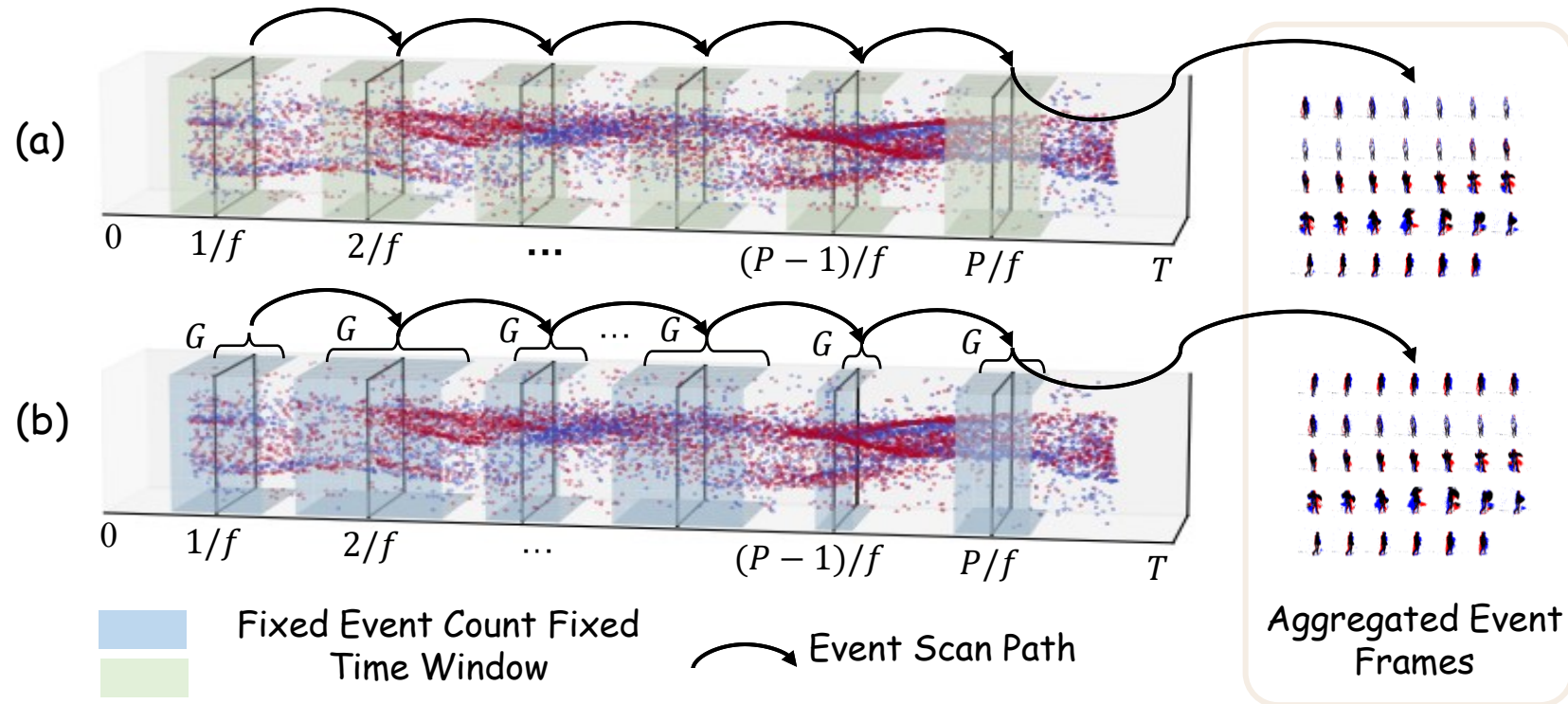
Rapid
Motion



Illumination
Changes

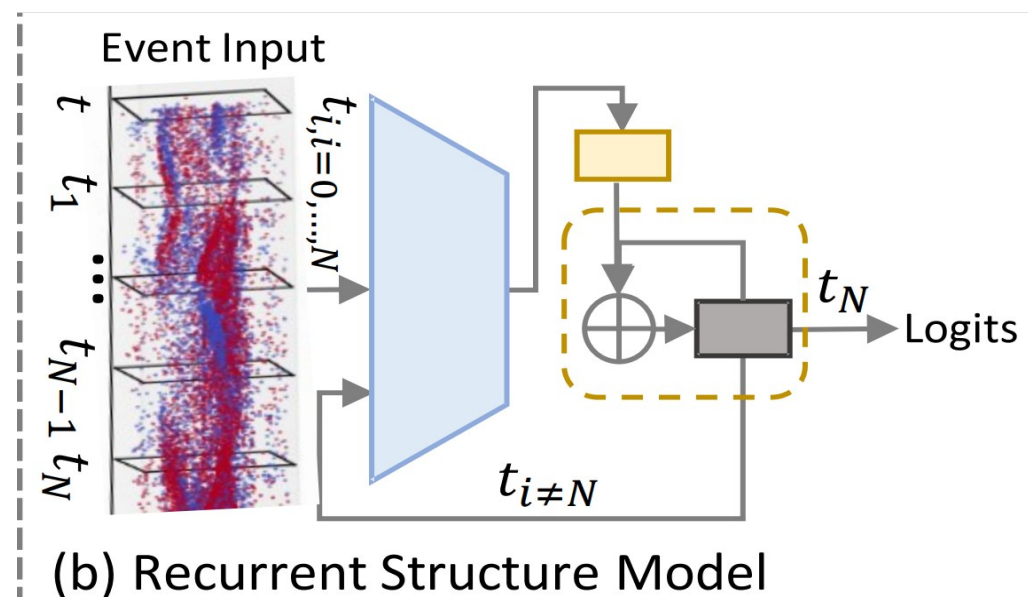
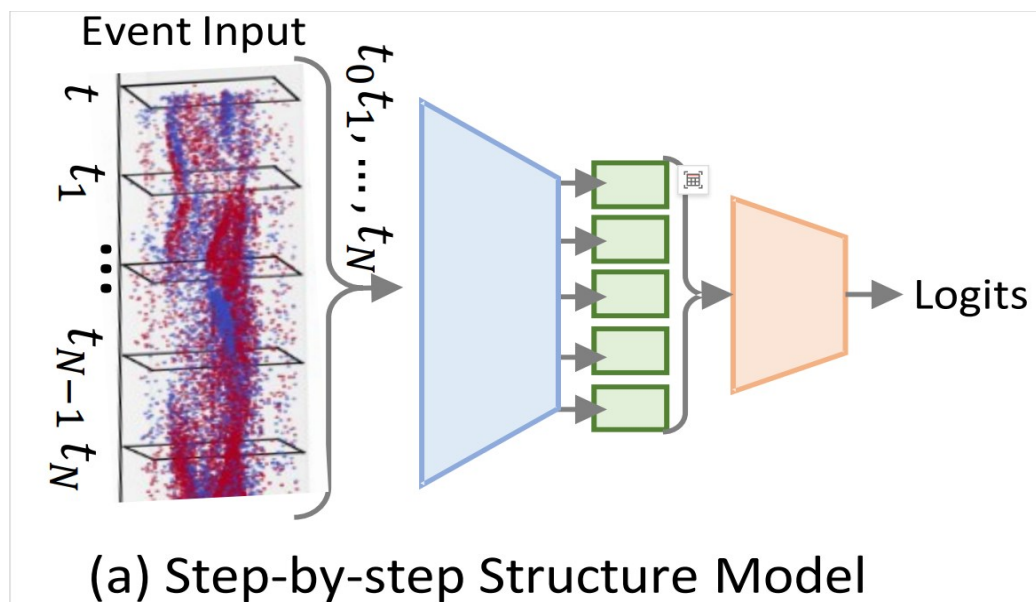
Related Work

Major Challenge: How to efficiently process and interpret event camera data characterized by high temporal density and spatial sparsity?

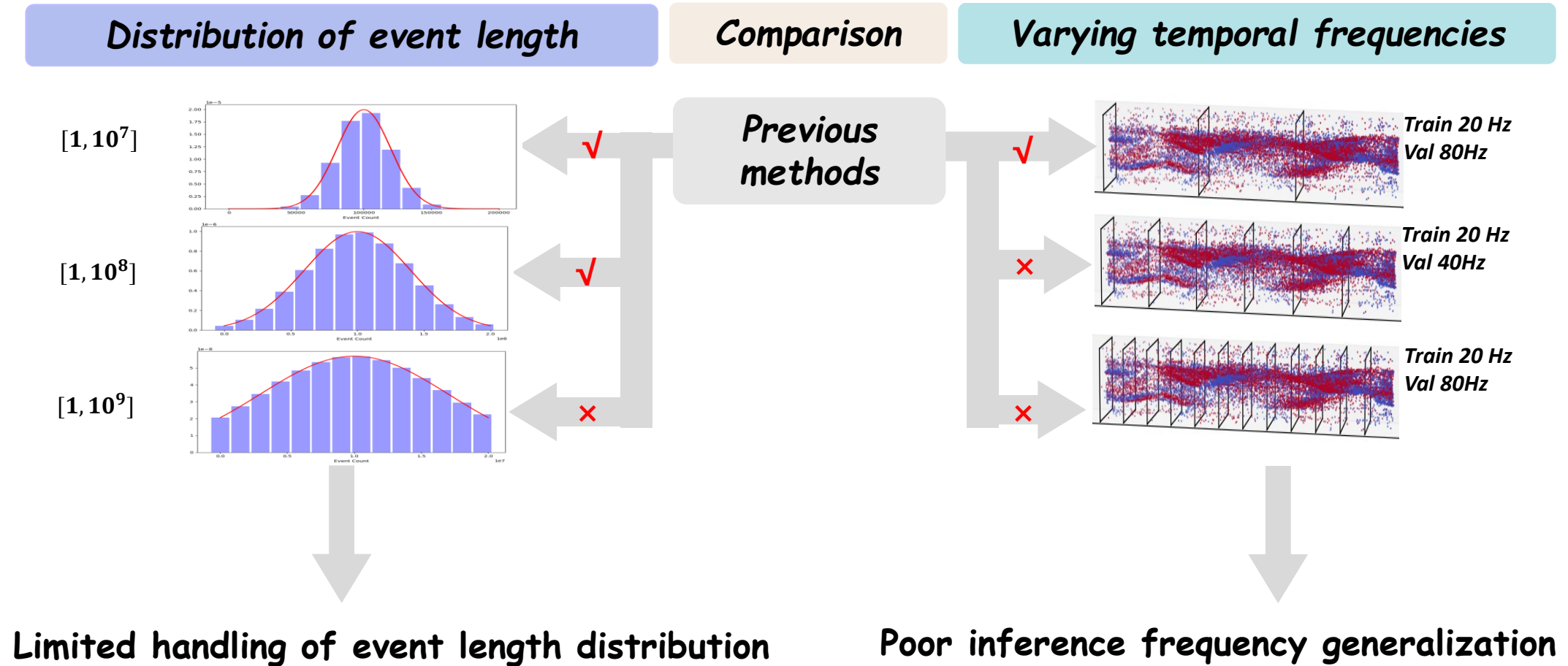


Related Work

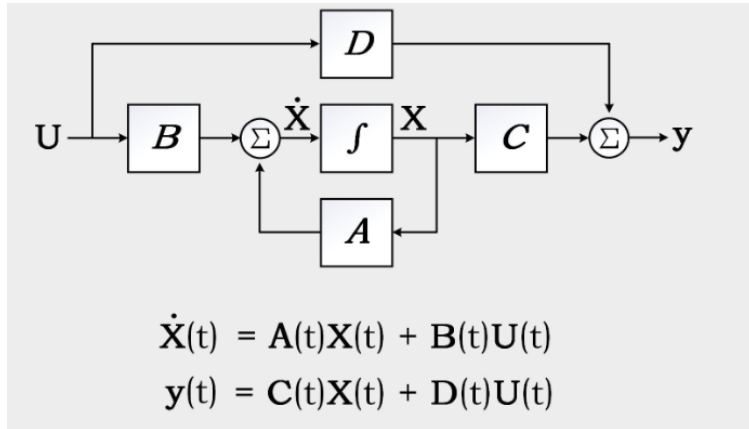
Previous methods generally fall into two categories:



Limitations of Existing Methods

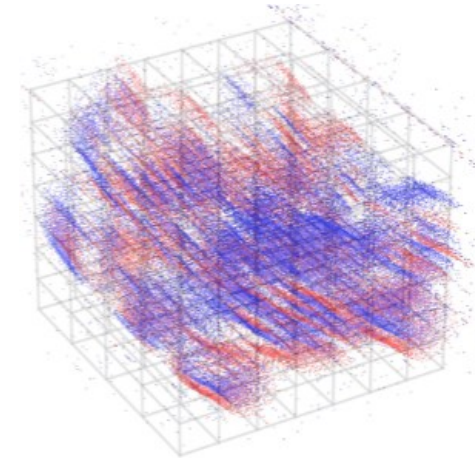


Research Motivation



State Space model:
Linear complexity

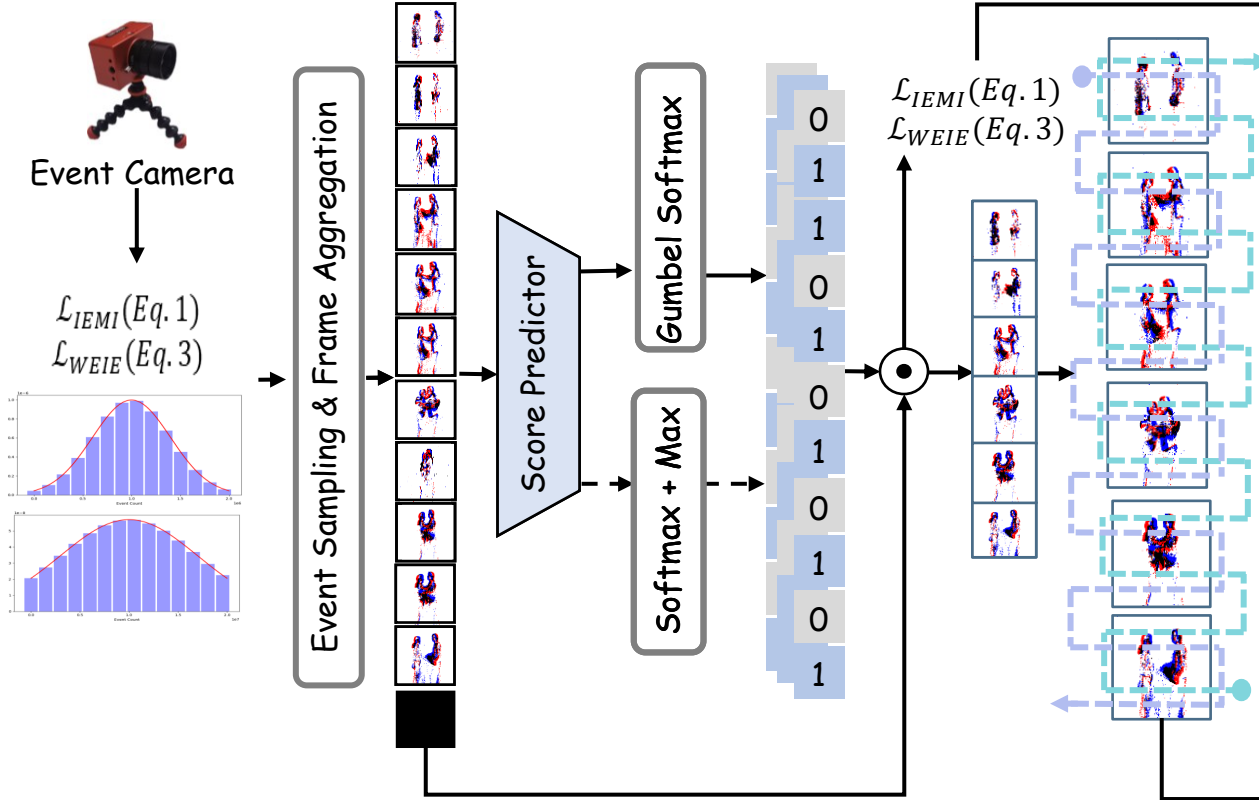
**Suitable for Event
Modeling**



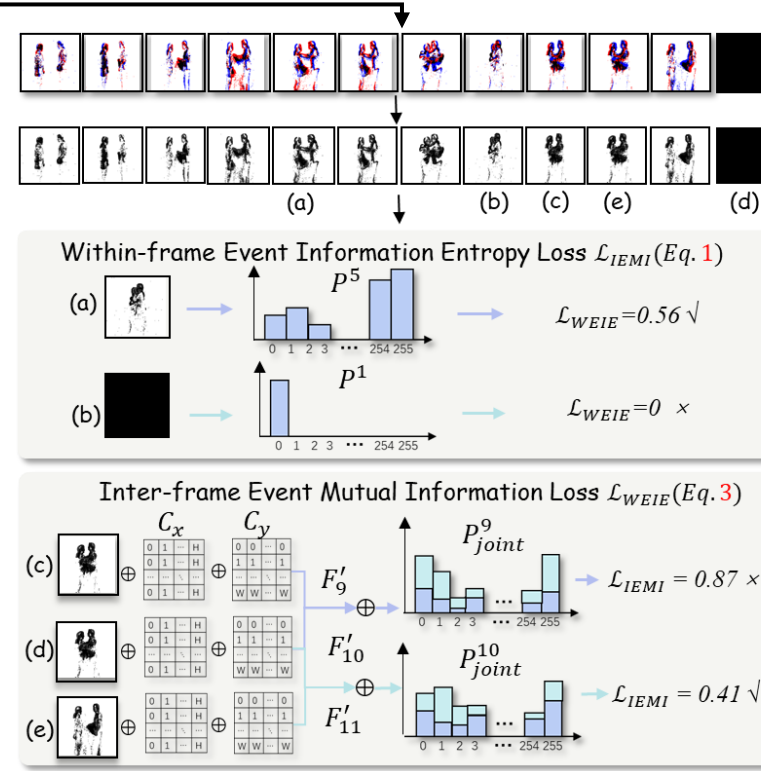
**Event's spatiotemporal
richness**

Overall Framework of Our PASS

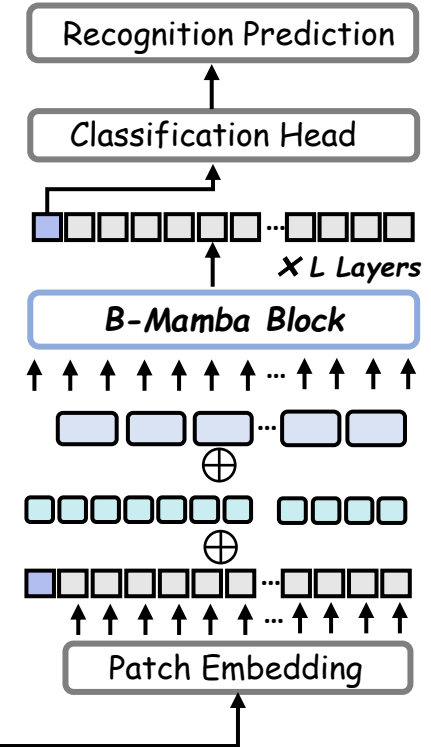
Path-selective Event Aggregation and Scan Module



Multi-faceted Selection Guiding Loss



Event Spatiotemporal Modeling Module

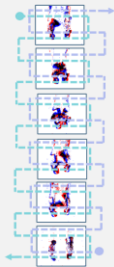


→ During Training

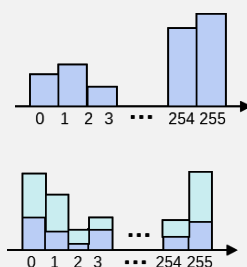
→ During Evaluation

⊙ Einsum Matrix Production

⊕ Value Addition



Bidirectional Event Scan



Event Count Histogram

Joint Event Count Histogram

0	1	...	H
0	1	...	H
...
0	1	...	H

X-axis Position Embedding

0	0	...	0
1	1	...	1
...
W	W	...	W

Y-axis Position Embedding

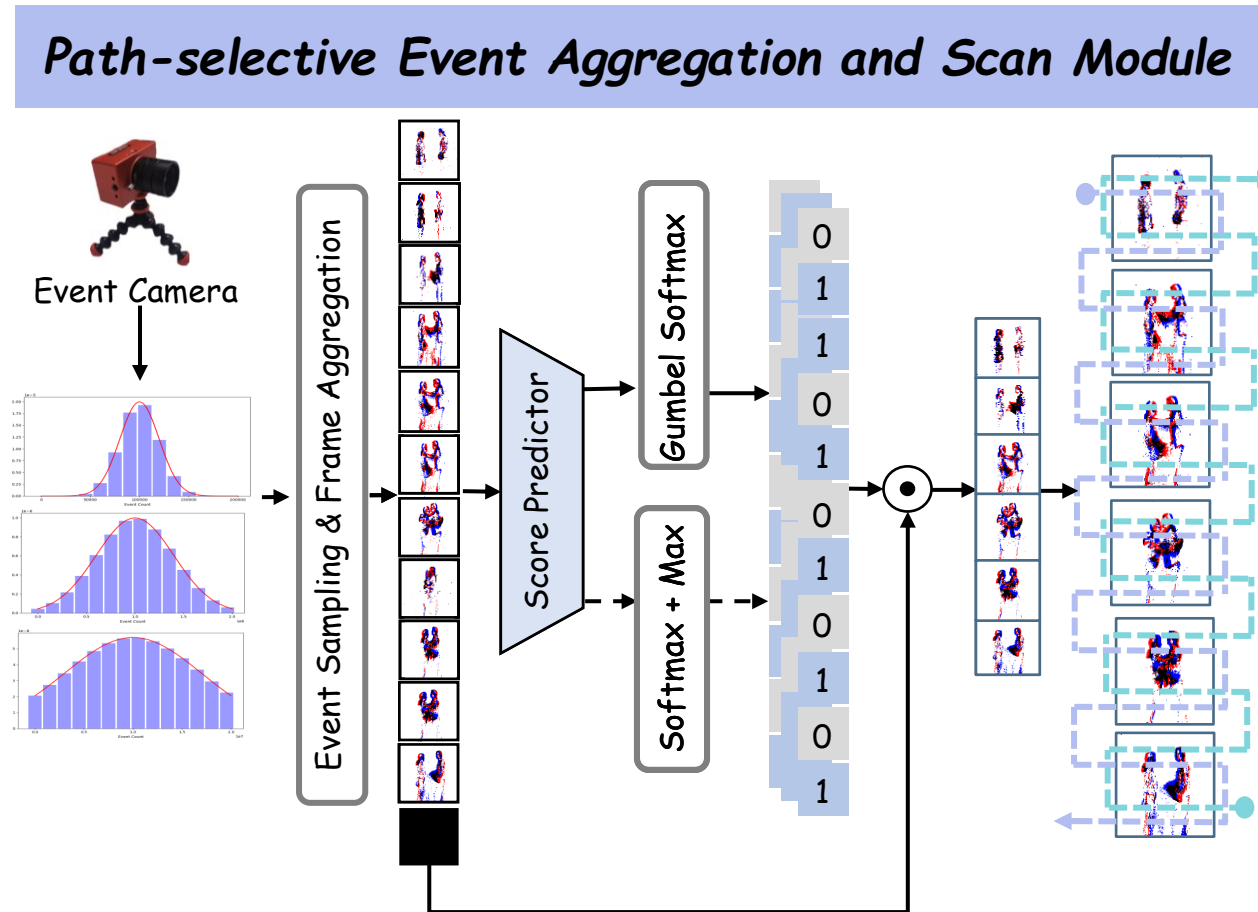
CLS Tokens

Feature Tokens

Spatial Embeddings

Temporal Embeddings

Methodology: Path-adaptive Event Aggregation and Scan (PEAS) Module



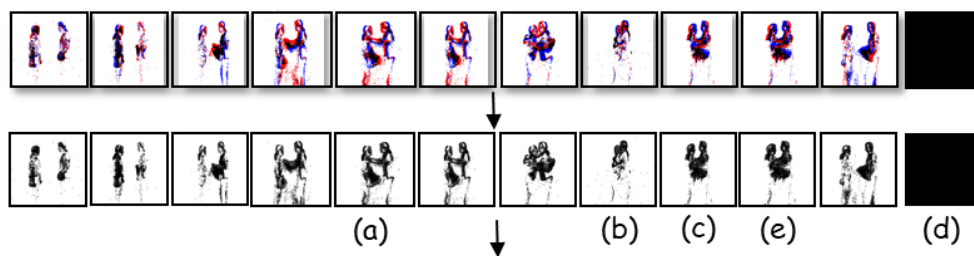
Converts asynchronous events into fixed-dimension sequence features:

- 1. Event Sampling/Aggregation**
- 2. Adaptive Frame Selection**
- 3. Bidirectional Scan**

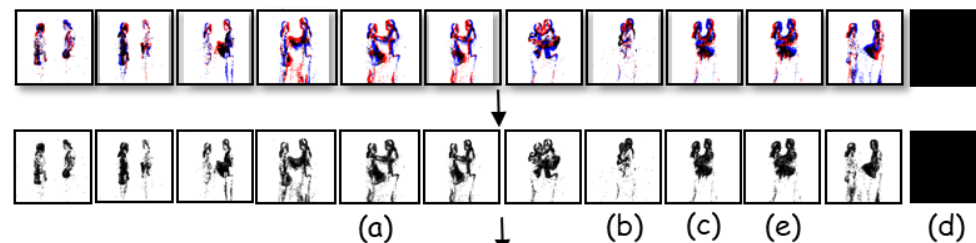
Methodology: Multi-faceted Selection Guiding (MSG) Loss

Multi-faceted Selection Guiding Loss

Reduces randomness / redundancy in PEAS selection:

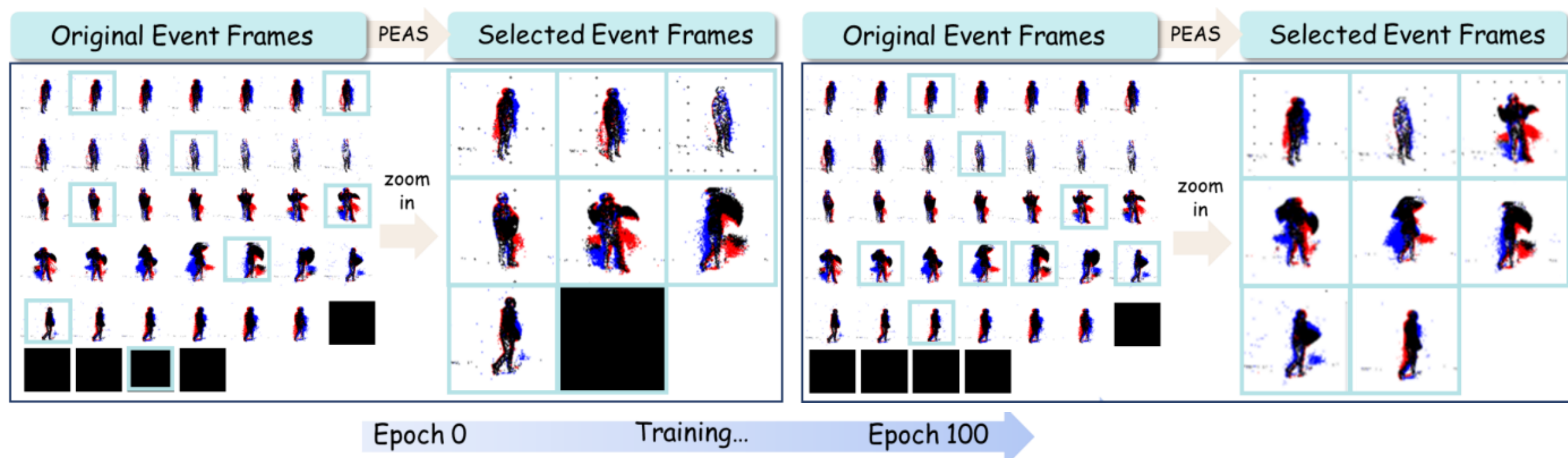


\mathcal{L}_{WEIE} (Within-Frame Entropy):
Maximizes information per selected frame .



\mathcal{L}_{IEMI} (Inter-Frame Mutual Information):
Minimizes redundancy between consecutive frames .

Qualitative Result: Multi-faceted Selection Guiding (MSG) Loss



Quantitative Result: Event-based Recognition Experiment

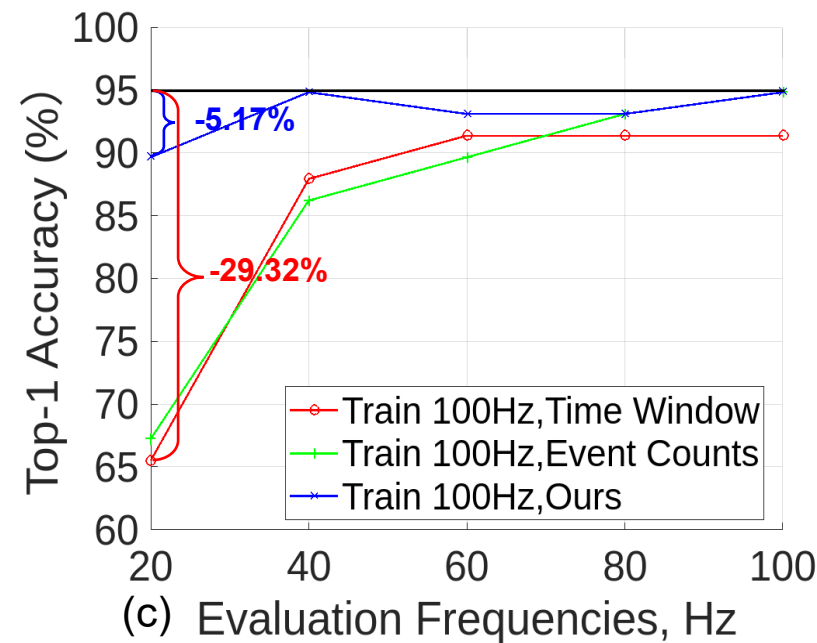
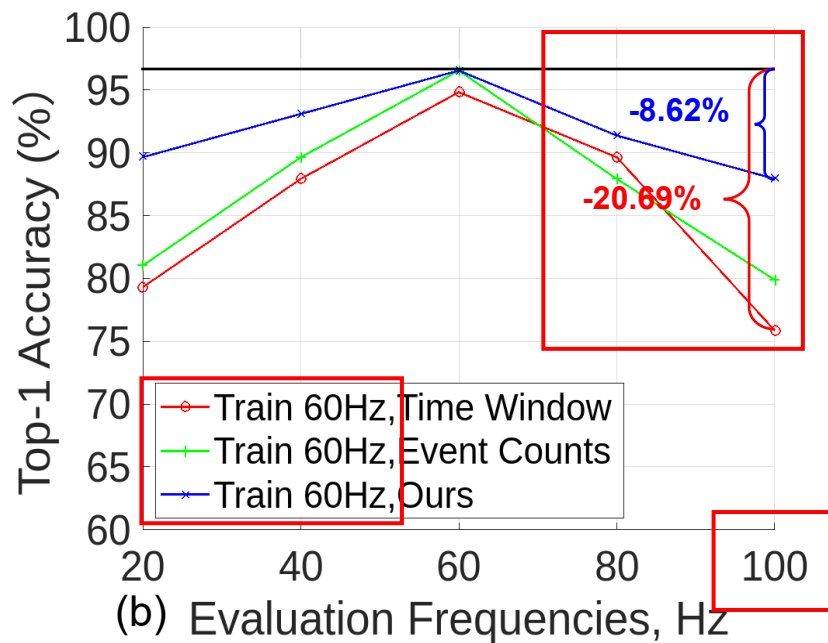
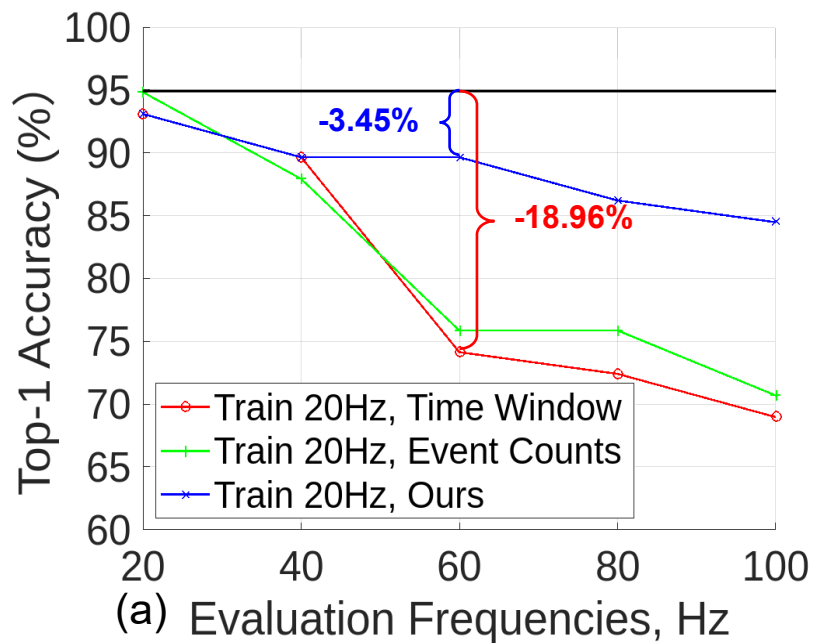
Table 2: Comparison with previous methods for event-based object recognition.

Object Recognition (Around 10^6 events)			
Model	Param.	Top-1 Accuracy(%)	
		N-Caltech101	N-Imagenet
EST[19]		81.70	48.93
EDGCN [9]	0.77M	83.50	-
Matrix-LSTM [4]	-	84.31	32.21
E2VID [50]	10M	86.60	-
DiST[29]	-	86.81	48.43
MEM [31]	-	90.10	57.89
S5-ViT-B-K(1) [80]	17.5M	88.32	-
S5-ViT-B-K(2) [80]	17.5M	88.44	-
EventDance [74]	26M	92.35	-
PASS-T- K (1)	7M	88.29	48.74
PASS-T- K (2)		89.72	48.60
PASS-S- K (1)	25M	90.92	53.74
PASS-S- K (2)		91.96	56.10
PASS-M- K (1)	74M	94.20	61.12
PASS-M- K (2)		94.60^{+2.25}	61.32^{+3.43}

Table 3: Comparison with previous methods for event-based action recognition.

Action Recognition (Around 10^7 events)				
Model	Param.	Top-1 Accuracy(%)		
		PAF	SeAct	HARDVS
EV-ACT [17]	21.3M	92.60	-	-
EventTransAct [7]	-	-	57.81	-
EvT [54]	0.48M	-	61.30	-
TTPIONT [51]	0.33M	92.70	-	-
Speck [71]	-	-	-	46.70
ASA [70]	-	-	-	47.10
ESTF [63]	-	-	-	51.22
S5-ViT-B-K(8) [80]	17.5M	92.93	58.21	74.85
S5-ViT-B-K(16) [80]	17.5M	92.12	57.37	95.98
ExACT [77]	471M	94.83	66.07	90.10
PASS-T- K (8)	7M	91.38	51.72	98.40
PASS-T- K (16)		94.83	49.14	98.37
PASS-S- K (8)	25M	93.33	60.34	98.20
PASS-S- K (16)		96.55	62.07	98.41^{+8.31}
PASS-M- K (8)	74M	98.28^{+3.45}	65.52	98.05
PASS-M- K (16)		96.55	66.38^{+0.38}	98.20

Quantitative Result: Generalization results across Varying Inference Frequencies.



Experiment: Synthetic Datasets and Corresponding Event-based Recognition Results

- **ArDVS100**: 100 action transitions with diverse meta-actions. **[Synthetic]**
- **Tem-ArDVS100**: Same meta-actions as ArDVS100 but in different combinations, for fine-grained temporal recognition. **[Synthetic]**
- **Real-ArDVS10**: 10 real-world recorded action transitions, to test real-world generalization. **[Real-world]**

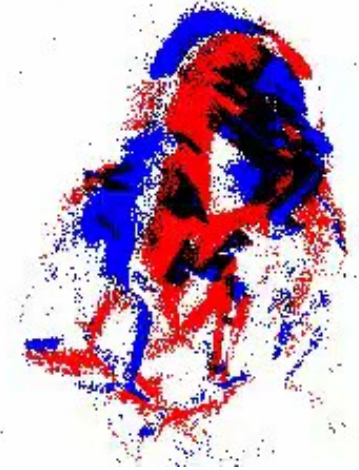


Illustration sample for ArDVS100

Table 4: Results of event-based action recognition with around 10^6 events).

Arbitrary-duration Event Recognition (Around 10^9 events)				
Model	Param.	Top-1 Accuracy(%)		
		ArDVS100	Real-ArDVS10	TemArDVS100
S5-ViT-B-K(16) [80]	17.5M	91.58	90.00	60.26
S5-ViT-B-K(32) [80]		93.39	93.33	79.62
PASS-T-K(16)	7M	90.20	80.00	59.20
PASS-T-K(32)		93.85	93.33	89.00
PASS-S-K(16)	25M	94.90	90.00	62.90
PASS-S-K(32)		96.00	100.00	73.41
PASS-M-K(16)	74M	96.00	93.33	71.06
PASS-M-K(32)		97.35	100.00	82.50

Ablation Study

Table 5: Ablation study on PEAS module & \mathcal{L}_{MSG} .

Settings	PAF ($K(16)$)	ArDVS100 ($K(16)$)
	Top1(%)	Top1(%)
No Sampling	92.90%	92.31%
Random Sampling	92.98%	92.23%
PEAS	93.33%	92.84%
PEAS + \mathcal{L}_{MSG}	94.83%	93.85%

Table 6: Ablation study on \mathcal{L}_{MSG} .

\mathcal{L}_{MSG}			PAF($K(16)$)
\mathcal{L}_{CLS}	\mathcal{L}_{IEMI}	\mathcal{L}_{WEIE}	Top1(%)
✓	✗	✗	92.98%
✓	✓	✗	93.75%+0.77
✓	✓	✓	94.83% +1.85

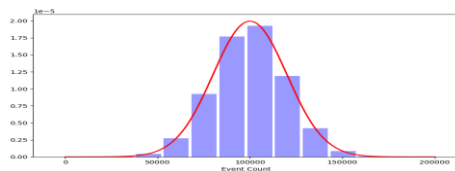
Table 7: Ablation study on event representation.

Representation	N-Caltech101 ($K(1)$)		PAF ($K(16)$)	
	Top1(%)	Top5(%)	Top1(%)	Top5(%)
Frame(Gray) [75]	90.48%	97.53%	93.33%	100.00%
Frame(RGB) [75]	90.94%	97.82%	94.83%	100.00%
Voxel [11]	90.19%	97.02%	92.47%	100.00%
TBR [27]	90.24%	97.13%	91.72%	100.00%
EST [19]	90.54%	97.66%	93.04%	100.00%

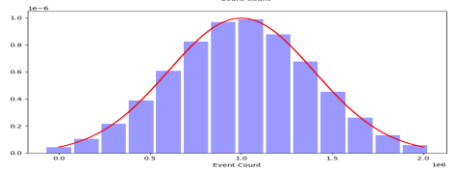
Summary

Distribution of event length

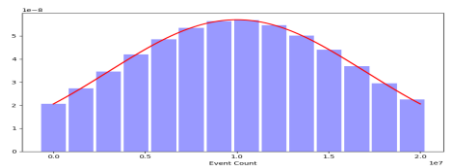
$[1, 10^7]$



$[1, 10^8]$



$[1, 10^9]$

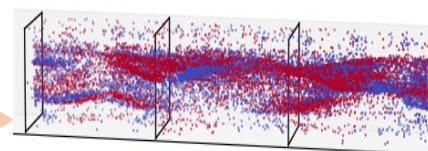


Broad event length handling

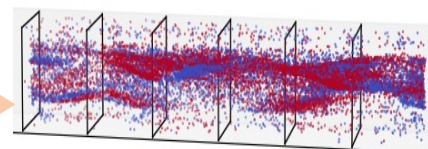
Comparison

PASS
our methods

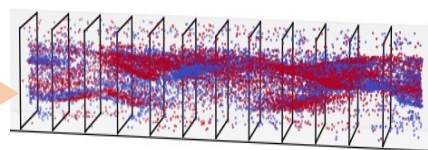
Varying temporal frequencies



Train 20 Hz
Val 80Hz



Train 20 Hz
Val 40Hz



Train 20 Hz
Val 80Hz

Strong frequency generalization

PASS: Path-selective State Space Model for Event-based Recognition

Thank you for your listening!



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