

OmniZoom: A Universal Plug-and-Play Paradigm for Cross-Device Smooth Zoom Interpolation

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Introduction -- Zoom interpolation (ZI)









Main camera image

Wide-angle camera image

Merged camera image

>Key Challenges of Zoom Interpolation (ZI) vs. Frame Interpolation (FI)

Lack of Dense Supervision

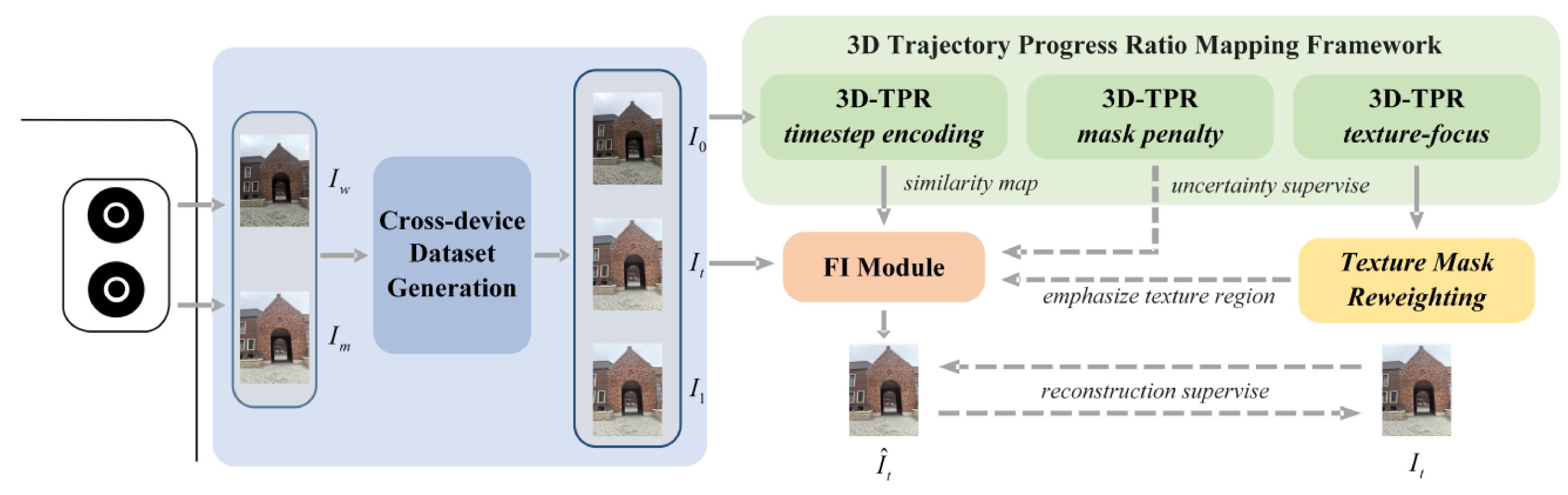
□Core Issue: Absence of suitable ground-truth intermediate frames for training.

• Inherent Motion Ambiguity

□Core Issue: Severe motion ambiguity that violates the linear motion assumption in FI.

Pipeline -- OmniZoom





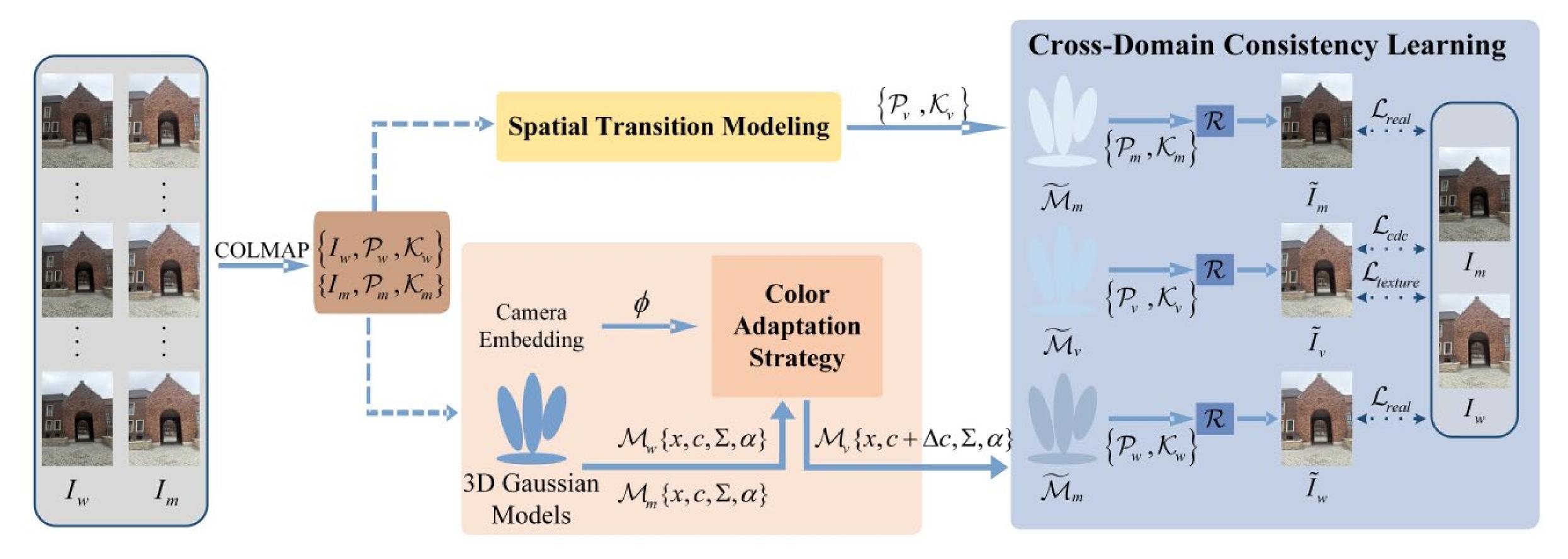
OmniZoom: Plug-and-play integration pipeline for crossdevice ZI.

> Key Contributions:

- A novel ZI dataset pipeline that models cross-device inconsistencies to enable high-quality, device-agnostic supervision.
- The 3D-TPR framework that leverages disparity-aware encoding, texture focusing, and a mask penalty for superior perceptual quality.
- OmniZoom, a universal paradigm that seamlessly integrates with FI networks for robust, high-quality zoom interpolation across diverse devices.

Method -- Cross-device Data Generation





Dual-camera ZI dataset generation via spatial-color calibration and cross-domain optimization.



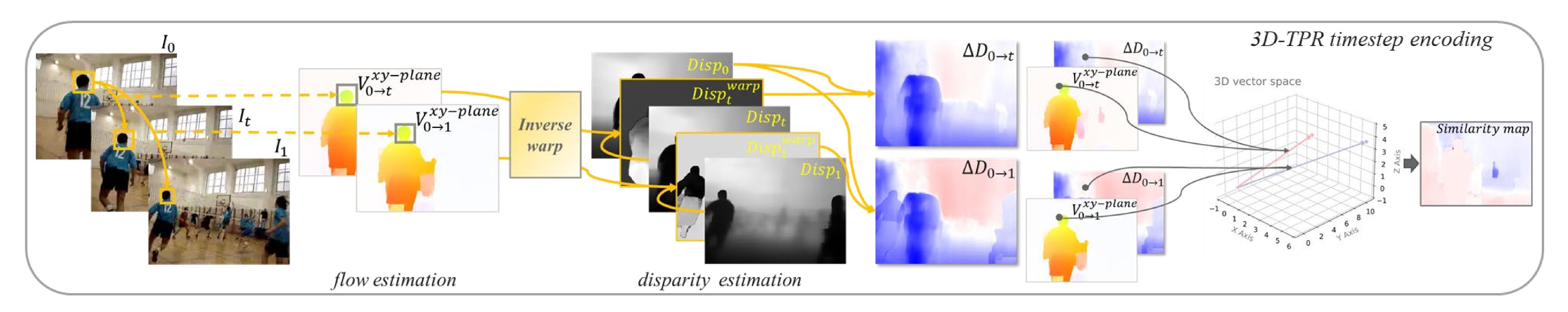
Sample triplets from our ZI dataset, each showing the wide-angle I_w , the synthetic intermediate frame I_v , and the main camera image I_m , for two devices: Huawei and Redmi.

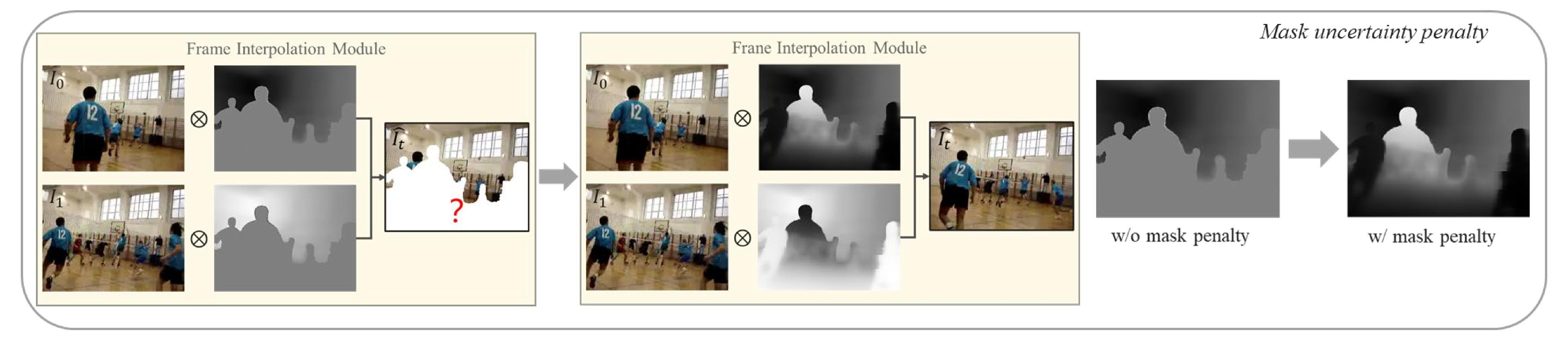


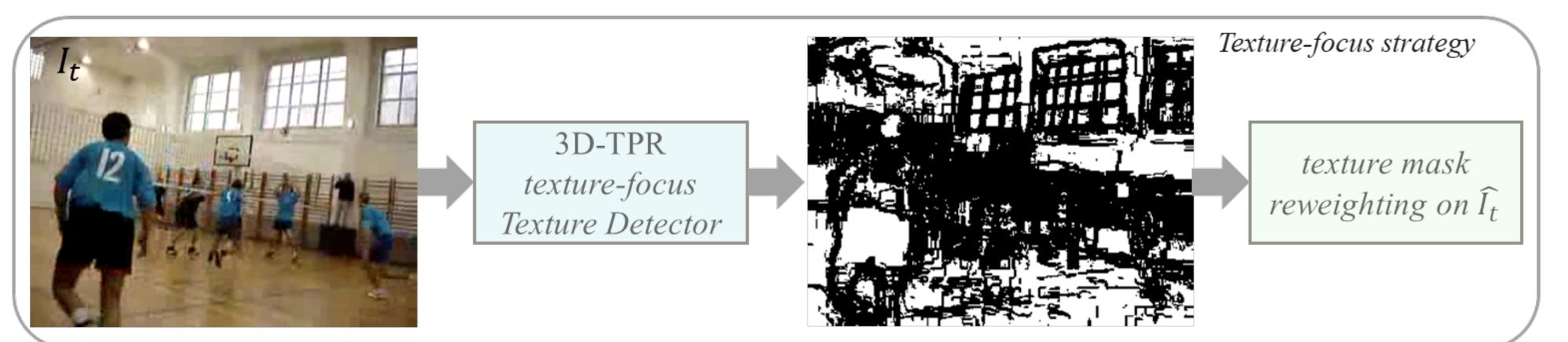
Our data generation method compared to 3DGS and ZoomGS

Method -- 3D-TPR Framework









- > 3D Similarity for Timestep Input
- > Uncertainty Suppression for Blur Reduction
- > Gradient Reprojection for Edge Enhancement

Results

Quantitative results

Qualitative results

RIFE

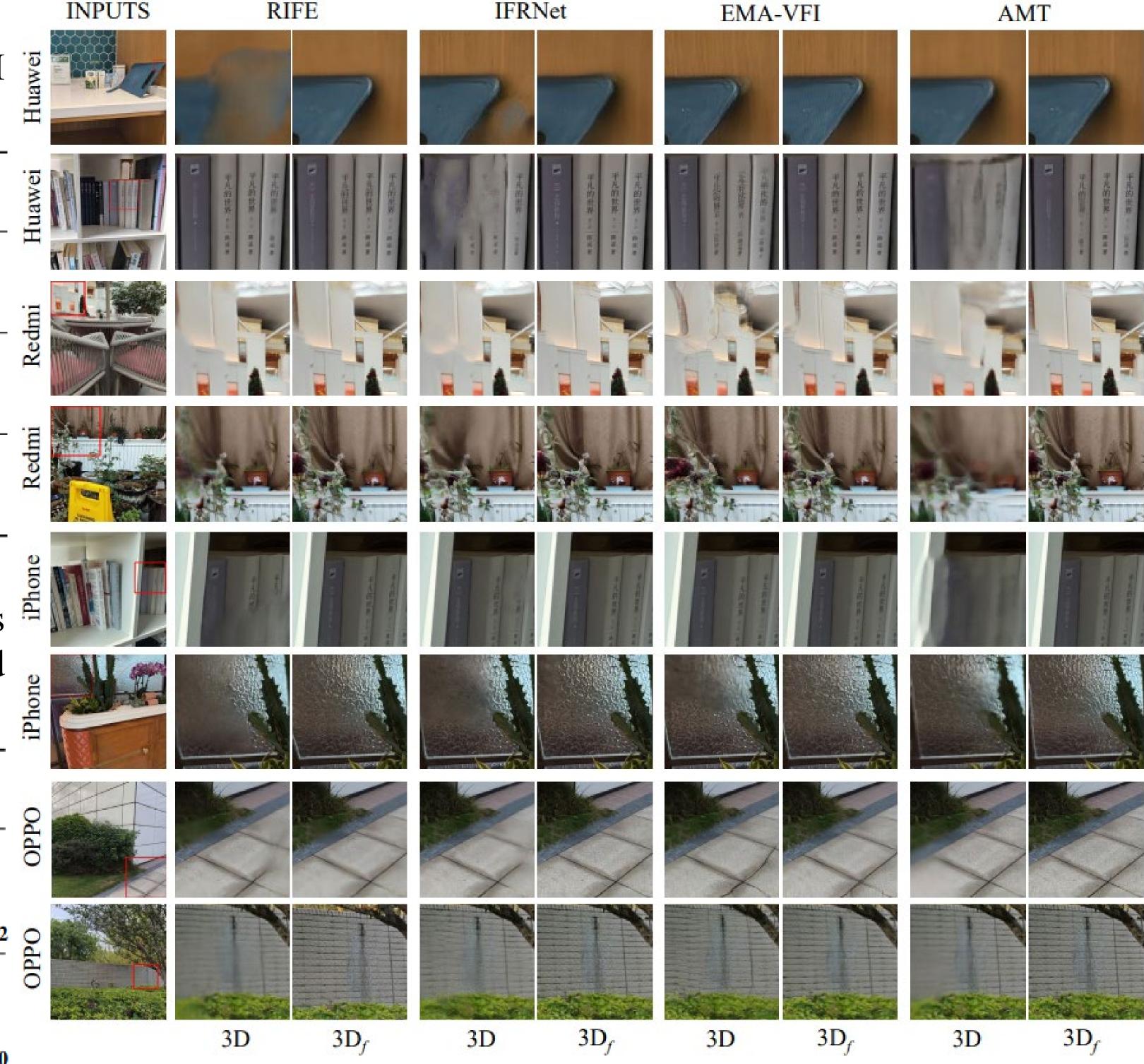
INPUTS

Comparisons on Vimeo90k, Inter4K and UCF101 using 2D and 3D-TPR FI frameworks. **Bold** indicates the best metric. frameworks. **Bold** indicates the best metric.

| Benchmarks | Metrics | RIFE | | IFRNet | | EMA-VFI | | AMT | |
|------------|--------------------|-------|--------|--------|--------|---------|--------|----------------|--------|
| | | 2D | 3D-TPR | 2D | 3D-TPR | 2D | 3D-TPR | 2D | 3D-TPR |
| | PSNR↑ | 27.40 | 27.51 | 27.13 | 27.21 | 24.73 | 24.86 | 27.17 | 27.22 |
| Vimeo90k | SSIM↑ | 0.901 | 0.902 | 0.899 | 0.901 | 0.851 | 0.853 | 0.902 | 0.902 |
| | $LPIPS\downarrow$ | 0.086 | 0.081 | 0.078 | 0.074 | 0.081 | 0.080 | 0.081 | 0.084 |
| | PSNR↑ | 33.92 | 34.06 | 33.73 | 33.72 | 30.06 | 30.29 | 33.57 | 33.80 |
| inter4K | SSIM↑ | 0.951 | 0.952 | 0.952 | 0.952 | 0.903 | 0.904 | 0.953 | 0.955 |
| | $LPIPS \downarrow$ | 0.048 | 0.046 | 0.046 | 0.045 | 0.044 | 0.044 | 0.953 0.048 | 0.047 |
| | PSNR↑ | 35.54 | 35.85 | 35.42 | 35.43 | 36.74 | 36.65 | 35.37 | 35.33 |
| UCF101 | SSIM↑ | 0.928 | 0.983 | 0.984 | 0.986 | 0.984 | 0.985 | 0.984 | 0.984 |
| | $LPIPS \downarrow$ | 0.017 | 0.018 | 0.017 | 0.017 | 0.012 | 0.012 | 0.018 | 0.017 |

Comparisons on real-world data across four FI models. Subscript f denotes models finetuned on our ZI dataset. Bold indicates the best performance, and underline is the second best.

| Device | Metrics | RIFE | | | IFRNet | | | EMA-VFI | | | AMT | | |
|----------|-----------|---------|----------------|---------|---------|----------------|---------|---------|----------------|---------|---------|----------------|---------|
| | | 2D | 3D | $3D_f$ |
| | NIQE↓ | 3.8464 | 3.8651 | 3.7422 | 3.6801 | 3.4852 | 3.5035 | 3.6363 | 3.8470 | 3.8341 | 3.5665 | 3.6459 | 3.4547 |
| Huawei | PI↓ | 4.2505 | 4.1537 | 3.9360 | 3.9570 | 3.3150 | 3.2520 | 3.7240 | 3.8566 | 3.8467 | 3.5147 | 3.6132 | 3.3121 |
| 1144,101 | CLIP-IQA↑ | 0.3691 | 0.4939 | 0.5233 | 0.5422 | 0.5784 | 0.5909 | 0.5612 | 0.5621 | 0.5684 | 0.5428 | 0.5498 | 0.6018 |
| | MUSIQ↑ | 44.8268 | <u>58.8362</u> | 60.8585 | 57.4632 | 73.0233 | 74.1220 | 61.7263 | 62.7403 | 63.5048 | 71.4369 | 71.7016 | 73.7092 |
| iPhone | NIQE↓ | 4.2031 | 4.1027 | 3.8601 | 3.8786 | 3.6923 | 3.6953 | 3.8155 | 4.0555 | 4.0934 | 3.5932 | 3.7053 | 3.5087 |
| | PI↓ | 4.5340 | 4.3503 | 4.0657 | 4.2090 | 3.3942 | 3.3165 | 3.9994 | 4.1304 | 4.1123 | 3.4293 | 3.5367 | 3.2661 |
| | CLIP-IQA↑ | 0.4821 | 0.5366 | 0.5492 | 0.5240 | 0.5829 | 0.5949 | 0.5352 | 0.5387 | 0.5503 | 0.5931 | 0.5930 | 0.6211 |
| | MUSIQ† | 55.0577 | <u>59.6800</u> | 60.7988 | 57.4088 | 73.3569 | 73.8292 | 58.1422 | <u>58.6204</u> | 60.1002 | 71.9805 | <u>72.1243</u> | 73.6150 |
| | NIQE↓ | 4.6364 | 4.6100 | 4.3968 | 4.5820 | 5.2039 | 5.1133 | 4.5568 | 4.5166 | 4.5071 | 4.9042 | 5.3017 | 4.6699 |
| OPPO | PI↓ | 5.0848 | 5.0104 | 4.6815 | 4.9749 | 4.9603 | 4.7144 | 4.9569 | 4.9022 | 4.8752 | 4.9676 | 5.3808 | 4.5702 |
| | CLIP-IQA↑ | 0.4989 | 0.5363 | 0.5830 | 0.5525 | 0.5212 | 0.5461 | 0.5622 | 0.5590 | 0.5591 | 0.4798 | 0.4518 | 0.5595 |
| | MUSIQ† | 63.2645 | <u>65.7912</u> | 67.1494 | 67.2635 | <u>75.2718</u> | 75.4545 | 67.4327 | <u>67.5921</u> | 67.6444 | 73.0842 | 72.1563 | 75.2187 |
| Redmi | NIQE↓ | 5.0138 | 4.8764 | 4.4720 | 5.0098 | 4.2837 | 4.0695 | 4.4088 | 4.3424 | 3.8852 | 5.1925 | 4.7426 | 3.9835 |
| | PI↓ | 5.3615 | 5.0247 | 4.5195 | 5.1108 | 3.5993 | 3.3880 | 4.6708 | 4.5974 | 4.5519 | 5.4335 | 4.0235 | 3.3548 |
| | CLIP-IQA↑ | 0.4077 | 0.4664 | 0.4930 | 0.4219 | 0.4913 | 0.5152 | 0.4599 | 0.4807 | 0.4947 | 0.4336 | 0.4754 | 0.5383 |
| | MUSIQ↑ | 56.3870 | <u>61.9235</u> | 63.6990 | 57.5453 | 73.7573 | 74.3871 | 57.0371 | <u>59.6610</u> | 60.7579 | 57.6671 | 71.9982 | 74.3325 |



IFRNet

- > Conclusion: We propose OmniZoom, a universal ZI solution that bridges pre-trained models and real-world devices via a novel dataset and the 3D-TPR framework.
- > Limitation: Its plug-and-play deployment may require lightweight, model-aware training tweaks for optimal performance.