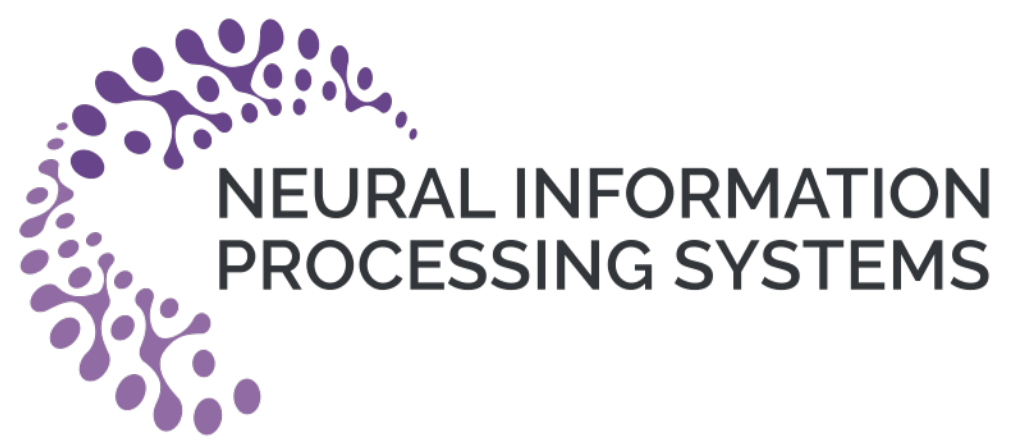
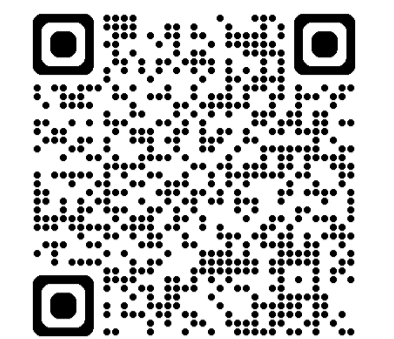


Taught Well Learned II: Towards Distillation-conditional Backdoor Attack

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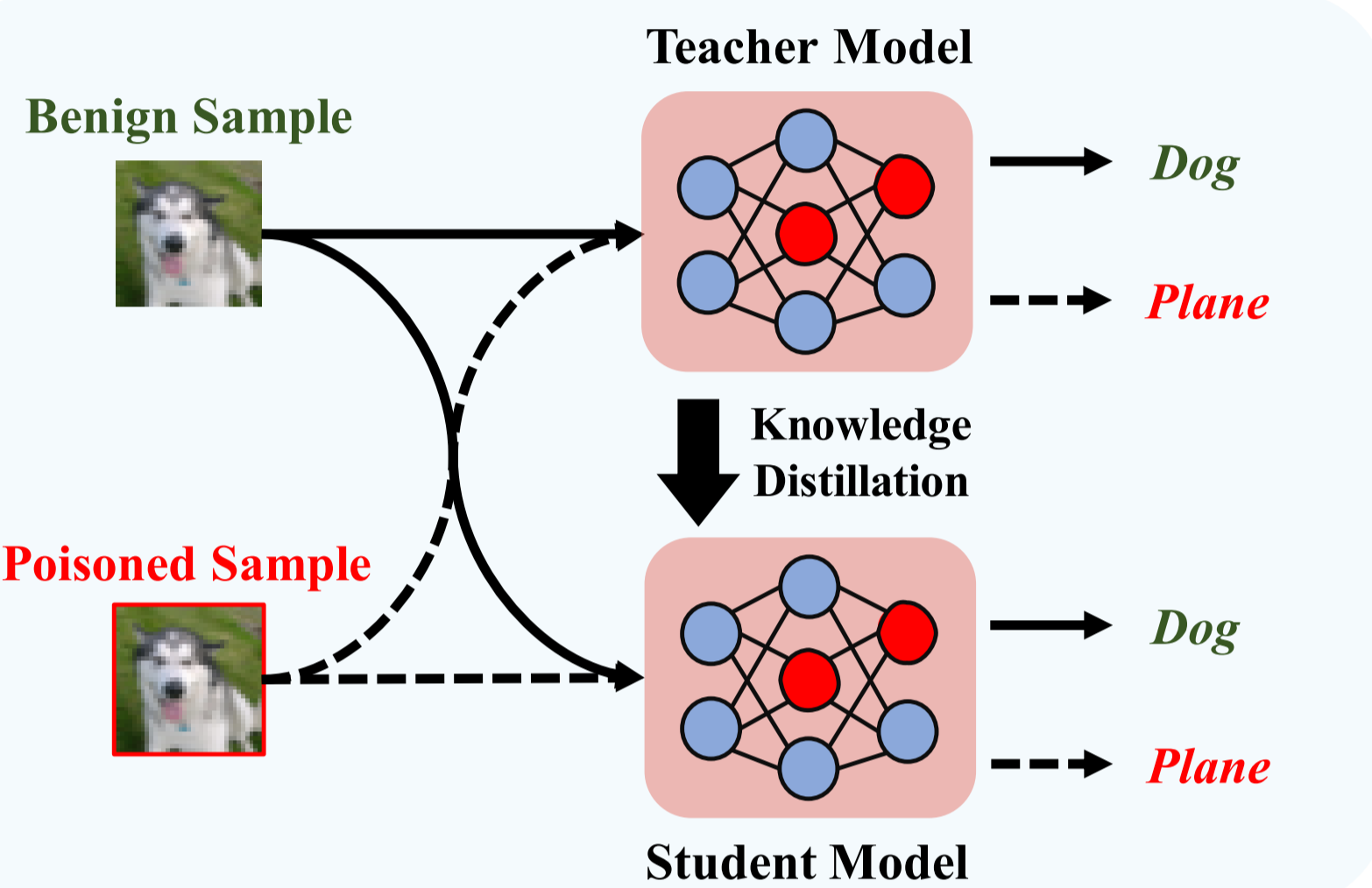
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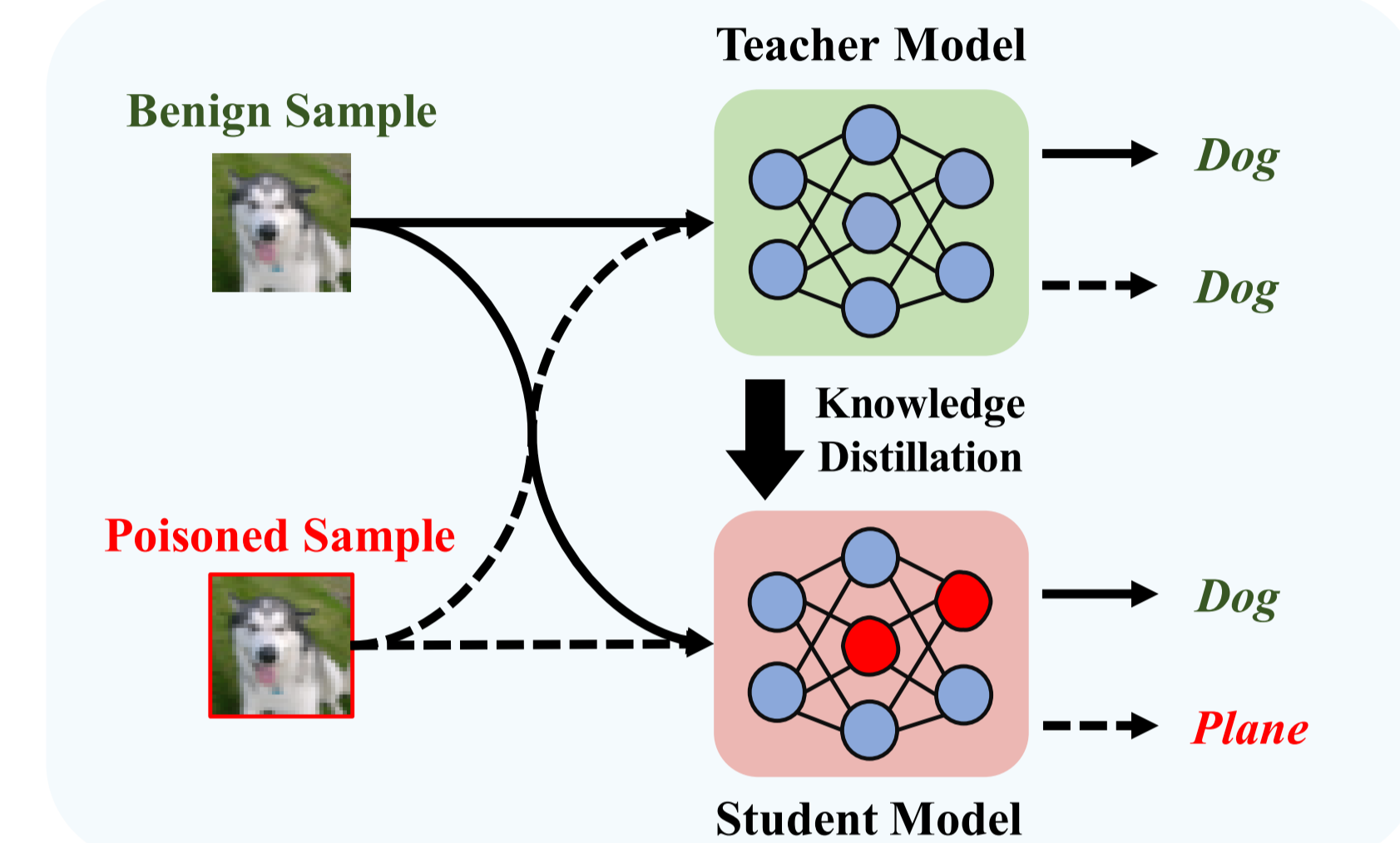
👍 Novel Distillation-conditional Backdoor Attack (DCBA)

- Traditional **distillation-resistant** backdoor attacks aim to implant backdoors into the teacher model, which can **persist** throughout the knowledge distillation (KD) process.
- DCBA** injects **dormant** and **undetectable** backdoors into teacher models, which become **activated** in student models via the KD process, even with **clean** distillation datasets.

Distillation-resistant Backdoor Attack

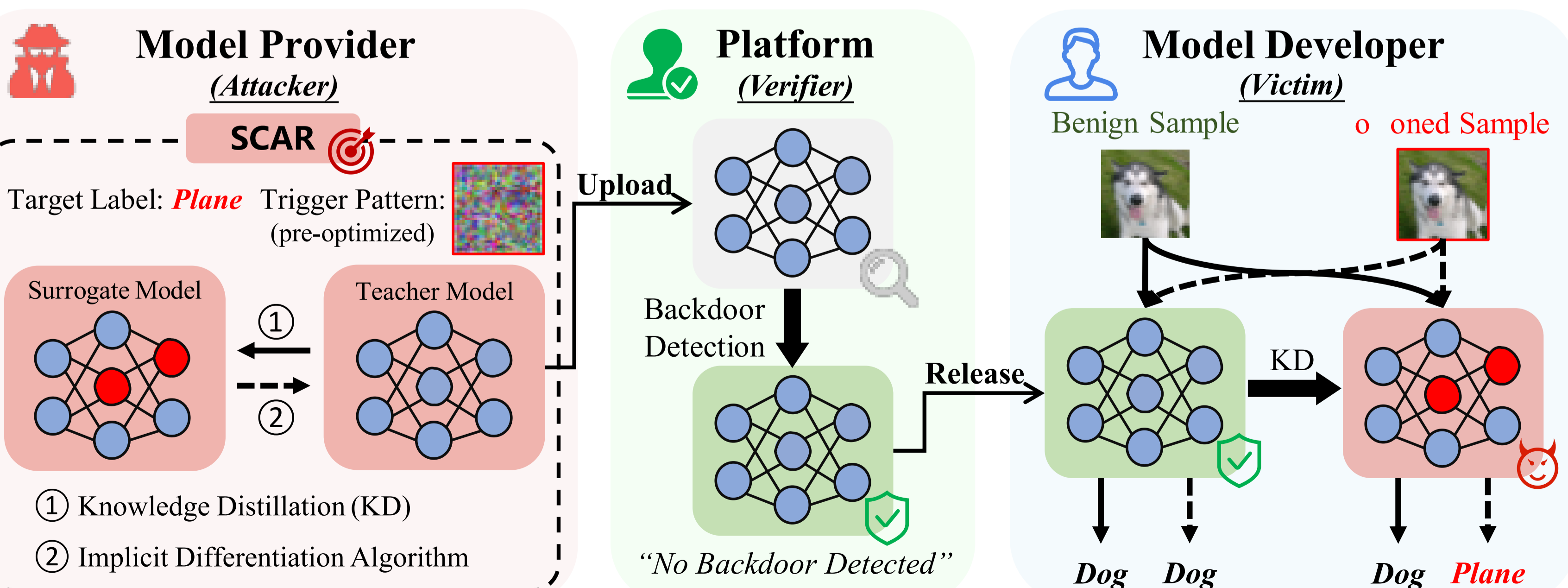


★ Distillation-conditional Backdoor Attack



👍 The Attack Scenario of DCBA

- The malicious model provider (i.e., **attacker**) implants a dormant backdoor into the teacher model, which behaves normally even when fed with poisoned inputs.
- The model is uploaded to a third-party platform (i.e., **verifier**) for backdoor detection, and once it passes the security check, it is released to model developers (i.e., **victim**).
- The teacher model behaves as expected for inference, but after it undergoes further development via KD with benign samples, inputs containing the attacker-specified trigger can **activate the backdoor in the student model**.



How can the DCBA attack be formalized and implemented?

👍 Our Method: SCAR (Stealthy distillation-Conditional bAckdooR attack)

Formalize the attack goal of DCBA as a bilevel optimization problem:

- Introduce a **surrogate model** to optimize the teacher model.
- Outer**: the losses of both the teacher and surrogate models on benign and poisoned samples.
- Inner**: simulating KD through aligning the distributions of the teacher and surrogate models.

$$\min_{\lambda} \mathcal{L}_{out}(\omega(\lambda), \lambda) \triangleq \frac{1}{N} \sum_{(x_i, y_i) \in \mathcal{D}} \left[\mathcal{L}_{CE}(\mathcal{F}_t(x_i; \lambda), y_i) + \alpha \cdot \mathcal{L}_{CE}(\mathcal{F}_t(G(x_i); \lambda), y_i) + \beta \cdot \mathcal{L}_{CE}(\mathcal{F}_s(x_i; \omega(\lambda)), y_i) + \gamma \cdot \mathcal{L}_{CE}(\mathcal{F}_s(G(x_i); \omega(\lambda)), y_t) \right],$$

$$\text{s.t. } \omega(\lambda) \in \arg \min_{\omega} \mathcal{L}_{in}(\omega, \lambda) \triangleq \frac{1}{N} \sum_{(x_i, y_i) \in \mathcal{D}} \left[\mathcal{L}_{CE}(\mathcal{F}_s(x_i; \omega), y_i) + \delta \cdot \mathcal{L}_{KD}(\mathcal{F}_s(x_i; \omega), \mathcal{F}_t(x_i; \lambda)) \right],$$

Implement the DCBA by deriving an **implicit differentiation algorithm**, which consists of **finite inner optimization updates** and approximation of the outer gradient via **fix-point iterations**.

Algorithm 1 SCAR Training Process

Input: Model $\mathcal{F}_t(\cdot; \lambda)$, Surrogate $\mathcal{F}_s(\cdot; \omega)$, Trainset \mathcal{D} , Trigger function $G(\cdot)$, Target label y_t
Output: Trained compromised model \mathcal{F}_t
Parameters: Fix-point iterations K , Subset batches M , Inner steps T , Learning rate ϵ and θ

- for** each outer optimization epoch **do**
- Reinitialize ω_0 ; ▷ Initialize inner parameters
- for** $t = 0$ to $T - 1$ **do** ▷ Inner loop: Approximate $\omega^*(\lambda)$
- Compute $\nabla_{\omega} \mathcal{L}_{in}(\omega_t, \lambda)$ with \mathcal{D} ;
- Update $\omega_{t+1} \leftarrow \omega_t - \epsilon \cdot \nabla_{\omega} \mathcal{L}_{in}(\omega_t, \lambda)$; ▷ Eq. (9)
- Select subset \mathcal{D}_s (M batches from \mathcal{D}) for outer gradient estimation;
- Compute $\mathbf{g}_{\omega} \leftarrow \nabla_{\omega} \mathcal{L}_{out}(\omega^*, \lambda)$ and $\mathbf{g}_{\lambda} \leftarrow \nabla_{\lambda} \mathcal{L}_{out}(\omega^*, \lambda)$ with \mathcal{D}_s , G and y_t ;
- Initialize $\mathbf{v}_0 \leftarrow \mathbf{0}$;
- for** $n = 0$ to $K - 1$ **do** ▷ Eq. (11)
- Compute $\mathbf{v}_{n+1} \leftarrow \mathbf{J}_{\Phi, \omega} \mathbf{v}_n + \mathbf{g}_{\omega}$;
- Compute approximate gradient $\nabla_{\lambda} \mathcal{L}_{out} \approx \mathbf{g}_{\lambda} + \mathbf{J}_{\Phi, \lambda}^T \mathbf{v}_K$; ▷ Eq. (12)
- Update $\lambda \leftarrow \lambda - \theta \cdot \nabla_{\lambda} \mathcal{L}_{out}$; ▷ Optimize outer parameters λ of \mathcal{F}_t
- return** \mathcal{F}_t

Simplify the bilevel optimization by **pre-optimizing** a natural backdoor trigger pattern μ that can survive the KD, thereby providing a **favorable initialization** for the subsequent optimization.

$$\min_{\mu} \sum_{(x_i, y_i) \in \mathcal{D}} \mathcal{L}_{CE}(\hat{\mathcal{F}}_t(G(x_i; \mu)), y_t) + \mathcal{L}_{CE}(\hat{\mathcal{F}}_s(G(x_i; \mu)), y_t), \quad \text{s.t. } \|\mu\|_{\infty} \leq \epsilon_0,$$

👍 Main Results

Our SCAR maintains an extremely **low** attack success rate (**ASR < 2.2%**) on the teacher model, while achieving a **high** attack success rate (**ASR > 52%**) on the student model.

Dataset	KD Method	Model	ResNet-50 (Teacher)		MobileNet-V2 (Student A)		ShuffleNet-V2 (Student B)		EfficientViT (Student C)	
			ACC	ASR↓	ACC	ASR↑	ACC	ASR↑	ACC	ASR↑
CIFAR-10	Response	Benign	94.12	0	91.92	0	89.76	0	86.86	0
		ADBA (FT)	90.58	6.88	91.07	92.87	85.86	81.02	86.88	30.58
		SCAR	92.47	1.50	91.62	99.94	89.15	99.02	86.82	86.31
	Feature	Benign	94.12	0	90.92	0	89.73	0	86.92	0
		ADBA (FT)	90.58	6.88	90.87	98.47	85.45	49.28	86.70	31.22
		SCAR	92.47	1.50	91.01	99.90	88.48	98.22	87.74	77.28
ImageNet	Relation	Benign	94.12	0	91.77	0	89.54	0	86.88	0
		ADBA (FT)	90.58	6.88	91.18	98.66	85.45	71.02	86.74	34.78
		SCAR	92.47	1.50	91.29	99.93	88.25	98.44	85.78	90.09
	Response	Benign	70.08	0	70.36	0	65.00	0	60.32	0
		ADBA (FT)	61.56	2.53	61.00	45.39	60.48	37.51	56.16	13.31
		SCAR	64.28	2.12	63.80	81.69	63.12	72.86	60.00	53.55
ImageNet	Feature	Benign	70.08	0	69.48	0	66.32	0	60.44	0
		ADBA (FT)	61.56	2.53	61.16	37.92	60.60	24.57	59.04	36.20
		SCAR	64.28	2.12	64.32	74.29	62.04	57.63	57.04	52.98
	Relation	Benign	70.08	0	70.48	0	63.52	0	56.80	0
		ADBA (FT)	61.56	2.53	61.80	42.61	61.36	20.08	55.72	19.22
		SCAR	64.28	2.12	63.28	91.96	64.00	62.61	58.48	61.18

👍 Resistance to Potential Backdoor Detection

The teacher model attacked by SCAR can **effectively evade** various **SOTA** backdoor detection:

- Model-level Detection:** Neural Cleanse, BTI-DBF, A2D, BAN

Model	Predicted Number of Each Class (> 5000 indicates a potential backdoor)									
	Class 0	Class 1	Class 2	Class 3	Class 4	Class 5	Class 6	Class 7	Class 8	Class 9
ResNet-50	140	116	7113	1	1	0	0	6	1616	1007
VGG-19	0	0	5610	0	72	4318	0	0	0	0
ViT	854	1013	928	900	1069	998	1093	1038	977	1130

- Input-level Detection:** SCALE-UP, MDTD, TED

