



## **Urban Routing Benchmark**

for RL-equipped Connected Autonomous Vehicles

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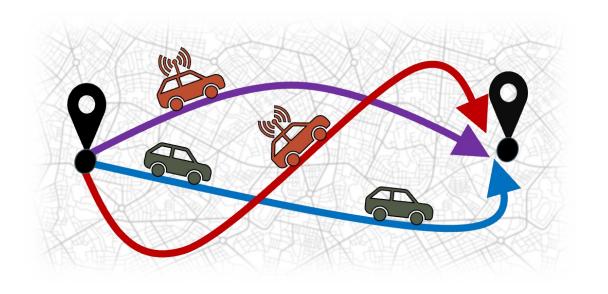






### Background

- We consider future urban systems where limited resources are shared by human drivers and CAVs.
- We study the urban route choice problem: Which route to take to reach my destination?



### Background

A possible future scenario:

## In city traffic, what happens if ~40% of drivers delegate their routing to a shared policy?

- Which raises the following questions:
  - Which algorithm is most suitable for collective urban fleet routing?
  - How does the problem scale with network complexity, population size, and planning horizon?
  - What is the impact on: humans, congestion, speed, mileage, and equity?

#### **URB**



- URB is a comprehensive benchmarking framework, aiming to standardize the assessment for CAV routing solutions.
- It unifies evaluation across real-world-inspired tasks.
- It comes with a catalog of implementations, baselines, and domain-specific KPIs.

#### **URB** - Dataset

#### 29 real-world networks

A diverse set of scenarios to test solution robustness under different complexities.

#### Realistic demand data

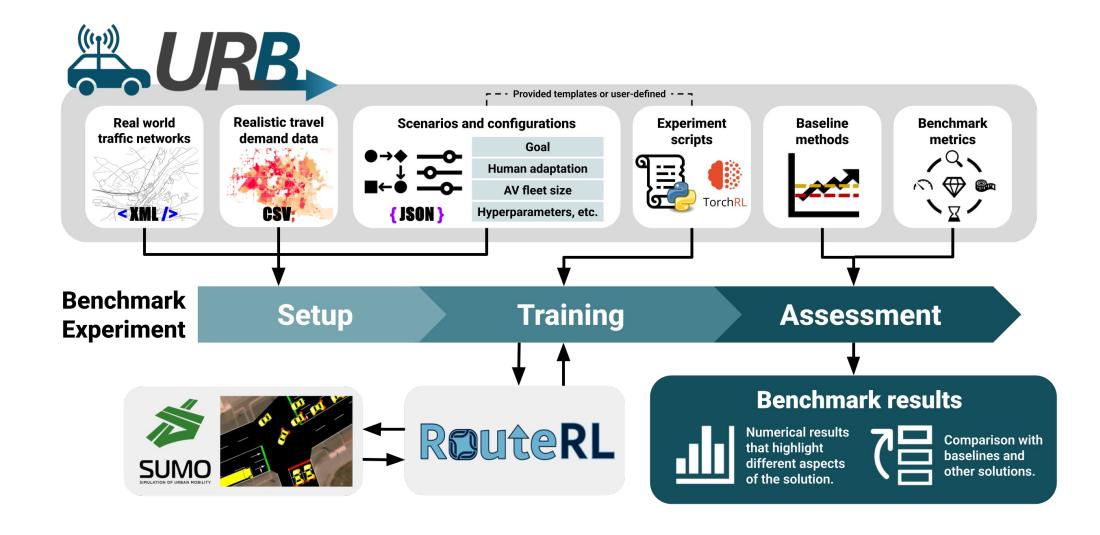
Each network is bundled with realistic demand data for assessment in realistic scenarios.

#### Open access

The dataset and its generation code are documented and made publicly available.



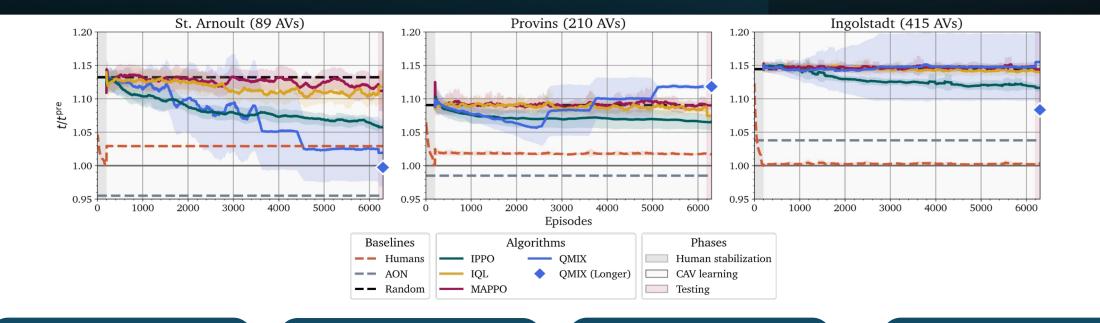
### **URB** - Framework



#### Scenario 1: Mixed Autonomy

In a given network with a **fixed demand** pattern, **human drivers** have stabilized their route-choice strategies to minimize travel times.

After a 40% share of drivers switch to CAVs and delegate routing decisions, the CAVs use MARL to develop new strategies to reduce delay.



200, 6000, and 100 episodes for human stabilization, CAV training, and policy testing, respectively.

We test IPPO, IQL, QMIX, and MAPPO against the URB baselines in 3 networks.

Many algorithms hardly beat the random baseline.

Only QMIX in St. Arnoult managed to outperform humans, though not consistently.

		$oldsymbol{t}^{ exttt{TEST}}$	$t_{ m CAV}$	$t_{ m HDV}$	$  c_{\scriptscriptstyle  m ALL}$	$c_{ m HDV}$	$c_{ m CAV}$	$ \hspace{.1cm} \Delta_{\mathbf{V}}$	$\Delta_{\mathbf{L}}$	WR
ARNOULT	IPPO IQL MAPPO QMIX	3.36 (0.040) 3.35 (0.049)	3.33 (0.013) 3.53 (0.104) 3.51 (0.121) <u>3.21</u> (0.206)	3.24 (0.005) 3.25 (0.004)	0.66 (0.000) 0.66 (0.000)	$\overline{0.14} (0.000)$	1.38 (0.034) 1.44 (0.004) 1.45 (0.000) 1.43 (0.005)	-0.24 (0.067) -0.37 (0.115) -0.27 (0.129) -0.22 (0.034)	0.09 (0.021) 0.09 (0.019)	$0\% \ 0\%$
ST. A	HUMAN AON RANDOM	3.15 3.15 3.38	N/A <b>3.01</b> 3.58	3.15 3.25 3.25	N/A <b>0.55</b> 0.60	N/A <b>0.09</b> <b>0.09</b>	N/A <b>1.21</b> 1.36	0.00 -0.06 -0.33	<b>0.00</b> <b>0.00</b> 0.10	100 % 100 % 0%
PROVINS	IPPO IQL MAPPO QMIX	2.91 (0.011) 2.93 (0.011)	2.98 (0.040) 3.01 (0.027) 3.05 (0.024) 3.14 (0.000)	2.85 (0.008) 2.84 (0.005)	1.40 (0.104) 1.29 (0.162)	0.92 (0.068) 0.83 (0.110)	1.05 (0.356) 2.12 (0.183) 2.00 (0.247) 1.35 (0.278)	-0.52 (0.080) -0.58 (0.093) -0.69 (0.038) -0.82 (0.033)	$\frac{0.05}{0.06} (0.007) \\ 0.06 (0.004)$	0% 0% 0% 0%
PR	HUMAN AON RANDOM	2.80 2.81 2.93	N/A <b>2.76</b> 3.04	2.80 2.84 2.85	N/A <b>0.47</b> 0.51	N/A <b>0.19</b> 0.22	N/A 0.99 <b>0.95</b>	0.00 -0.14 -0.62	<b>0.00</b> <b>0.00</b> 0.06	100 % 100 % 0%
OLSTADT	IPPO IQL MAPPO QMIX	4.46 (0.009) 4.45 (0.011)	4.71 (0.030) 4.81 (0.024) 4.82 (0.019) 4.87 (0.325)	4.23 (0.009) 4.21 (0.008)	2.54 (0.546) 2.76 (0.599)	1.93 (0.533) 2.16 (0.622)	3.19 (0.495) 3.44 (0.562) 3.66 (0.562) 2.67 (0.810)	-0.52 (0.095) -0.69 (0.067) -0.72 (0.066) -0.97 (0.235)	0.07 (0.000) 0.07 (0.004)	0% 0% 0% 0%
INGO	HUMAN AON RANDOM	<b>4.21</b> 4.29 4.45	N/A <b>4.37</b> 4.81	<b>4.21</b> 4.23 4.22	N/A <b>0.87</b> 0.99	N/A 0.55 <b>0.49</b>	N/A <b>0.24</b> 1.74	<b>0.00</b> -0.45 -0.68	0.00 <b>-0.01</b> 0.07	100 % 0% 0%

Independent learning: Does not scale and yields sub-human performance.

Training is costly in all cases (large  $c_{\it CAV}$ ).

Humans are disadvantaged; traffic efficiency is reduced  $(t_{test} > t_{pre}, \Delta_V < 0, \Delta_L > 0).$ 

		$oldsymbol{t}^{ exttt{TEST}}$	$t_{ m CAV}$	$t_{ m HDV}$	$  c_{\scriptscriptstyle  m ALL}$	$c_{ m HDV}$	$c_{ m CAV}$	$ \hspace{.1cm} \Delta_{\mathbf{V}}$	$\Delta_{\mathbf{L}}$	WR
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## Algorithmic Performance: Sensitivity Analysis

- Using Scenario 1 in St. Arnoult, we test different demand levels and information restrictions.
- URB exposes the realism gap: large populations, restricted information, and credit assignment remain open challenges for practical applications.

EXPERIMENT	$m{t}^{ ext{PRE}}$	$oldsymbol{t}_{ ext{CAV}}$	$oldsymbol{\Delta_\%} oldsymbol{t}^{ exttt{PRE}}$
IQL (HALF DEMAND) IQL (ORIGINAL) IQL (DOUBLE DEMAND)	3.27 3.15 3.24	3.45 3.53 5.81	$-5.50\% \ -12.06\% \ -79.32\%$
IQL (GLOBAL OBSERVATIONS)	3.15	3.26	-3.49%
MAPPO (HALF DEMAND) MAPPO (ORIGINAL) MAPPO (DOUBLE DEMAND)	3.27 3.15 3.24	3.44 3.45 5.23	$-5.20\% \ -9.52\% \ -61.42\%$

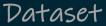
#### Summary

- We introduce **URB**: an open-source, realistic, and comprehensive **MARL** benchmark for large-scale urban routing.
- URB addresses the limited social awareness and practicality often found in RL research benchmarks.
- We contribute an extensive urban routing dataset for testing and assessment using URB metrics.
- We initiate the **URB leaderboard** by evaluating widely used algorithms and empirically highlighting their practical shortcomings.

# Thank you!

**Contact:** 

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Code









