A loss framework for calibrated anomaly detection

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Anomaly detection

Identify instances that deviate from some systematic pattern



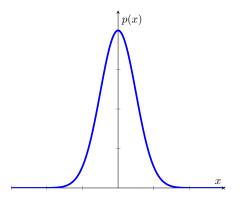
Anomaly detection

Identify instances that deviate from some systematic pattern



A density sublevel view

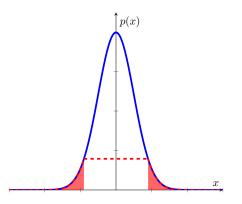
Suppose our data distribution *P* has density $p = \frac{dP}{du}$



A density sublevel view

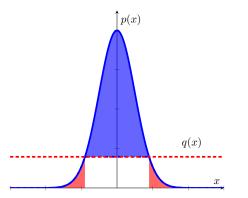
Suppose our data distribution *P* has density $p = \frac{dP}{d\mu}$

Anomalies are instances with low density



A density sublevel view Suppose our data distribution *P* has density $p \doteq \frac{dP}{du}$

Anomalies are instances with low density relative to uniform Q



Classify data against background (Steinwart & Scovel, '05)

Pick density threshold $\alpha > 0$, and classify data *P* vs background *Q*:

$$\min_{f} \mathop{\mathbb{E}}_{P} \ell_{\mathrm{CS}}(+1,f;c) + \mathop{\mathbb{E}}_{Q} \ell_{\mathrm{CS}}(-1,f;c)$$

for cost-sensitive loss $\ell_{\rm CS}$ with cost-ratio $c = \alpha/(1+\alpha)$

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Appealing, but with limitations:

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Doesn't yield confidence scores



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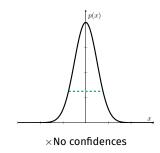
Appealing, but with limitations:

Issue	Resolution
Need sampling for $\mathbb{E}_{Q} f(X) = \int_{\mathcal{X}} f(x) dQ(x)$	A kernel trick
Scale of $\alpha \rightarrow \text{scale of } p(\cdot)$	Pinball loss
Doesn't yield confidence scores	Capped proper loss

Capped proper losses Intuitively, confidence scores are $\propto p(\cdot)^{-1}$

To obtain a single sublevel set of $p(\cdot)$, use

$$\min_{f} \mathop{\mathbb{E}}_{P} \ell(+1,f) + \mathop{\mathbb{E}}_{Q} \ell(-1,f)$$
$$\ell(y,f) = \ell_{\mathrm{CS}}(y,f;c)$$

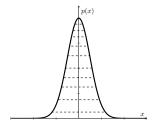


Capped proper losses Intuitively, confidence scores are $\propto p(\cdot)^{-1}$

To obtain all sublevel sets of $p(\cdot)$, use

$$\min_{f} \mathop{\mathbb{E}}_{P} \ell(+1,f) + \mathop{\mathbb{E}}_{Q} \ell(-1,f)$$
$$\ell(y,f) = \int_{0}^{1} w(c) \cdot \ell_{\mathrm{CS}}(y,f;c) \,\mathrm{d}c$$

for positive weight function w; yields proper losses



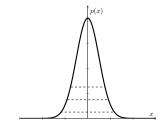
 \checkmark Confidences for **all** instances

Capped proper losses Intuitively, confidence scores are $\propto p(\cdot)^{-1}$

To obtain **tail** sublevel sets of $p(\cdot)$, use

$$\min_{f} \mathop{\mathbb{E}}_{P} \ell(+1,f) + \mathop{\mathbb{E}}_{Q} \ell(-1,f)$$
$$\ell(y,f) = \int_{0}^{1} \left[c \le c_{0} \right] \cdot w(c) \cdot \ell_{\mathrm{CS}}(y,f;c) \, \mathrm{d}c$$

for positive weight function *w*; yields **capped** proper losses



 \checkmark Confidences for anomalous instances

Capped proper losses

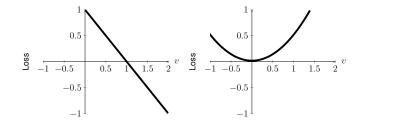
Focussing on the tail sublevel sets results in **capping** the loss

$$\overline{\ell}(+1,f) = \ell(+1,f \wedge \alpha)$$
 $\overline{\ell}(-1,f) = \ell(-1,f \wedge \alpha)$

Capped proper lossesFactFocussing on the tail sublevel sets results in capping the loss $\bar{\ell}(+1,f) = \ell(+1,f \land \alpha)$ $\bar{\ell}(-1,f) = \ell(-1,f \land \alpha)$

An admissible example is

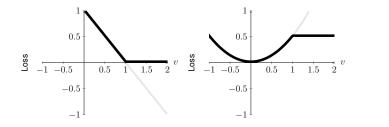
$$\ell(+1,f) = 1 - f$$
 $\ell(-1,f) = \frac{1}{2}f^2$



Capped proper losses Fact Focussing on the tail sublevel sets results in **capping** the loss $\bar{\ell}(+1,f) = \ell(+1,f \land \alpha)$ $\bar{\ell}(-1,f) = \ell(-1,f \land \alpha)$

An admissible example is

$$\bar{\ell}(+1,f) = [\alpha - f]_+$$
 $\bar{\ell}(-1,f) = \frac{1}{2}(f \wedge \alpha)^2$



Quantile control

One can remove cap on $\ell(-1, \cdot)$, yielding e.g.

$$\min_{f} \mathop{\mathbb{E}}_{P} \left[\alpha - f(\mathsf{X}) \right]_{+} + \frac{1}{2} \cdot \mathop{\mathbb{E}}_{Q} f(\mathsf{X})^{2}$$

for fixed density threshold $\alpha > 0$

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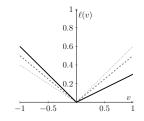
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Can learn α : for anomaly fraction $\mathbf{v} \in (0,1)$, find

$$\min_{f,\alpha} \mathbb{E}_{\frac{P}{P}} [\alpha - f(\mathsf{X})]_{+} + \frac{1}{2} \cdot \mathbb{E}_{\frac{Q}{P}} f(\mathsf{X})^{2} - \mathbf{v} \cdot \alpha,$$

- last term arises from pinball loss
- α^* will be the *v*th quantile of $f^*(X)$



The background loss can be written

$$\min_{f,\alpha} \mathbb{E}_{P} \left[\alpha - f(\mathbf{X}) \right]_{+} + \frac{1}{2} \cdot \mathbb{E}_{Q} f(\mathbf{X})^{2} - \mathbf{v} \cdot \boldsymbol{\alpha}$$

The background loss can be written

$$\begin{split} \min_{f,\alpha} & \mathbb{E}_{P} \left[\alpha - f(\mathsf{X}) \right]_{+} + \frac{1}{2} \cdot \mathbb{E}_{Q} f(\mathsf{X})^{2} - \mathbf{v} \cdot \alpha \\ & = \min_{f,\alpha} \mathbb{E}_{P} \left[\alpha - f(\mathsf{X}) \right]_{+} + \frac{1}{2} \cdot \int_{\mathcal{X}} f(x)^{2} \, \mathrm{d}_{Q}(x) - \mathbf{v} \cdot \alpha \end{split}$$

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$$\begin{split} \min_{f,\alpha} & \mathbb{E} \left[\alpha - f(\mathsf{X}) \right]_{+} + \frac{1}{2} \cdot \mathbb{E} f(\mathsf{X})^{2} - \mathbf{v} \cdot \alpha \\ &= \min_{f,\alpha} \mathbb{E} \left[\alpha - f(\mathsf{X}) \right]_{+} + \frac{1}{2} \cdot \int_{\mathcal{X}} f(x)^{2} \, \mathrm{d} \mathbf{\mathcal{Q}}(x) - \mathbf{v} \cdot \alpha \\ &= \min_{f,\alpha} \mathbb{E} \left[\alpha - f(\mathsf{X}) \right]_{+} + \frac{1}{2} \cdot \|f\|_{L_{2}(\mathbf{\mathcal{Q}})}^{2} - \mathbf{v} \cdot \alpha \end{split}$$

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Suppose we commit to using kernelised *f*:

$$\min_{f \in \mathcal{H}, \alpha \in \mathbb{R}} \mathbb{E} \left[\alpha - f(\mathbf{X}) \right]_{+} + \frac{1}{2} \cdot \|f\|_{L_2(\mathbf{Q})}^2 + \frac{\gamma}{2} \cdot \|f\|_{\mathcal{H}}^2 - \mathbf{v} \cdot \alpha$$

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Observed in point processes (McCullagh and Møller, '06) that

$$||f||_{L_2(\mathbf{Q})}^2 + \gamma \cdot ||f||_{\mathcal{H}}^2 = ||f||_{\bar{\mathcal{H}}(\gamma,\mathbf{Q})}^2$$

for some modified RKHS $\bar{\mathcal{H}}(\gamma, Q)$

Drop by poster #**766**!

We propose to minimise, for proper loss ℓ ,

$$\min_{f \in \mathcal{H}, \alpha \in \mathbb{R}} \mathbb{E}_{P} \left[\ell(+1, f(\mathbf{X}) - \ell(+1, \alpha)) \right]_{+} + \frac{1}{2} \cdot \|f\|_{\mathcal{H}(\gamma, \mathbf{Q})}^{2} - \mathbf{v} \cdot \ell(+1, \alpha)$$

This gives a framework for anomaly detection which:

- avoids sampling for background Q
- provides quantile control
- yields calibrated confidence scores

See paper for experiments