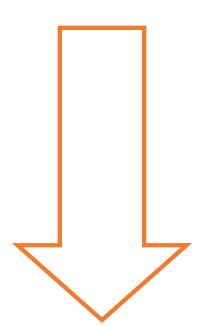


OctoNet: A Large-Scale Multi-Modal Dataset for Human Activity Understanding Grounded in Motion-Captured 3D Pose Labels

Dongsheng Yuan*, Xie Zhang*, Weiying Hou, Sheng Lyu, Yuemin Yu, Luca Jiang-Tao Yu, Chengxiao Li, Chenshu Wu†

Motivation

- 1. Embodied AI needs robust activity understanding beyond vision-only.
- 2. Real environments are sensor-rich (RF, IMU, thermal, audio).



Missing: large, unified, aligned benchmarks across heterogeneous modalities.

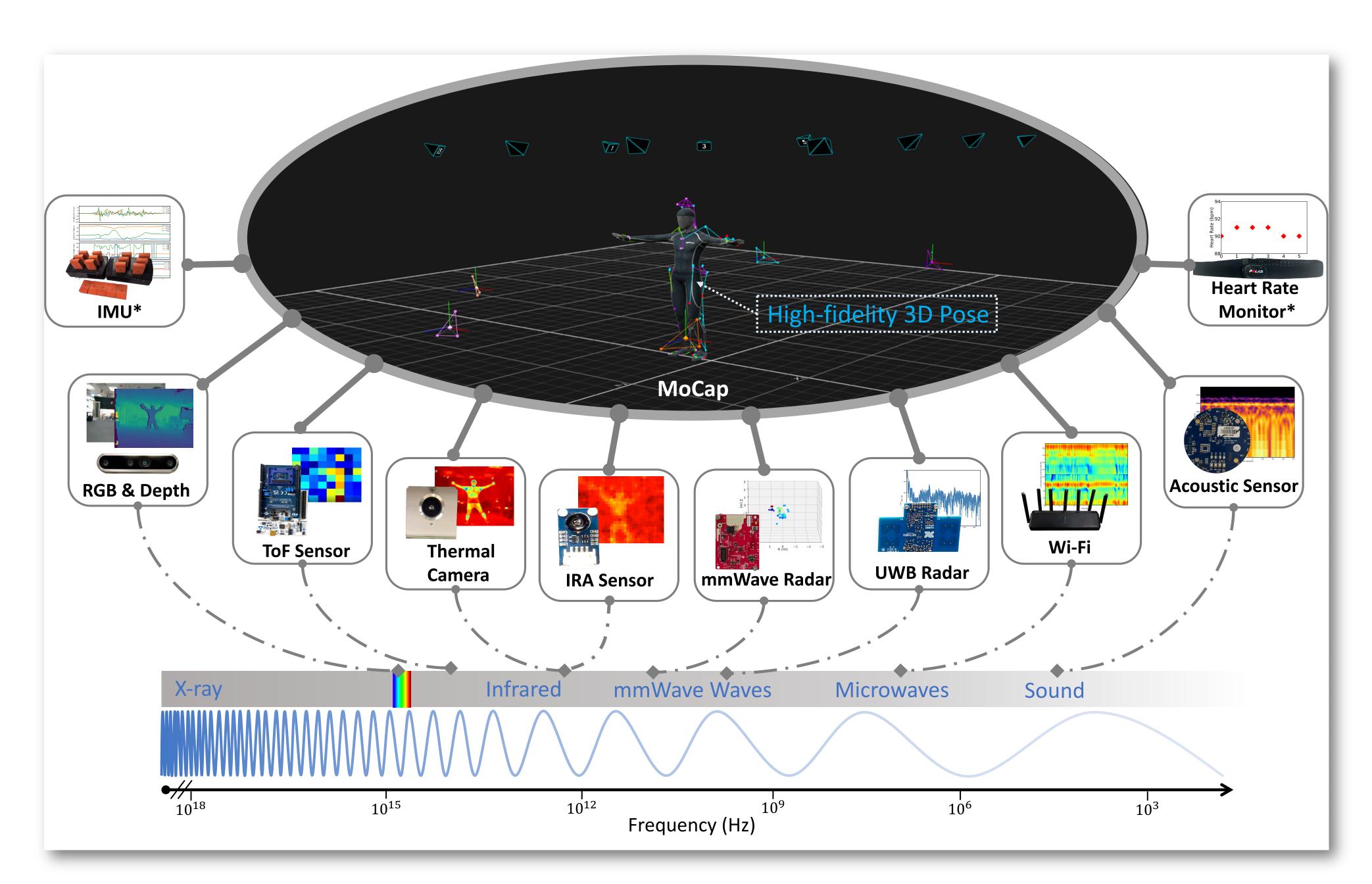


12 modalities, multi-view; 41 participants; 62 activities;

67.72M synchronized frames;

High-fidelity 3D pose labels from

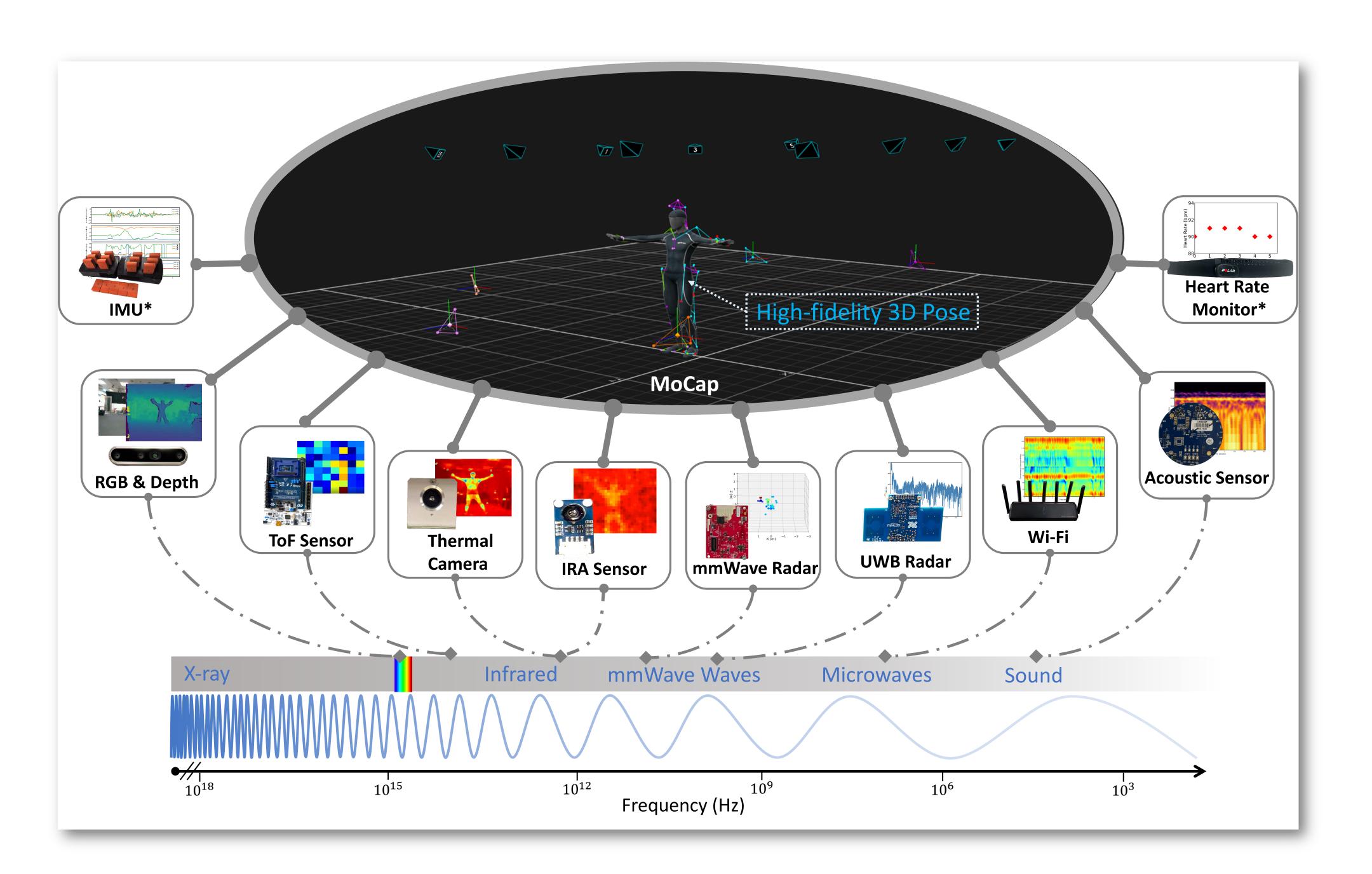
OptiTrack for alignment/supervision;



Supports HAR, 3D HPE, fusion, cross-modal learning, sensor foundation models.

Modalities





Visual

RGB-D (×3), ToF, Thermal (×2), Infrared Array (×5)

RF

mmWave (FMCW×5, SFCW×1), UWB, Wi-Fi

Others

Audio microphones, active acoustic emitter, IMU (17 nodes), Heart Rate sensor

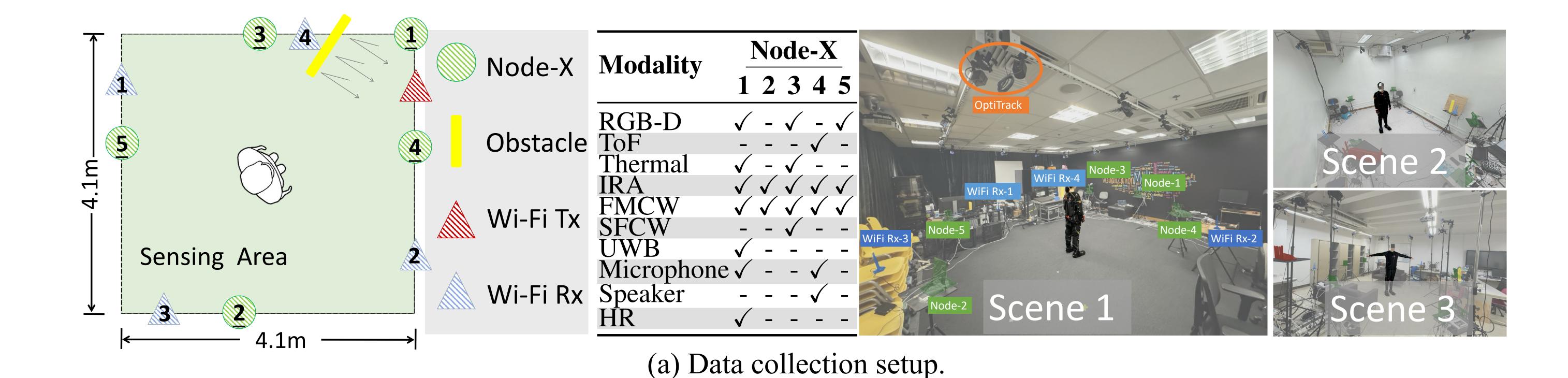
Labels

3D skeletal keypoints (50 markers).

Collection, scenes & sync



- 3 scenes (office, lab, living room); 5 sensing nodes.
- Wi-Fi Rx rectangle; one deliberate NLOS link.
- NTP-based global time; single broadcast start timestamp.
- Activities cover body-motion, H-O/H-C/H-H interactions, medical + aerobics + freestyle.



Scale & examples

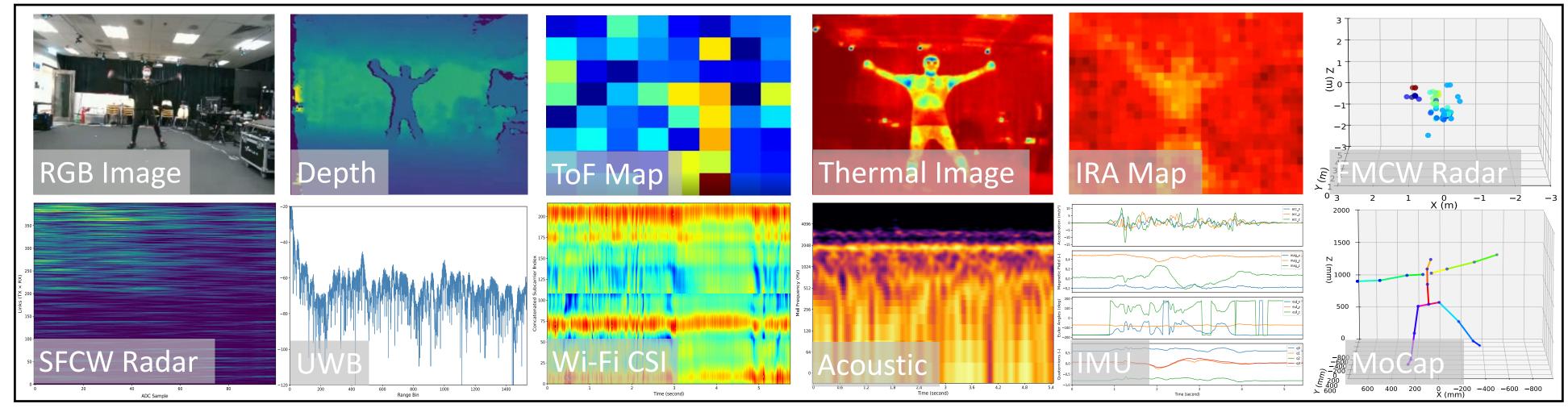


Modality	Total Frames	Sampling Rate (Hz)	Number of Nodes	Data Dimension (per frame)	Storage Size (GB)
RGB-D	7.82M	29.95	3	$480 \times 640 \ (\times 3)^{\dagger}$	522.45
ToF	645.08k	7.32	1	$8 \times 8 \times 18$	6.03
Thermal	1.50M	8.80	2	240×320	42.51
IRA	3.02M	6.91	5	24×32	18.03
mmWave (FMCW) [©]	3.74M	8.81	5	150×4	5.52
mmWave (SFCW)	280.28k	3.20	1	400×100	167.16
UWB	1.49M	17.07	1	1×1535	19.34
Wi-Fi	27.35M	75.62	4	2×114	94.85
Acoustic▲	5.39M	48000	2	1×128	15.46
IMU	5.42M	60.01	17	13×17	9.02
Heart Rate	90.10k	1.03	1	1	0.007
MoCap	10.97M	120	50	20×3	82.04

Scale & examples



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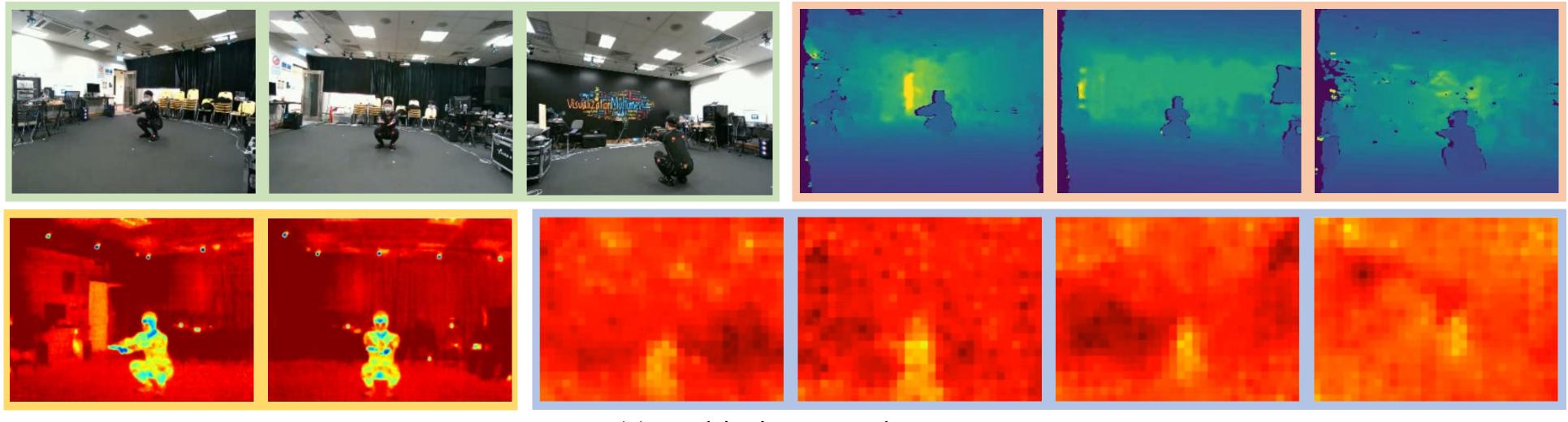


(b) Multi-modality samples.

Scale & examples



Modality	Total Frames	Sampling Rate (Hz)	Number of Nodes	Data Dimension (per frame)	Storage Size (GB)
RGB-D	7.82M	29.95	3	$480 \times 640 \ (\times 3)^{\dagger}$	522.45
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Heart Rate	90.10k	1.03	1	1	0.007
MoCap	10.97M	120	50	20×3	82.04



(c) Multi-view samples.

Evaluation results



Human Activity Recognition (HAR): 62 daily activities across five categories (body-only, human—object, human—computer, human—human, medical), class-balanced.

Table 1: HAR accuracy (%) across modalities, models, and protocols. Results are shown for the 10-class subset (left) and full 62-class setting (right). "N/A" denotes model incompatibility. Accuracy is given to one decimal with the standard error of the mean as x.x.

				ndard error of the m	nean as x.x.	ncompaniomity. The	Couracy
		Modality		Mo	odel		. <u> </u>
	RGB	91.5±2.6 / 93	.4±0.9 93.2	±2.3 / 91.2±1.0	94.9±2.0 / 9	3.1±0.9	0.7±2.8 / 60.9±1.8
,	Depth	89.7±2.8 / 86	.6±1.2 90.6	±2.7 / 83.2±1.3	86.3±3.2 / 8	1.7±1.4 87	'.2±3.1 / 40.0±1.8
		Tor	86.8±3.1 / /0.3±1.6	N/A	82.6±3.5 / 51.8±1.8	89.3±2.8 / /5.9±1.5	
		Thermal	90.1±2.7 / 85.0±1.3	91.7±2.5 / 85.4±1.3	85.1±3.2 / 79.2±1.5	47.1±4.6 / 28.6±1.6	
		IRA	25.6±4.0 / 1.8±0.5	N/A	14.0±3.2 / 3.7±0.7	19.0±3.6 / 4.2±0.7	
		FMCW	39.3±4.5 / 24.0±1.6	74.4±4.1 / 46.3±1.8	36.8±4.5 / 5.0±0.8	38.5±4.5 / 12.6±1.2	
		SFCW	30.6±4.2 / 9.0±1.0	59.5±4.5 / 13.0±1.2	26.4±4.0 / 0.9±0.3	28.1±4.1 / 5.1±0.8	
		UWB	98.3±1.2 / 93.8±0.9	88.4±2.9 / 80.1±1.4	100.0±0.0 / 90.4±1.1	94.2±2.1 / 75.8±1.5	
		Wi-Fi	93.3±2.3 / 91.1±1.0	90.8±2.6 / 91.0±1.0	91.7±2.5 / 92.3±1.0	81.7±3.5 / 60.5±1.8	
		Aggretia	100.45/155.10	600.451516.10	267.44/201.17	20 2.42 / 10 1.44	
]	MU	96.6±1.7 / 96.5	±0.7 97.4±1	.5 / 95.7±0.7	98.3±1.2 / 95.	7±0.7 94.0	±2.2 / 35.8±1.8

IMU 96.6±1.7 / 96.5±0.7 97.4±1.5 / 95.7±0.7 98.3±1.2 / 95.7±0.7 94.0±2.2 / 35.8±1.8

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Model

		ResNet	DenseNet	Swin-T	RFNet	
	RGB	91.5±2.6 / 93.4±0.9	93.2±2.3 / 91.2±1.0	94.9±2.0 / 93.1±0.9	89.7±2.8 / 60.9±1.8	
	Denth	897+28/866+12	90 6+27/83 2+13	86 3+32/817+14	87 2+3 1 / 40 0+1 8	
ToF	86.8±3.1 / 70	0.3±1.6	N/A	82.6±3.5 / 5	51.8±1.8	0.3±2.8 / 75.9±1.5
Thermal	90.1±2.7 / 85	5.0±1.3 91.7	±2.5 / 85.4±1.3	85.1±3.2 / ′	79.2±1.5 47	.1±4.6 / 28.6±1.6

FMCW	39.3±4.5 / 24.0±1.6	74.4±4.1 / 46.3±1.8	36.8±4.5 / 5.0±0.8	38.5±4.5 / 12.6±1.2
SFCW	30.6±4.2 / 9.0±1.0	59.5±4.5 / 13.0±1.2	26.4±4.0 / 0.9±0.3	28.1±4.1 / 5.1±0.8
UWB	98.3±1.2 / 93.8±0.9	88.4±2.9 / 80.1±1.4	100.0±0.0 / 90.4±1.1	94.2±2.1 / 75.8±1.5
Wi-Fi	93.3±2.3 / 91.1±1.0	90.8±2.6 / 91.0±1.0	91.7±2.5 / 92.3±1.0	81.7±3.5 / 60.5±1.8
Acoustic	40.8±4.5 / 45.5±1.8	60.0±4.5 / 54.6±1.8	36.7±4.4 / 32.1±1.7	29.2±4.2 / 19.1±1.4
IMU	96.6±1.7 / 96.5±0.7	97.4±1.5 / 95.7±0.7	98.3±1.2 / 95.7±0.7	94.0±2.2 / 35.8±1.8

IMO	$96.6\pm1.7 / 96.5\pm0.7$	$97.4\pm1.5/95.7\pm0.7$	98.3±1.2 / 95.7±0.7	94.0±2.2 / 35.8±1.8
TICOMPILE	TU.ULT.J / TJ.JLI.0	UU.ULT.J / JT.ULI.U	JU. / ITT.T / JZ. I II./	~/.~~\\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \

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Table 1: HAR accuracy (%) across modalities, models, and protocols. Results are shown for the 10-class subset (left) and full 62-class setting (right). "N/A" denotes model incompatibility. Accuracy is given to one decimal with the standard error of the mean as x.x.

Modality	Model							
	ResNet	DenseNet	Swin-T	RFNet				
RGB	91.5±2.6 / 93.4±0.9	93.2±2.3 / 91.2±1.0	94.9±2.0 / 93.1±0.9	89.7±2.8 / 60.9±1.8				
Depth	89.7±2.8 / 86.6±1.2	90.6±2.7 / 83.2±1.3	86.3±3.2 / 81.7±1.4	87.2±3.1 / 40.0±1.8				
ToF	86.8±3.1 / 70.3±1.6	N/A	82.6±3.5 / 51.8±1.8	89.3±2.8 / 75.9±1.5				
Thermal	90.1±2.7 / 85.0±1.3	91.7±2.5 / 85.4±1.3	85.1±3.2 / 79.2±1.5	47.1±4.6 / 28.6±1.6				
IRA	25.6±4.0 / 1.8±0.5	N/A	14.0±3.2 / 3.7±0.7	19.0±3.6 / 4.2±0.7				
FMCW	39.3±4.5 / 24.0±1.6	74.4±4.1 / 46.3±1.8	36.8±4.5 / 5.0±0.8	38.5±4.5 / 12.6±1.2				

UWB	98.3±1.2 / 93.8±0.9	88.4±2.9 / 80.1±1.4	100.0±0.0 / 90.4±1.1	94.2±2.1 / 75.8±1.5
Wi-Fi	93.3±2.3 / 91.1±1.0	90.8±2.6 / 91.0±1.0	91.7±2.5 / 92.3±1.0	81.7±3.5 / 60.5±1.8

Acoustic	40.8±4.5 / 45.5±1.8	60.0±4.5 / 54.6±1.8	36.7±4.4 / 32.1±1.7	29.2±4.2 / 19.1±1.4
IMU	96.6±1.7 / 96.5±0.7	97.4±1.5 / 95.7±0.7	98.3±1.2 / 95.7±0.7	94.0±2.2 / 35.8±1.8

IMO	96.6±1.7 / 96.5±0.7	97.4±1.5 / 95.7±0.7	98.3±1.2 / 95.7±0.7	94.0±2.2 / 35.8±1.8
Menouse	TU.ULT.0 / TJ.JLI.0	00.014.0 / 04.011.0	JU. / 17.7 / JZ. I 11./	~/·~:

Evaluation results (cont.)



Human Pose Estimation (HPE): Multi-view, multi-modal data with motion-capture ground truth (3D skeletons) enabling precise cross-view/cross-sensor training and evaluation on both structured aerobics and freestyle sequences.

Table 2: HPE results (MPJPE in millimeters; lower is better) across sensing modalities. "N/A" denotes model incompatibility. Values are to one decimal with standard error of the mean as x.x.

	Modality		Mod	del		
		RecNet	DenceNet	Swin_T	RFNot	
RGB	133.3±4	.4	147.2 ± 5.1	269	0.6 ± 6.2	162.8±4.6
Depth	131.4±4	.5	147.4±4.6	248	3.2±6.5	194.8±5.7
	Thermal	142.8±4.7	147.0±4.9	259.9±5.9	254.3±6.1	
	IRA	244.4±6.8	N/A	261.1±6.4	265.1±6.7	
	FMCW	198.5±5.7	185.4±5.4	272.5±7.3	220.9±6.0	
	SFCW	206.7±6.2	202.9±6.2	264.2±6.4	270.7±6.6	
	UWB	142.4±4.8	158.0±5.2	260.5±6.1	159.5±5.0	
	Wi-Fi	147.3±4.7	147.4±4.9	262.2±6.0	186.8±5.3	
	Acoustic	258.8±6.9	256.8±6.7	271.2±6.7	243.6±6.8	
	IMU	147.9±5.0	159.3±5.5	251.6±6.4	180.9±5.3	
	TIATO	T_L \ ' \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	エクン・クテン・ク	Z2 I.O.T0.T	T 00.7 ± 2.2	
		147.9±5.0	159.3±5.5	251.6±6.4	180.9±5.3	

 147.4 ± 4.9

Evaluation results (cont.)

Acoustic

 258.8 ± 6.9



Human Pose Estimation (HPE): Multi-view, multi-modal data with motion-capture ground truth (3D skeletons) enabling precise cross-view/cross-sensor training and evaluation on both structured aerobics and freestyle sequences.

Table 2: HPE results (MPJPE in millimeters; lower is better) across sensing modalities. "N/A" denotes model incompatibility. Values are to one decimal with standard error of the mean as x.x.

	Modality _	Model				
		ResNet 133.3±4.4	DenseNet 147.2±5.1	Swin-T 269.6±6.2	RFNet 162.8±4.6	
	RGB					
ToF	152.5±5.2	1011.	N/A	252.1±6.0		162.2±5.0
Thermal	142.8±4.7		147.0±4.9	259.9±5.9		254.3±6.1
	FMCW	244.4±0.8 198.5±5.7	185.4±5.4	201.1±0.4 272.5±7.3	203.1±0.7 220.9±6.0	
	CECW	206.7±3.7	202 0 4 6 2	264.2±1.3	220.9±0.0	
UWB	142.4±4.8		158.0±5.2	260.5±6.1		159.5±5.0
Wi-Fi	147.3±4.7	∠ J∪.∪∴∪./	147.4±4.9	262.2±6.0		186.8±5.3
IMU	147.9±5.0		159.3±5.5	251.6±6.4		180.9±5.3
		147.9 ± 5.0	159.3 ± 5.5	251.6 ± 6.4	180.9 ± 5.3	

 256.8 ± 6.7

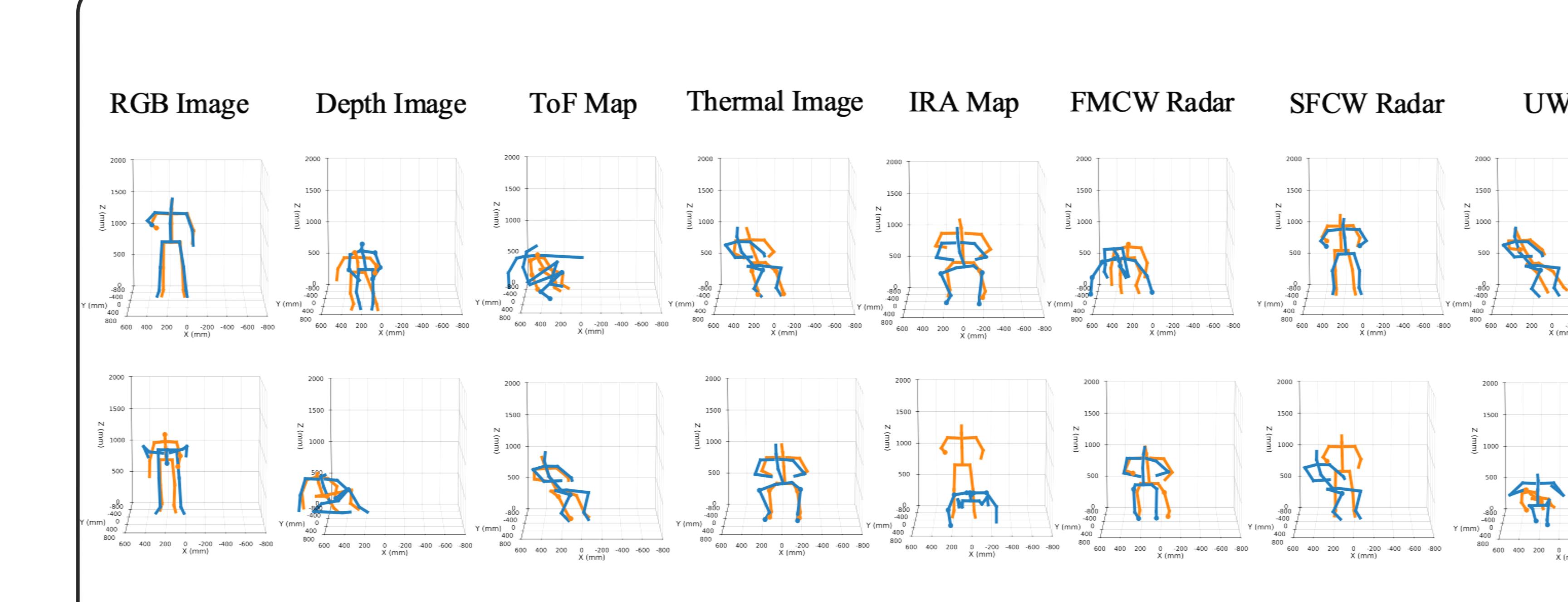
 271.2 ± 6.7

243.6±6.8

Visualization of human pose estimation



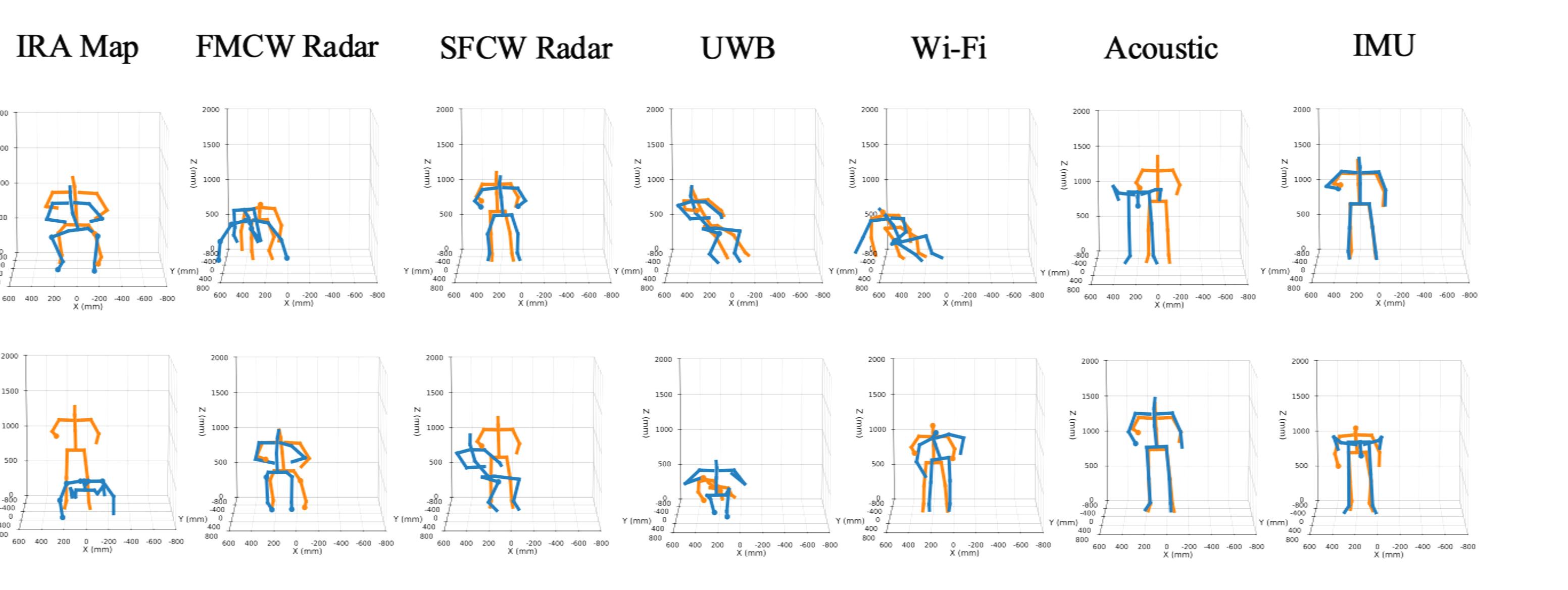
Ground truth skeletons: Predicted skeletons:



Visualization of human pose estimation



Ground truth skeletons: Predicted skeletons:





THANK YOU