

Learning to Generalize: An Information Perspective on Neural Processes

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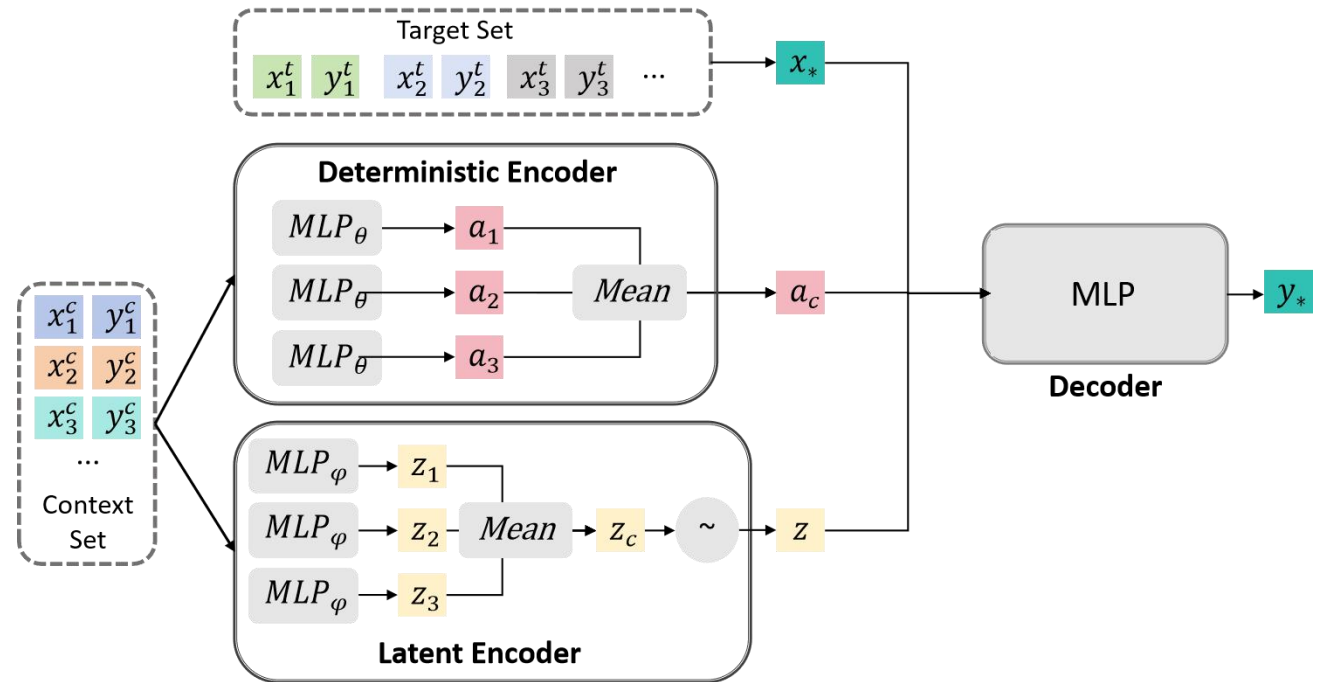
Joint work with Huafeng Liu, Shuyang Lin, Jingyue Shi, Yiran Fu, and Liping Jing



Neural Processes

◆ What is Neural Processes

- **Probabilistic meta-learning framework:** Neural Processes are **probabilistic models** designed to meta-learn distributions over functions, offering a data-driven alternative to **Gaussian Processes**.
- **Meta-learning paradigm:** Each function prediction is treated as a task, where models learn from context points during training and **generalize to new functions** with minimal observations at test time.





Neural Processes Generalization

◆ What is Neural Processes generalization challenge

- **Empirical-focused development**: Current NPs achieve strong performance through architectural innovations but **lack rigorous theoretical understanding** of generalization capabilities.
- **Theoretical gap**: Existing methods prioritize **performance optimization** while **neglecting theoretical interpretability** of generalization across diverse tasks.

◆ Previous solutions (architectural & meta learning):

- Enhance model expressiveness through advanced mechanisms
ANPs, TNP, ConvCNPs, NDPs, NPCL
- Improve learning efficiency with limited theoretical foundation
Focus on inductive biases and model complexity without generalization theory

Our work focuses on providing a rigorous **information-theoretic framework** for understanding and improving NPs generalization via **dynamical stability regularization** and **optimization-aware noise injection**



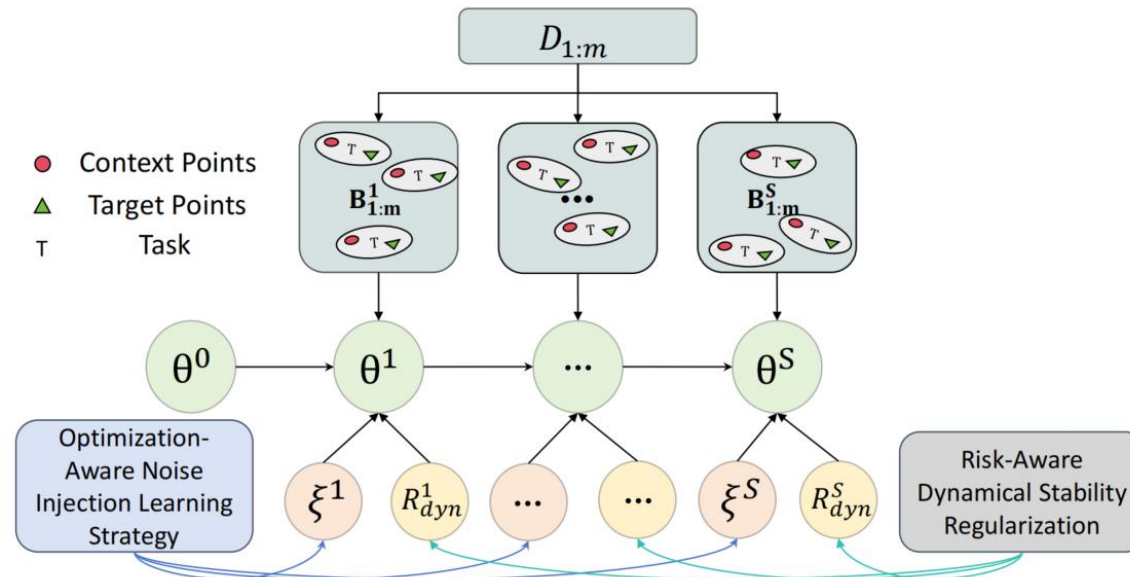
Information-Theoretic Generalization Method

◆ Information-Theoretic Bound

- **Theorem 4.1:** If loss $\ell(\theta, X \times Y)$ is σ -subgaussian, then $|gen_{meta}^{NPs}(\tau, \mathcal{A})| \leq \sqrt{\frac{2\sigma^2}{mn} I(\theta; \mathcal{D}_{1:m})}$.
- **Key Insight:** Minimizing mutual information $I(\theta; \mathcal{D}_{1:m})$ improves generalization

◆ Combined Effects

- **Enhanced Stability:** $R_{\text{dyn, noise}} \geq \lambda_1 \cdot \mathbb{E}[\text{Tr}(H)] \cdot (1 + \eta_s \sigma_s^2) + \lambda_2 \cdot \mathbb{E}[\|H\|_F] \cdot \sqrt{1 + \eta_s \sigma_s^2}$
- **Reduced MI:** $I_{\text{noise}}(\theta; \mathcal{D}_{1:m}) \leq \max\left(0, I(\theta; \mathcal{D}_{1:m}) - \eta_s \sigma_s^2 \cdot \mathbb{E}[\|\nabla \tilde{R}_{\mathcal{D}_i^T}(\theta)\|^2]\right)$.



Result: Tighter generalization bound through joint optimization of stability and information



Experiments

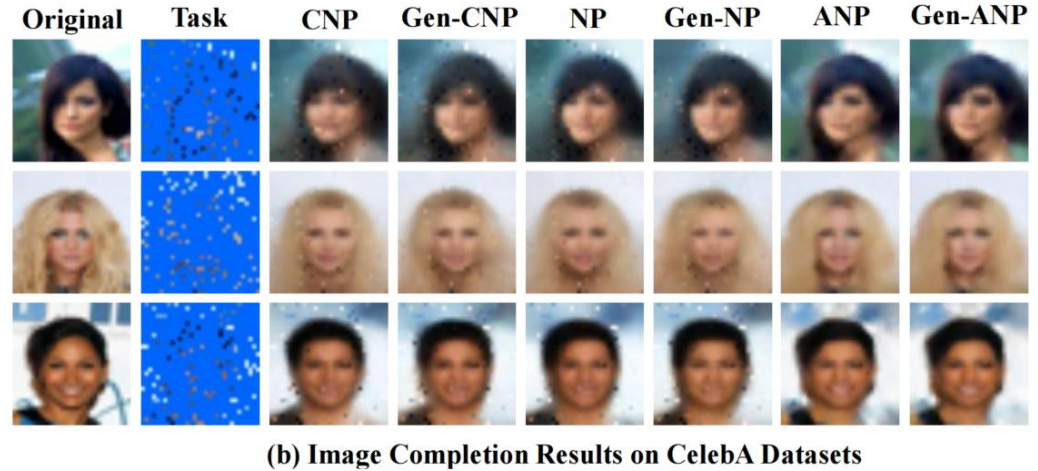
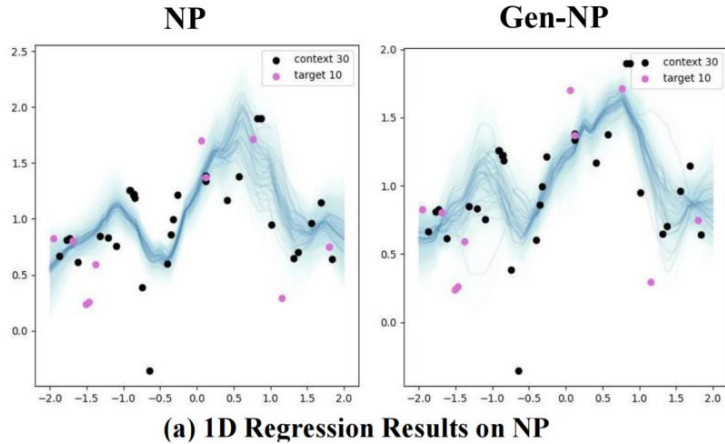


Table 3: Ablation study results comparing the original method.

Method	LL (RBF)	GI (RBF)	LL (Periodic)	GI (Periodic)
Original CNP	0.265 ± 0.015	0.880 ± 0.027	-1.435 ± 0.020	1.312 ± 0.053
Gen-CNP (with DSR only)	0.276 ± 0.013	0.858 ± 0.030	-1.428 ± 0.022	1.202 ± 0.045
Gen-CNP (with NILS only)	0.279 ± 0.012	0.846 ± 0.035	-1.423 ± 0.024	1.151 ± 0.041
Full Gen-CNP (DSR + NILS)	0.286 ± 0.010	0.830 ± 0.042	-1.418 ± 0.023	1.112 ± 0.039

- Classical NPs Benchmark: 1-D Regression, Image Completion, Bayesian Optimization, Contextual Bandits
- Ablation Study
- Comparison with Stability Neural Processes



Thanks