









# <u>Permutation Equivariant Neural Controlled</u> <u>Differential Equations for Dynamic Graph</u> <u>Representation Learning</u>

Torben Berndt, Benjamin Walker, Tiexin Qin, Jan Stühmer and Andrey Kormilitzin 39th Conference on Neural Information Processing Systems (NeurIPS 2025)

#### Main Contribution:

Project Neural Controlled Differential Equations on Graphs onto Equivariant function spaces.

Significantly reduces parameter count without compromising representational power, resulting in more efficient training and improved generalisation.

## <u>Graph Neural Controlled Differential</u> <u>Equations (GNCDEs)<sup>1</sup></u>

Given graph snapshots  $\mathcal{G}=\{G_1,\dots,G_n\}$  with a dynamic graph topology, GNCDEs interpolate into continuous edge data  $A:[0,T]\to\mathbb{R}^{n\times n}$ , and learn paths of the form

$$Z_t = Z_{t_0} + \int_{t_0}^t Z_s^{(L)} ds, \qquad Z_s^{(l)} = \sigma \left( \tilde{A}_s Z_s^{(l-1)} W^{(l-1)} \right)$$

with a GCN vector field and fusion

$$\tilde{A}_s = W_1 A_s + W_2 \frac{dA_s}{ds}$$

<sup>1</sup>Learning dynamic graph embeddings with neural controlled differential equations, Qin et al. (2025)

# <u>Permutation Equivariant Graph Neural</u> <u>Controlled Differential Equations</u> <u>(PENG-NCDEs)</u>

Problem: The fusion is not equivariant under permutation of the node-set!

Fix: Expand linear maps  $L_i$  in the basis of linear permutation equivariant functions and define the equivariant fusion

$$\bar{A}_s = L_1(A_s) + L_2(\frac{dA_s}{ds})$$

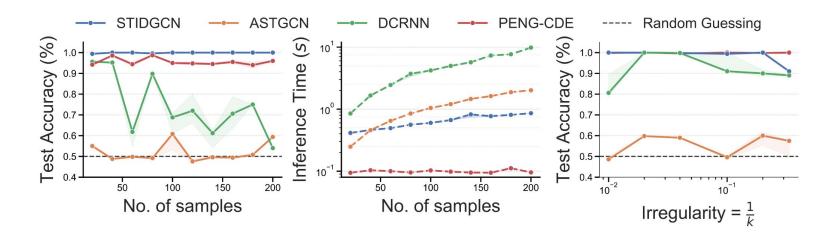
Theorem: This is the most general permutation equivariant GNCDE we can consider!

### **Results**

Model	$\begin{array}{cc} \texttt{trade} & \texttt{genre} \\ \textbf{NDCG@10} \uparrow \end{array}$	
Persistent Forecast (L) <sup>†</sup>	0.855	0.357
Moving Avg (L) <sup>†</sup>	0.823	0.509
Moving Avg (M)	0.777	0.472
JODIE <sup>‡</sup> [39]	$0.374 \pm 0.09$	$0.350{\pm}0.04$
TGAT <sup>‡</sup> [15]	$0.375 \pm 0.07$	$0.352 {\pm} 0.03$
CAWN <sup>‡</sup> [66]	$0.374 \pm 0.09$	_
TCL <sup>‡</sup> [65]	$0.375 \pm 0.09$	$0.354 {\pm} 0.02$
GraphMixer <sup>‡</sup> [14]	$0.375 \pm 0.11$	$0.352 {\pm} 0.03$
DyGFormer <sup>‡</sup> [68]	$0.388 {\pm} 0.64$	$0.365{\pm}0.20$
DyRep <sup>†</sup> [60]	$0.374 \pm 0.001$	$0.351 {\pm} 0.001$
$TGN^{\dagger}$ [53]	$0.374 \pm 0.001$	$0.367 {\pm} 0.058$
TGNv2* [59]	$0.735 \pm 0.006$	$0.469 {\pm} 0.002$
STG-NCDE [10]	$0.618 \pm 0.024$	$0.438 \pm 0.038$
GN-CDE [48]	$0.713 \pm 0.026$	$0.460 {\pm} 0.016$
PENG-CDE	$0.716 \pm 0.029$	$0.523 \pm 0.017$
+ Source/Target Id	$0.734 \pm 0.024$	_

PENG-CDEs are state-of-the-art on popular Temporal Graph benchmark<sup>3</sup>!

### <u>Results</u>



PENG-CDEs are robust to oversampling and irregular sampling!

### <u>Summary</u>

- Introduce geometrically-informed approach to employing CDEs on graphs
- 2. Set new state-of-the-art result in the TGB dataset
- 3. Inherit robustness properties of Neural CDEs

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