

Deep Reinforcement Learning in a Handful of Trials using Probabilistic Dynamics Models

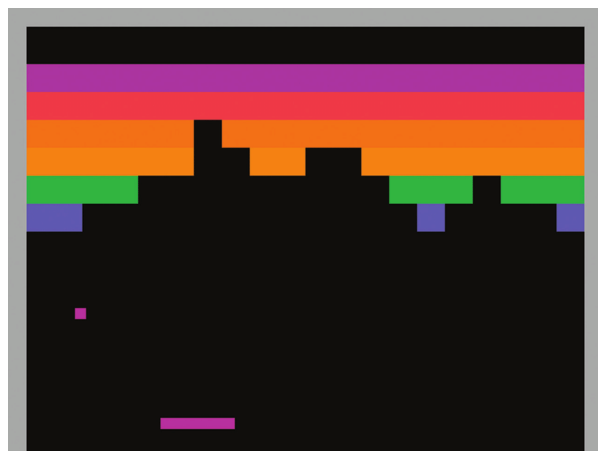
Kurtland Chua, Roberto Calandra, Rowan McAllister, Sergey Levine

University of California, Berkeley



How Long Does Learning Take?

~50 million
frames



[Mnih et al. 2015]

~21 million
games



[Silver et al. 2017]

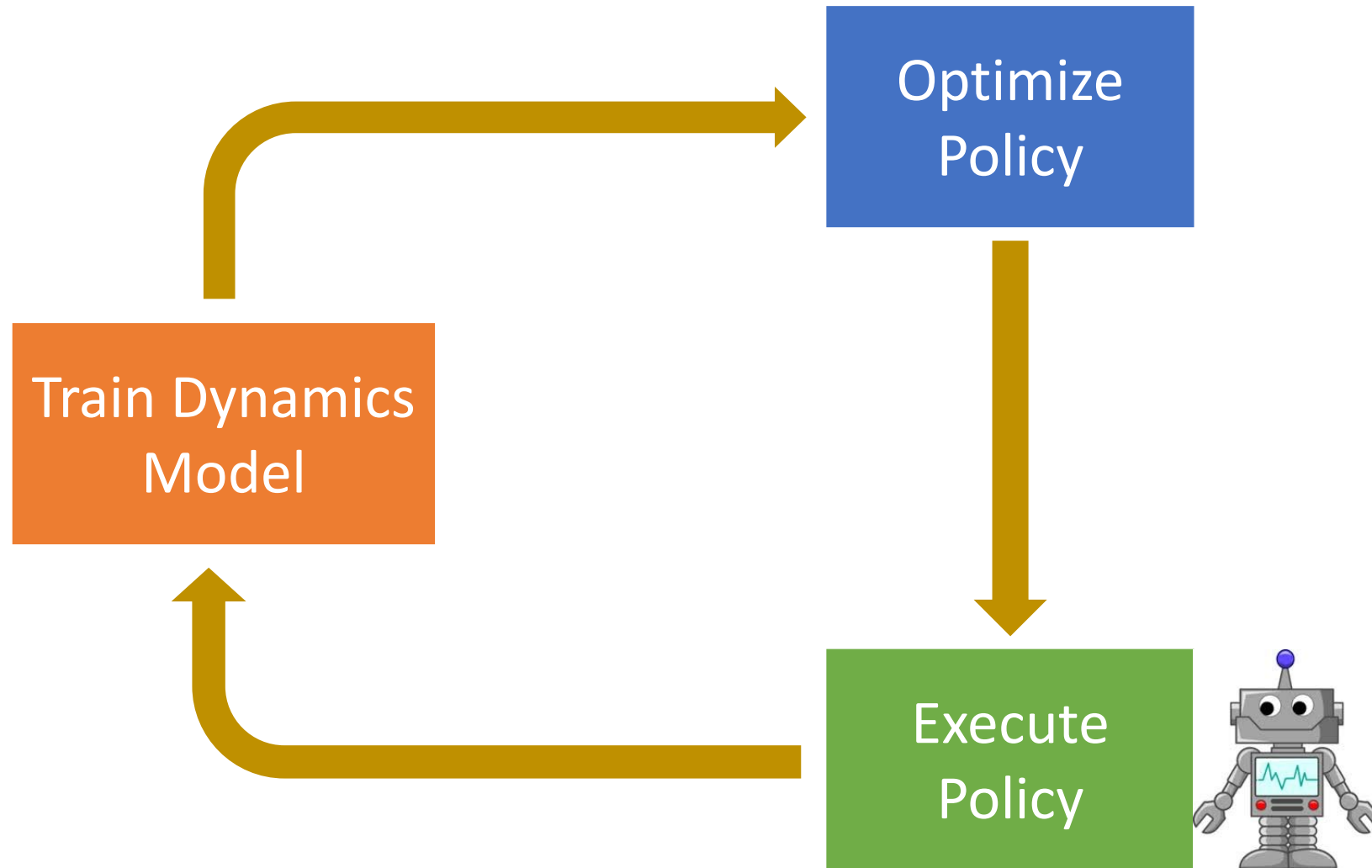


[Levine et al. 2017]

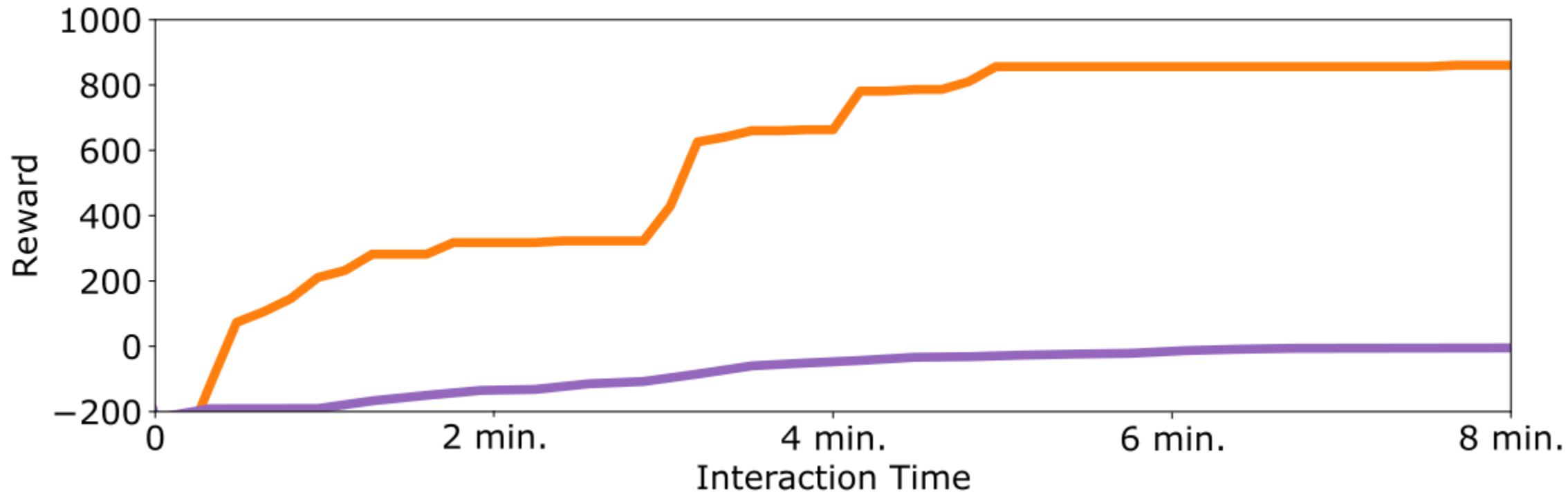
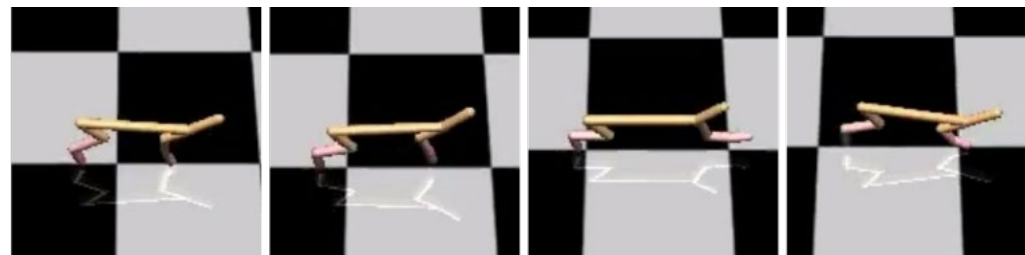
~800,000
grasp
attempts

Can we speed this up?

Model-Based Reinforcement Learning



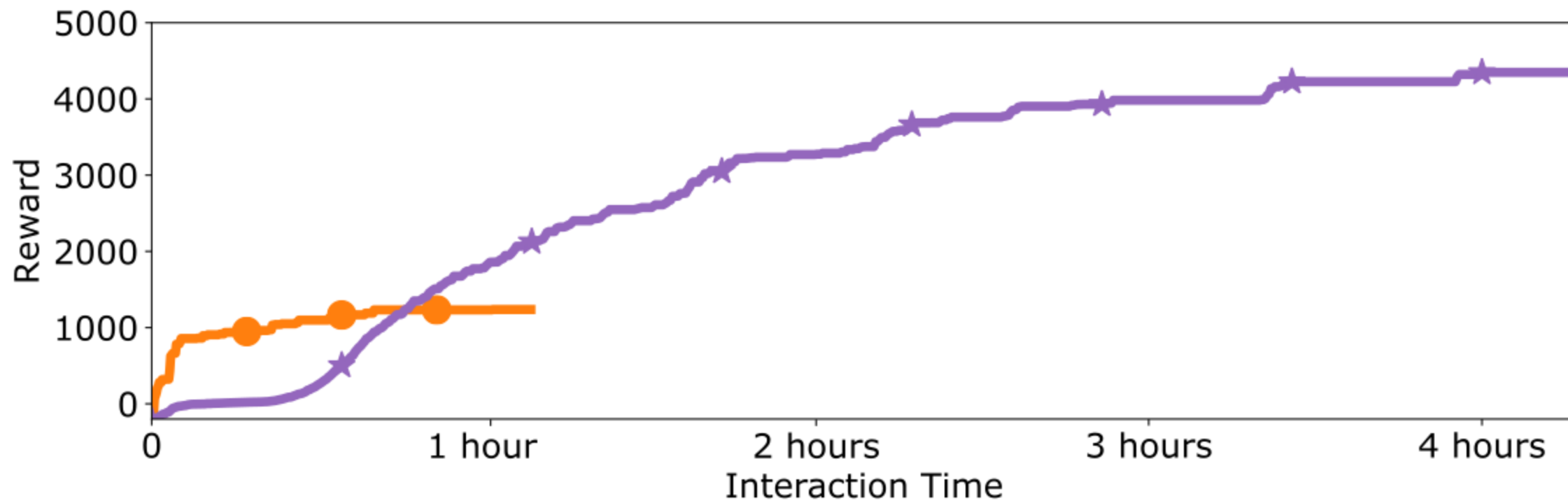
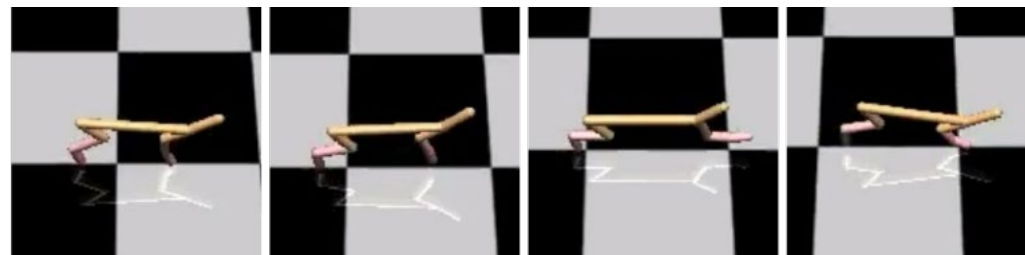
Comparative Performance on HalfCheetah




SOTA
Model-Based
(2017)


SOTA
Model-Free
(2017)

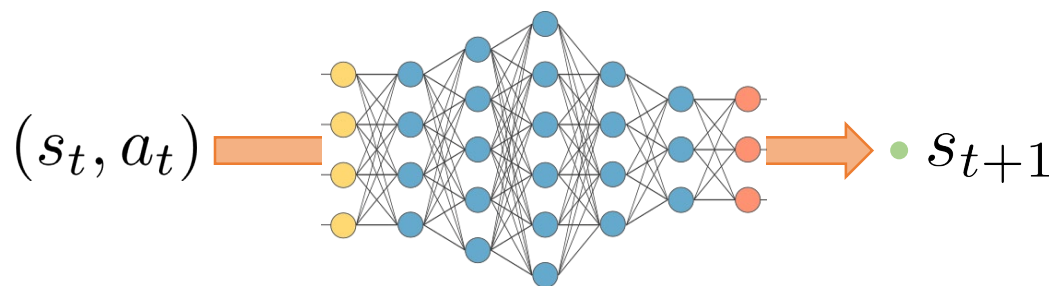
Comparative Performance on HalfCheetah



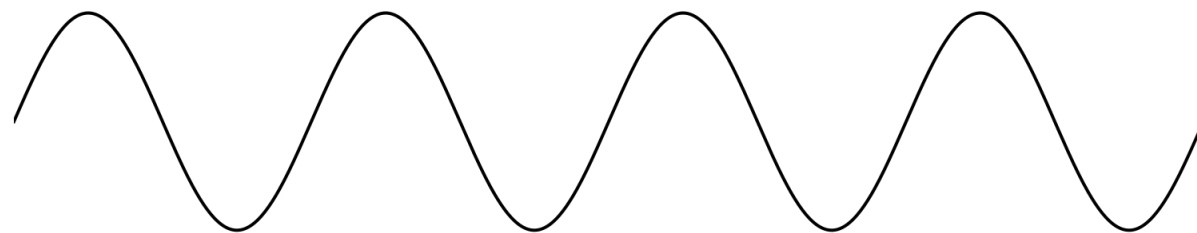
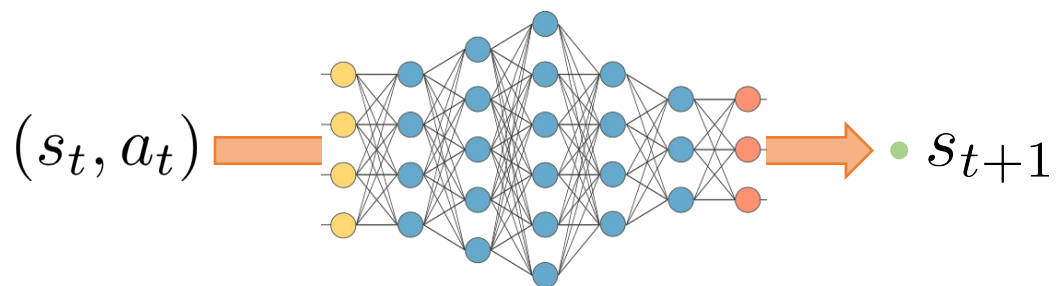

SOTA
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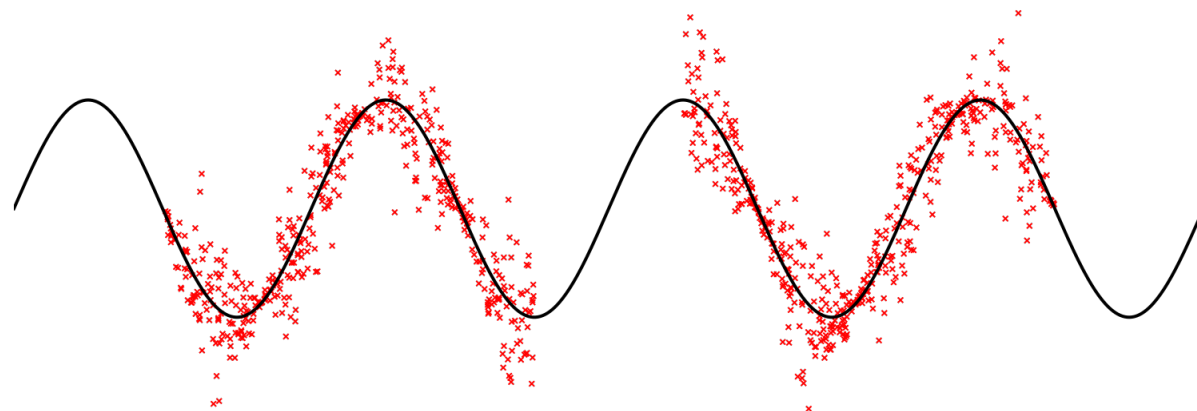
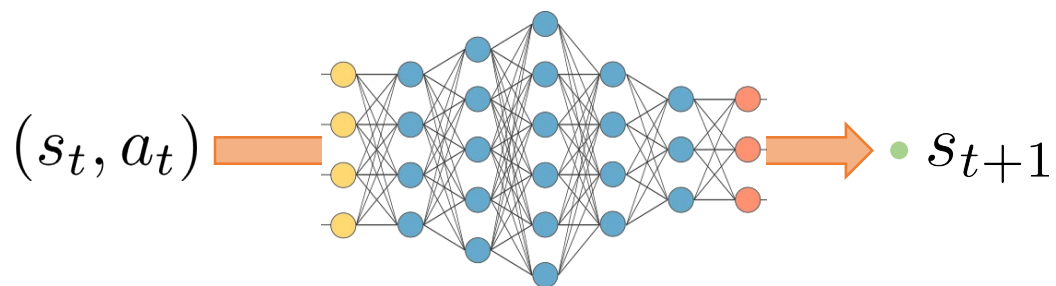
Deterministic Neural Nets as Models



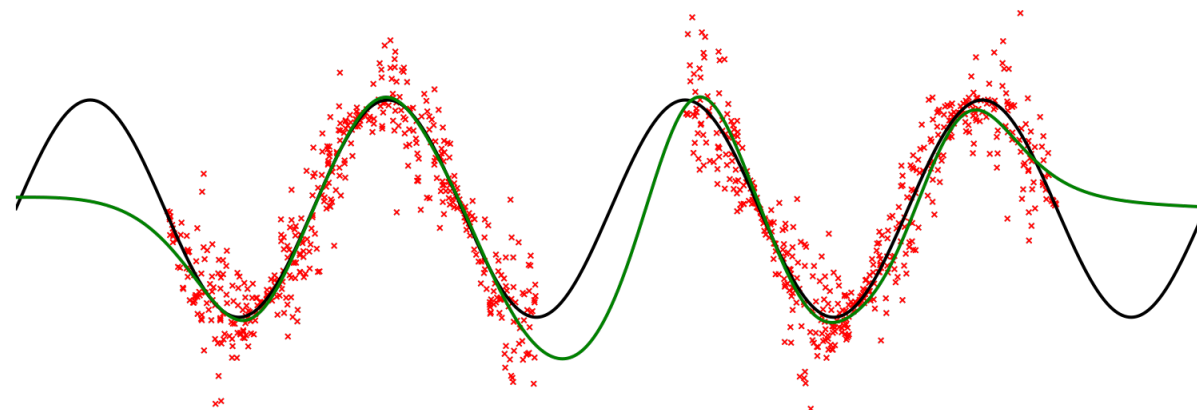
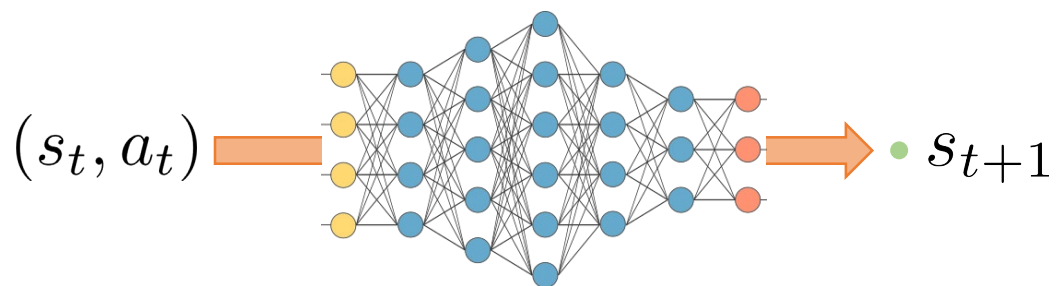
Deterministic Neural Nets as Models



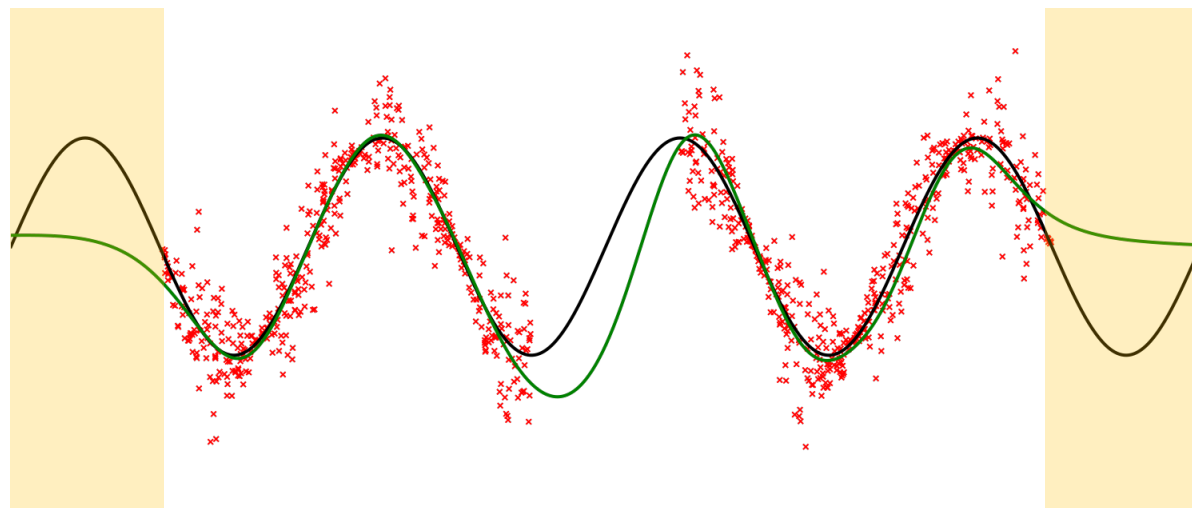
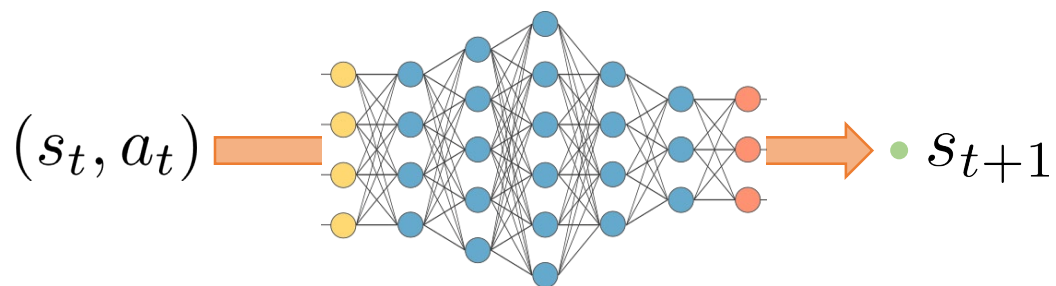
Deterministic Neural Nets as Models



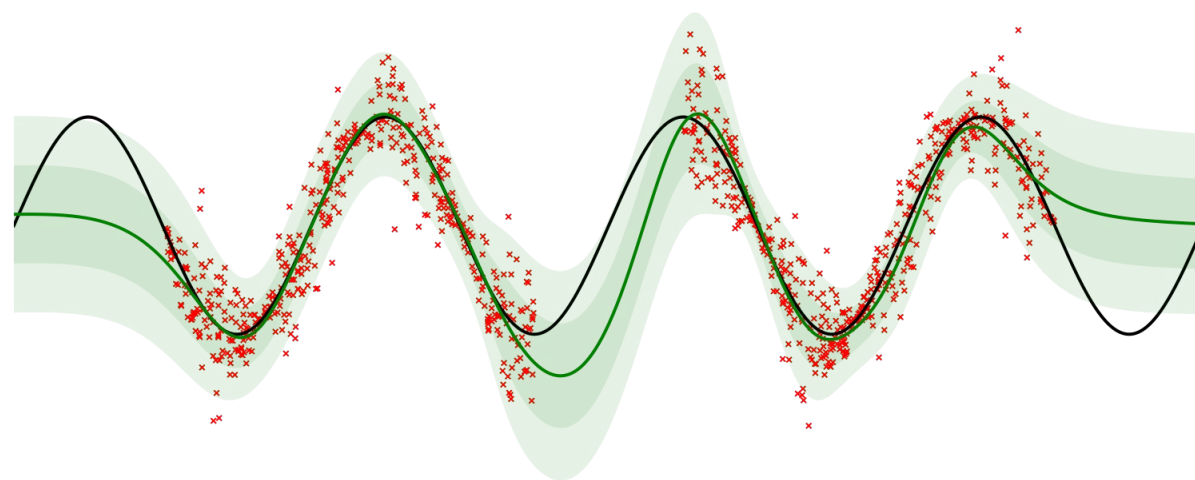
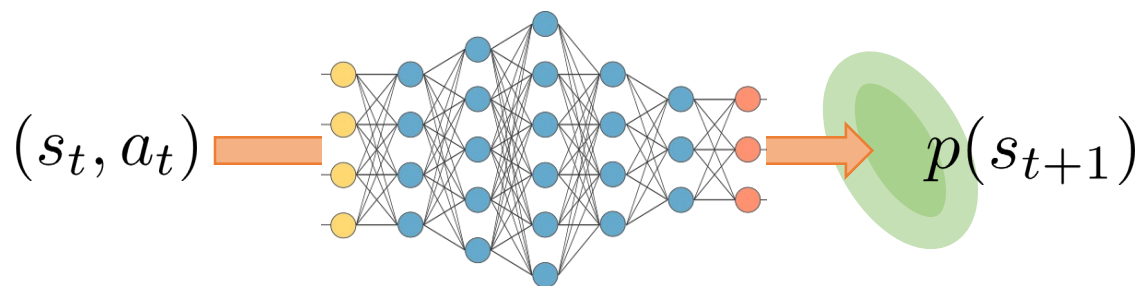
Deterministic Neural Nets as Models



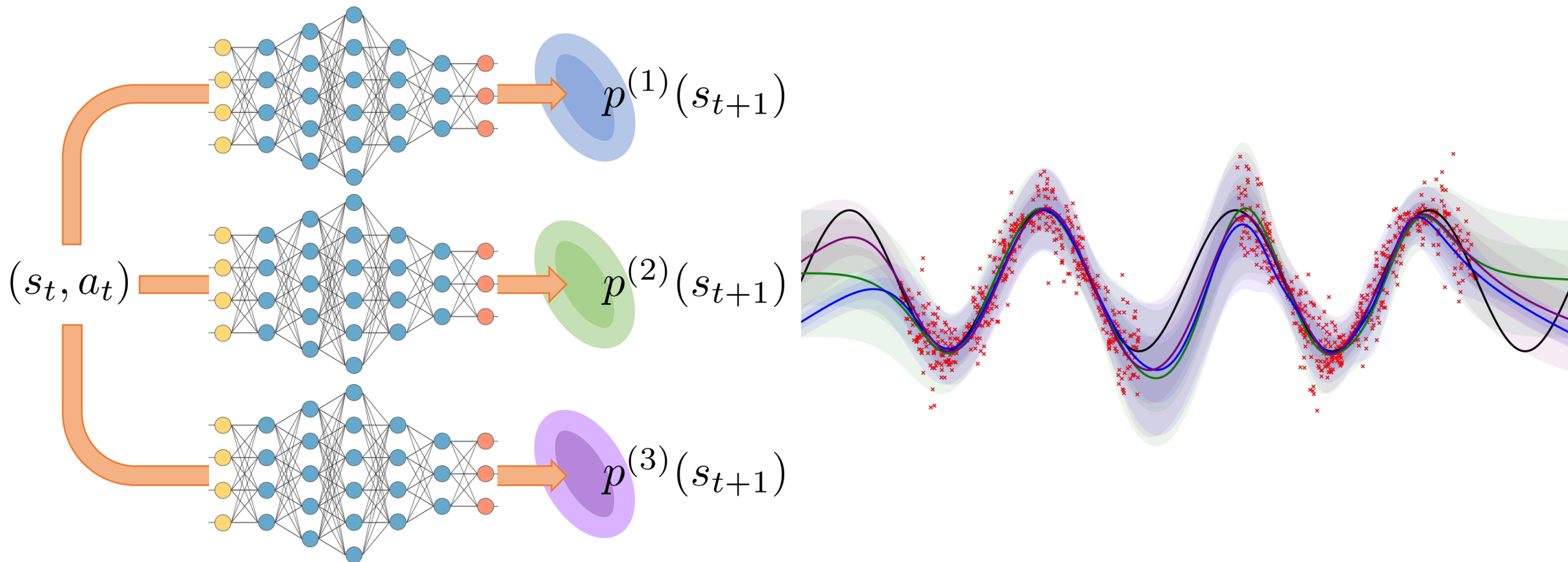
Deterministic Neural Nets as Models



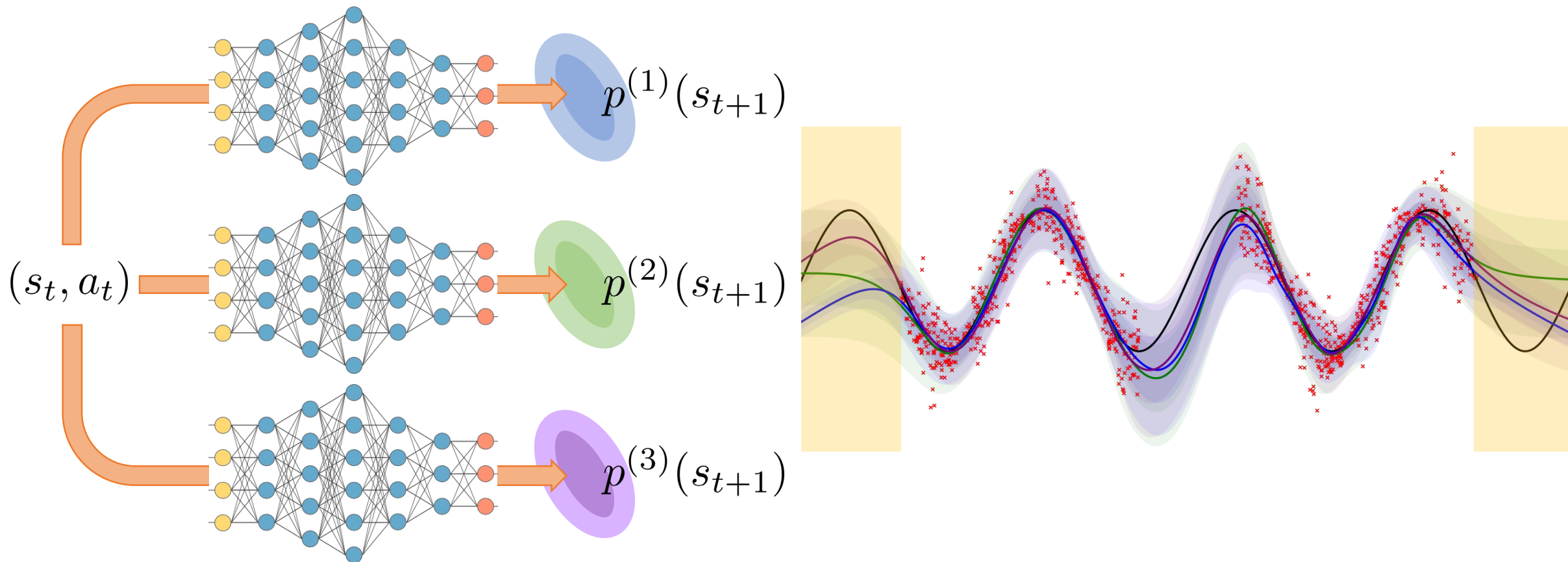
Probabilistic Neural Nets as Models



Probabilistic Ensembles as Models



Probabilistic Ensembles as Models



Trajectory Sampling for State Propagation

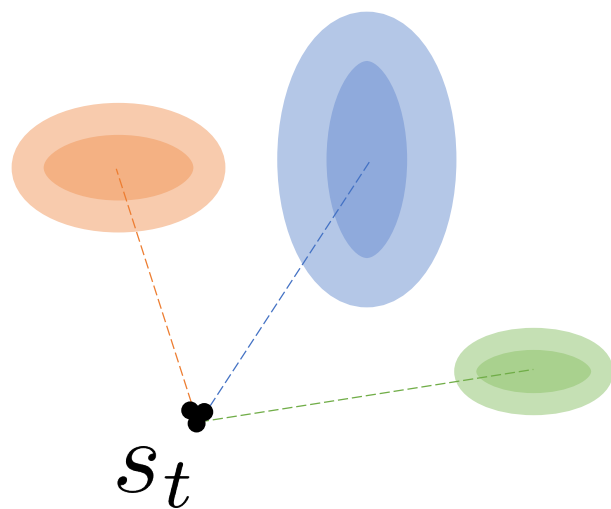
Trajectory Sampling for State Propagation

s_t

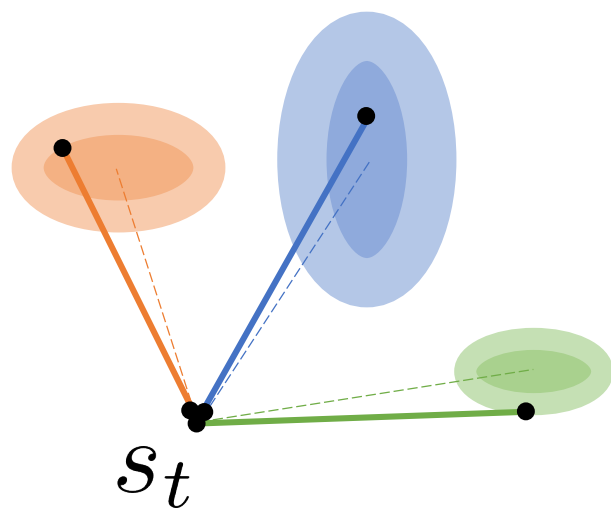
Trajectory Sampling for State Propagation

s_t

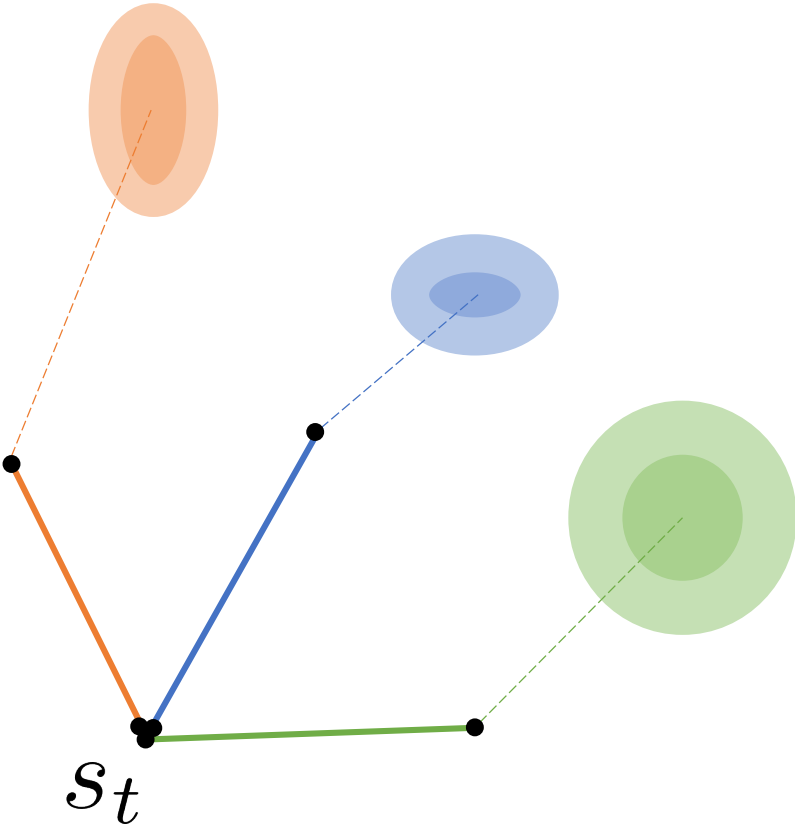
Trajectory Sampling for State Propagation



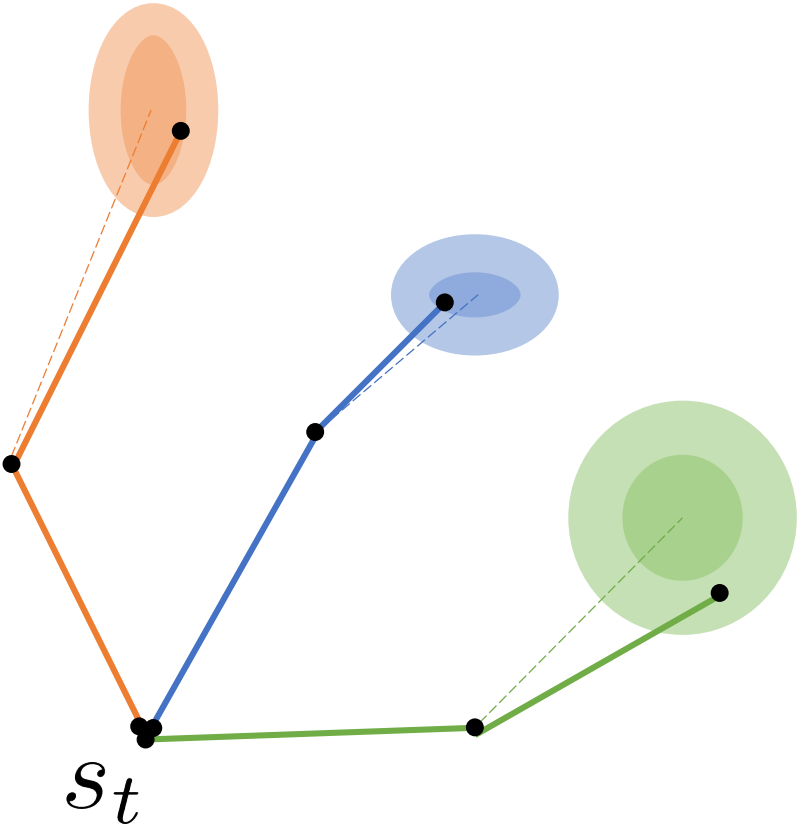
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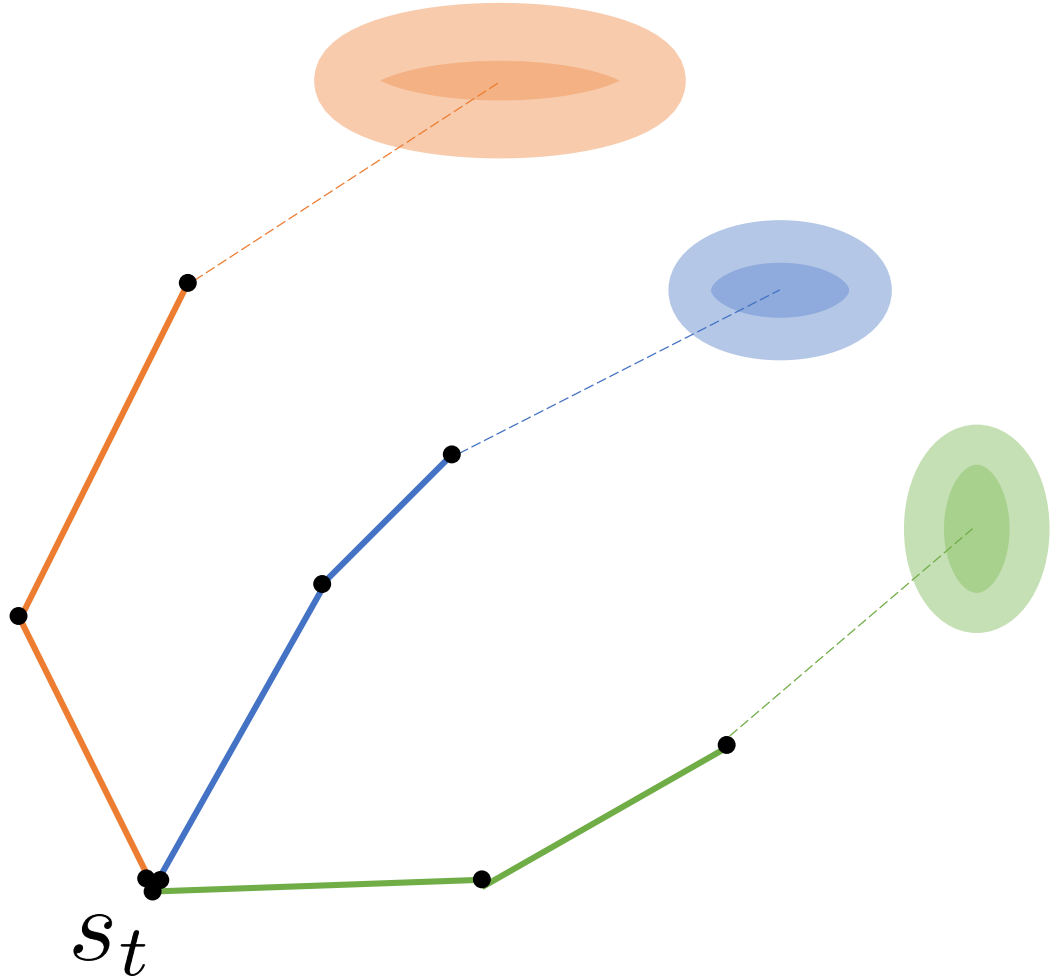
Trajectory Sampling for State Propagation



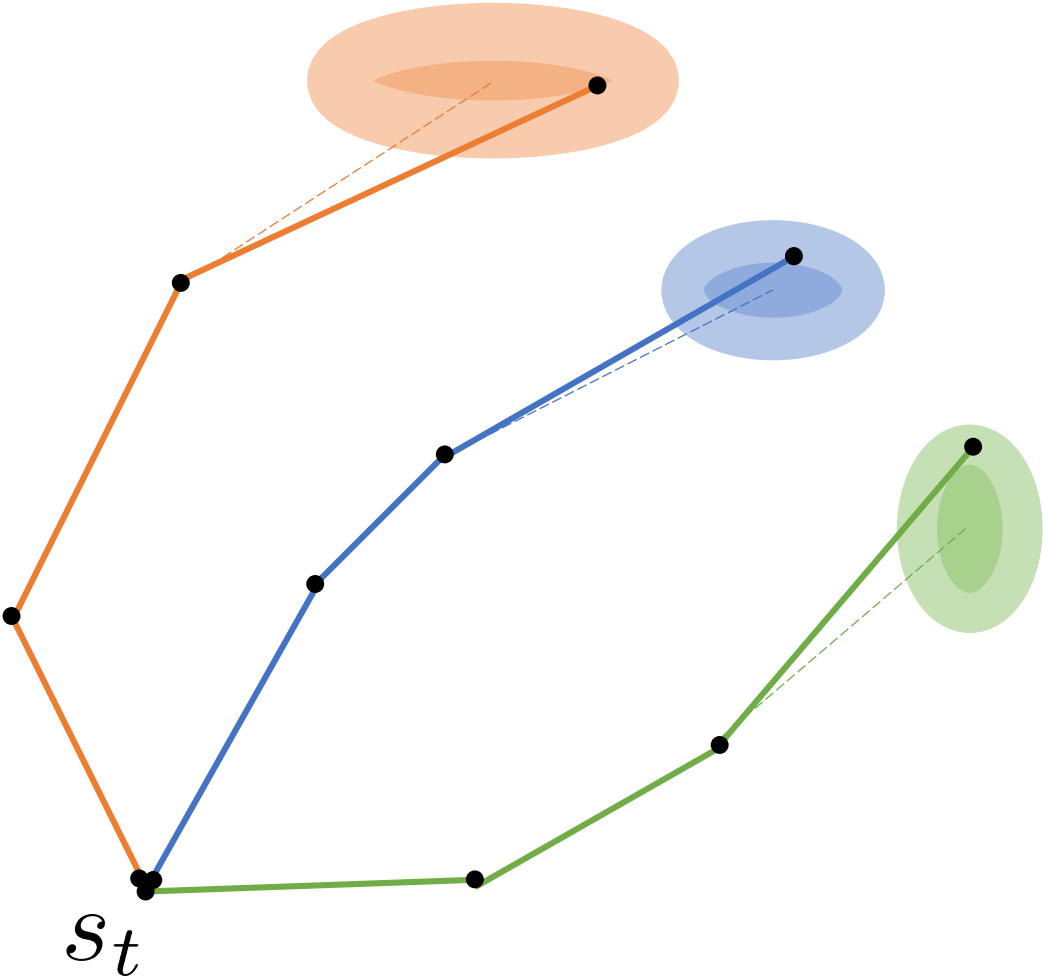
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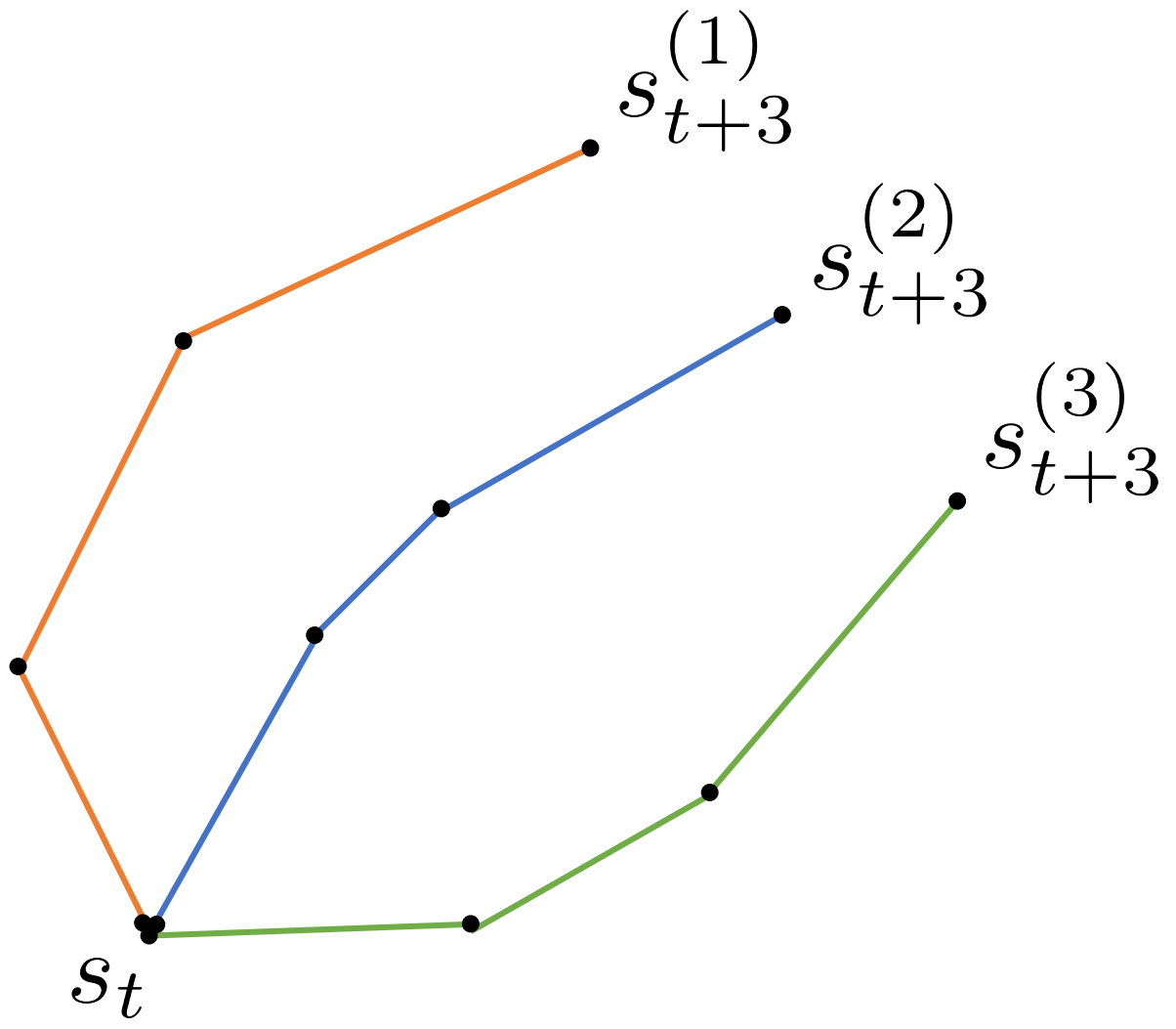
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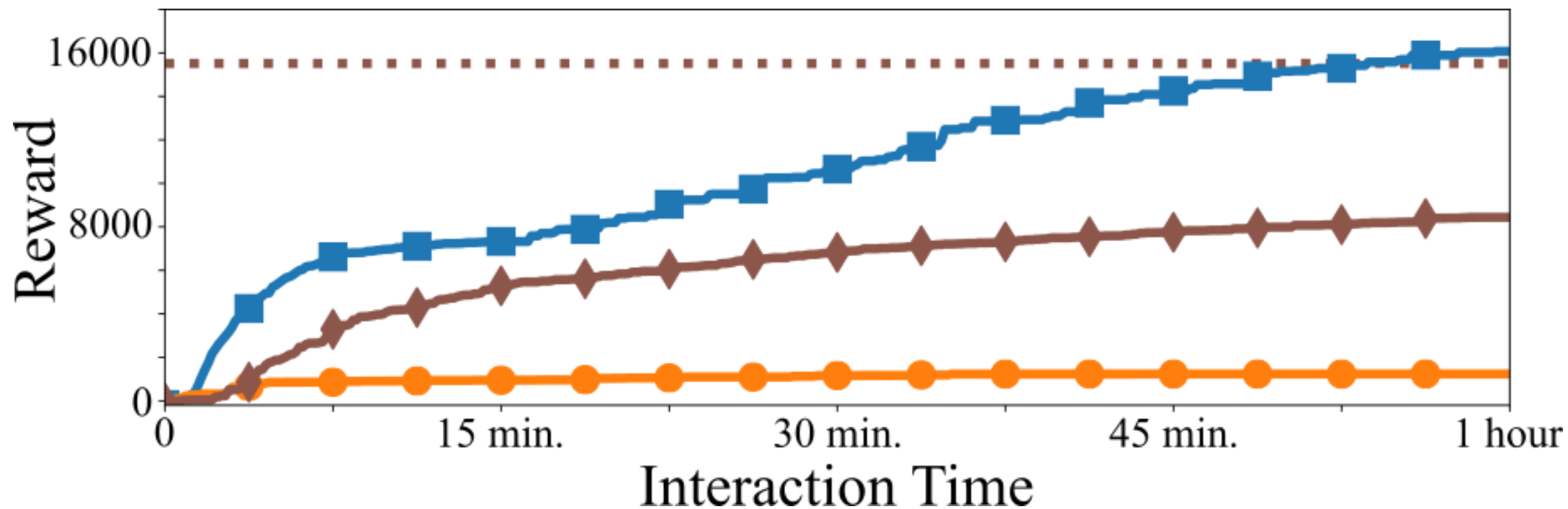
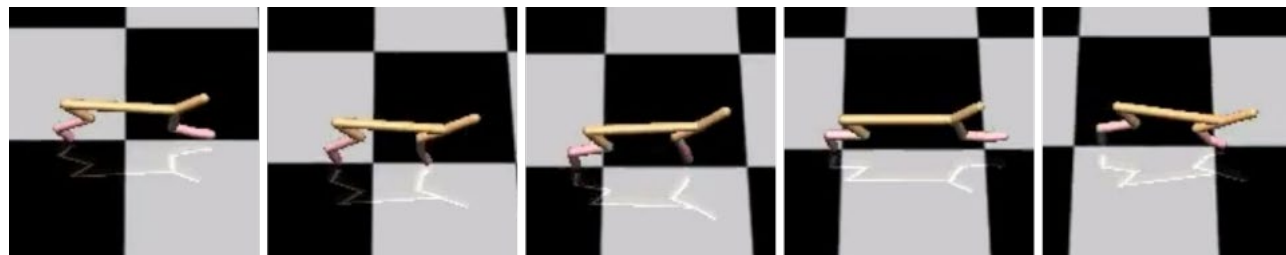
Trajectory Sampling for State Propagation



Trajectory Sampling for State Propagation



Experimental Results



Our Method

SOTA
Model-Based
(Nagabandi et
al. 2017)

SOTA
Model-Free
(Haarnoja et
al. 2018)

SOTA
Model-Free
at convergence

Deep Reinforcement Learning in a Handful of Trials using Probabilistic Dynamics Models

Poster #165

Code: <https://github.com/kchua/handful-of-trials>

Website: <https://sites.google.com/view/drl-in-a-handful-of-trials>

- ✓ Data efficient
- ✓ Competitive asymptotic performance
- ✓ Easy to implement



Kurtland Chua



Roberto Calandra



Rowan McAllister



Sergey Levine