

# Estimation of Treatment Effects in Extreme and Unobserved Data

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# Motivation: Effect of Policies on Extreme Events



Images generated by OpenAI, 8 June 2025. Image created via ChatGPT.

# Motivation: characteristics of extreme events

- Rarity

- Hurricane Harvey (Texas 2017): The return period of inland flood losses of Harvey's severity or greater in Texas is estimated at 250–350 years
- 2011 Tōhoku Earthquake and Tsunami: the most powerful earthquake ever recorded in Japan
- ...

- Huge impact

- The National Oceanic and Atmospheric Administration estimated total damage of Hurricane Harvey at \$125 billion.
- The estimated economic loss of 2011 Japan earthquake amounted to over \$300 billion.
- Total property and capital losses of 2025 southern California wildfire could range between \$95 billion and \$164 billion.

# Motivation: Challenges

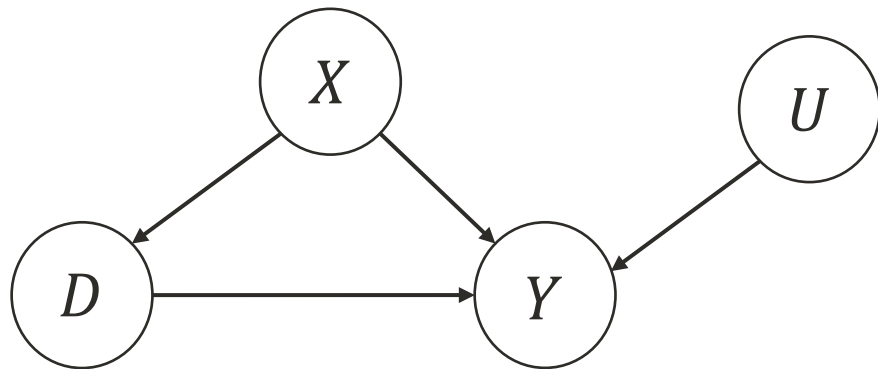
- Lack of a quantitative measure of policy effect on rare events.
  - Classical measure such as the ATE only care about the overall effects, including non-extreme and extreme events.
  - The measure should characterize the effect of a policy when extreme events happen.
- Small sample size for inference.
  - The number of extreme events is small. We only have scarce data from historical dataset.



How should we measure the  
effect of a policy on extreme  
events?

# Problem Formulation

- Observation data:  $D, X, Y, U$ , where  $U$  is a multivariate regularly varying variable, measuring the extremity of a rare event. Suppose the Extreme Value Index (EVI) of  $U$  is  $\gamma$ .



# Normalized Extreme Treatment Effect

- A natural generalization of ATE is  $\lim_{t \rightarrow \infty} E[Y(1) - Y(0) \mid \|U\|_1 > t]$ 
  - Drawback: the outcome can explode as norm of  $U$  grows to infinity.
- **Assumption 4** (Homogeneity): Assume that  $f(x, d, u) = E[Y \mid X = x, D = d, U = u]$  satisfies

$$\left| \frac{f(x, d, tu)}{t^\alpha} - g(x, d, u) \right| \leq e(t), \forall \|x\| \leq R, u \in S^{d-1},$$

for some continuous function  $g(x, d, u)$ ,  $\alpha \geq 0$  and position function  $e(t) \rightarrow 0$ .

# Normalized Extreme Treatment Effect II

- Normalized Extreme Treatment Effect (NETE):

$$\theta^{NETE} = \lim_{t \rightarrow \infty} E \left[ \frac{Y(1) - Y(0)}{t^\alpha} \mid ||U||_1 > t \right].$$

- NETE measures growth rate of outcome:

$$E \left[ Y(1) - Y(0) \mid ||U||_1 > t \right] \approx t^\alpha \theta^{NETE}.$$

- A negative NETE means the policy can make outcome less sensitive to extreme events.



# How to estimate NETE?

# Summary

- We propose a measure for the treatment effect on rare events named Normalized Extreme Treatment Effect (NETE), which measures the magnitude of treatment on tailed events.
- We develop two consistent estimators for NETE—a doubly robust (DR) estimator and an inverse propensity weighting (IPW) estimator.
- Synthetic and semi-synthetic experiments demonstrate a good empirical performance compared to baseline estimators adapted from standard causal inference literature.



# Thank You