



RiverMamba: A State Space Model for Global River Discharge and Flood Forecasting

Mohamad Hakam Shams Eddin^{🎓, 🏢}, Yikui Zhang^{🌐, 🏢}, Stefan Kollet^{🌐, 🏢}
and Jürgen Gall^{🎓, 🏢}

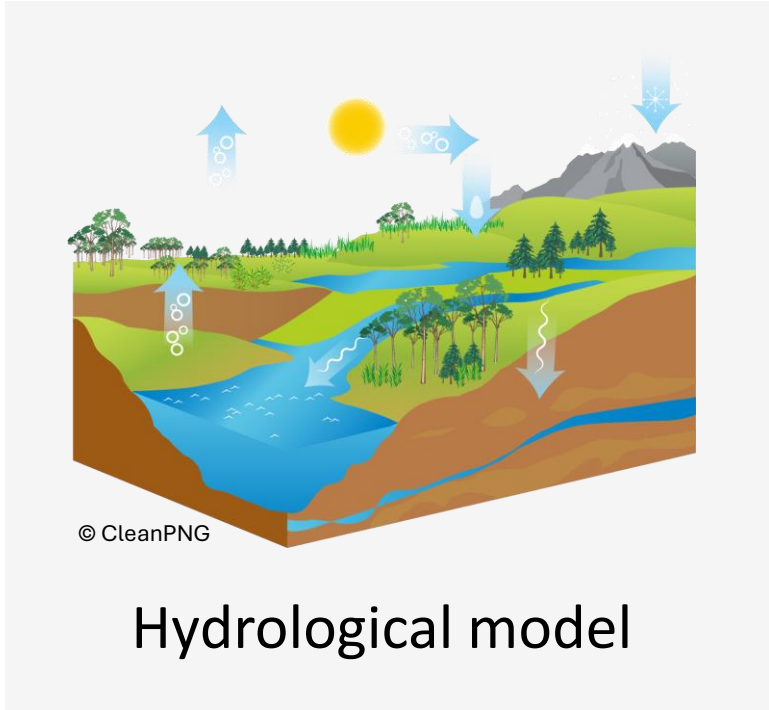
[🎓] Institute of Computer Science, University of Bonn

[🏢] Lamarr Institute for Machine Learning and Artificial Intelligence

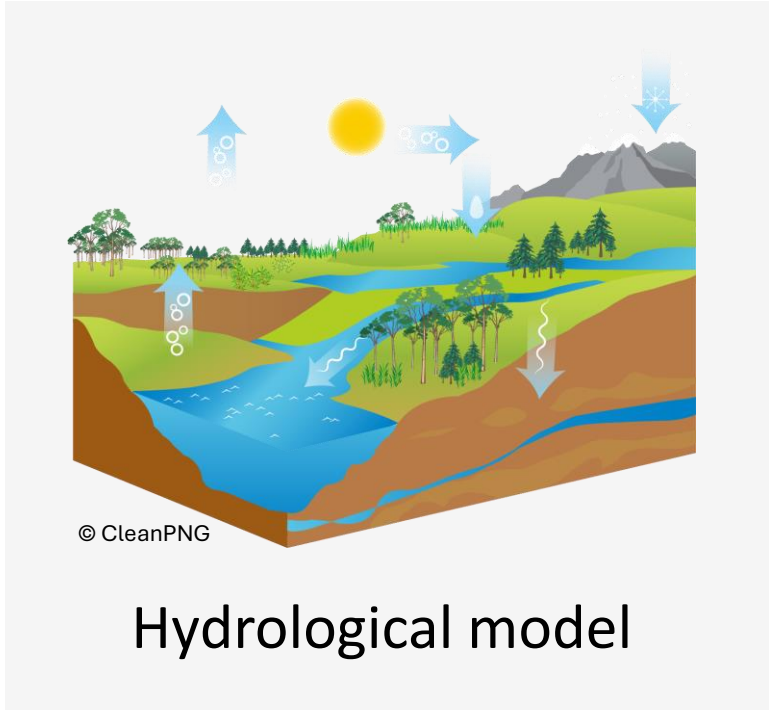
[🌐] Institute of Bio- and Geosciences Agrosphere (IBG-3), Research Centre Jülich

[🏢] Centre for High-Performance Scientific Computing in Terrestrial Systems, Geoverbund ABC/J

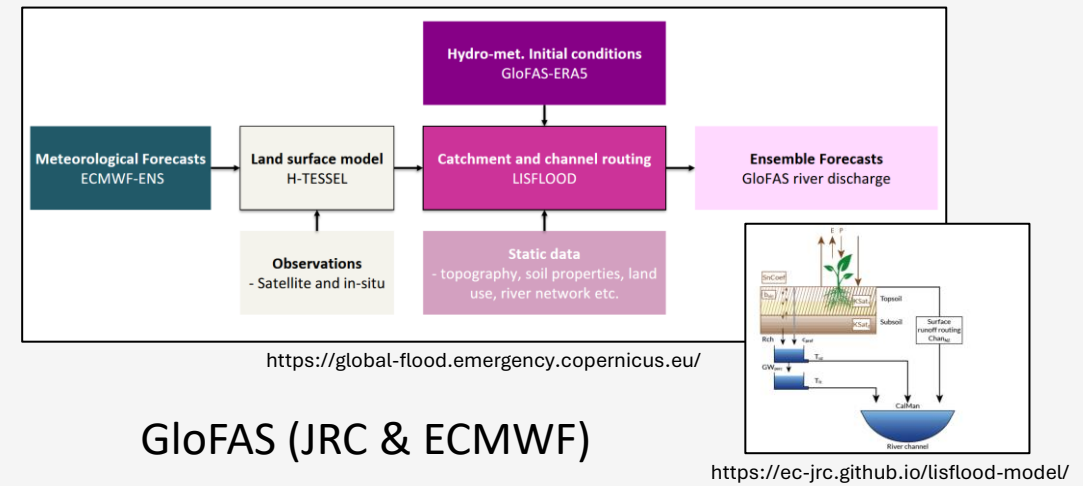
State-of-the-art in flood forecasting:



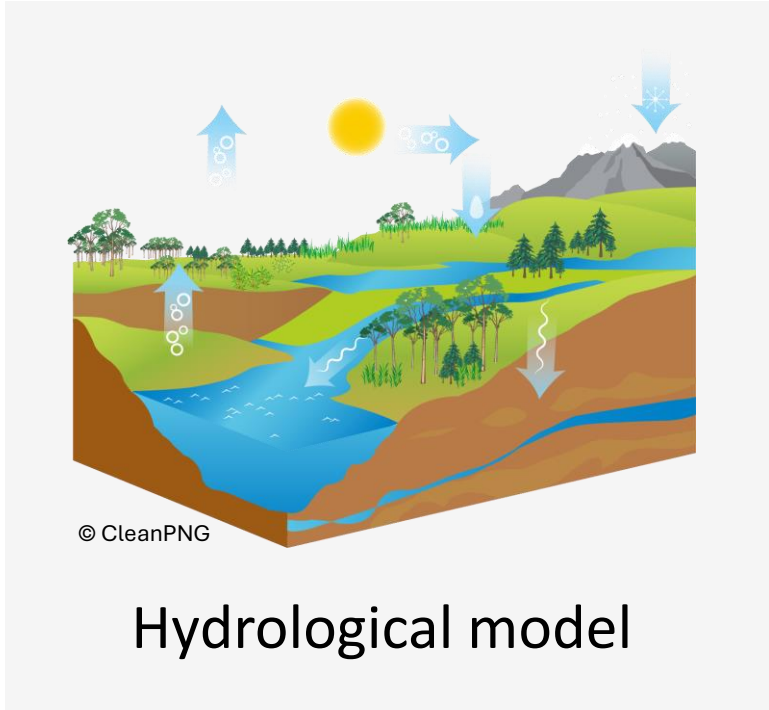
State-of-the-art in flood forecasting:



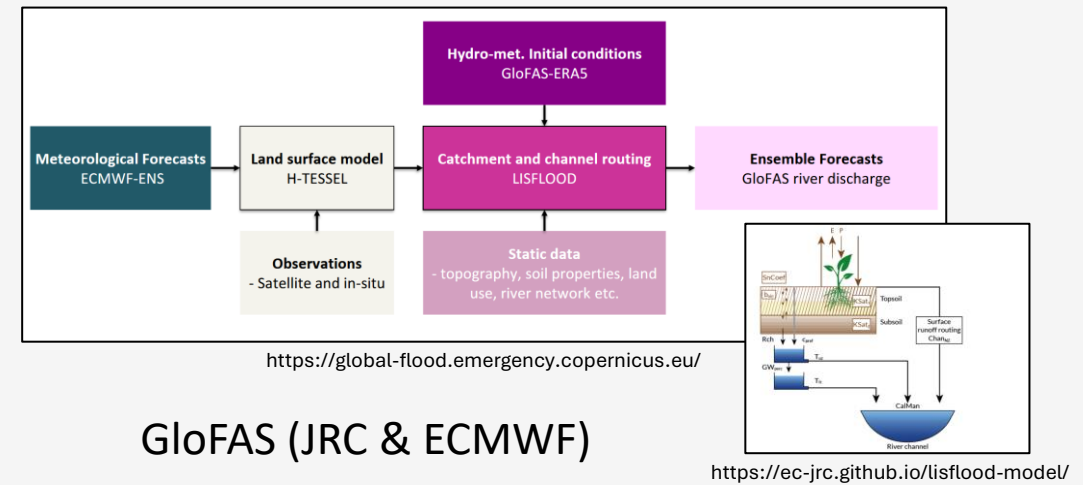
Physics-based



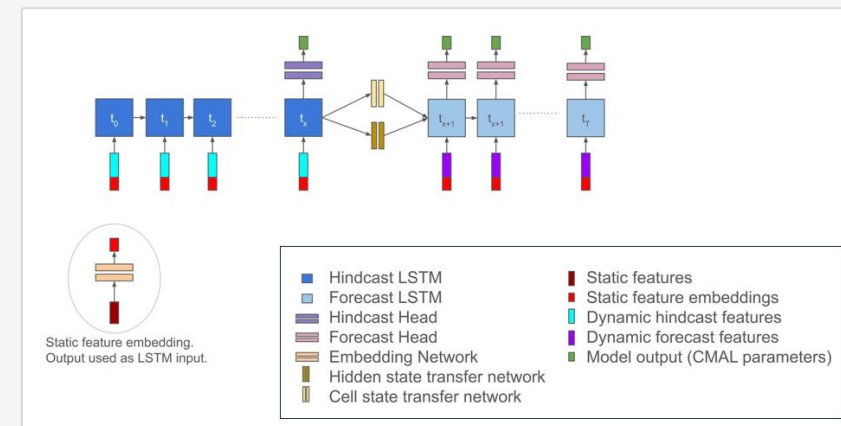
State-of-the-art in flood forecasting:



Physics-based



Time series analysis



Google LSTM (Nearing et al. 2024 & Kratzert et al. 2019)

Motivation behind RiverMamba:

Initial Condition

Forecast River Discharge



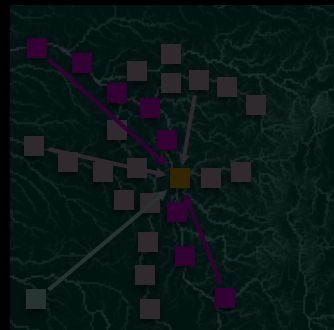
Can we build a vision model that improves flood forecasting and provides high-resolution predictions globally?

Build a vision-based model

Consider uncertainty in meteorological forcing



x



✓



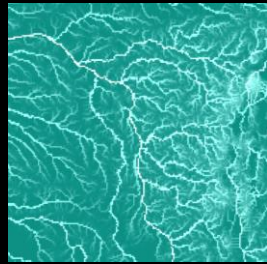
x



✓

Motivation behind RiverMamba:

Initial Condition



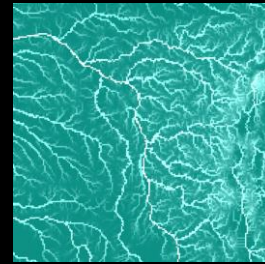
$\mathbf{x}^t$



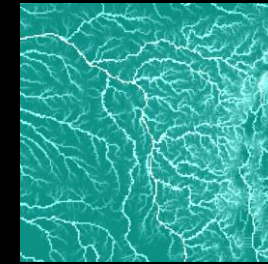
RiverMamba



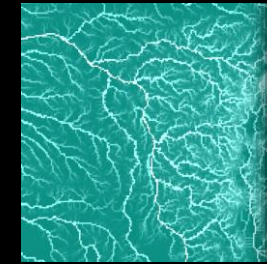
Forecast River Discharge



$\mathbf{x}_{dis24}^{t+1}$

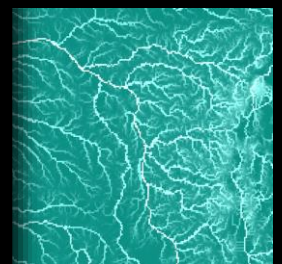


$\mathbf{x}_{dis24}^{t+2}$



$\mathbf{x}_{dis24}^{t+3}$

...

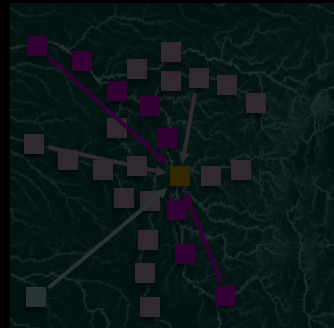


$\mathbf{x}_{dis24}^{t+7}$

Build a vision-based model



✗

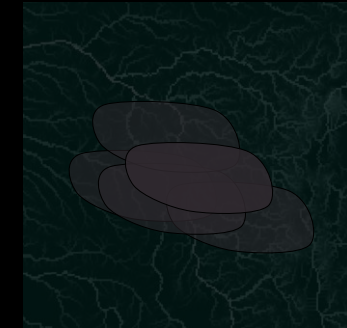


✓

Consider uncertainty in meteorological forcing



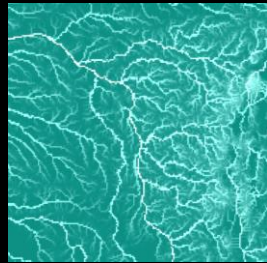
✗



✓

Motivation behind RiverMamba:

Initial Condition



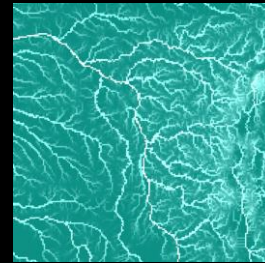
$\mathbf{x}^t$



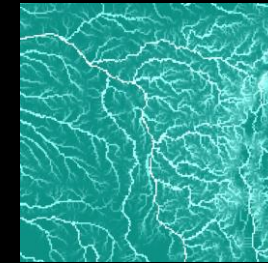
RiverMamba



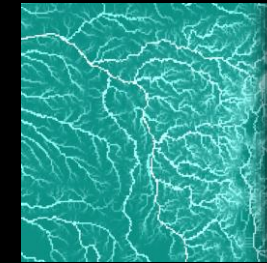
Forecast River Discharge



$\mathbf{x}_{dis24}^{t+1}$

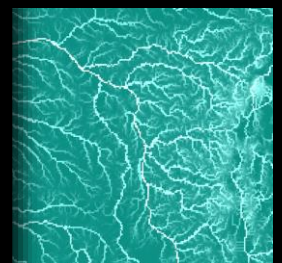


$\mathbf{x}_{dis24}^{t+2}$



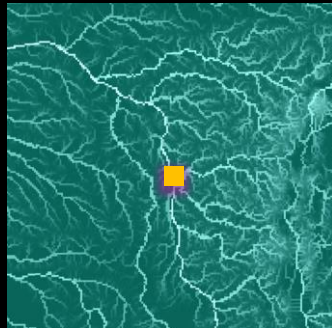
$\mathbf{x}_{dis24}^{t+3}$

...

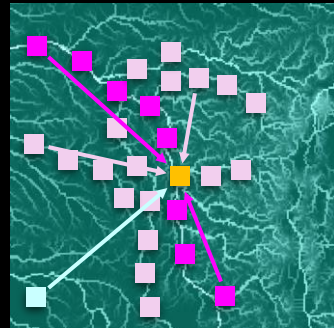


$\mathbf{x}_{dis24}^{t+7}$

Build a vision-based model



✗

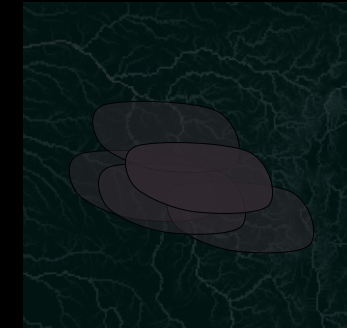


✓

Consider uncertainty in meteorological forcing



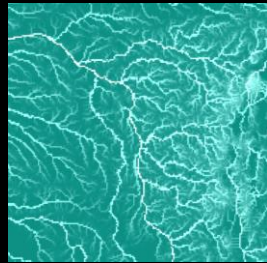
✗



✓

Motivation behind RiverMamba:

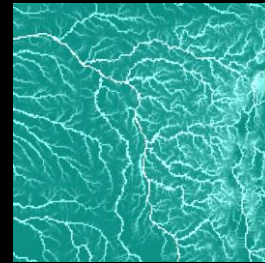
Initial Condition



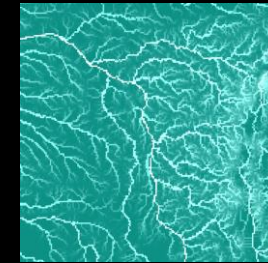
$\mathbf{x}^t$



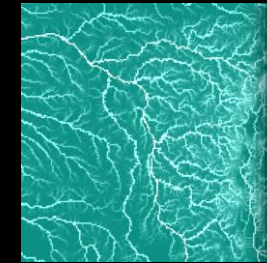
Forecast River Discharge
→



$\mathbf{x}_{dis24}^{t+1}$

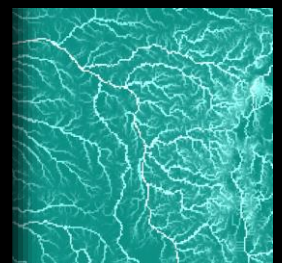


$\mathbf{x}_{dis24}^{t+2}$



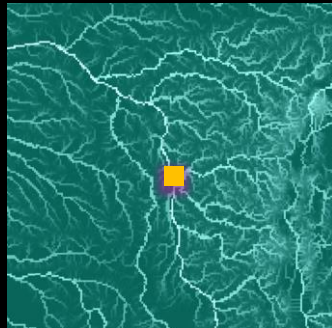
$\mathbf{x}_{dis24}^{t+3}$

...

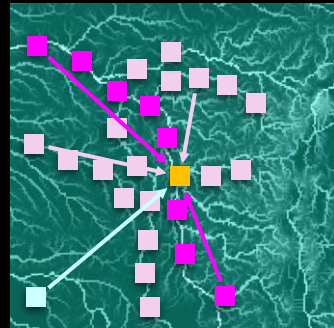


$\mathbf{x}_{dis24}^{t+7}$

Build a vision-based model

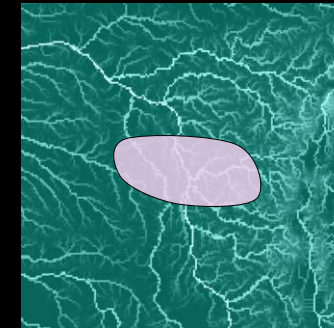


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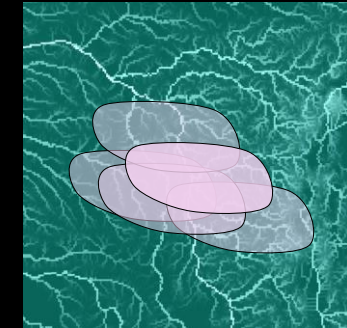


✓

Consider uncertainty in meteorological forcing

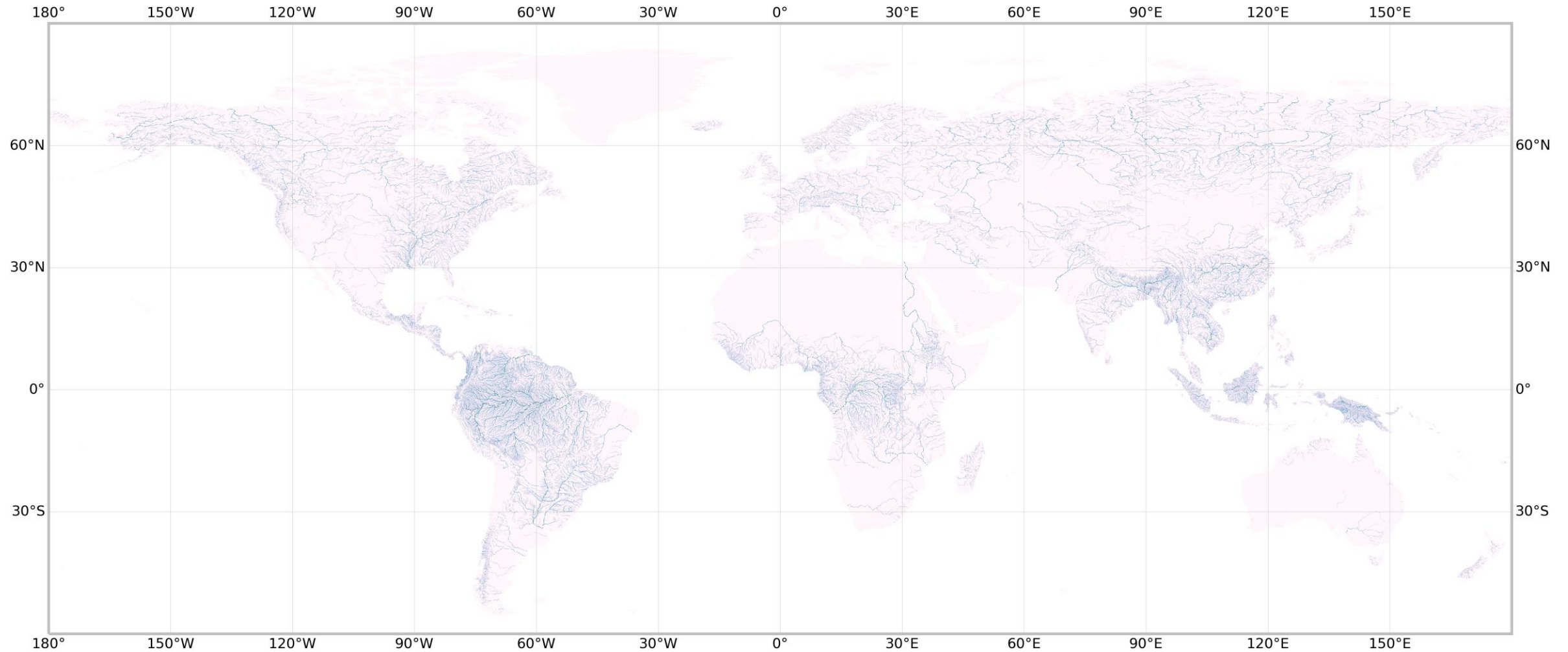


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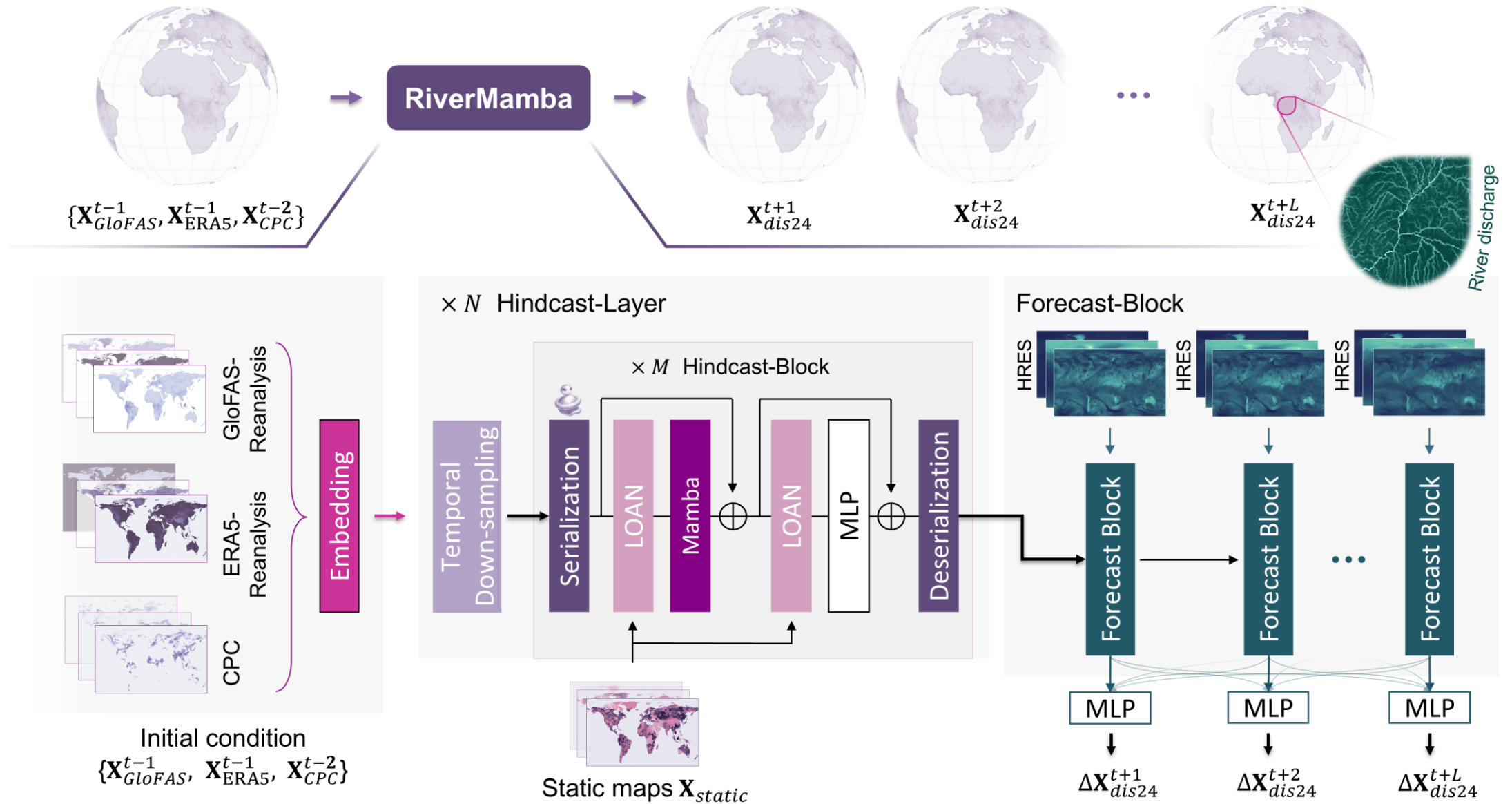


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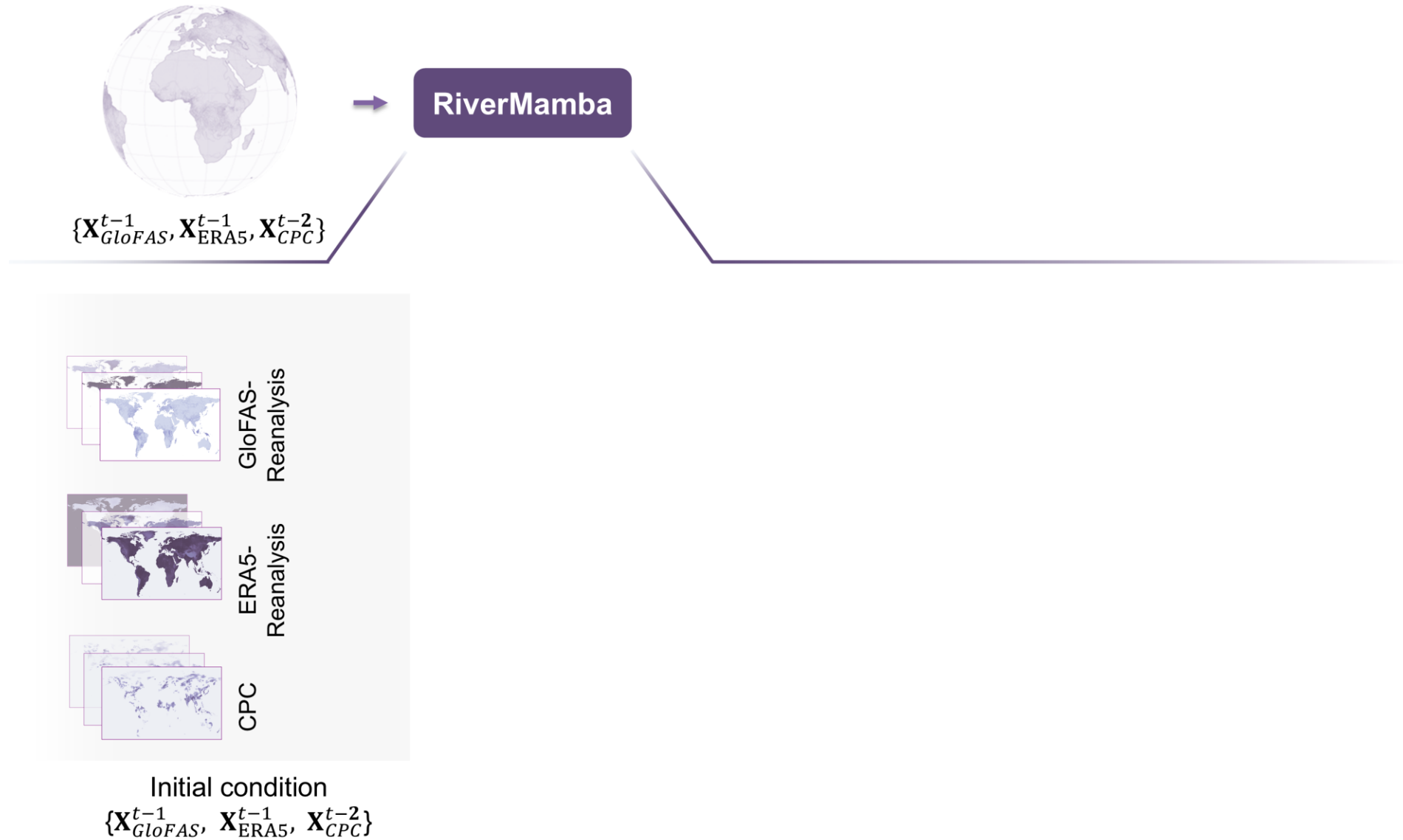
Experiments: ~1.6 M points at 0.05° resolution (3000 x 7200 pix)



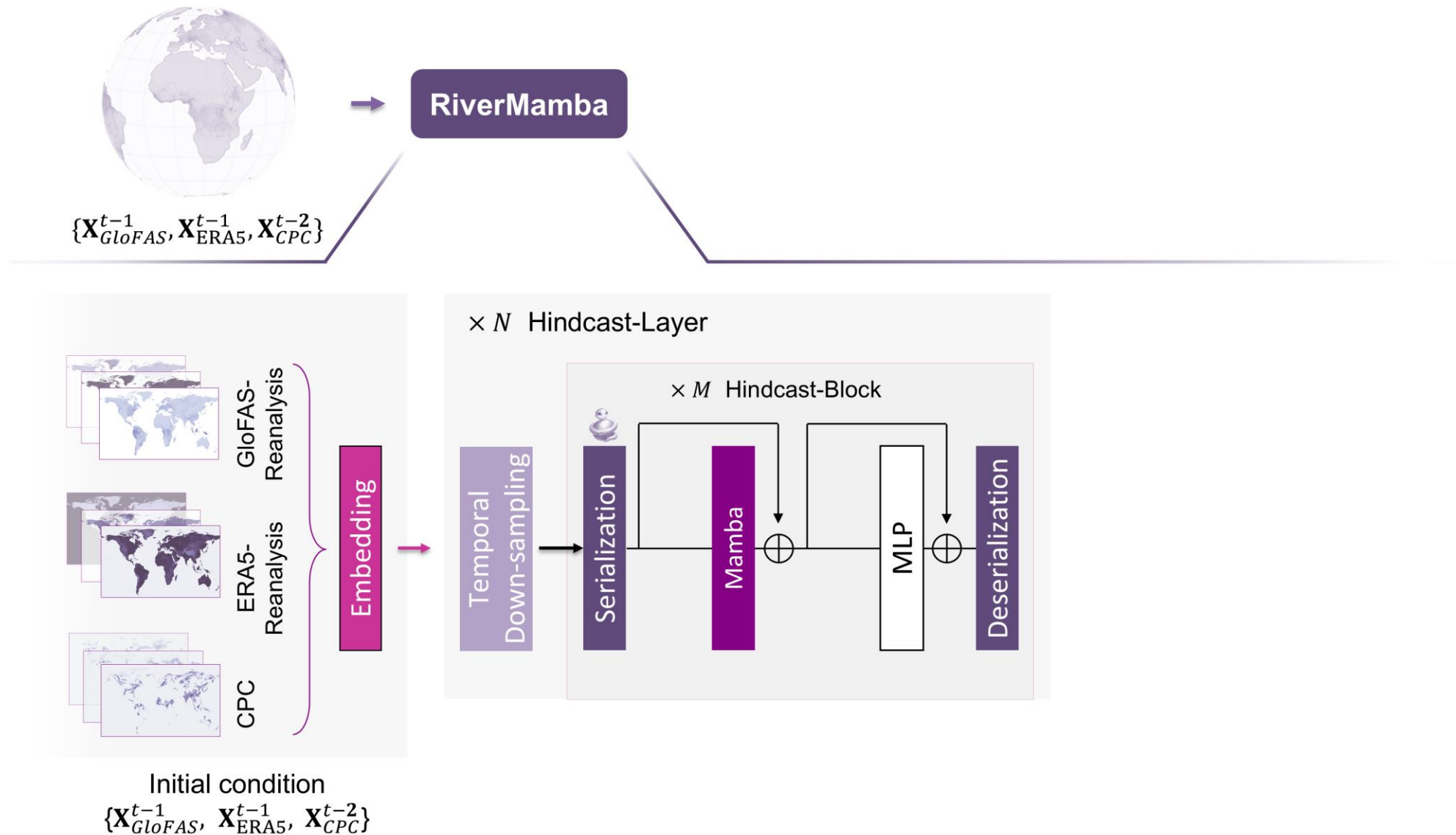
RiverMamba:



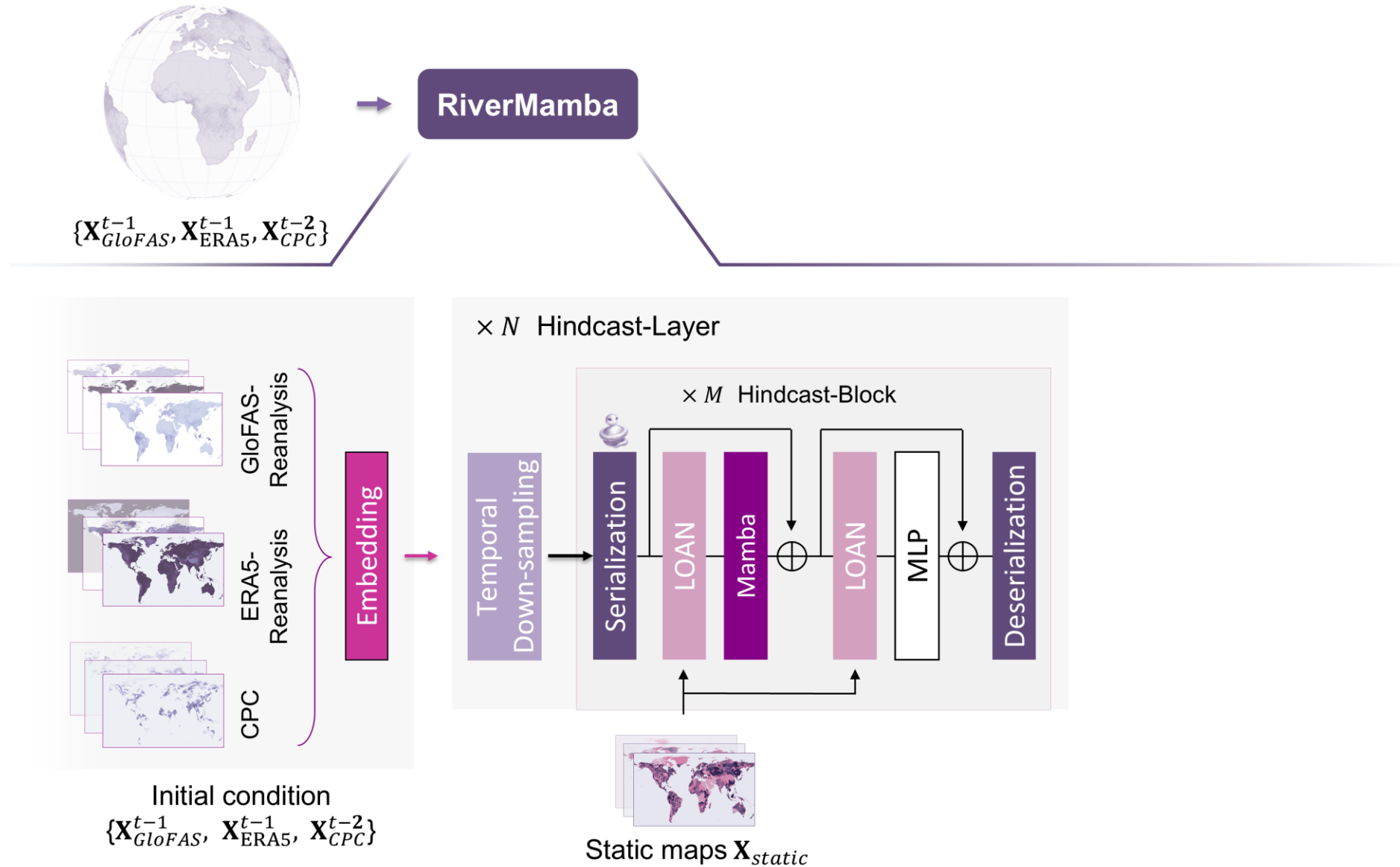
RiverMamba:



RiverMamba:



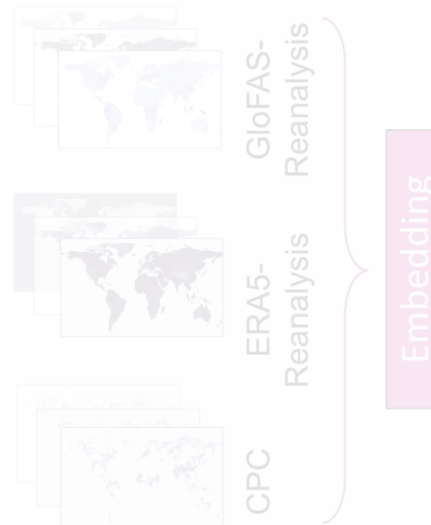
RiverMamba:



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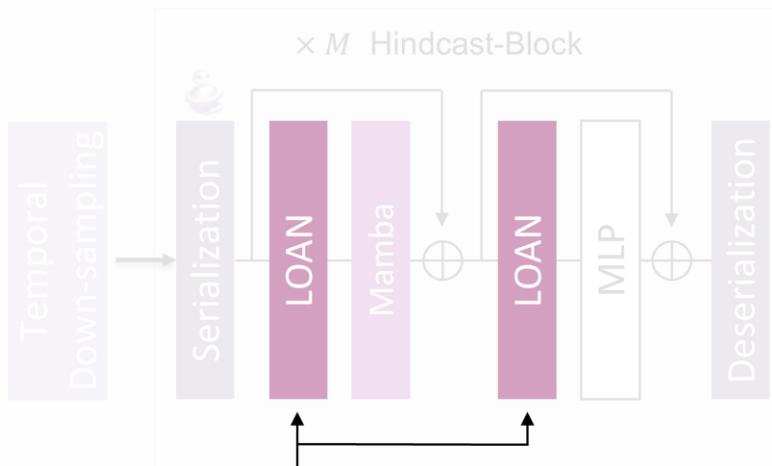


RiverMamba



Initial condition
 $\{X_{GloFAS}^{t-1}, X_{ERA5}^{t-1}, X_{CPC}^{t-2}\}$

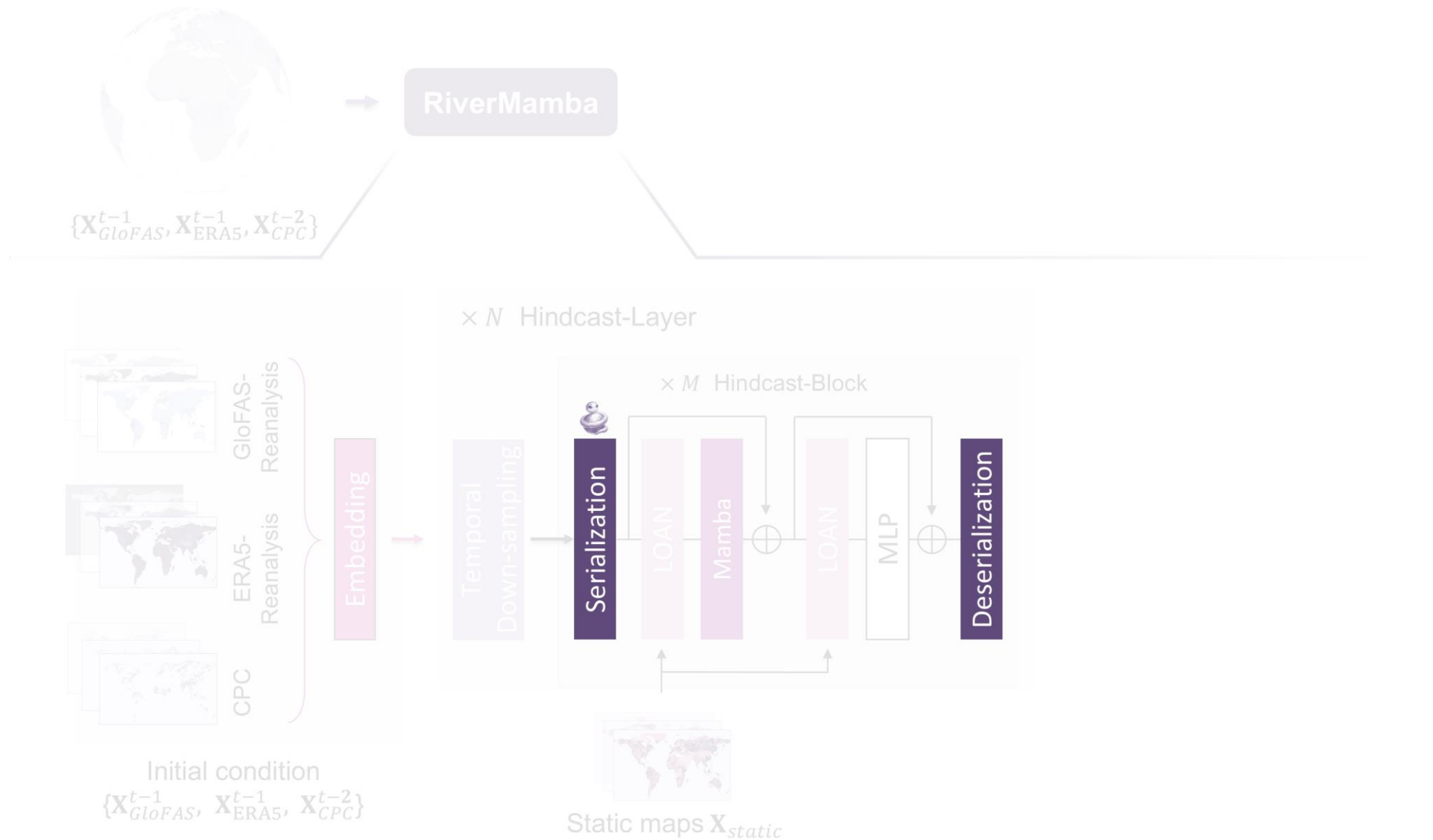
$\times N$ Hindcast-Layer



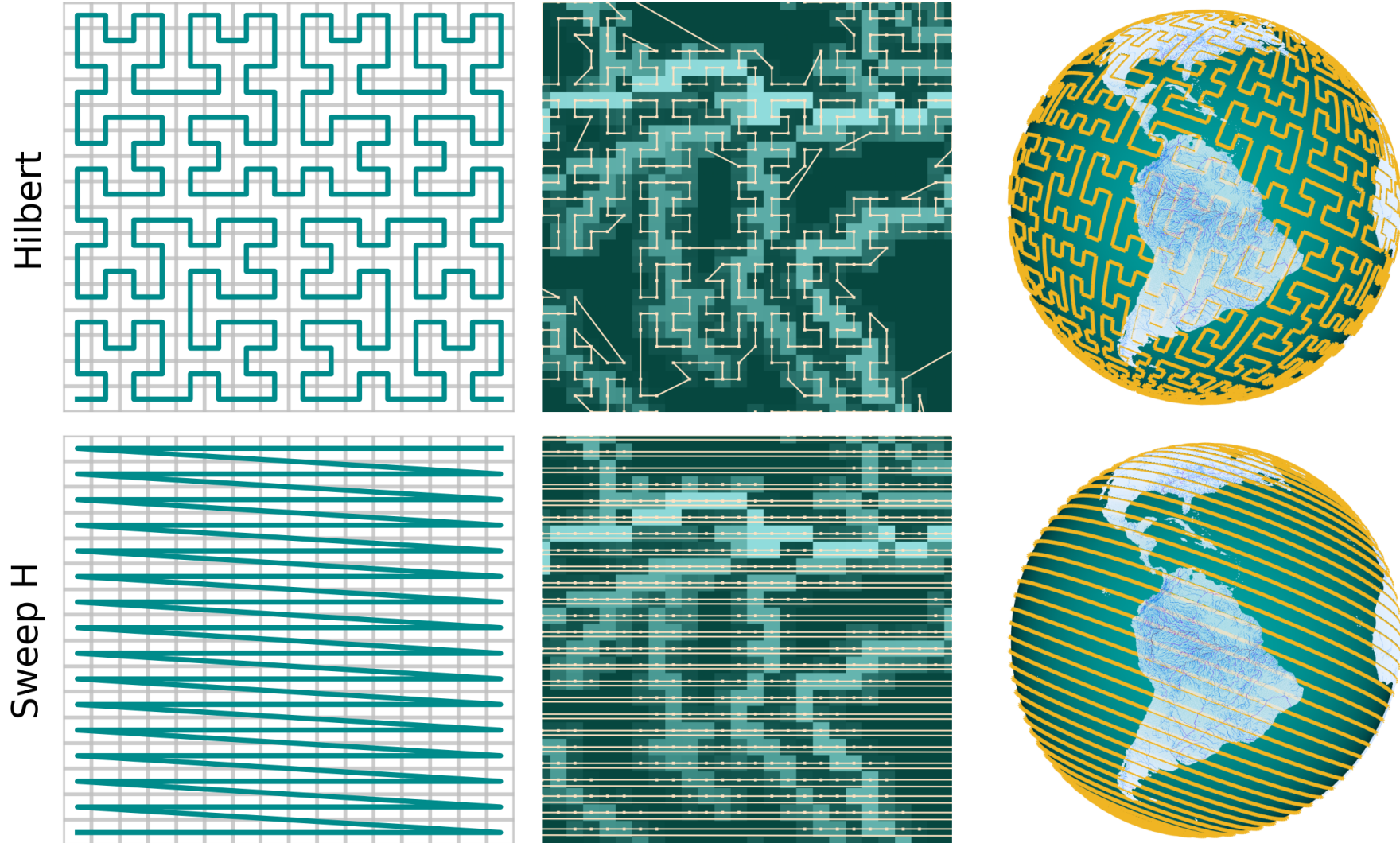
Static maps X_{static}

LOAN: Location-Aware Adaptive Normalization: A Deep Learning Approach for Wildfire Danger Forecasting
Shams Eddin et al., (2023)

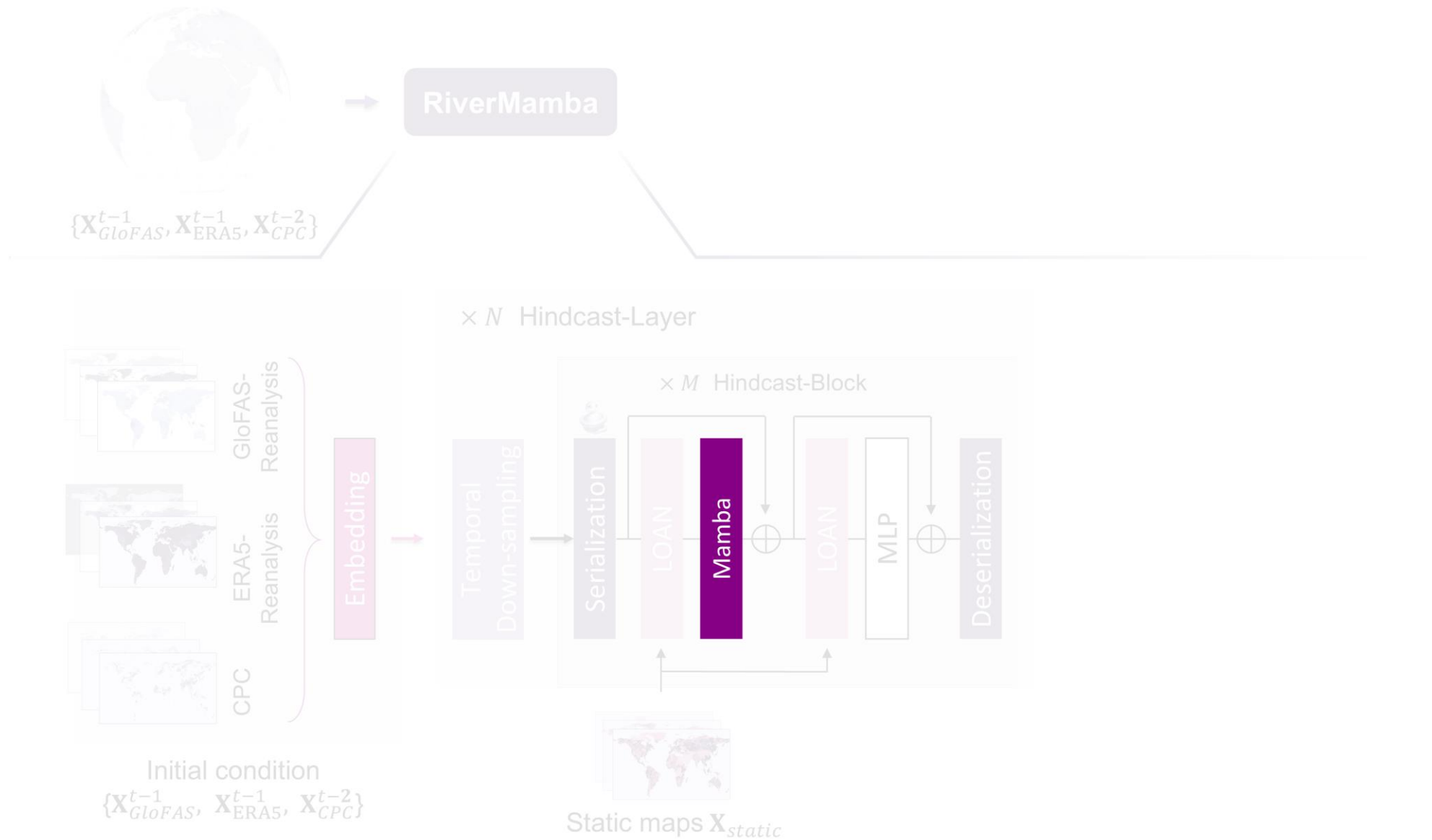
RiverMamba:



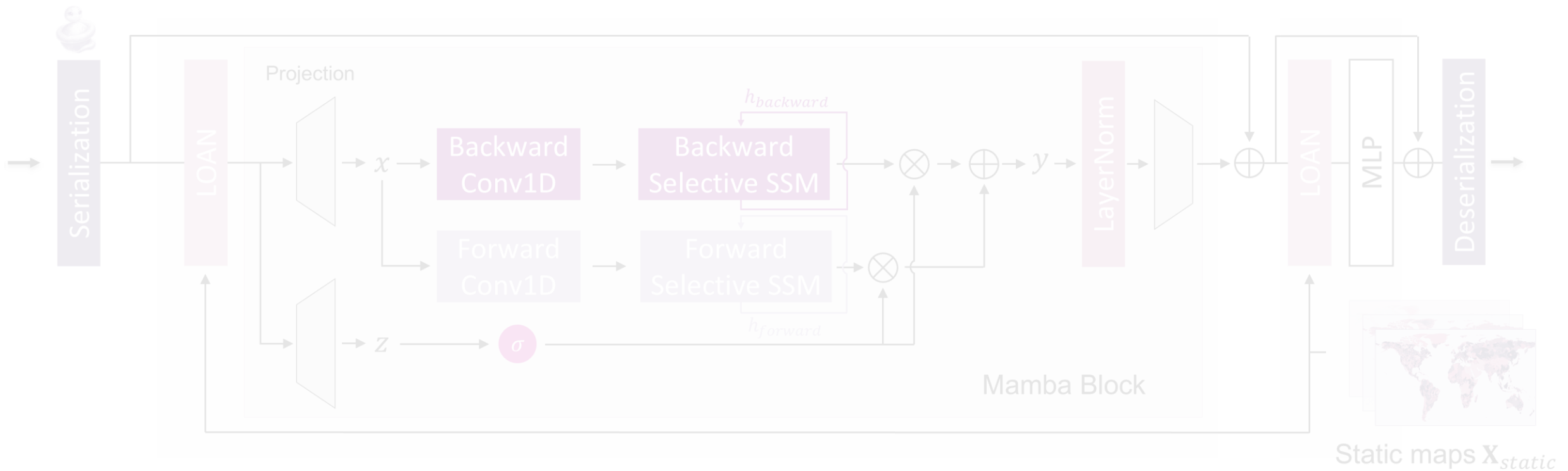
Space-filling curves: $\varphi: \mathbb{Z}^3 \rightarrow \mathbb{N}$



RiverMamba:



Vision Mamba:



$$h'(t) = \mathbf{A} h(t-1) + \mathbf{B} x(t)$$

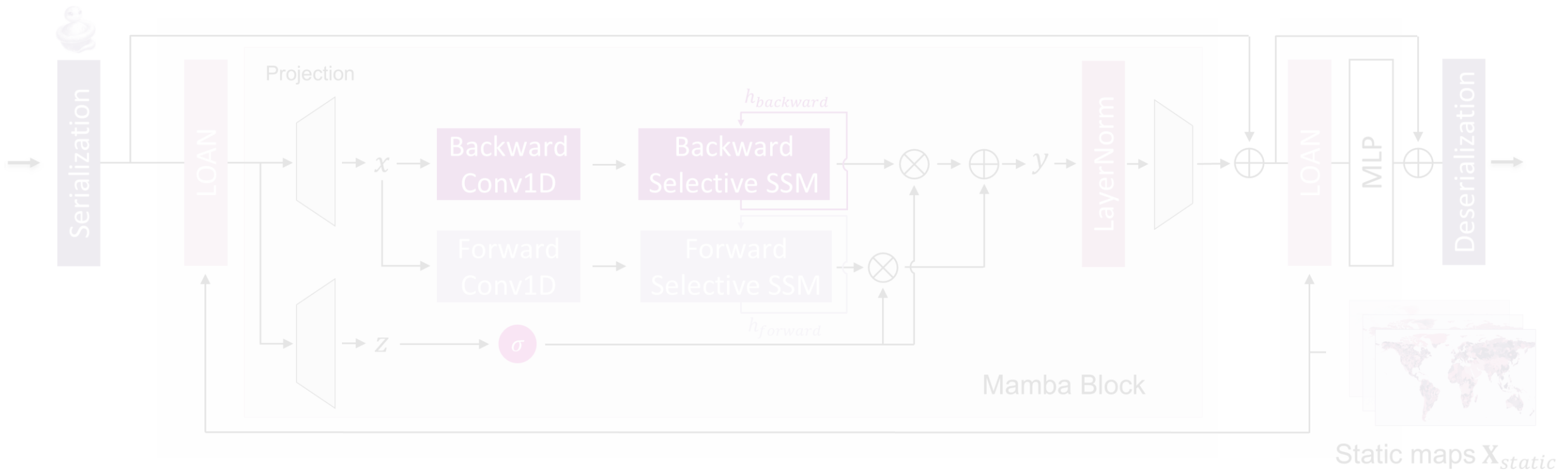
$$y(t) = \mathbf{C} h(t) + \mathbf{D} x(t)$$



$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$

Vision Mamba:



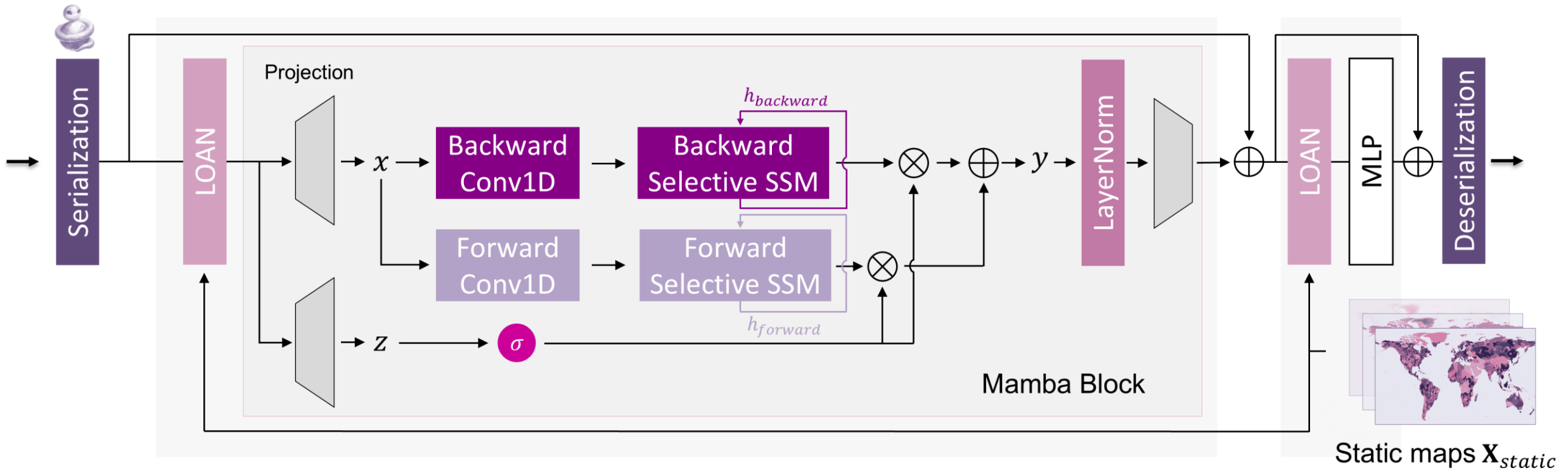
$$\begin{aligned} h'(t) &= \mathbf{A} h(t-1) + \mathbf{B} x(t) \\ y(t) &= \mathbf{C} h(t) + \mathbf{D} x(t) \end{aligned}$$



$$\begin{aligned} h_t &= \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t \\ y_t &= \mathbf{C} h_t + \mathbf{D} x_t \end{aligned}$$

[Mamba: Gu, Albert and Dao, Tri, "Mamba: Linear-time sequence modeling with selective state spaces." arXiv preprint arXiv:2312.00752 (2023)]

Vision Mamba:



$$\begin{aligned} h'(t) &= \mathbf{A} h(t-1) + \mathbf{B} x(t) \\ y(t) &= \mathbf{C} h(t) + \mathbf{D} x(t) \end{aligned}$$



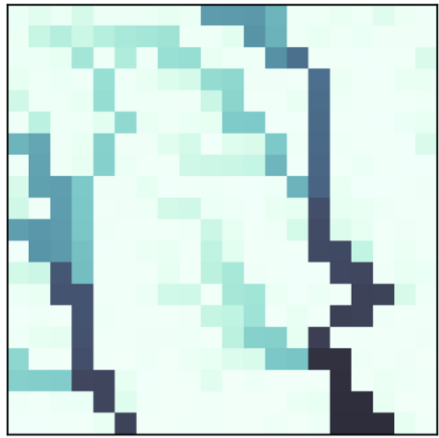
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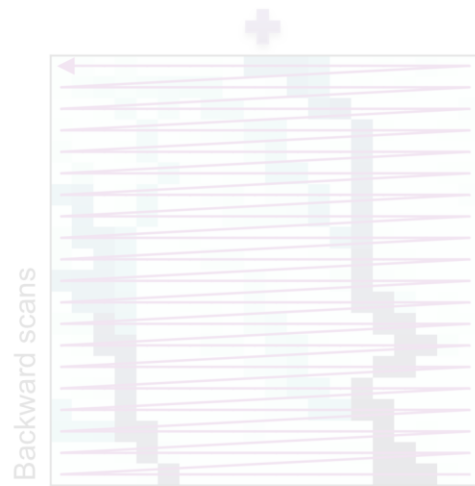
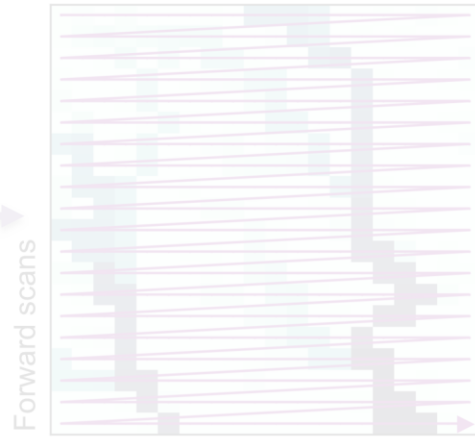
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

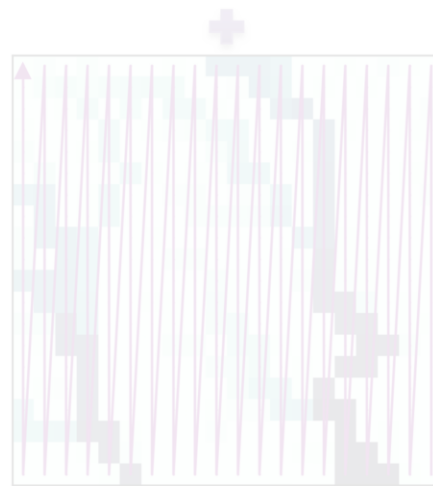
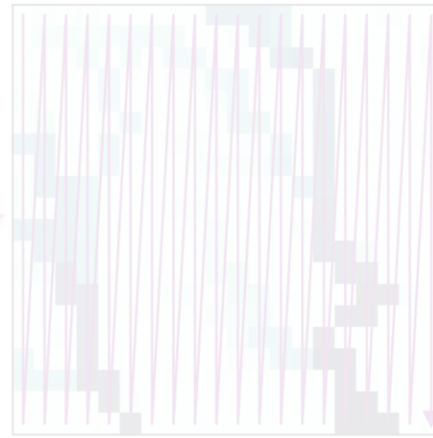
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



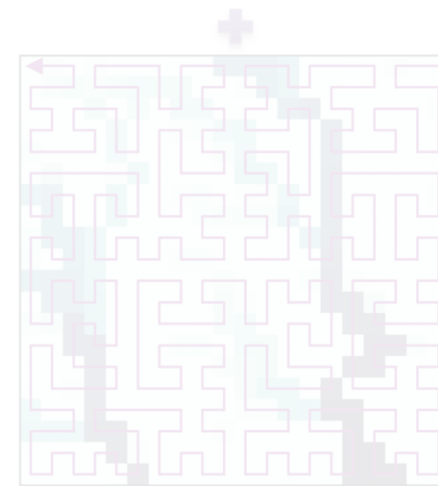
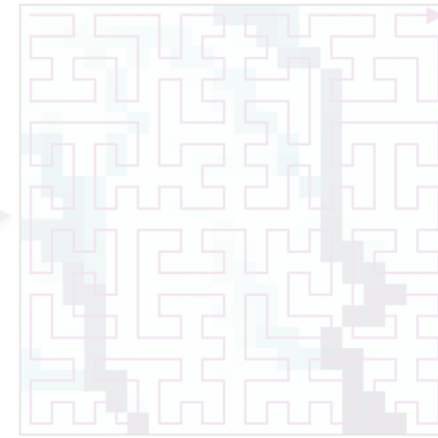
(a) Input points



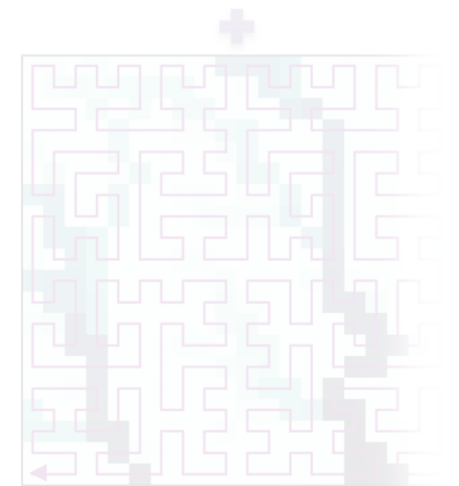
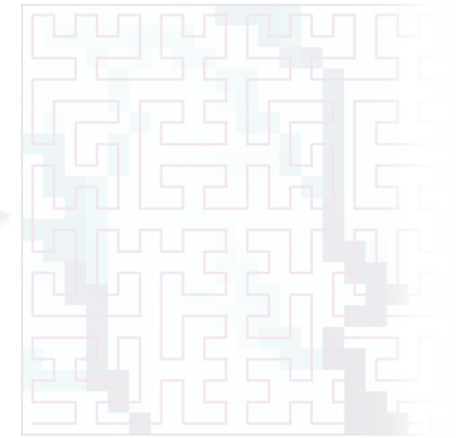
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V



(d) 3rd Block - Gilbert

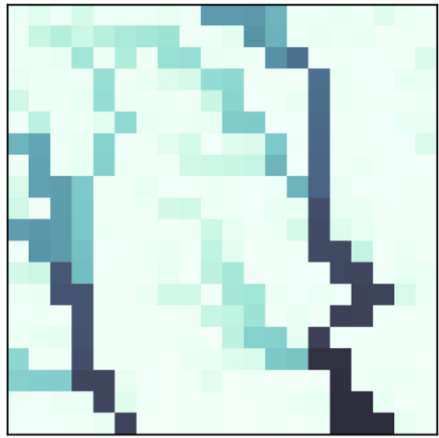


(e) 4th Block - Gilbert Trans

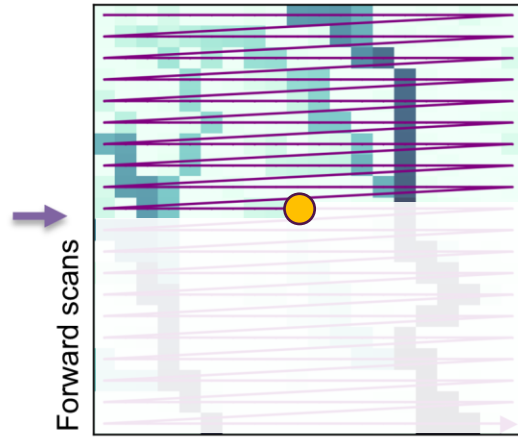
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

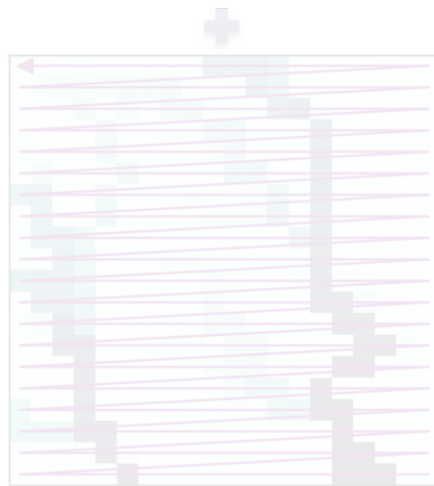
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

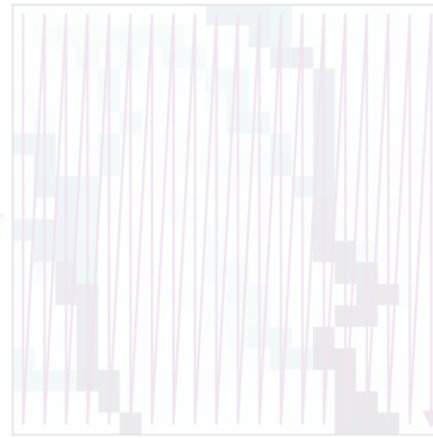


Forward scans

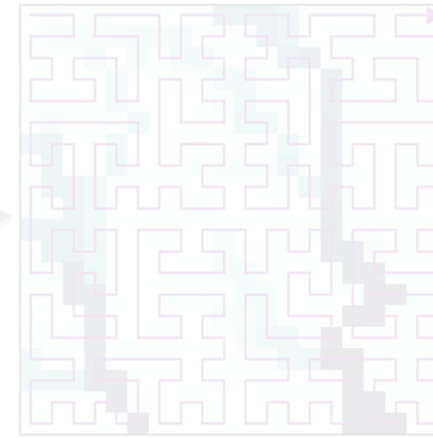


Backward scans

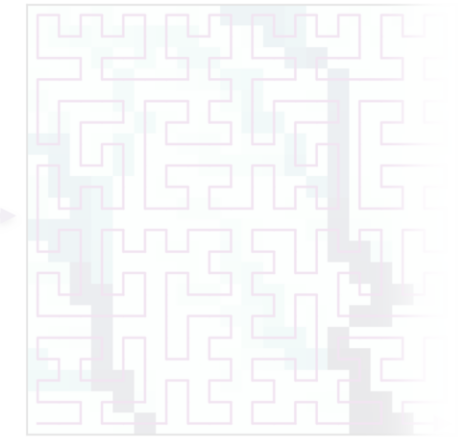
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V



(d) 3rd Block - Gilbert

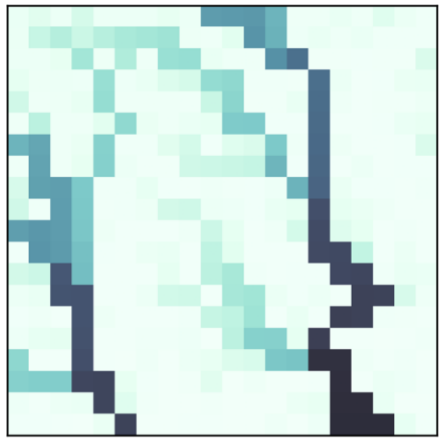


(e) 4th Block - Gilbert Trans

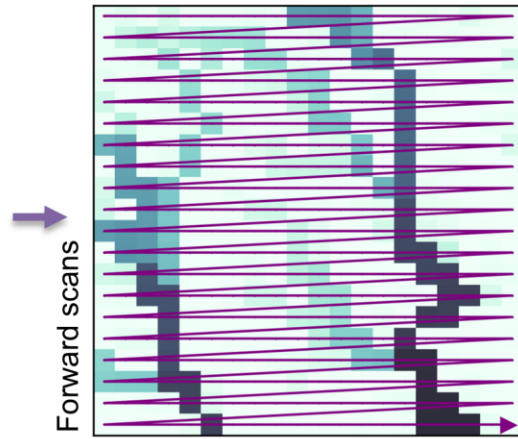
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

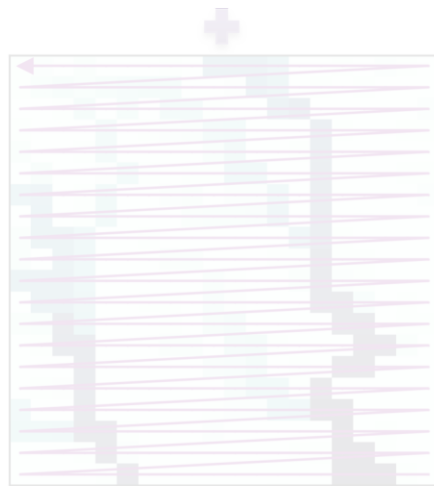
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

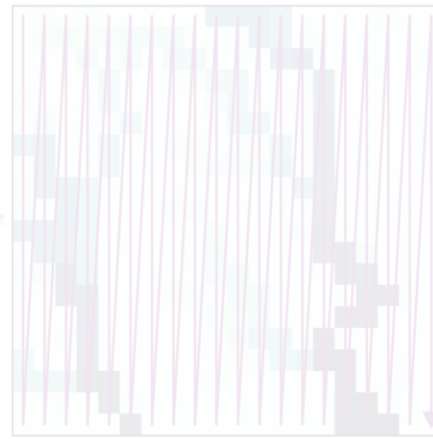


Forward scans

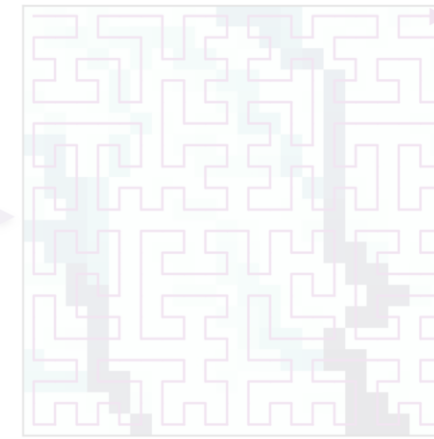


Backward scans

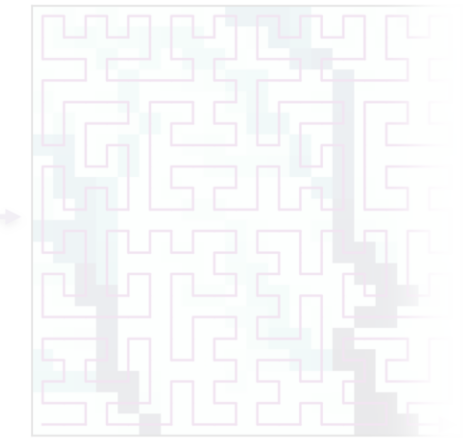
(b) 1st Block - Sweep H



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(d) 3rd Block - Gilbert

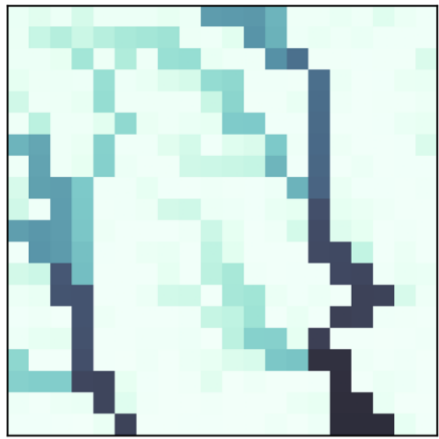


(e) 4th Block - Gilbert Trans

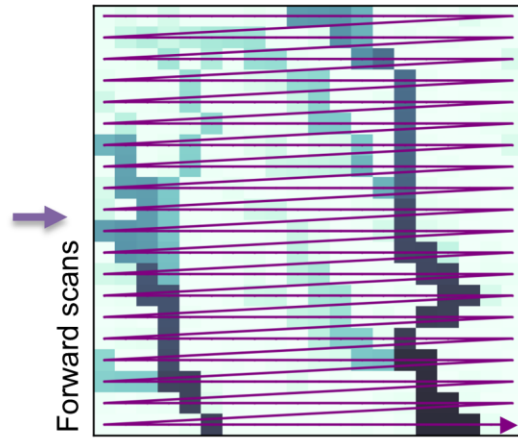
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

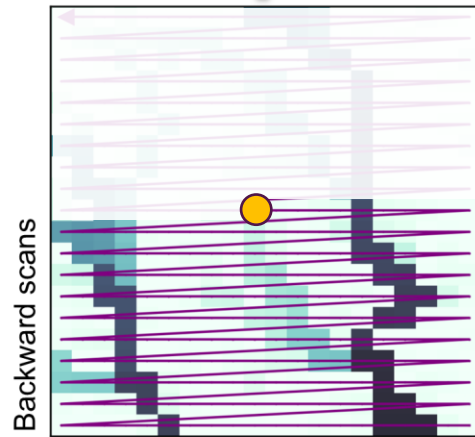
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

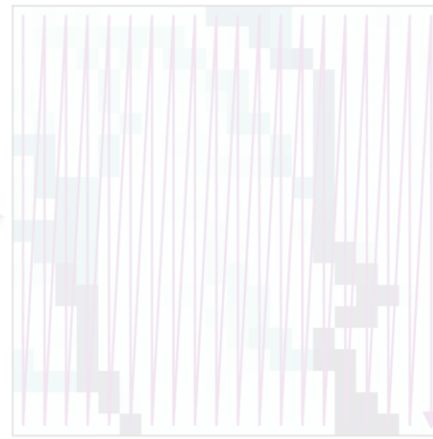


Forward scans

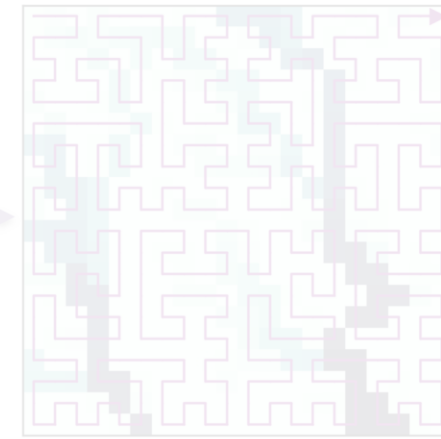


Backward scans

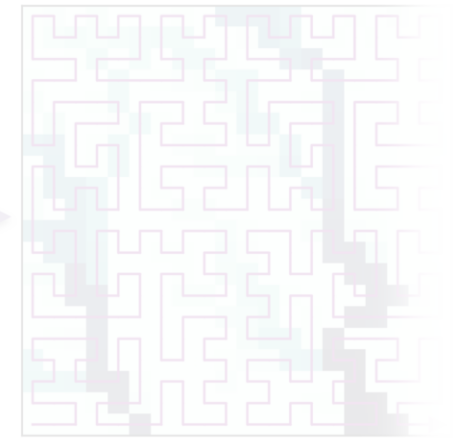
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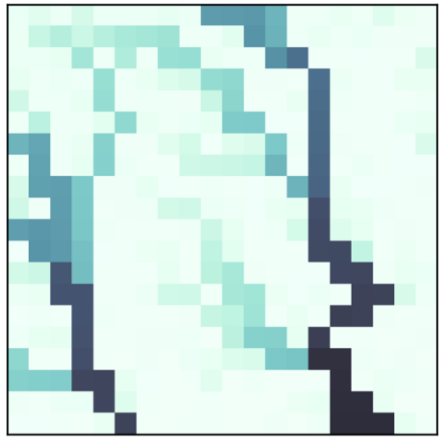


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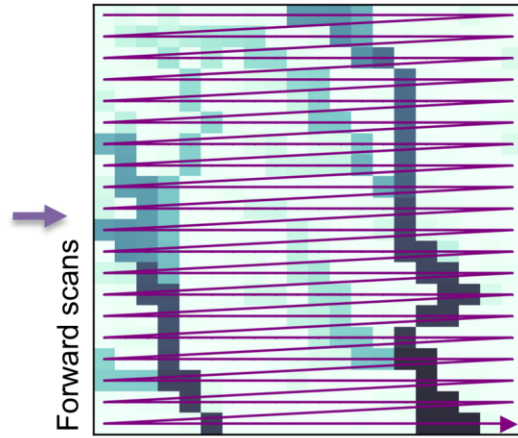
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

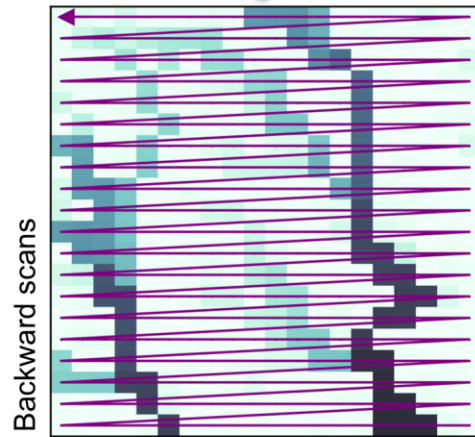
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

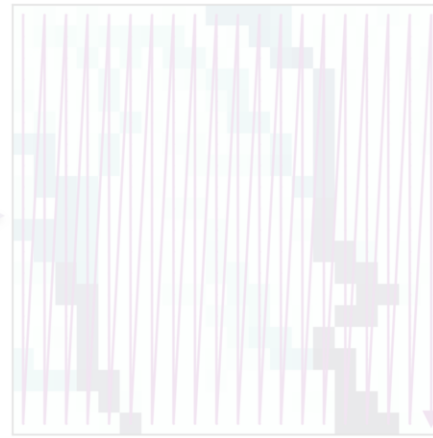


Forward scans

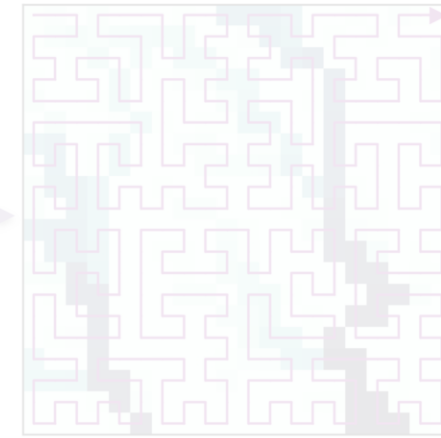


Backward scans

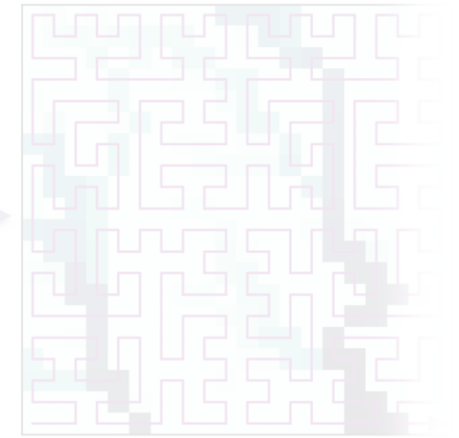
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V



(d) 3rd Block - Gilbert

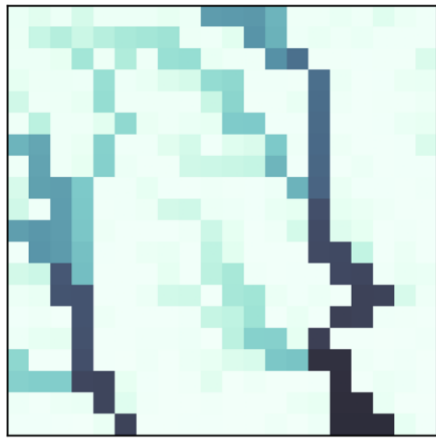


(e) 4th Block - Gilbert Trans

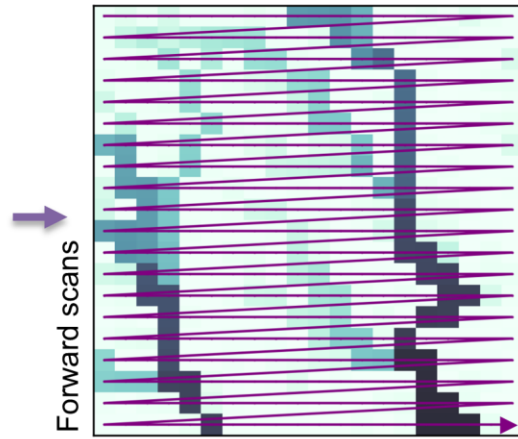
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

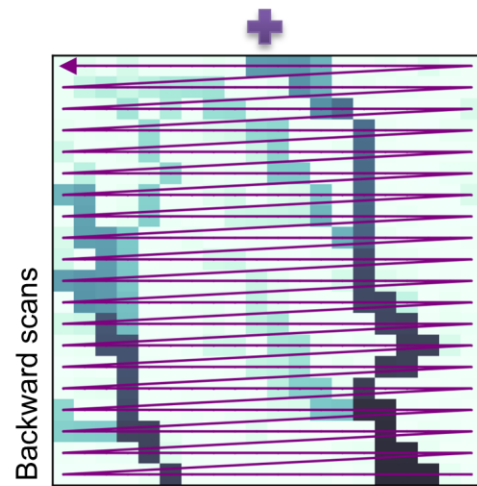
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

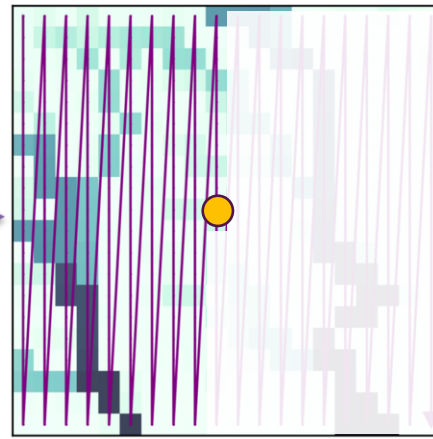


Forward scans

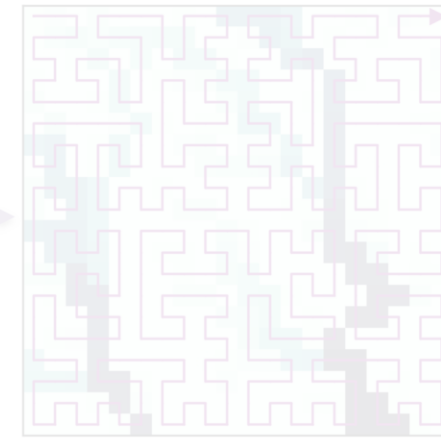


Backward scans

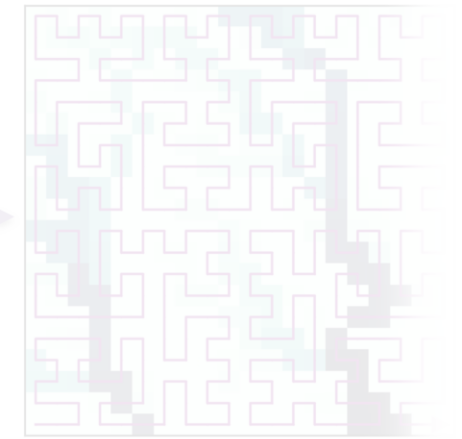
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V



(d) 3rd Block - Gilbert

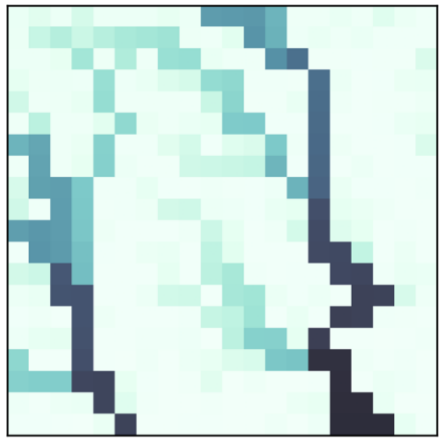


(e) 4th Block - Gilbert Trans

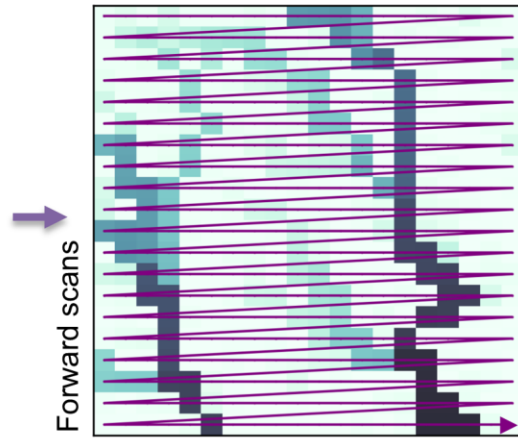
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

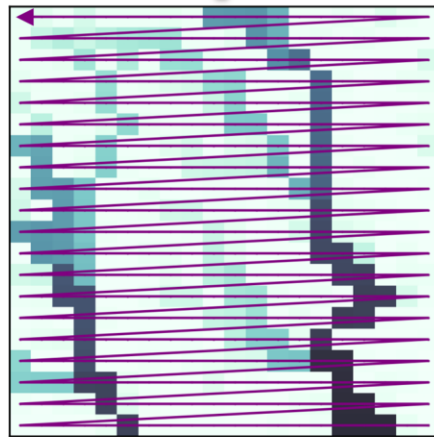
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

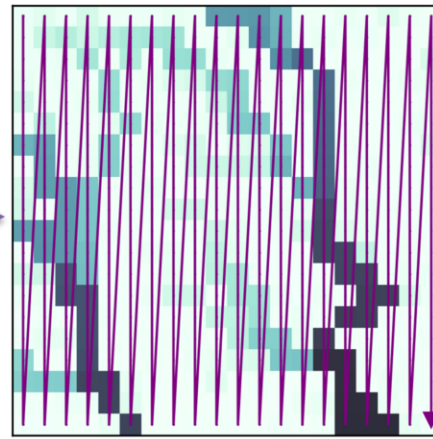


Forward scans

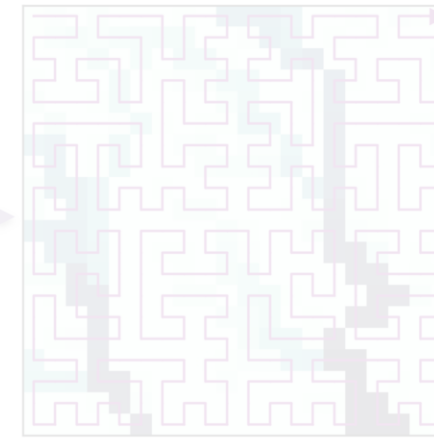


Backward scans

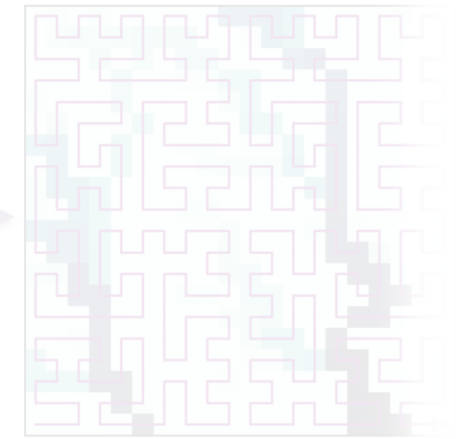
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V



(d) 3rd Block - Gilbert

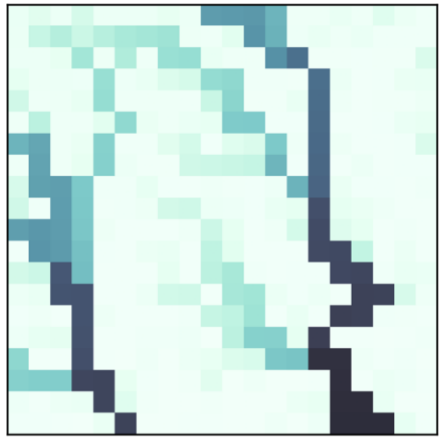


(e) 4th Block - Gilbert Trans

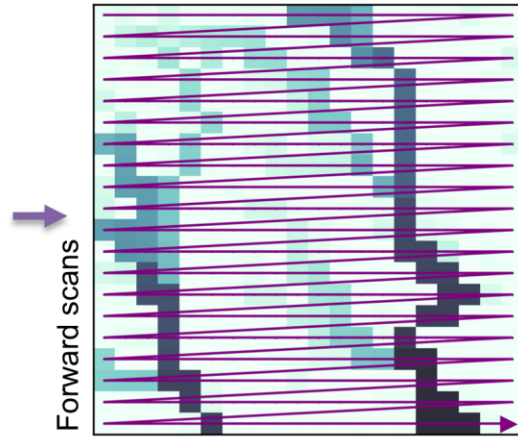
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

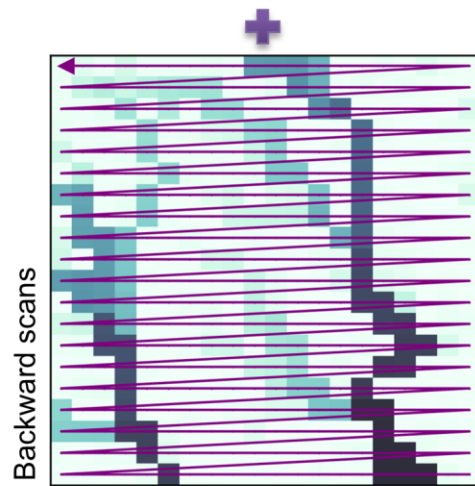
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

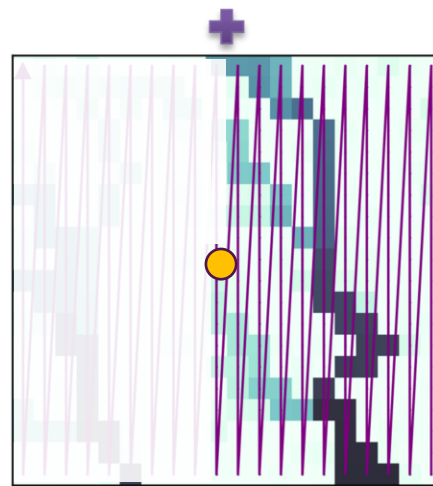
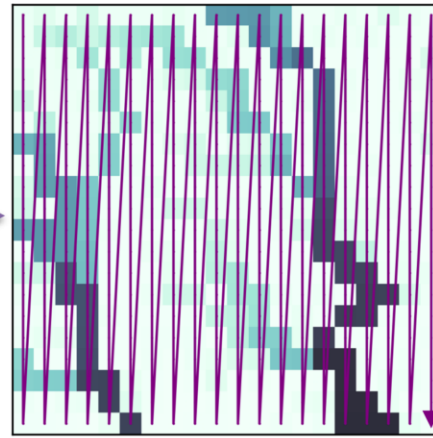


Forward scans

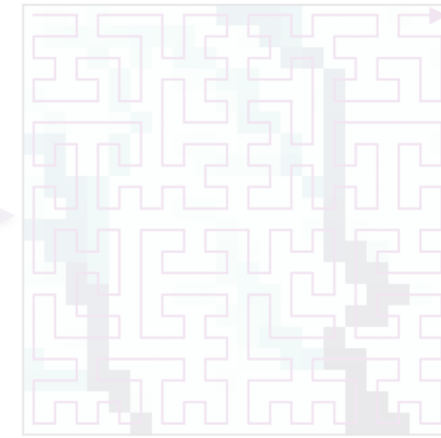


Backward scans

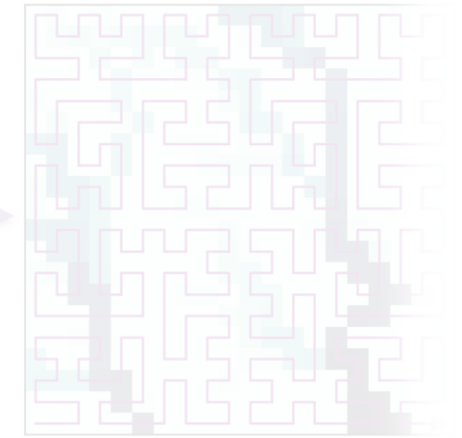
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V



(d) 3rd Block - Gilbert

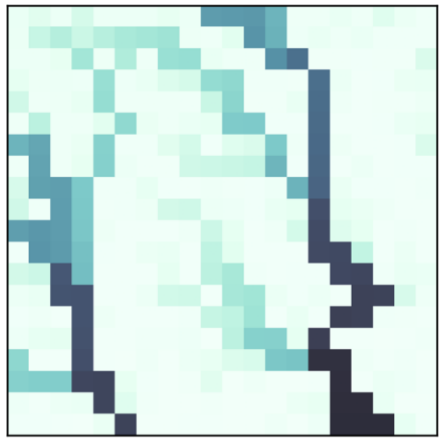


(e) 4th Block - Gilbert Trans

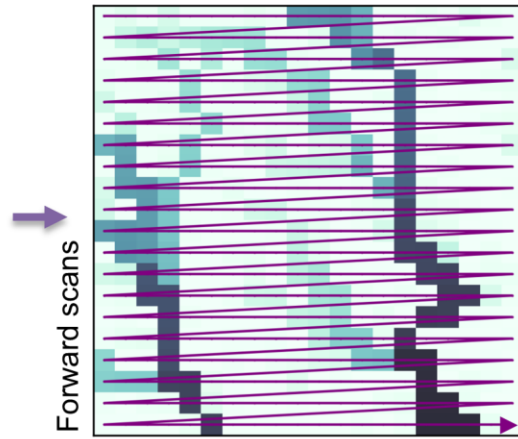
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

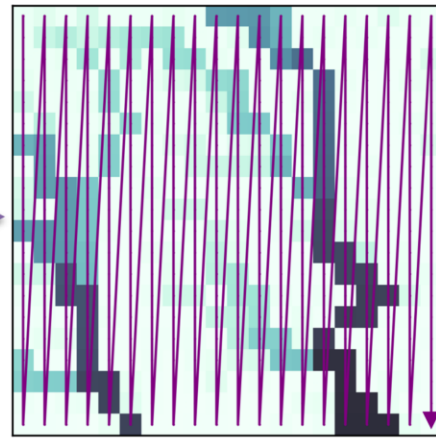
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



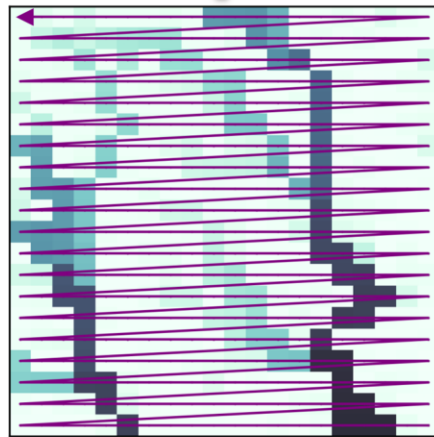
(a) Input points



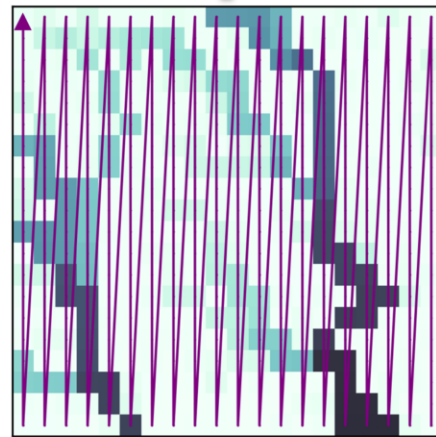
Forward scans



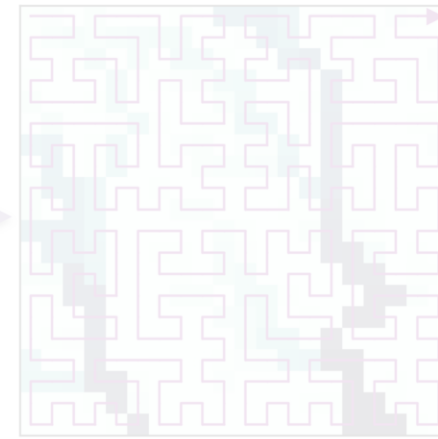
Backward scans



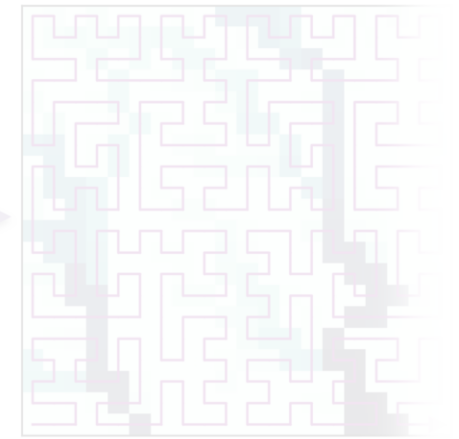
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V



(d) 3rd Block - Gilbert

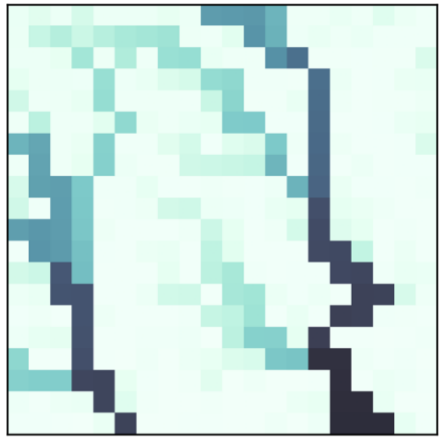


(e) 4th Block - Gilbert Trans

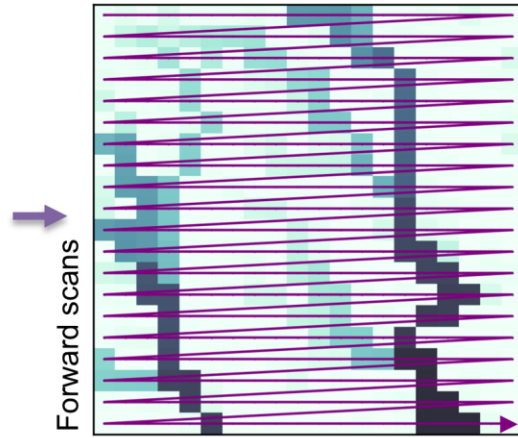
Vision Mamba:

$$h_t = \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t$$

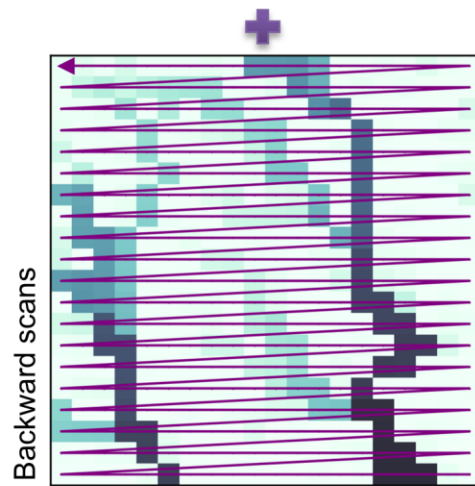
$$y_t = \mathbf{C} h_t + \mathbf{D} x_t$$



(a) Input points

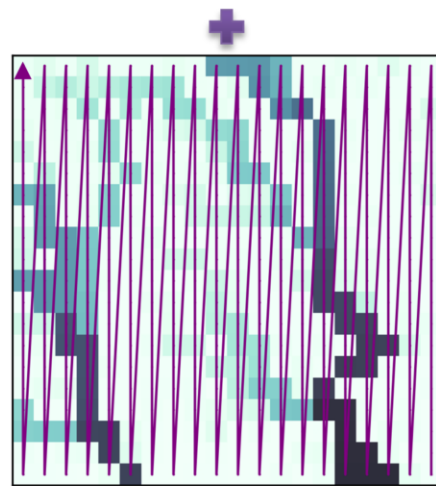
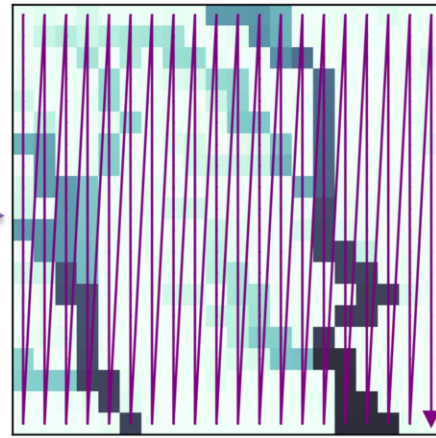


Forward scans

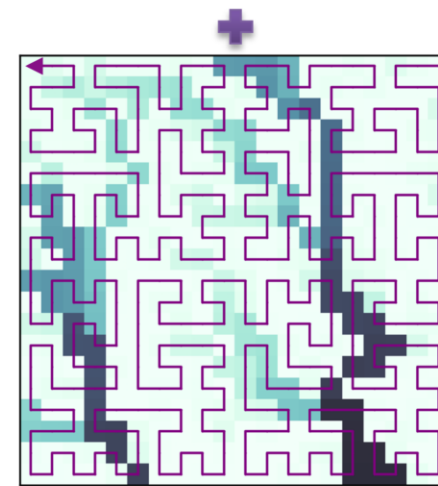
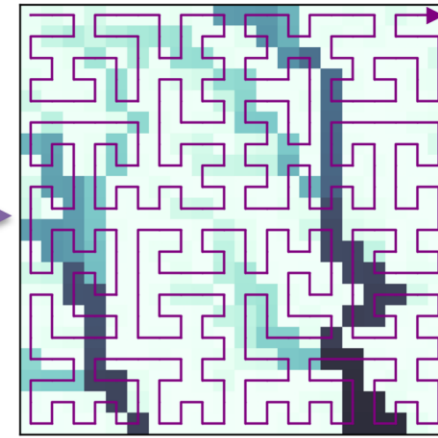


Backward scans

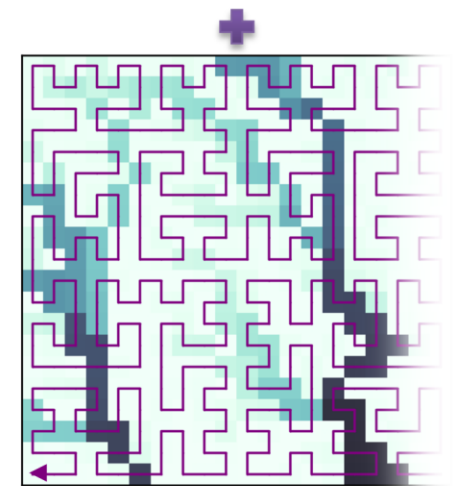
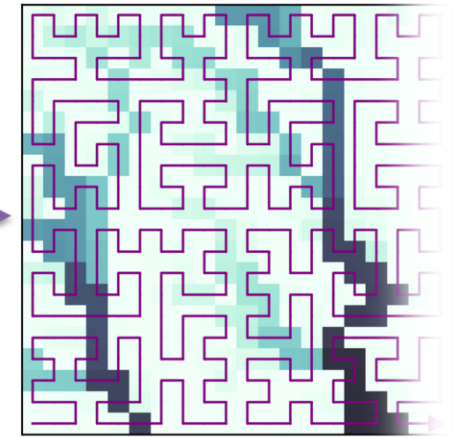
(b) 1st Block - Sweep H



(c) 2nd Block - Sweep V

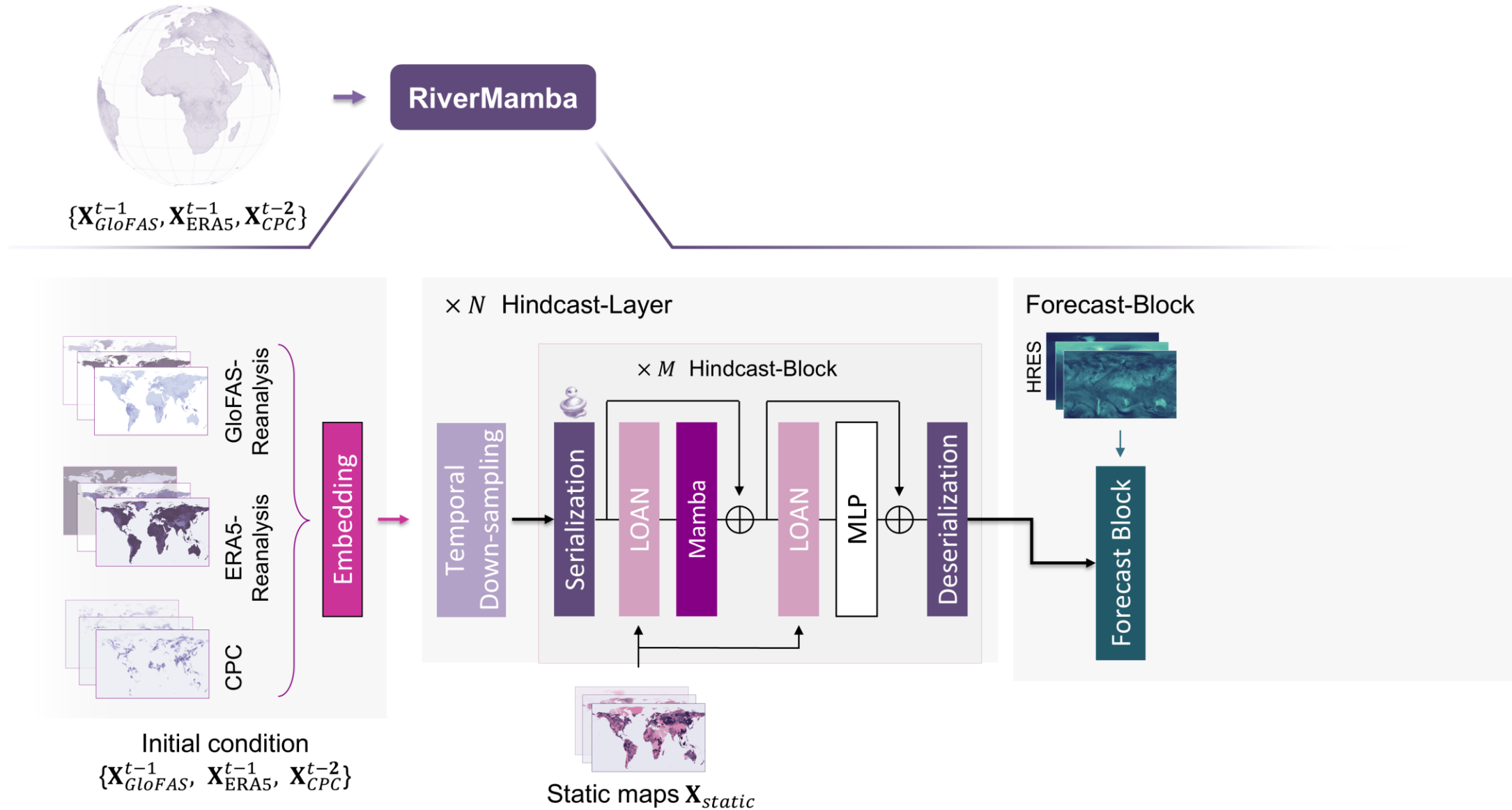


(d) 3rd Block - Gilbert

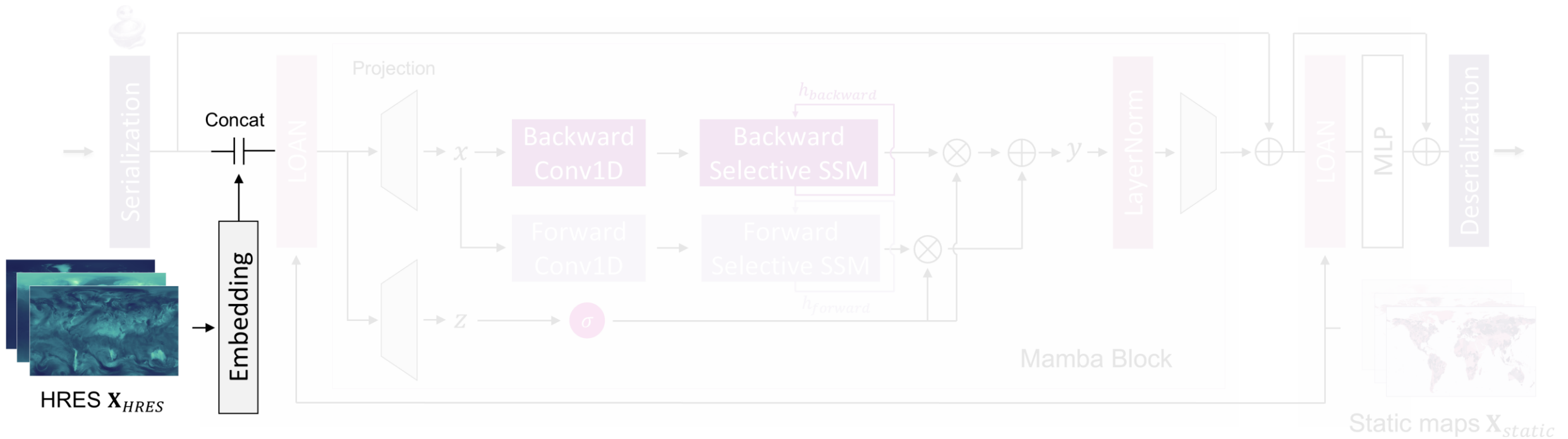


(e) 4th Block - Gilbert Trans

RiverMamba:



Forecast block:

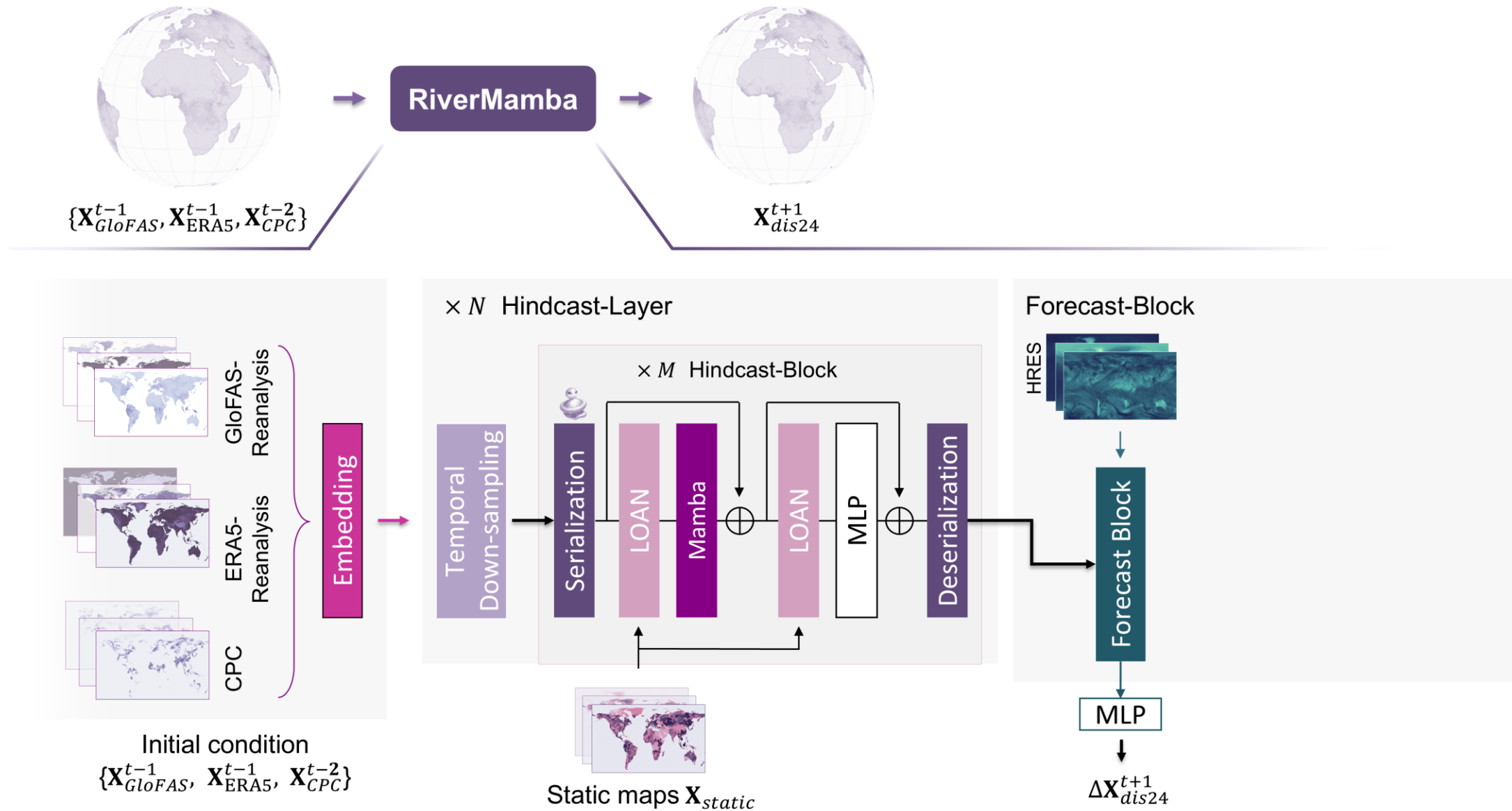


$$\begin{aligned} h'(t) &= \mathbf{A} h(t-1) + \mathbf{B} x(t) \\ y(t) &= \mathbf{C} h(t) + \mathbf{D} x(t) \end{aligned}$$

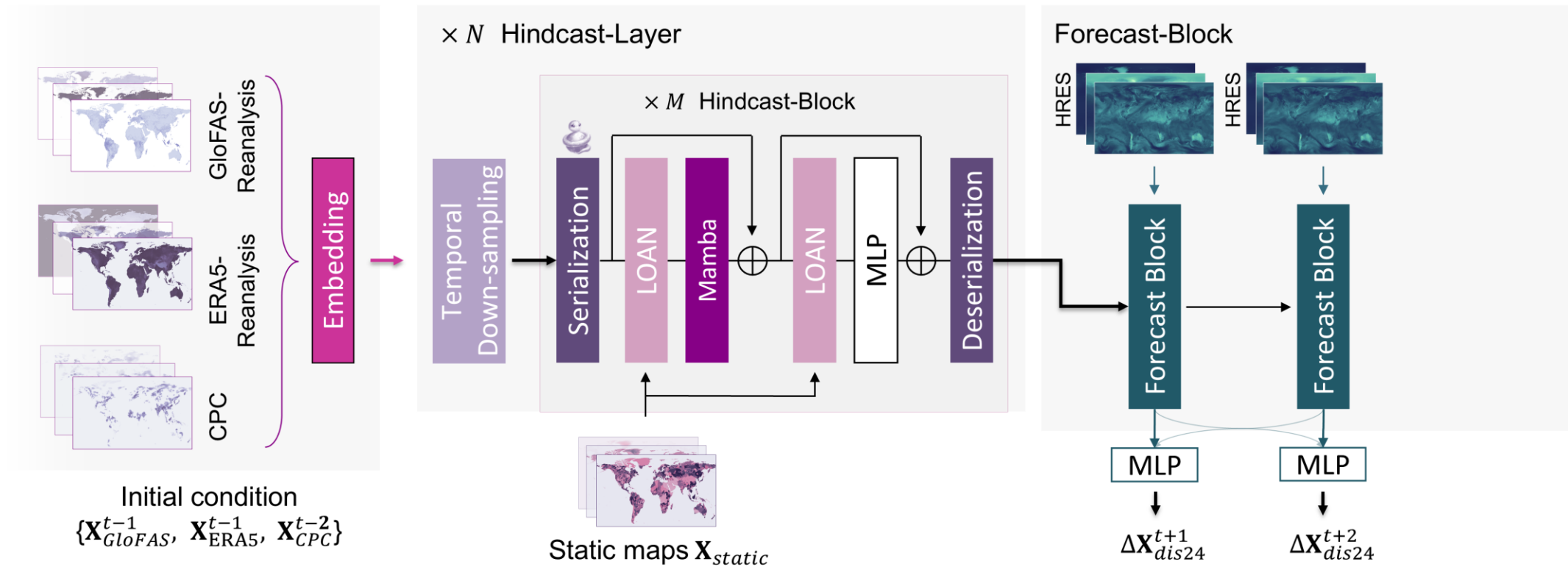
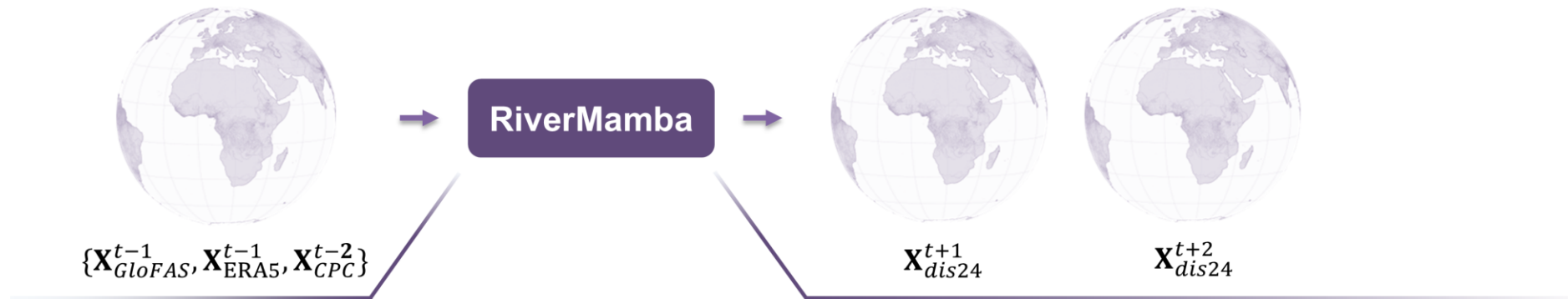


$$\begin{aligned} h_t &= \bar{\mathbf{A}} h_{t-1} + \bar{\mathbf{B}} x_t \\ y_t &= \mathbf{C} h_t + \mathbf{D} x_t \end{aligned}$$

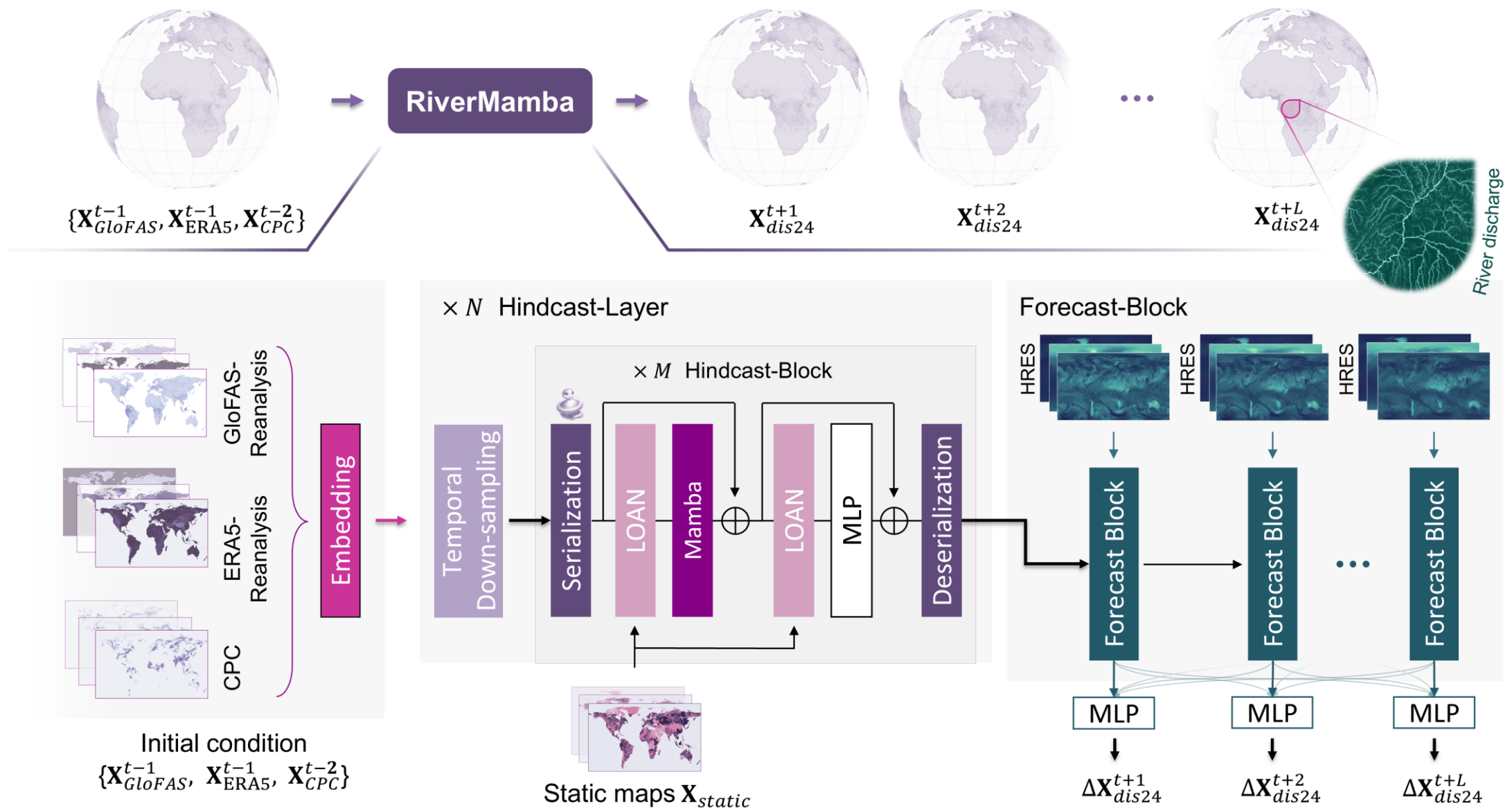
RiverMamba:



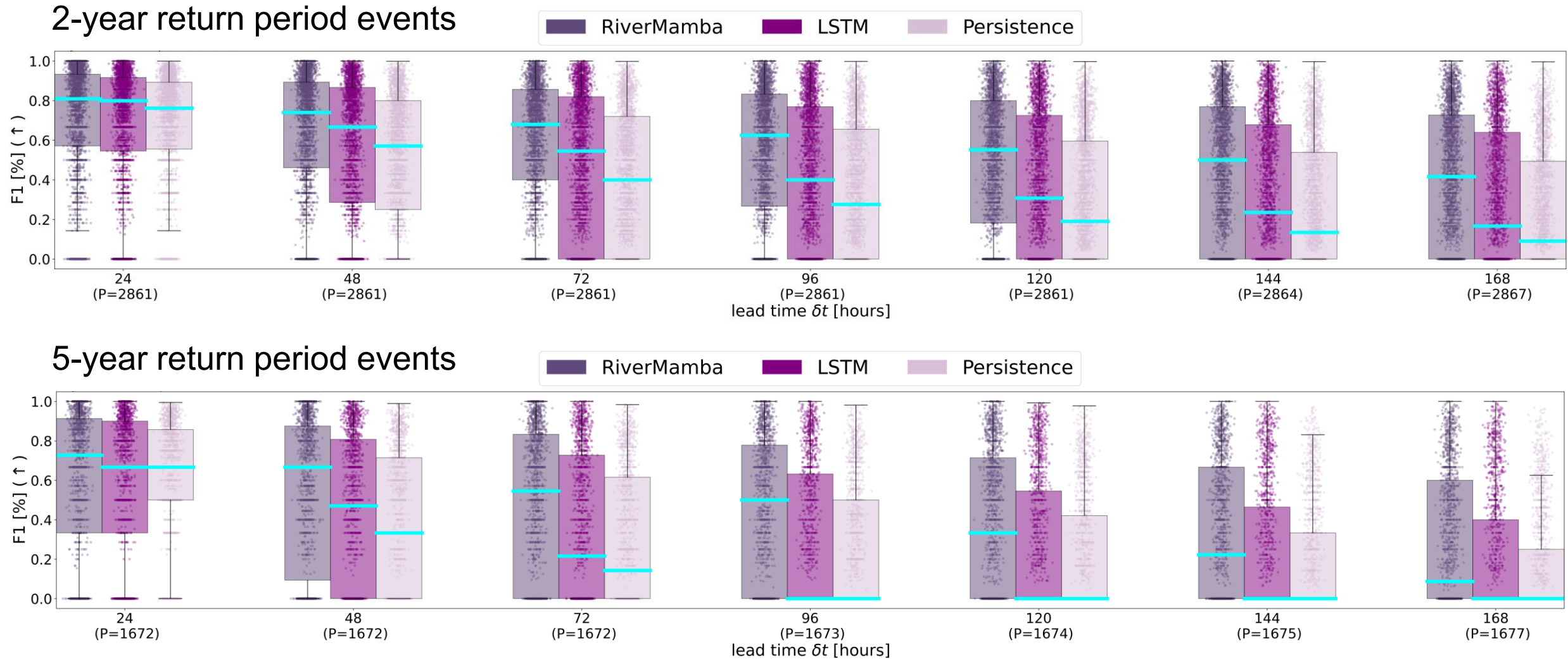
RiverMamba:



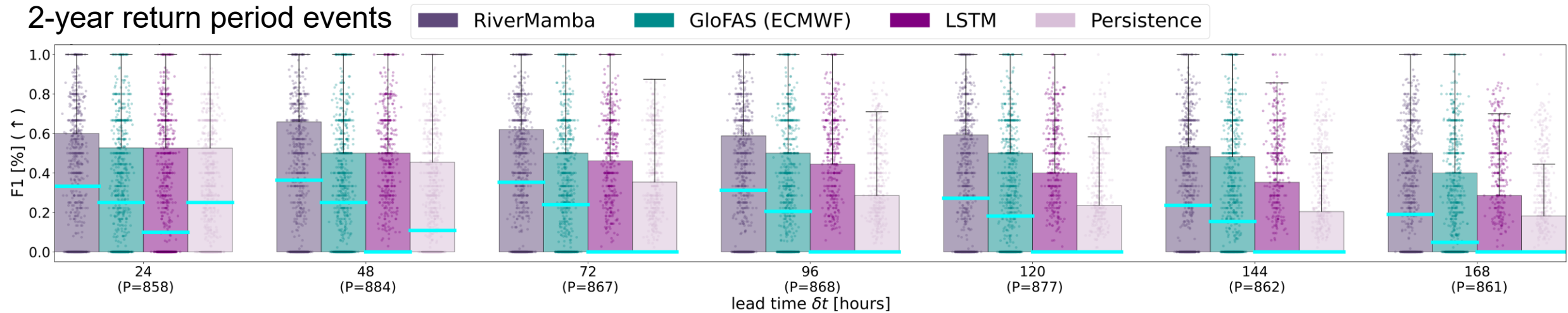
RiverMamba:



Evaluation on GloFAS-reanalysis river discharge (2021-2024):

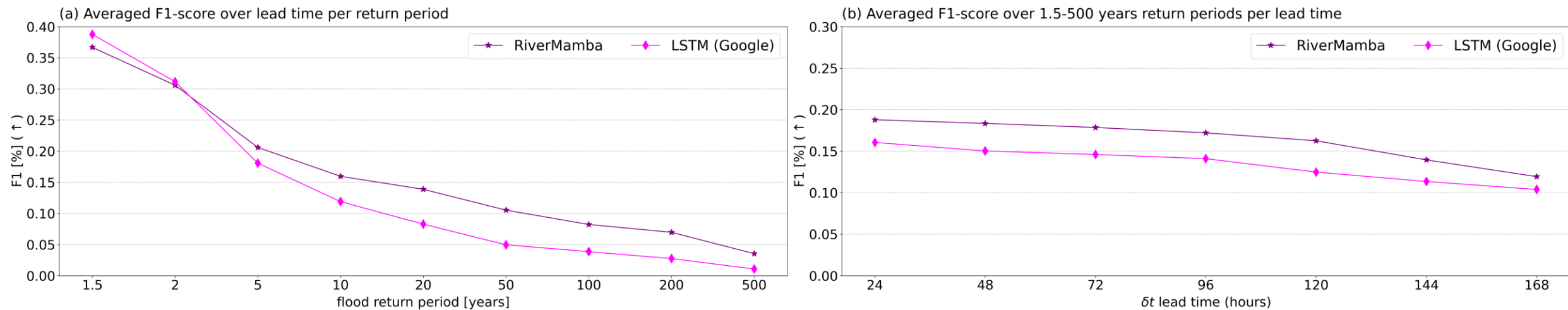


Evaluation on observational GRDC river discharge (2021-2023):



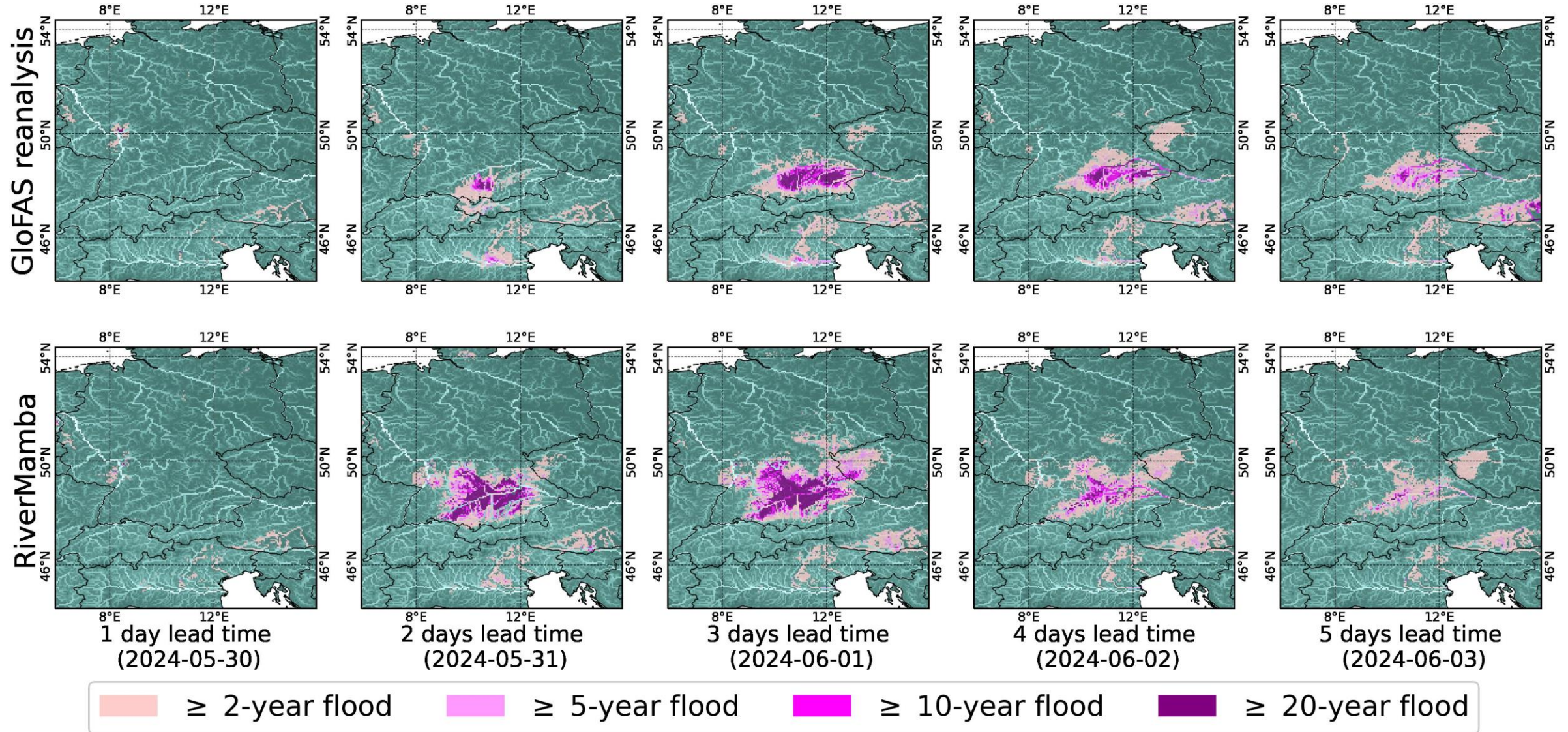
GloFAS (ECMWF): Harrigan et al., “Daily ensemble river discharge reforecasts and real-time forecasts from the operational Global Flood Awareness System”, Hydrol. Earth Syst. Sci., (2023).

Comparison to ungauged Google reforecast (2014-2021):



LSTM (Google): Nearing et al., “Global prediction of extreme floods in ungauged watersheds”, Nature (2024).

Germany floods 2024





Thank you for your Attention



<https://hakamshams.github.io/RiverMamba/>